



MS Keyfob
Master Development System
User's Guide

Wireless made simple[®]



Warning: Some customers may want Linx radio frequency ("RF") products to control machinery or devices remotely, including machinery or devices that can cause death, bodily injuries, and/or property damage if improperly or inadvertently triggered, particularly in industrial settings or other applications implicating life-safety concerns ("Life and Property Safety Situations").

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Customers may use our (non-Function) Modules, Antenna and Connectors as part of other systems in Life Safety Situations, but only with necessary and industry appropriate redundancies and in compliance with applicable safety standards, including without limitation, ANSI and NFPA standards. It is solely the responsibility of any Linx customer who uses one or more of these products to incorporate appropriate redundancies and safety standards for the Life and Property Safety Situation application.

Do not use this or any Linx product to trigger an action directly from the data line or RSSI lines without a protocol or encoder/decoder to validate the data. Without validation, any signal from another unrelated transmitter in the environment received by the module could inadvertently trigger the action.

All RF products are susceptible to RF interference that can prevent communication. RF products without frequency agility or hopping implemented are more subject to interference. This module does not have a frequency hopping protocol built in.

Do not use any Linx product over the limits in this data guide. Excessive voltage or extended operation at the maximum voltage could cause product failure. Exceeding the reflow temperature profile could cause product failure which is not immediately evident.

Do not make any physical or electrical modifications to any Linx product. This will void the warranty and regulatory and UL certifications and may cause product failure which is not immediately evident.

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MS Keyfob Master Development System User's Guide

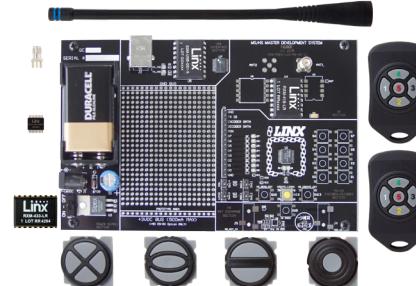


Figure 1: MS Keyfob Transmitter Master Development System

Introduction

The Linx MS keyfob transmitter offers a simple, efficient and cost-effective method of adding remote control capabilities to any product. This Master Development System gives a designer all the tools necessary to incorporate the transmitter, LR Series receiver and MS Series decoder into a product. It serves several important functions:

- Rapid Evaluation: It allows the performance and features of the transmitter, LR Series receiver and MS Series encoders and decoders to be evaluated quickly in a user's environment.
- Range Testing: The transmitter and receiver board form a full remote control system so that the range performance can be evaluated.
- Design Benchmark: The boards provide a known benchmark against which the performance of a custom design may be judged.
- Application Development: An onboard prototyping area allows for the development of custom circuits directly on the development board. All signal lines are available on a header for easy access.

The Master Development System includes 2 MS keyfob transmitters, 2 LR Series receivers*, 2 MS Series decoders*, 1 receiver / decoder development board, 1 CW Series antenna, demonstration software CD and full documentation.

*One part is soldered to the board, one extra is for use on the first prototype board

Ordering Information

Ordering Information	
Part Number	Description
MDEV-***-HH-KF-MS	MS Keyfob Master Development System
*** = 418 (Standard) or 433MHz	

