New Product

OMRON

Multifunction Counter/Tachometer

Ultra-compact Counter Provides More Complete Functionality.

Basic Features

- Short body with depth of only 59 mm (for 12 to 24-VDC Models with Screw Terminals).*1
- Better readability with character height of 12 mm on 4-digit models and 10 mm
- on 6-digit models.
 The present value display characters can be switched between red, green, and orange.²

Safety and Reliability

• New set value limit and counter functions have been added.

Other Features

- Front Panel can be changed to white or light gray.*3
- New models with two tachometer inputs and two tachometer outputs have been added to the series.^{*4}
- *1.For 100 to 240-VAC Models with Screw Terminals: 78 mm, Models with Sockets: 63.7 mm (case dimension).
- *2. The H7CX-A11 and H7CX-R11 have only red characters.
- *3. The Front Panel can be replaced with an optional Front Panel (except for Tachometer-only Models). *4. Only one prescale value provided.

Features

Basic Features

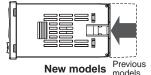
Ultra Short Body

The body depth has been greatly reduced. Helps in making thinner control panels.

12 to 24-VDC Models with Screw Terminals: 59 mm

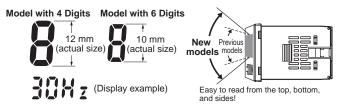
100 to 240-VAC Models with Screw Terminals: 78 mm* Models with Sockets: 63.7 mm (case dimension)

* Power supply circuit and input circuits are isolated for safety and reliability



Easier to Read

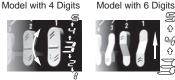
For better readability, the character height for the present value display is 12 mm on models with 4 digits, the largest class in the industry. The wide viewing angle and brightness provide excellent visibility. The number of display segments has also been increased to make settings easier to understand, and the present value display can be switched between red, green, and orange so that output status can be seen from a distance.



Note: The display color can be switched on all models except for the H7CX-A11 and H7CX-R11.

The Easiest Operation

Operation is simplified by the Up/Down Key for each digit on 4-digit models and Up Key for each digit on 6-digit models.





For the most recent information on models that have been certified for safety standards, refer to your OMRON website.



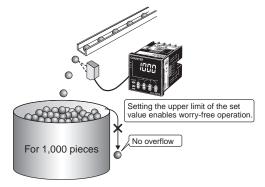
Safety and Reliability Isolated Power Supply and Input Circuits

Power supply circuit and input circuits are isolated inside the Counter/ Tachometer. Previous non-isolated counters had wiring restrictions and could be damaged if wired incorrectly. The H7CX removes these worries.

Note: Except 12 to 24-VDC models.

Set Value Limit

You can set an upper limit for the set value to prevent unexpected operation of output devices caused by setting mistakes.



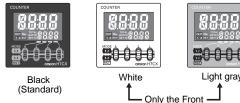
Output Counter

The output counter counts the number of times the output turns ON (alarms can be displayed and the count can be monitored in increments of 1,000 operations). This counter is useful in managing the service life of the Counter/Tachometer or the load.

Other Features

The front color can be changed simply by replacing the Front Panel.

The Front Panel can be replaced with an optional Front Panel (sold separately) with a different color to match the installation site. Select from black, white, and light gray (except for models with tachometer function only).



 Only the Front — Panel can be replaced.

Universal NPN/PNP Input

DC 2-wire sensors can be connected for a wide range of input devices.

Waterproof, Dust-proof Structure (UL508 Type 4X and IP66)

Worry-free application is possible in locations subject to water. **Note:** When the Y92S-29 Waterproof Packing is used.

Model Number Structure

Model Configuration

Key Protection

Select from any of seven protection patterns. Use the best one for the application.

New Functions

Many useful functions have been added, including a Twin Counter Mode and many tachometer functions to handle even more applications.

New Tachometer Functions

- Control with two independent inputs (independent measurements, differential, absolute ratio, and error ratio)
- Peak/bottom hold function
- Output hysteresis setting
- Output OFF delay
- · Switching the measurement method (pulse cycle/pulse width)
- Startup time
- Auto-zero time
- · Averaging method/Number of averaging times
- AMD-compatible Mode

Note: Refer to *"Model Configuration"* below, for details on applicable functions.

| | oomiguiu | - | | | H7CX Series | | |
|------------------|---------------------------|---------------|-----------------|------------------|--|----------------------------------|---|
| | | Th OX Genes | | | | | |
| | | | | | | | - |
| | | | | | | | |
| | | H7C | X-A-seri | es Multifunction | Preset Counter | H7CX-R-series Digital Tachometer | |
| Model | | | | | | | |
| Classification | | Preset co | | unter | Preset counter/tachometer | Tac | hometer |
| Model | | H7CX-A |]-N | H7CX-A4W⊡-N | H7CX-AW□-N/-AU□-N | H7CX-R11□-N | H7CX-R11W□-N |
| | 1-stage preset counter | Yes | | Yes | Yes | No | |
| | 2-stage preset counter | No | | Yes | Yes | No | |
| Function | Total and preset counter | Yes | | Yes | Yes | No | |
| | Batch counter | No | | Yes | Yes | No | |
| | Dual counter | No | | Yes | Yes | No | |
| | Twin counter | No | | Yes | Yes | No | |
| | Tachometer | No | | No | Yes ^{*1} | Yes | |
| Tachometer input | | No | | No | Yes 1 input or 2 inputs (independent measurements, differential, absolute ratio value, and error ratio value) | Yes 1 input | Yes 2 inputs (independent measurement) only |
| Settings | | 1-stage | | 2-stage | | 1-stage | |
| External c | onnections | 11-pin socket | | Screw ter | minals | 11-pin socket | |
| Display co | lor of present value | Red | | Red, green, | or orange | Red | |
| Display di | gits | 4 or 6 di | digits 4 digits | | 6 digits | 6 digits | |

*1. Set the tachometer input mode from the function setting mode to switch to the tachometer function.

Model Number Legend (Not all possible combinations of functions are available.)

H7CX-_________-N

1. Type

| Meaning |
|---------------|
| Standard type |
| Tachometer |
| |

4. Settings

| _ | | | | | |
|--------|---------------------------------|--|--|--|--|
| Symbol | Meaning | | | | |
| None | 1-stage setting | | | | |
| U | Factory-set to 1-stage setting | | | | |
| W | Factory-set to 2-stage setting* | | | | |

* The H7CX-R11W is a 1-stage (2 inputs and outputs) rather than a 2-stage Counter.

2. External connections

| Symbol | Meaning |
|--------|-----------------|
| None | Screw terminals |
| 11 | 11-pin socket |

5. Output type

| Symbol | Meaning |
|--------|---|
| None | Contact output or contact output + transistor output |
| S | Transistor output |

3. Digits

| - | |
|--------|----------|
| Symbol | Meaning |
| None | 6 digits |
| 4 | 4 digits |

6. Supply voltage

| Symbol | Meaning |
|--------|---------------------------------|
| None | 100 to 240 VAC at 50/60 Hz |
| D | 12 to 24 VDC |
| D1 | 12 to 24 VDC/24 VAC at 50/60 Hz |

Note: Estimates can be provided for coatings and other specifications that are not given in the datasheet. Ask your OMRON representative for details.