Figure 2: Ordering Information

MS Series Decoder Development Board

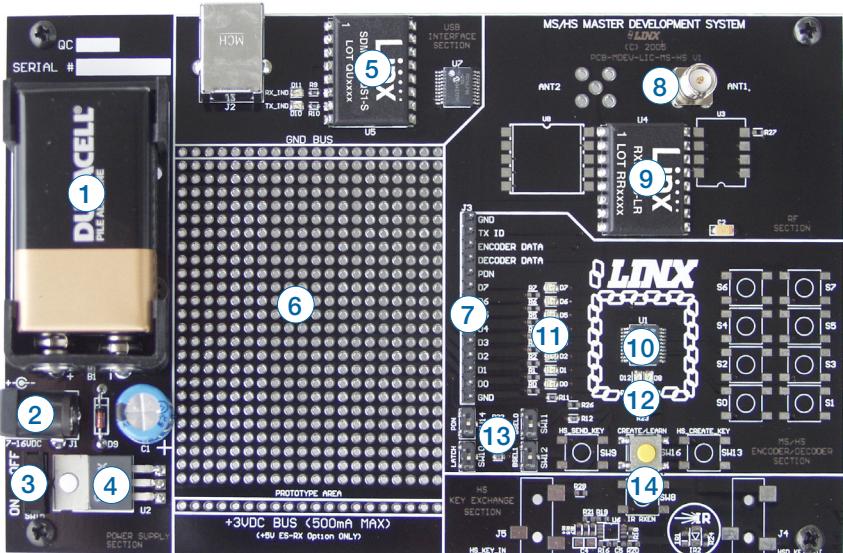


Figure 3: The MS Series Decoder Development Board

- 1. 9V Battery
- 2. Power Jack
- 3. On-Off Switch
- 4. Voltage Regulator
- 5. QS Series USB Module
- 6. Prototype Area
- 7. Break-Out Header
- 8. RP-SMA Antenna Connector
- 9. LR Series Receiver
- 10. MS Series Decoder
- 11. Data Line LEDs
- 12. Indicator LEDs
- 13. Function Switches
- 14. LEARN Button

Using the Master Development System

Using the Master Development System is straightforward. After unpacking the board, screw the antenna onto the connector, install the supplied 9V battery, and turn on the power switch. The encoder and decoder are configured at the factory and work straight out of the box. To create a new address, follow these easy steps:

1. Press and hold the CREATE_ADDR button on the transmitter to create a new Code Word. This is done by sticking a paper clip through the hole on the back of the case and pressing the button inside. The Address is randomized for as long as the button is held down. Once comfortable that the number is sufficiently random, release the button.
2. Once the button is released, the MODE_IND LED begins to flash to indicate that it is ready to accept Control Permissions. Press all of the data line buttons that are to be recognized, then press the CREATE_ADDR button again or let it time out after seventeen seconds.
3. Press the LEARN button on the decoder board and the MODE_IND LED starts flashing. Press any of the data line buttons on the transmitter and press the LEARN button again. The encoder's Address has now been learned by the decoder and they will operate together.

Troubleshooting

If the boards fail to work out of the box, then try the following:

- Check the battery to make sure it is not dead.
- Make sure the baud rate switches are set to 9,600bps on the decoder board.
- Make sure that the antenna is connected.
- Check to see if the PDN switch is on, placing the decoder into Power Down Mode. In most cases, the encoder PDN switch should be on.
- Make sure that you set your Control Permissions correctly. If you have not set the encoder to use a particular line, then when you press a button on the encoder board, the MODE_IND LED on the decoder board lights up, but the data line LED does not light up.

If all of these appear to be in order, then call +1 800 736 6677 or e-mail techsupport@linxtechnologies.com for technical support.

Setting the Transmitter Address

The address is changed by using a paper clip or probe to press the CREATE_ADDR button on the board through the hole in the back of the case. When the button is depressed, an LED lights up on the front of the keyfob, indicating that the address is being created. The address is randomized for as long as the button is held down. When the button is released, the randomized address is saved and the LED begins flashing to indicate that the Control Permissions may now be set.



Figure 4: CREATE_ADDR Button Access

Press the buttons that the Keyfob user will have the authority to access. Press the CREATE_ADDR button with the paper clip again or wait 17 seconds for it to time out. The address and Control Permissions are now set. The decoder needs to learn the address before it accepts any transmissions. Please see the MS Series Decoder Data Guide for details.

Button Assignments

The Keyfob is available in five button configurations. Those configurations and the corresponding switch numbers are shown in Figure 5. The table shows which encoder data line has been assigned to each switch. When a button is pressed, the data line goes high, causing the corresponding data line on the decoder to go high if the address has been learned.

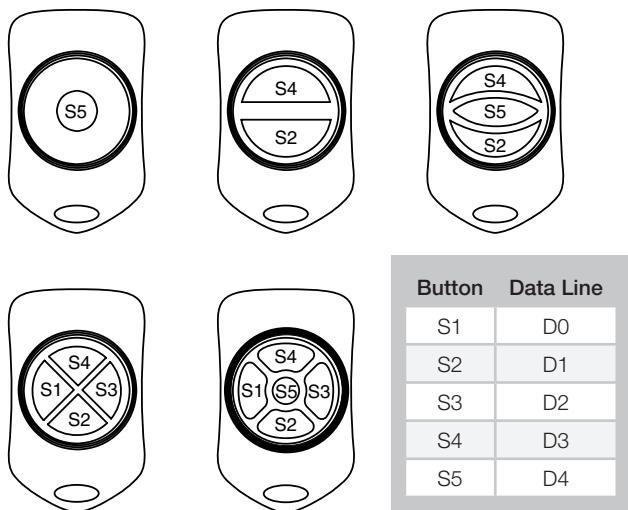


Figure 5: OTX-***-HH-KF#-MS Button Assignments

The Decoder Board

The decoder board included with the evaluation kit uses the LR Series receiver to receive the signal from the Keyfob transmitter and then feeds it into the MS Series decoder. The board is designed to allow full access to the many features of the decoder and to speed development and integration of the LR and MS into a product. The following sections describe the features of this board in detail.

The Prototyping Area

The prototyping area on the decoder board contains a large area of plated through-holes so that external circuitry can be placed on the board. This circuitry can be interfaced with the MS Series decoder through the breakout header to the right of the holes. At the bottom of this area is a row connected to the 3V power supply and at the top is a row connected to ground.

All of the data lines are connected to a wire-wrap header to the right, allowing easy access from the prototyping area. The Decoder Data and TX ID lines are also available on the header as well as the PDN line from the RF module. This allows complete control of the entire system from the prototyping area, giving the designer a great deal of flexibility in using the board.

The Power Supply

The power supply on the decoder board consists of a standard 9V battery and power jack connected to a 3.0V voltage regulator. It can provide approximately 500mA of current to the prototyping area, so if the added circuitry needs more than this, the designer must add an external supply. If the circuit consistently draws more than 100mA of current, it might be better to use the power jack rather than the battery, as the battery may run down fairly quickly, reducing testing and development time.

The jack accepts a standard 5.5mm plug with the tip ground and the outer shell 7 to 16VDC positive supply. While a reverse voltage protection diode has been included on the board to protect the circuitry in case the voltage on the plug is reversed, it is still a good idea to double-check the polarity.

The RF Area

Figure 6 shows the RF area of the development board. The board uses the LR Series receiver as shown. Attach the included antenna to the reverse polarity SMA connector before operation.

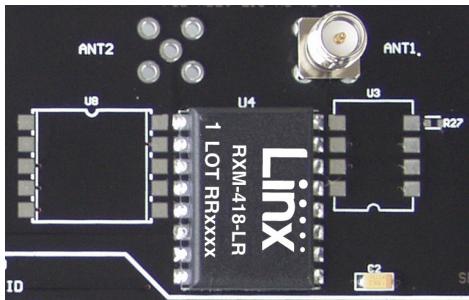


Figure 6: The Decoder Board RF Area

The Decoder Area

Figure 7 shows the decoder area of the development board.

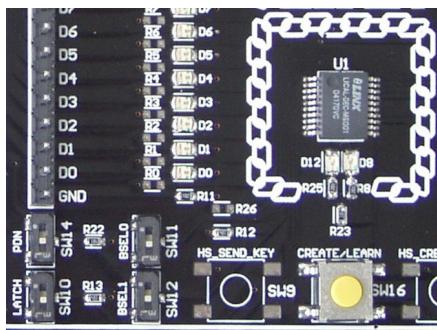


Figure 7: The Decoder Area

The decoder is in the center beneath the Linx logo. To the left are LEDs that are connected to the decoder data lines. These light up when the decoder receives a signal from the transmitter instructing it to take the data line high. LED D0 corresponds to data line D0 and so forth.