Ordering Information

List of Models

| Туре | Classification | Configuration | External connections | Settings | Display digits | Outputs | Power supply voltage | Model | |
|------------------|-------------------------|---|----------------------|----------------------|--------------------------|---|------------------------------|----------------|-------------|
| | | | | | 4 digits | Contact output (SPDT) | 100 to 240 VAC | H7CX-A114-N | |
| | | | | | | Transistor output (SPST) | | H7CX-A114S-N | |
| | | | | | | Contact output (SPDT) | 12 to 24 VDC/24 VAC | H7CX-A114D1-N | |
| | | | 11-pin socket | | 6 digits | Contact output (SPDT) | 100 to 240 VAC | H7CX-A11-N | |
| | | | | | | Transistor output (SPST) | | H7CX-A11S-N | |
| | | | | | | Contact output (SPDT) | 12 to 24 VDC/24 VAC | H7CX-A11D1-N | |
| | | 1-stage preset | | | | Transistor output (SPST) | | H7CX-A11SD1-N | |
| | | counterTotal and preset | | 1-stage | | Contact output (SPDT) | 100 to 240 VAC | H7CX-A4-N | |
| | | counter | | | 4 digits | Transistor output (SPST) | 100 to 240 VAC | H7CX-A4S-N | |
| | | | | | 4 aigits | Contact output (SPDT) | 12 to 24 VDC | H7CX-A4D-N | |
| | Preset counter | | | | | Transistor output (SPST) | 12 10 24 VDC | H7CX-A4SD-N | |
| | | | | | | Contact output (SPDT) | 100 to 240 V/AC | H7CX-A-N | |
| | | | Screw terminals | | Caliaita | Transistor output (SPST) | 100 to 240 VAC | H7CX-AS-N | |
| | | | | | 6 digits | Contact output (SPDT) | 12 to 24 VDC | H7CX-AD-N | |
| | | | | | | Transistor output (SPST) | | H7CX-ASD-N | |
| H7CX-A Series | | 1-stage preset counter 2-stage preset counter Total and preset counter Batch counter Dual counter Twin counter | | | 4 digits | Contact output (SPST + SPDT) | 100 to 240 VAC | H7CX-A4W-N | |
| | | | | | | Transistor output (DPST) | 12 to 24 VDC | H7CX-A4WSD-N | |
| | | 1-stage preset | | 2-stage | | Contact output (SPST + SPDT) | - 100 to 240 VAC | H7CX-AW-N | |
| | | | | | | Transistor output (DPST) | | H7CX-AWS-N | |
| | | counter | | | | Contact output (SPST + SPDT) | | H7CX-AWD1-N | |
| | | 2-stage preset counter Total and preset counter Total and preset counter Batch counter Dual counter Twin counter Tachometer | | | | | 12 to 24 VDC/24 VAC | H7CX-AWSD1-N | |
| | Preset counter/ | | | | | Transistor output (DPST) | 12 to 24 VDC | H7CX-AWSD-N | |
| | lachometer | | | | | Contact output (SPDT) + Transistor output (SPST) | 100 to 240 VAC | H7CX-AU-N | |
| | | | | | | Contact output (SPDT) + Transistor output (SPST) | 12 to 24 VDC/24 VAC | H7CX-AUD1-N | |
| | | | | | | Transistor output (DPST) | | H7CX-AUSD1-N | |
| | | | 11-pin socket | 1-stage | | 0 | 100 to 240 VAC | H7CX-R11-N | |
| H7CX-R | Tachometer • Tachometer | hometer • Tachometer 11 | | (1 input and output) | 6 digits | Contact output (SPDT) | 12 to 24 VDC/24 VAC | H7CX-R11D1-N | |
| Series | | | | | 1-stage (2 inputs and | tage | Contact output (SPDT + SPST) | 100 to 240 VAC | H7CX-R11W-N |
| | | | | outputs) | | | 12 to 24 VDC/24 VAC | H7CX-R11WD1-N | |

Note: 1. The functions that are provided depend on the model. Check detailed specifications before ordering.

2. Refer to page page 37 and later for information on H7CX-R Tachometers.

Accessories (Order Separately)

Front Panels (Replacement Part)

| Model | Color | Applicable Counters | Page |
|------------|--------------------|---------------------|------|
| Y92P-CXC4G | Light gray (5Y7/1) | 4-digit Counter | |
| Y92P-CXC4S | White (5Y9.2/0.5) | | |
| Y92P-CXC4B | Black (N1.5) | | 12 |
| Y92P-CXC6G | Light gray (5Y7/1) | 6-digit Counter | 12 |
| Y92P-CXC6S | White (5Y9.2/0.5) | | |
| Y92P-CXC6B | Black (N1.5) | | |

Note: 1. You can change the color of the Front Panel when mounting the Counter. The Counter is shipped with a black (N1.5) Front Panel. 2. "COUNTER" is printed on the front of Replacement Front Panels.

Soft Cover

| Model | Remarks | Page | |
|-----------|---------|------|--|
| Y92A-48F1 | | 12 | |

Hard Cover

| Model | Remarks | Page |
|---------|---------|------|
| Y92A-48 | | 12 |

Flush Mounting Adapter

| Model | Remarks | Page |
|---------|--|------|
| Y92F-30 | Included with models with screw terminals. | |
| Y92F-45 | Use this Adapter to install the Counter/ Tachometer in a cutout previously made for a DIN 72 \times 72 mm device (panel cutout: 68 \times 68 mm). | 12 |

Waterproof Packing

| Model | Remarks | Page |
|---------|--|------|
| Y92S-29 | Included with models with screw terminals. | 12 |

Connection Sockets

| Model | Classification | Connectable Counter/ Tachometers | Remarks | Page |
|-----------|--|--|---|------|
| P2CF-11 | Front-connecting Socket | | | |
| P2CF-11-E | Front-connecting Socket (Finger-safe Type) | H7CX-□11□-N | Round crimp terminals cannot be used on Finger-safe Sockets. Use forked crimp terminals. | 13 |
| P3GA-11 | Back-connecting Sockets | 1 | A Y92A-48G Terminal Cover can be used with the Socket to create a finger-safe construction. | |

Terminal Covers for P3GA-11 Back-connecting Socket

| Model | Remarks | Page |
|----------|---------|------|
| Y92A-48G | | 13 |

H7CX-A□-N

- Easy to check the output status from a long distance with changing display colors^{*1} (red, green, and orange).
- Includes total and preset counter, batch counter, dual counter, twin counter, and tachometer.*2
- *1. Not supported by the H7CX-A11□-N.
- *2. The functions that can be selected depend on the model.



For the most recent information on models that have been certified for safety standards, refer to your OMRON website.