Beneath the decoder are two LEDs. D12 is connected to the MODE_IND line. D8 is connected to the RX_CNTL line and provides visual feedback by lighting up when the decoder activates the receiver when in RX Control Mode.

Under the LEDs is a button that is connected to the LEARN line. This button is used to learn the Address from the encoder as described in the MS Series Decoder Data Guide.

There are four switches to the left of the CREATE / LEARN button. BSEL0 and BSEL1 are used to set the baud rate of the decoder as shown in Figure 8. The Keyfob transmitter is set to 9,600bps, so BSEL0 should be on and BSEL1 should be off. If the switch is up, then the line is high (on); if down, then the line is low (off).

Baud Rate Selection

BSEL1	BSEL0	Baud Rate
0	0	2,400
0	1	9,600
1	0	19,200
1	1	28,800

Figure 8: Baud Rate Selection

Note: The decoder board must be set to the same baud rate as the transmitter in order for the signal to be received correctly.

The PDN switch connects the RX_CNTL line of the encoder to the PDN line of the receiver so that the RX Control Mode can be tested. This mode is described in the MS Series Decoder Data Guide.

The LATCH switch places the decoder into Latch Mode when on, so that the data lines go high when a valid signal is received and stay high until a second valid signal is received. If the switch is off, the data lines are momentary.

The USB Area

The decoder board has a Linx SDM-USB-QS-S USB module for use with the included development software. This module is powered by the USB bus, so it does not pull any current from the battery. Figure 9 shows this section.

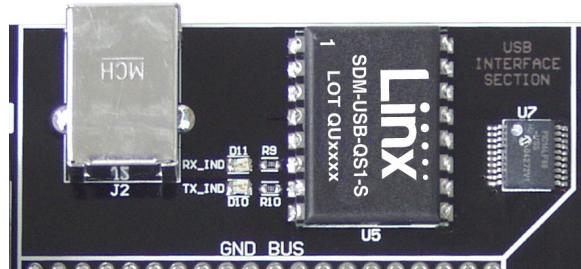


Figure 9: The Decoder Board USB Area

The microcontroller on the right monitors the data lines and generates commands that are sent to the development software on the PC via the QS Series USB module. The RX_IND LED to the left of the module flashes to indicate that data is being received from the PC, and the TX_IND line flashes to indicate that the module is sending data to the PC.

The QS Series USB module provides a simple serial link to a PC via a USB connection. It converts logic-level serial signals to USB-compliant signals and vice versa, so it can be connected to virtually any serial device, including microcontrollers, RS-232 / RS-485 level converters, or Linx RF modules. It is completely self-contained, requiring only a USB type B jack, and includes all necessary firmware and drivers.

Installing the Software and Drivers

The Master Development System uses the QS Series USB module to provide a simple serial interface to a PC via a USB connection. The module requires drivers to be installed on the PC before it can function properly. The QS Series drivers are included on the CD with the software.

The first time the QS module is plugged into the computer, Windows displays the Found New Hardware Wizard, which guides you through installing the drivers. Application Note AN-00201 describes the installation of the drivers in detail. The drivers should be installed before running the Development Software.

The MS Series Master Development Software automatically starts when the CD is inserted and the player in Figure 10 appears.



Figure 10: Software Installer

Clicking the Install Software button starts the Installation Wizard, which guides you through the installation of the development software. The View Documentation button shows a list of the application notes and manuals related to the MS Series. Selecting one of these opens the file in Adobe Acrobat. The Play Movie button plays a short video about Linx on the Player Screen, which can be controlled with the Selection Keypad. Clicking the button on the bottom right of the player opens the Linx Technologies website in the computer's default browser.

The View Documentation list allows for the installation of Adobe Acrobat Reader so that the documents may be viewed. There is also the option of installing Flash, which may be required if the Linx video does not play correctly.

Master Development Software

This software is designed to give a complete understanding of how the MS Series encoders and decoders work together, as well as providing an idea of how they can be used in a system.

The Master Development software can be used in one of two modes. The default mode is a software simulation of the system and does not require any hardware. It simulates two handheld transmitters as well as two receiving devices. This is a good way of showing how the MS Series can work in a system by turning on lights and opening doors.

The second mode is for use with the Master Development System. When the decoder board is plugged into a USB port on the PC, the transmitter can be used to activate the features in the software. If the LEDs on the evaluation board turn on, then the LEDs in the program turn on and activate the corresponding data line function.

Figure 11 is a screen shot of the program set up in Software Operation Mode for simulating the operation of the system.



Figure 11: MS Encoder / Decoder Demonstration Software

The transmitters are on the right hand side and the receivers are at the bottom. Complete instructions for using the software can be found by clicking on the Help label at the top right of the window.

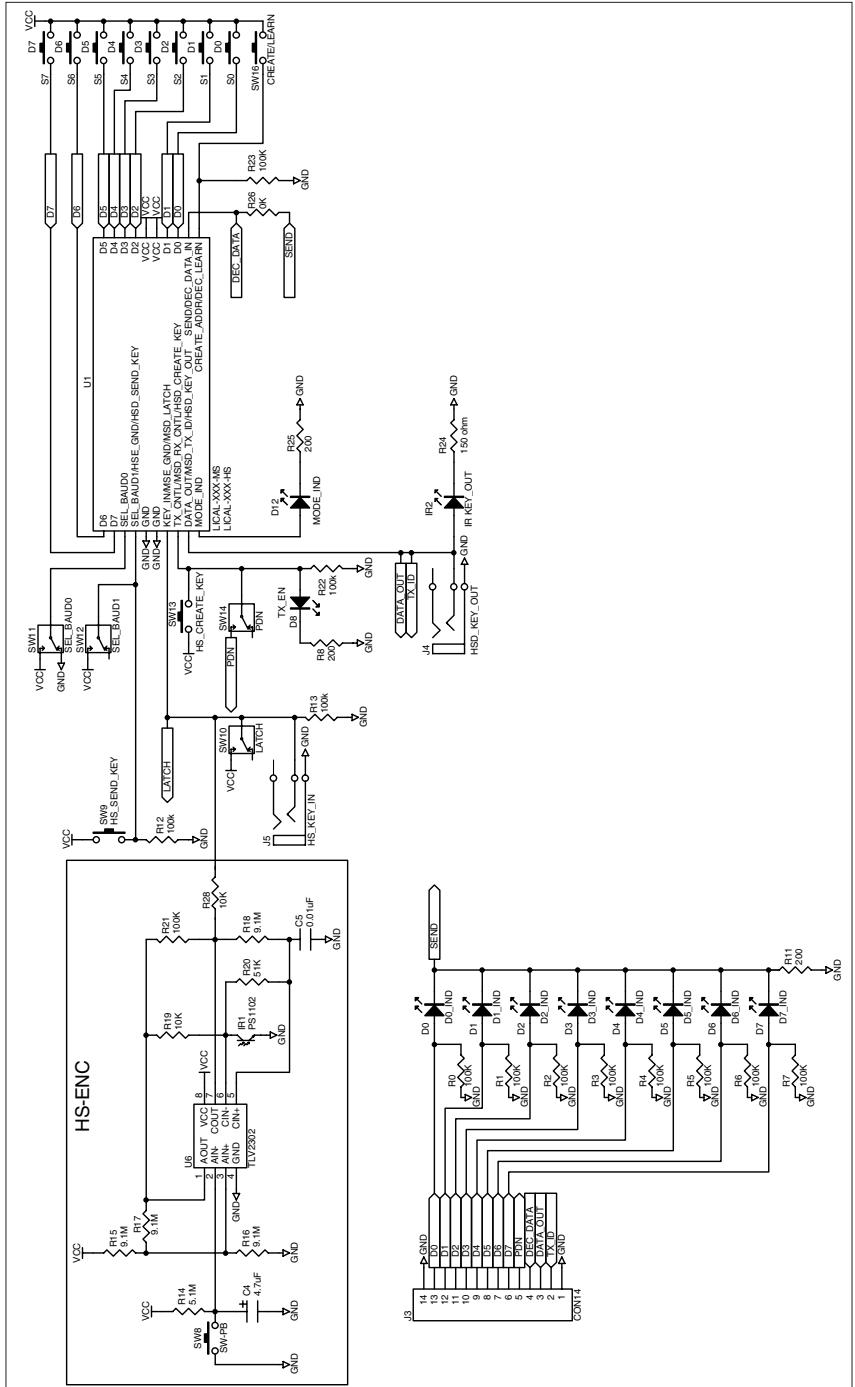
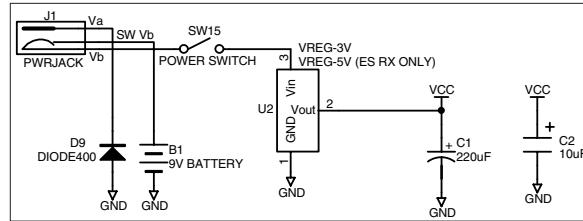