Specifications

Ratings

| Item | Models | H7CX-A114□-N | H7CX-A11□-N | H7CX-A4□-N | H7CX-A□-N | H7CX-A4W□-N | H7CX-AW -N/-AU -N |
|--------------------|---|---|---|---|---|---|---|
| Classificat | tion | Preset counter | | | | | Preset counter/ tachometer |
| Configura | tion | 1-stage preset counter, 1- | stage preset counter with | total counter (selectable)*1 | | 1-stage/2-stage preset counter, total and preset counter*1, batch counter, dual counter, and twin counter (selectable) | 1-stage/2-stage preset counter, total and preset counter*1, batch counter, dual counter, twin counter, and tachometer (selectable) |
| | Power supply voltage*2 | 100 to 240 VAC, 50/60 24 VAC, 50/60 Hz or 12 | | • 100 to 240 VAC, 50/60 • 12 to 24 VDC | Hz | | 100 to 240 VAC at 50/ 60 Hz 24 VAC at 50/60 Hz or 12 to 24 VDC 12 to 24 VDC |
| Ratings | Operating volt- age fluctuation range | 85% to 110% of rated sup | oply voltage (12 to 24 VDC | : 90% to 110%) | | | • |
| | Power con- sumption | | | 1 | /DC, Approx. 3.7 W at 12 to | o 24 VDC | |
| Mounting | method | Flush mounting or surface | e mounting | Flush mounting | | | |
| External c | onnections | 11-pin socket | | Screw terminals | | | |
| Degree of | protection | IEC IP66, UL508 Type 4> | (indoors) for panel surfac | e only and only when Y928 | S-29 Waterproof Packing is | used. | |
| Input sign | als | CP1, CP2, reset, and tota | l reset | | | CP1, CP2, reset 1, and re | eset 2 |
| | Maximum counting speed | 30 Hz (minimum pulse wi *Common setting for CP1 | | nimum pulse width: 0.1 ms) | (selectable) (ON/OFF ratio | o 1:1)*3 | |
| | Input mode | Increment, decrement, inc | crement/decrement (UP/DO | OWN A (command input), l | JP/DOWN B (individual inp | uts), or UP/DOWN C (quad | frature inputs)) |
| Counter | Output mode | N, F, C, R, K-1, P, Q, A, H | <-2, D, and L. | | | N, F, C, R, K-1, P, Q, A, H | <-2, D, L, and H. |
| | One-shot out- put time | 0.01 to 99.99 s | | | | | |
| | Reset system | External (minimum reset | signal width: 1 ms or 20 ms | s, selectable), manual, and | automatic reset (internal a | ccording to C, R, P, and Q | mode operation) |
| Tachomet | er | Refer to the separate tabl | e for tachometer function r | atings. | | | |
| Prescaling | a function | Yes (0.001 to 9.999) | Yes (0.001 to 99.999) | Yes (0.001 to 9.999) | Yes (0.001 to 99.999) | Yes (0.001 to 9.999) | Yes (0.001 to 99.999) |
| - | oint adjustment | Yes (rightmost 3 digits) | | | | | |
| Sensor wa | • | | out is turned OFF and no i | nput is accepted during ser | nsor waiting time) | | |
| Input meth | hod | ON residual voltage: $3 V$ OFF impedance: $100 k\Omega$ Voltage input: High (logic) level: 4.5 to 3 | min. 0 VDC DC (Input resistance: appro | | | | |
| External p | ower supply | 12 VDC (±10%), 100 mA | (except for H7CX-AD mc | odels) Refer to Precautions | for Correct Use on page p | age 53 for details. | |
| Control ou | utput | | | | oplied load: 10 mA at 5 VD 1.5 VDC max. (approx. 1 \ | | |
| Display*4 | | 7-segment, negative transmissive LCD Character height Count value: 12 mm (red) Set value: 6 mm (green) | 7-segment, negative transmissive LCD Character height Count value: 10 mm (red) Set value: 6 mm (green) | 7-segment, negative transmissive LCD Character height Count value: 12 mm (red, green, or orange selectable) Set value: 6 mm (green) | 7-segment, negative transmissive LCD Character height Count value: 10 mm (red, green, or orange selectable) Set value: 6 mm (green) | 7-segment, negative transmissive LCD Character height Count value: 12 mm (red, green, or orange selectable) Set value: 6 mm (green) | 7-segment, negative transmissive LCD Character height Count value: 10 mm (red, green, or orange selectable) Set value: 6 mm (green) |
| Digits | | 4 digits -999 to 9999 (-3 digits to +4 digits) | 6 digits -99999 to 999999 (-5 digits to +6 digits) | 4 digits -999 to 9999 (-3 digits to +4 digits) | 6 digits -99999 to 999999 (-5 digits to +6 digits) | 4 digits -999 to 9999 (-3 digits to +4 digits) | 6 digits -99999 to 999999 (-5 digits to +6 digits), tachometer: 0 to 999999 |
| Memory b | ackup | EEPROM (overwrites: 10 | 0,000 times min.) that can | store data for 10 years min |). | | • |
| Operating range | temperature | -10 to 55°C (-10 to 50°C | if Counter/Tachometers an | re mounted side by side) (v | vith no icing or condensatio | n) | |
| Storage te | emperature range | -25 to 70°C (with no icing | or condensation) | | | | |
| Operating | humidity range | 25% to 85% | | | | | |
| Case colo | | | ont Panels are available to | change the Front Panel co | lor to light gray or white.) | | |
| Attachmer | | - | - | | waterproof packing, termin | al cover | Flush mounting adapter, waterproof packing, terminal cover, label for DIP switch settings |

*1. 1-stage preset counter and total counter functionality.

*2. Do not use the output from an inverter as the power supply. The ripple must be 20% maximum for DC power.

*3. A response of 10 kHz (minimum pulse width: 0.05 ms) is possible if the response speed is 5 kHz and the 1-stage preset counter input mode is increment, decrement, or increment/decrement (command input).

*4. The display is lit only when the power is ON. Nothing is displayed when power is OFF.

Tachometer Function Ratings

| Model | H7CX-A114 H7CX-A11 H7CX-A4 H7CX-A4 H7CX-A H7CX-A H7CX-A4W | | H7CX-AWE |]-N/-AU□-N | | |
|-------------------------------|---|---|---|---|--|--|
| Input mode | | Selectable from independent n for 2 inputs. | Selectable from independent measurements for 1 or 2 inputs, differential input for 2 inputs, absolute ratio for 2 inputs, and error ratio for 2 inputs. | | | |
| Pulse measurement method | | Periodic measurement | | Pulse width measurement | | |
| Maximum counting speed | | 30 Hz (minimum pulse width: 16.7 ms) | 1-input mode: 10 kHz (minimum pulse width: 0.05 ms) Other modes: 5 kHz (minimum pulse width: 0.1 ms) | 30 Hz (minimum pulse width: 16.7 ms) | 1-input mode: 10 kHz (minimum pulse width: 0.05 ms Other modes: 5 kHz (minimum pulse width: 0.1 ms) | |
| Minimum input signal width | | | | 30 ms*1 | 1-input mode: 0.2 ms Other modes: 0.4 ms* | |
| Measuring ranges | No tachometer | 0.001 to 30.00 Hz | 1-input mode: 0.001 to 10 kHz, Other modes: 0.01 to 5 kHz | 0.030 to 999999 s | 1-input mode: 0.0002 to 99999 s Other modes: 0.0004 to 99999 s | |
| Sampling period | functionality | 200 ms min. | 200 ms min. or continuous selectable (minimum interval of 10 ms) | Continuous (minimum interval | of 10 ms) | |
| Measuring accuracy | | ±0.1% FS ±1 digit max. (at 23 | ±5°C) | | | |
| Output mode | | Input mode: Not 2-input independent meas 2-input independent measuren | urement: HI-LO, AREA, HI-HI, LO-L nent: HI-HI, LO-LO | 0 | | |
| Auto-zero time | | 0.1 to 999.9s | | | | |
| Startup time | | 0.0 to 99.9s | | | | |
| Averaging | | Simple averaging/moving aver | aging selectable, Processing: OFF, | 2, 4, 8, or 16 times | | |
| Hold input | | Minimum input signal width: 20 |) ms | | | |

* An input OFF time of at least 20 ms is required.

Characteristics

| Insulation re | esistance | $100\ M\Omega$ min. (at 500 VDC) between current-carrying terminals and exposed non-current-carrying metal parts, and between non-continuous contacts |
|---------------------|----------------|---|
| Dielectric strength | | 2,000 VAC, 50/60 Hz for 1 min between current-carrying metal parts and non- current-carrying metal parts 2,000 VAC, 50/60 Hz for 1 min between power supply and input circuit for all models except H7CX-IDD (1,000 VAC for 24 VAC/12 to 24 VDC) 1,000 VAC (for H7CX-ISD), 50/60 Hz for 1 min between control output, power supply, and input circuit (2,000 VAC for models other than H7CX-ISDI) 1,000 VAC, 50/60 Hz for 1 min between non-continuous contacts |
| Impulse with | nstand voltage | 3.0 kV between power terminals (1.0 kV for models with 24 VAC/12 to 24 VDC or 12 to 24 VDC) 4.5 kV between current-carrying terminals and exposed non-current-carrying metal parts (1.5 kV for models with 24 VAC/12 to 24 VDC or 12 to 24 VDC) |
| Noise immu | nity | ± 1.5 kV between power terminals (± 480 V for models with 12 to 24 VDC) ± 600 V between input terminals Square-wave noise by noise simulator (pulse width: 100 ns/1 μ s, 1-ns rise) |
| Static immu | nity | Malfunction: 8 kV Destruction: 15 kV |
| Vibration | Destruction | 10 to 55 Hz with 0.75-mm single amplitude each in three directions for 2 h each |
| resistance | Malfunction | 10 to 55 Hz with 0.35-mm single amplitude each in three directions for 10 min each |
| Shock re- | Destruction | 300 m/s ² each in three directions |
| sistance | Malfunction | 100 m/s ² each in three directions |
| Life expecta | ncy | Mechanical: 10,000,000 operations min. Electrical: 100,000 operations min. (3 A at 250 VAC, resistive load, ambient temperature condition: 23°C)* |
| Weight | | Approx. 130 g (Counter only) |

* Refer to the Life-test Curve.

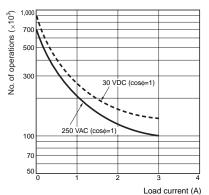
Applicable Standards

| Approved safety standards | CULus (or cURus): UL508/CSA C EN 61010-1 (IEC 61010-1): Pollu B300 PILOT DUTY 1/4 HP 120 VAC, 1/3 HP, 240 VA VDE0106/P100 (finger protection | tion degree 2/ove | 6 6 7 |
|---------------------------------|---|---|--|
| EMC | (EMI) Emission Enclosure: Emission AC mains: (EMS) Immunity ESD: Immunity RF-interference: Immunity Conducted Disturbance Immunity Burst: Immunity Surge: | EN 61000-4-3: EN 61000-4-6: EN 61000-4-4: | y p 1 class A 4 kV contact discharge; 8 kV air discharge 10 V/m (Amplitude-modulated, 80 MHz to 1 GHz); 10 V/m (Pulse-modulated, 900 MHz ±5 MHz) |
| | Immunity Voltage Dip/Interruption | n: EN 61000-4-11 | 2 kV line to ground (power and output lines) : 0.5 cycle, 100% (rated voltage) |

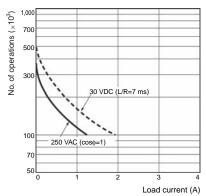
* The following safety standards apply to models with sockets (H7CX-A11_ or H7CX-A114_). cUL (Listing): Applicable when an OMRON P2CF(-E) Socket is used. cUR (Recognition): Applicable when any other socket is used.

Life-test Curve (Reference Values)

Resistive load



Inductive load



A current of 0.15 A max. can be switched at 125 VDC ($\cos\phi=1$) and current of 0.1 A max. can be switched if L/R=7 ms. In both cases, a life of 100,000 operations can be expected.

I/O Functions Using as a Counter^{*1}

| Inputs | CP1, CP2 | (1) In general (except for Dual Counter Mode) Reads counting signals. Increment, decrement, command, individual, and quadrature inputs accepted. (2) When used as a dual counter or twin counter Reads CP1 count signals with CP1 input and CP2 count signals with CP2 input. Increment signals can be input. |
|---------|------------------------|---|
| Inputs | Reset/reset 1 | (1) In general (except for Dual Counter Mode) Resets present value and outputs (OUT2 when using the batch counter)*2. Counting cannot be performed during reset/reset 1 input. Reset indicator is lit while reset input is ON. (2) When used as a dual counter or twin counter. Resets the CP1 present value (to 0). Counting for CP1 input cannot be performed while the reset 1 input is ON. The reset indicator is lit while the reset 1 input is ON. |
| | Total reset or reset 2 | The reset function depends on the selected configuration*3. |
| Outputs | OUT1, OUT2 | Outputs signals according to the specified output mode when a set value is reached. |

 *1. For information on operation of I/O functions, refer to pages page 22 to page 25.
 *2. In increment mode or increment/decrement mode, the present value returns to 0; in decrement mode, the present value returns to the set value with 1-stage models, and returns to set value 2 with 2-stage models. - + ha lit) *3.

| 3. | Reset operates as desc | ribed in the following table. (The reset indicator will not be lit.) |
|----|-----------------------------------|--|
| | Configuration | Reset operation |
| | 1-stage/2-stage preset counter | Does not operate (not used). |
| | Total and preset counter | Resets the total count value. The total count value is held at 0 while the total reset input is ON. |
| | Batch counter | Resets the batch count value and batch output (OUT1). The batch count value is held at 0 while the reset 2 input is ON. |
| | Dual counter | Resets the CP2 present value. Counting for CP2 input cannot be performed while the reset 2 input is ON. |
| | Twin counter | Resets the CP2 present value. |

• The following table shows the delay from when the reset signal is input until the output is turned OFF. (Reference values)

| Minimum reset signal width | Output delay time |
|----------------------------|-------------------|
| 1 ms | 0.8 to 1.2 ms |
| 20 ms | 15 to 25 ms |

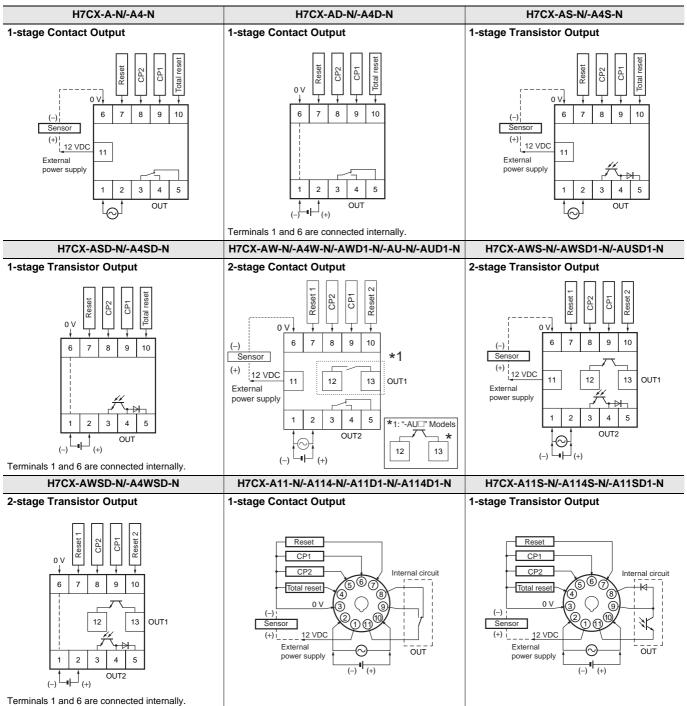
Operating Procedures (Tachometer Function)

| CP1, CP2 | | Reads counting signals. (The CP2 input can be used when the input mode is not 1-input mode.) |
|----------|---------------|--|
| Inputs | Reset/reset 1 | Holds the measurement value and outputs. (The reset 2 input can be used when the input mode is 2-input independent measurement.) Functions as a hold input. The measurement value (displayed value) and the outputs are held while the RST Key on the front panel is pressed. The reset indicator is lit when the value is being held. |
| Outputs | OUT1, OUT2 | Outputs signals according to the specified output mode when a set value is reached. |

Connections

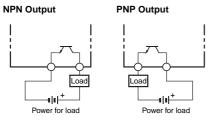
Terminal Arrangement

Confirm that the power supply meets specifications before use.