Figure 12: Encoder / Decoder Section



Notes

Figure 13: Power Supply Section

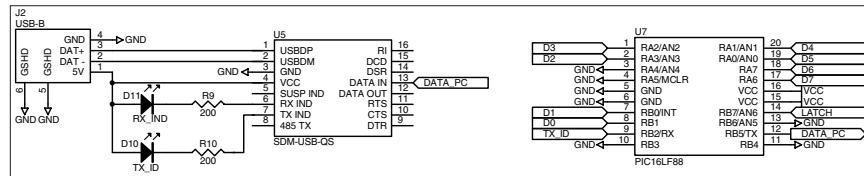


Figure 14: USB Section

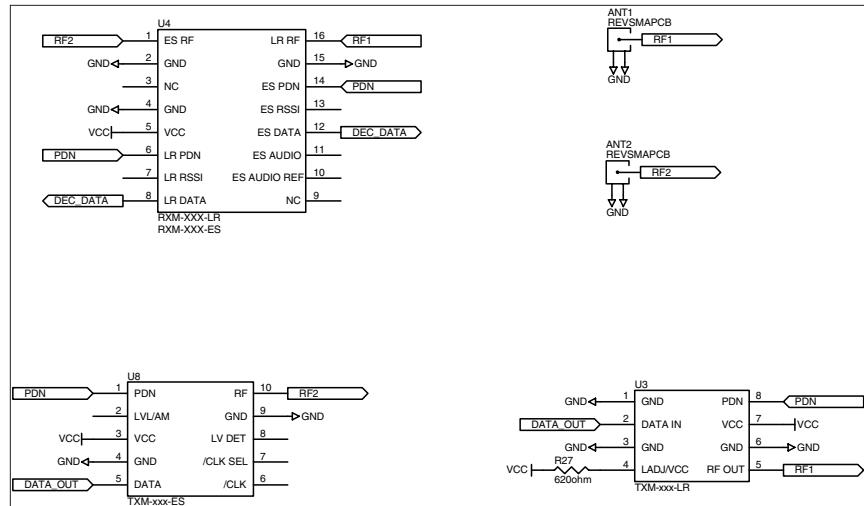


Figure 15: RF Section

Resources

Support

For technical support, product documentation, application notes, regulatory guidelines and software updates, visit www.linxtechnologies.com

RF Design Services

For customers who need help implementing Linx modules, Linx offers design services including board layout assistance, programming, certification advice and packaging design. For more complex RF solutions, Apex Wireless, a division of Linx Technologies, creates optimized designs with

RF components and firmware selected for the customer's application. Call +1 800 736 6677 (+1 541 471 6256 if outside the United States) for more information.

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