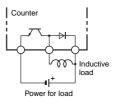


Transistor Output

• The transistor output of the H7CX is isolated from the internal circuitry by a photocoupler, so the transistor output can be used as both NPN and PNP output.



• The diode connected to the collector of the output transistor is used to absorb inverted voltage that is generated when an inductive load is connected to the H7CX.



Internal

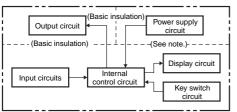
circuit

Voltage Inputs (PNP Inputs)

Approx. 4.7 kΩ

-

Block Diagram



Note: All models except for H7CX-D-N have basic insulation.

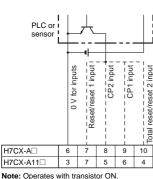
Input Connections

The inputs of the H7CX-D-N are no-voltage (short-circuit or open) inputs or voltage inputs.

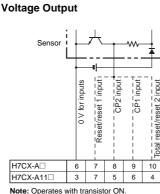
No-voltage Inputs (NPN Inputs)

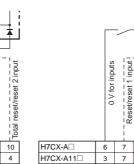
Open Collector

No-contact input



No-voltage Input Signal Levels





Note: Operates with relay ON

Contact Input

Input Circuits

No-voltage Inputs

+14\

CP2 input input eset 2 inpu

8 9 10

5

6

19

eset/I

otal

4

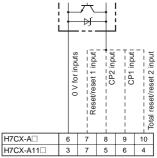
Interna circuit

kΩ

(NPN Inputs)

Input

DC Two-wire Sensor



Note: Operates with transistor ON

Applicable Two-wire Sensor

• Leakage current: 1.5 mA max.

- Switching capacity: 5 mA min.
- Residual voltage: 3 VDC max.
- Operating voltage: 10 VDC

Contact input Use contacts which can adequately switch 5 mA at 10 V. Note: The DC voltage must be 30 VDC max.

Short-circuit level (transistor ON)

Impedance when ON: 1 kΩ max.

Impedance when OFF: 100 kΩ min.

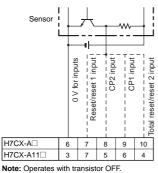
(The leakage current is approx. 12 mA when the impedance is 0 Ω .)

Residual voltage: 3 V max.

Open level (transistor OFF)

Voltage Inputs (PNP Inputs)

No-contact Input (NPN Transistor)



Voltage Input Signal Levels

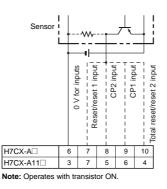
High level (input ON): 4.5 to 30 VDC

Low level (input OFF): 0 to 2 VDC

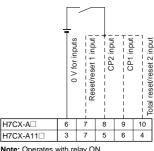
Note: 1. The DC voltage must be 30 VDC max.

2. Input resistance: Approx. 4.7 kΩ

No-contact Input (PNP Transistor)







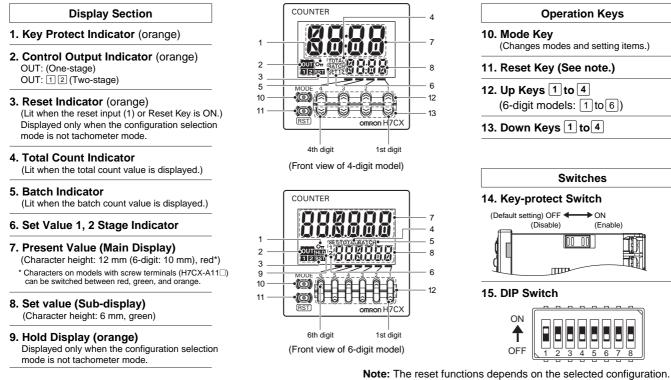
Note: Operates with relay ON.

IN C

CP1, CP2, Reset/Reset 1, and Total Reset/Reset 2

H7CX-A

Nomenclature



Model with 4 Digits

Character Size for Main Display



Character Size for Sub-display

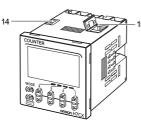




Model with 6 Digits Character Size Character Size for Main Display



for Sub-display 6 mm



| Configuration | Reset operation |
|-----------------------------------|--|
| 1-stage/2-stage preset counter | Resets the present value and outputs. |
| Total and preset counter | Resets the present value and outputs. When the total count value is displayed, resets the present value, the total count value, and outputs. |
| Batch counter | Resets the present value and OUT2. When the batch count value is displayed, resets the present value, the batch count value, and outputs. |
| Dual counter | Resets the CP1 present value, CP2 present value, dual count value, and outputs. |
| Twin counter | Resets the CP1 present value and output 1 when the CP1 present value is displayed. Resets the CP2 present value and output 2 when the CP2 present value is displayed. |
| Tachometer | Holds the measurement value and outputs (hold function). (When the input mode is 2-input independent measurement, the CP1 measurement value display will hold the CP1 measurement value and output 1 and the CP2 measurement value display will hold the CP2 measurement value and output 2.) |

Dimensions

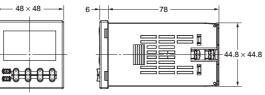
Counters

(Unit: mm)

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H7CX-A-N/-AS-N/-AW-N/-AWS-N/-AWD1-N/-AWSD1-N/-A4-N/-A4S-N/-A4W-N/-AU-N/-AUD1-N/-AUSD1-N (Flush Mounting Models)



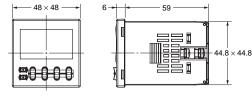


Note: M3.5 terminal screw (effective length: 6 mm)

10

H7CX-AD-N/-ASD-N/-AWSD-N/-A4D-N/-A4SD-N/-A4WSD-N (Flush Mounting Models)

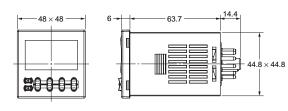




Note: M3.5 terminal screw (effective length: 6 mm)

H7CX-A11-N/-A11S-N/-A11D1-N/-A11SD1-N/-A114-N/-A114S-N/-A114D1-N (Flush Mounting/Surface Mounting Models)

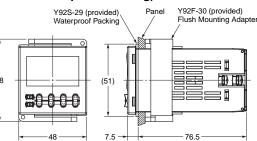




Dimensions with Flush Mounting Adapter

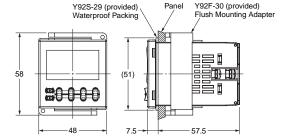
H7CX-A-N/-AS-N/-AW-N/-AWS-N/-AWD1-N/-AWSD1-N/-A4-N/-A4S-N/-A4W-N (Provided with Adapter and Waterproof Packing)





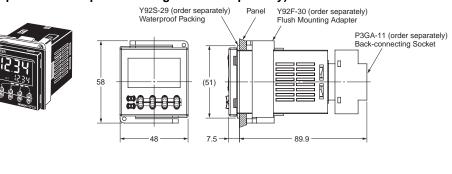
H7CX-AD-N/-ASD-N/-AWSD-N/-A4D-N/-A4SD-N/-A4WSD-N (Provided with Adapter and Waterproof Packing)





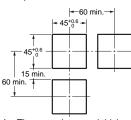
Panel

H7CX-A11-N/-A11S-N/-A11D1-N/-A11SD1-N/-A114-N/-A114S-N/-A114D1-N (Adapter and Waterproof Packing Ordered Separately)



Panel Cutouts

Panel cutouts are as shown below. (according to DIN43700).



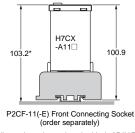
Note: 1. The mounting panel thickness should be 1 to 5 mm.

- 2. To allow easier operation, it is recommended that Adapters be mounted so that the gap between sides with hooks is at least 15 mm (i.e., with the panel cutouts separated by at least 60 mm).
- It is possible to horizontally mount Timers side by side. Attach the Flush 3. Mounting Adapters so that the surfaces without hooks are on the sides of the Timers. If they are mounted side-byside, water-resistance will be lost.

| | n Units mounted side by side |
|---|---|
| | <u>ــــــــــــــــــــــــــــــــــــ</u> |
| | A=(48n-2.5) ⁺¹ ₋₀ |
| ١ | With Y92A-48F1 attac |

ched A={48n-2.5+(n-1)×4} +1 With Y92A-48 attached. A=(51n-5.5) +1 -0

Dimensions with Front Connecting Socket



These dimensions depend on the kind of DIN Track. (Reference value)

Accessories (Order Separately)

Note: Depending on the operating environment, the condition of resin products may deteriorate, and may shrink or become harder. Therefore, it is recommended that resin products are replaced regularly.

Front Panel (Replacement Part)

You can change the color of the Front Panel when mounting the Counter/Tachometer. The Counter/Tachometer is shipped with a black (N1.5) Front Panel. "COUNTER" is printed on the front of Replacement Front Panels.

Y92P-CXC4G

4-digit Counter Light gray (5Y7/1)

Y92P-CXC4S

4-digit Counter White (5Y9.2/0.5)

Y92P-CXT4B 4-digit Counter Black (N1.5)

Y92P-CXT6G

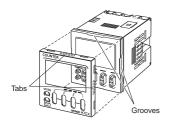
6-digit Counter Light gray (5Y7/1)

Y92P-CXT6S

6-digit Counter White (5Y9.2/0.5)

Y92P-CXT6B 6-digit Counter Black (N1.5)

Replacement Method



The Front Panel is attached to the Counter/Tachometer with tabs in four locations. To remove the Front Panel, open the tabs and pull the Front Panel forward. To attach the Front Panel, press it onto the Counter/Tachometer so that all four tabs lodge into the grooves on the body of the Counter/Tachometer.

Soft Cover Y92A-48F1 Hard Cover Y92A-48



Protecting the Counter/Tachometer in Environments Subject to Oil

The H7CX's panel surface is water-resistive (conforming to IP \Box 6, UL Type 4X) and so even if drops of water penetrate the gaps between the keys, there will be no adverse effect on internal circuits. If, however, there is a possibility of oil being present on the operator's hands, use the Soft Cover. The Soft Cover ensures protection equivalent to IP54F against oil. Do not, however, use the H7CX in locations where it would come in direct contact with oil.

Flush Mounting Adapter Y92F-30 Y92F-45

Order the Flush Mounting Adapter with the following model number separately if it is lost or damaged. **Note:** The Waterproof Packing is included with

models with

screw terminals.

Note



Use this Adapter to install the Counter/ Tachometer in a cutout previously made for a DIN 72 × 72 mm device (panel cutout: 68 × 68 mm).



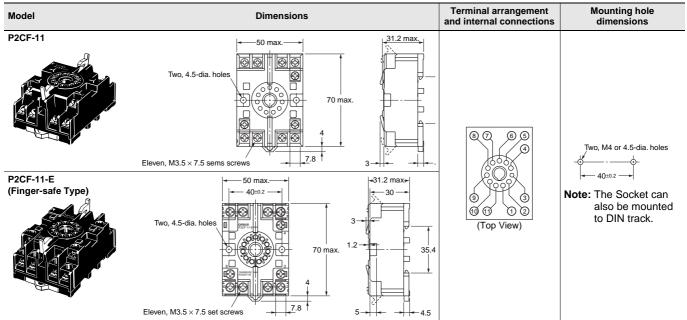
Waterproof Packing Y92S-29

| 2 | 5-29 | |
|---|--|--|
| | The Waterproof Packing is included with models with screw | |
| | terminals. | |

Order the Waterproof Packing separately if it is lost or damaged. The Waterproof Packing can be used to achieve IP66 protection.

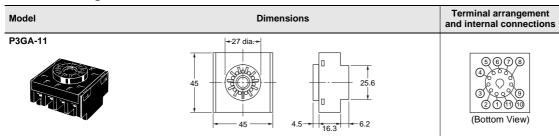
The Waterproof Packing will deteriorate, harden, and shrink depending on the application environment. To ensure maintaining the IP□6, UL Type 4X waterproof level, periodically replace the Waterproof Packing. The periodic replacement period will depend on the application environment. You must confirm the proper replacement period. Use 1 year or less as a guideline. If the Waterproof Packing is not replaced periodically, the waterproof level will not be maintained. It is not necessary to mount the Waterproof Packing if waterproof construction is not required.

Connection Sockets Front Connecting Socket



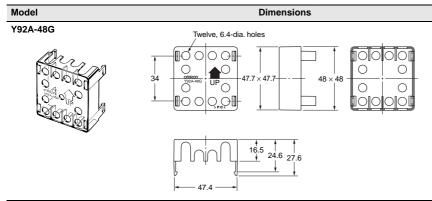
Note: Round crimp terminals cannot be used on Finger-safe Sockets. Use forked crimp terminals.

Back-connecting Sockets



Note: A Y92A-48G Terminal Cover can be used with the Socket to create a finger-safe construction.

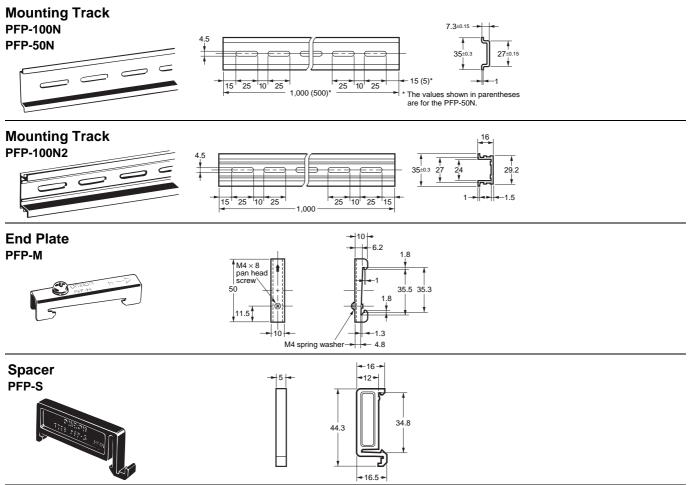
Terminal Covers for P3GA-11 Back-connecting Socket



Note: The Terminal Cover can be used with a Back-mounting Socket (P3GA-11) to create a finger-safe construction.

H7CX-A□-N

Optional Products for Track Mounting



Note: Order Spacers in increments of 10.

Operating Procedures

Setting Procedure Guide

Setting for Counter Operation *

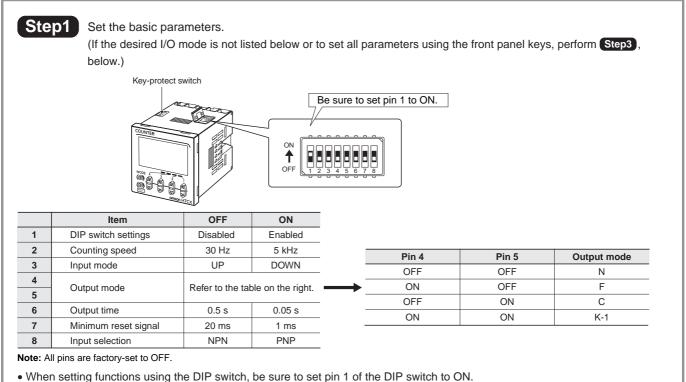
Use the following settings.

Setting for Tachometer Operation *

Refer to page page 27.

* At the time of delivery, the H7CX is set to the 1-stage preset counter configuration. (2-stage models are set to the 2-stage preset counter configuration.) Refer to page page 35 for information on switching models.

I/O Functions for Counter Operation



• DIP switch settings are effective when the power is turned ON again. (Perform DIP switch settings while the power is OFF.)

 Step2
 The H7CX-A□-N is a Counter that contains more than one functional counter.

 When using the Counter in any mode other than the default mode*, use the following chart to enter Configuration Selection Mode and set the functions that are suitable to the application.

 * The default mode is 1-stage preset counter configuration (2-stage preset counter configuration for 2-stage models).

 Note:
 Step2 can be performed first, followed by

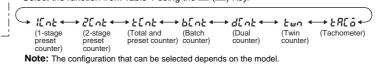
 Step1

 Power ON
 Configuration selection mode

 Hold down for 1 s min.

 Num mode

Select the function from Table 1 using the



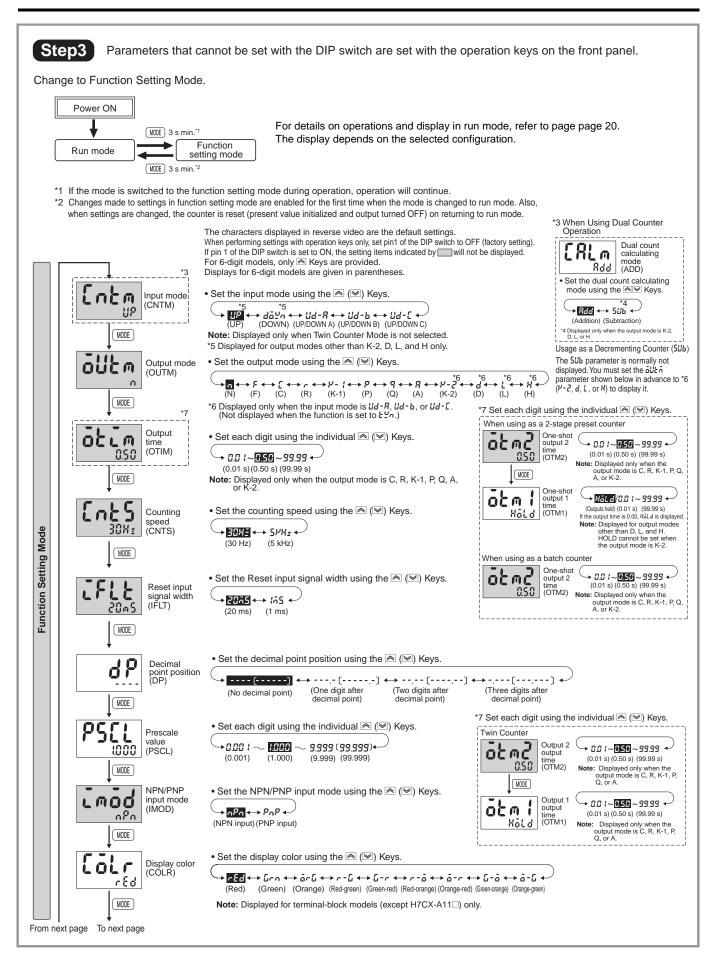
After making DIP switch settings for basic operations, advanced functions can be added using the operation keys. For details, refer to page page 16.

10 nb

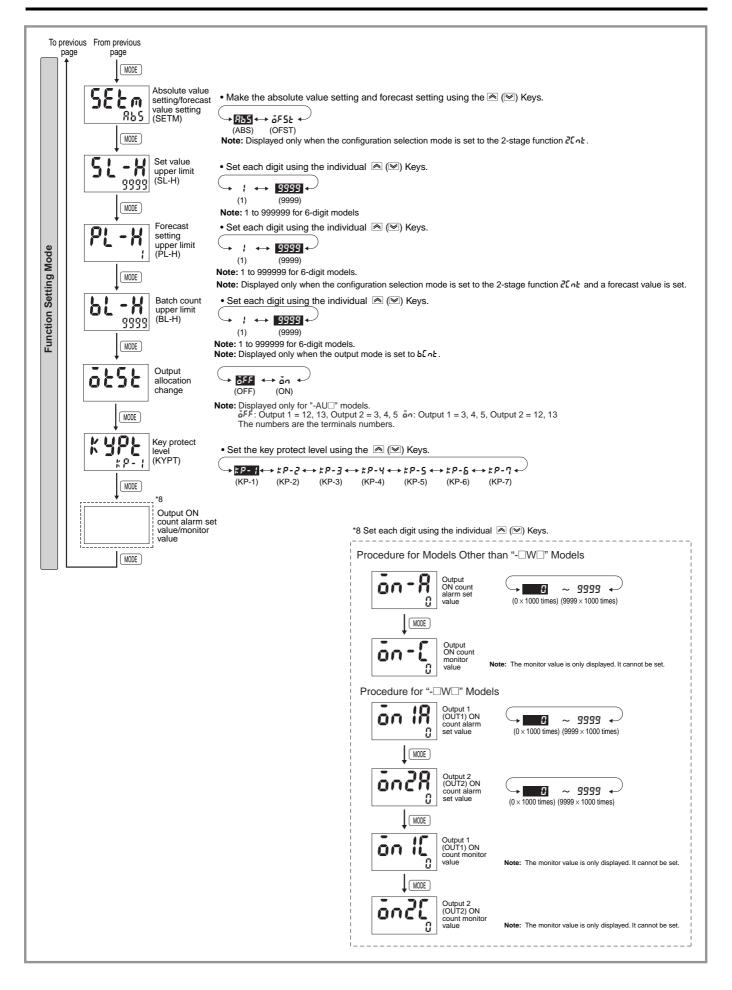
(MODE) + (♠1)

Hold down for 1 s min

H7CX-A⊡-N Counter



16



Explanation of Functions

Items marked with stars \star can be set using the DIP switch.

Input Mode (โก≿ก)★

Set increment mode (UP), decrement mode (DOWN), or one of the increment/decrement modes (UP/DOWN A, UP/DOWN B, or UP/ DOWN C) as the input mode.

Input modes other than UP or DOWN modes cannot be set using the DIP switch and so use the operation keys if other modes are required. (For details on the operation of the input modes, refer to *Input Modes and Present Value* on page page 21.)

Dual Count Calculating Mode ([RLm)

When using as a dual counter, select either ADD (addition) or SUB (subtraction) as the calculation method for the dual count value. ADD: Dual count value = CP1 PV + CP2 PV SUB: Dual count value = CP1 PV - CP2 PV

Output Mode (ä⊔ta)★

Set the way that control output for the present value is output. The possible settings are N, F, C, R, K-1, P, Q, A, K-2, D, L, and H. Output modes other than N, F, C, or K-1 cannot be set using the DIP switch and so use the operation keys if other modes are required. The output modes that can be set vary with the model.

(For details on the operation of the output modes, refer to *Input/ Output Mode Settings* on page page 22.)

One-shot Output Time (፩と⊆̄m)★

Set the one-shot output time (0.01 to 99.99 s) for control output. One-shot output can be used only when C, R, K-1, P, Q, A, or K-2 is selected as the output mode. Output times other than 0.5 s or 0.05 s cannot be set with the DIP switch and so use the operation keys if other settings are required.

One-shot Output 2 Time (ಎ೭ ಇ೭)★

Set the one-shot output time (0.01 to 99.99 s) for control output (OUT2).

One-shot output can be used only when C, R, K-1, P, Q, A, or K-2 is selected as the output mode. Output times other than 0.5 s or 0.05 s cannot be set with the DIP switch and so use the operation keys if other settings are required.

One-shot Output 1 Time (ふとっ /)

Set the one-shot output time (0.01 to 99.99 s) for control output (OUT1).

One-shot output can be used only when D, L, or H is selected as the output mode.

If the output time is set to 0.00, Hall d is displayed, and outputs are held.

Counting Speed (Ent 5)★

Set the maximum counting speed (30 Hz/5 kHz) for CP1 and CP2 inputs together.

If contacts are used for input signals, set the counting speed to 30 Hz. Processing to eliminate chattering is performed for this setting.

Reset Input Signal Width (こFLと)★

Set the reset input signal width (20 ms/1 ms) for reset/reset 1 and total reset/reset 2 inputs together.

If contacts are used for the input signal, set the input signal width to 20 ms. Processing to eliminate chattering is performed for this setting.

Decimal Point Position (dP)

Decide the decimal point position for the present value, CP1/CP2 present values, set value (SV1, SV2), total count value, and dual count set value.

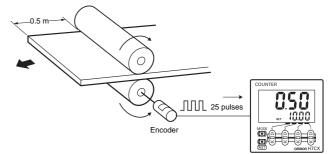
Prescale Value (PSEL)

Pulses input to the counter are converted according to the specified prescale value.

(Setting range: 0.001 to 99.999 for 6-digit models and 0.001 to 9.999 for 4-digit models.)

Example: To display the feed distance for systems that output 25 pulses for a feed length of 0.5 m in the form $\Box\Box.\Box\Box$ m:

- 1. Set the decimal point position to 2 decimal places.
- 2. Set the prescale value to 0.02 (0.5 \div 25).



 Observe the following points when setting a prescale value. Set the set value to a value less than {Maximum countable value – Prescale value}.

Example: If the prescale value is 1.25 and the counting range is 0.000 to 999.999, set the set value to a value less than 998.749 (= 999.999 - 1.25).

If the set value is set to a value greater than this, output will not turn ON.

• Output will turn ON, however, if a present value overflow occurs (FFFFFF or FFFF).

Note: If the prescale value setting is incorrect, a counting error will occur. Check that the settings are correct before using this function.

_ _ _ _ _ _ _ _ _ _ _ _ _

NPN/PNP Input Mode (เัดอัส)

Select either NPN input (no-voltage input) or PNP input (voltage input) as the input format. When using a two-wire sensor, select NPN input.

The same setting is used for all external inputs.

For details on input connections, refer to *Input Connections* on page page 9.

Display Color (L a L r) (Displayed for terminal block models (except H7CX-A11 \Box) only.)

Set the color used for the present value.

| | Output OFF* | Output ON* |
|------------|-------------|------------|
| rEd | Red (| fixed) |
| Gen | Green | (fixed) |
| õrű | Orange | e (fixed) |
| r-6 | Red | Green |
| <u>5-r</u> | Green | Red |
| r-ŏ | Red | Orange |
| ŏ-r | Orange | Red |
| ũ-õ | Green | Orange |
| ō-G | Orange | Green |

* Output 2 for 2-stage models

With the twin counter, output 1 and output 2 will both turn OFF when the output status is OFF. Either output 1 or output 2 will turn ON when the output status is ON.

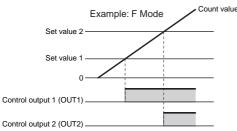
Absolute Value Setting/Forecast Value Setting (582m)

For the 2 count output mode, an absolute value setting (Rb5) or forecast value setting ($\tilde{a}F5t$) can be set for set value 1. When a forecast value is set, specify the forecast value set value (i.e.,

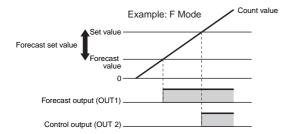
the deviation for the set value).

The forecast output (output 1) turns ON when the present value reaches the forecast value.

If the forecast set value is greater than or equal to the set value, the forecast output (output 1) will turn ON as soon as counting starts.



If the forecast value setting is used, specify the set value 2 minus the forecast value setting for set value 1.



Set Value Upper Limit (5L - H)

Set the upper limit for the set value when it is set in run mode. The setting can be made from 1 to 9999 for 4-digit models and from 1 to 999999 for 6-digit models.

Forecast Set Upper Limit (PL - H)

Set the upper limit for the forecast set value. The setting can be made from 1 to 9999 for 4-digit models and from 1 to 999999 for 6-digit models.

Batch Count Upper Limit (bL - H)

Set the upper limit for the batch count value. The setting can be made from 1 to 9999 for 4-digit models and from 1 to 999999 for 6-digit models.

Output Allocation (ab 5b)

When using an H7CX-AU \Box -N model as a 2-stage counter, the output can be flexibly allocated to either stage 1 or 2.

The transistor output can be allocated to SV1 and the contact output to SV2 or vice verse, as in the following tables.

H7CX-AU-N/-AUD1-N

| | Output 1 | Output 2 |
|-------------------------|-------------------|--------------------|
| ۵۶۶۶ Transistor (12-13) | | Contact (3, 4, 5) |
| <u>ăn</u> | Contact (3, 4, 5) | Transistor (12-13) |

H7CX-AUSD1-N

| Output 1 | | Output 2 |
|---------------------------------|--------------------|---------------------------------|
| õf f | Transistor (12-13) | Transistor with diode (3, 4, 5) |
| Transistor with diode (3, 4, 5) | | Transistor (12-13) |

Key Protect Level (* 3Pt)

Set the key protect level.

Refer to Key Protect Level on page page 36.

Output ON Count Alarm Set Value (an - R)

Set the alarm value for the output ON count.

The limit can be set to between $\underline{0} \times 1000$ (0 times) and $\underline{9999} \times 1000$ (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of the output exceeds the alarm set value, $\xi \exists$ will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to *Self-diagnostic Function* on page page 36 for information on the $\xi \exists$ display.

ON Count Alarm Set Values for Outputs 1 and 2 (OUT1 and OUT2) (an IR and an 2R)

Set the ON count alarm values for the outputs 1 and 2.

The limit can be set to between $\underline{0} \times 1000$ (0 times) and $\underline{9999} \times 1000$ (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of instantaneous output 1 or 2 exceeds the alarm set value, $\mathcal{E}3$ will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to *Self-diagnostic Function* on page page 36 for information on the $\mathcal{E}3$ display.

Output ON Count Monitor Value (an-L)

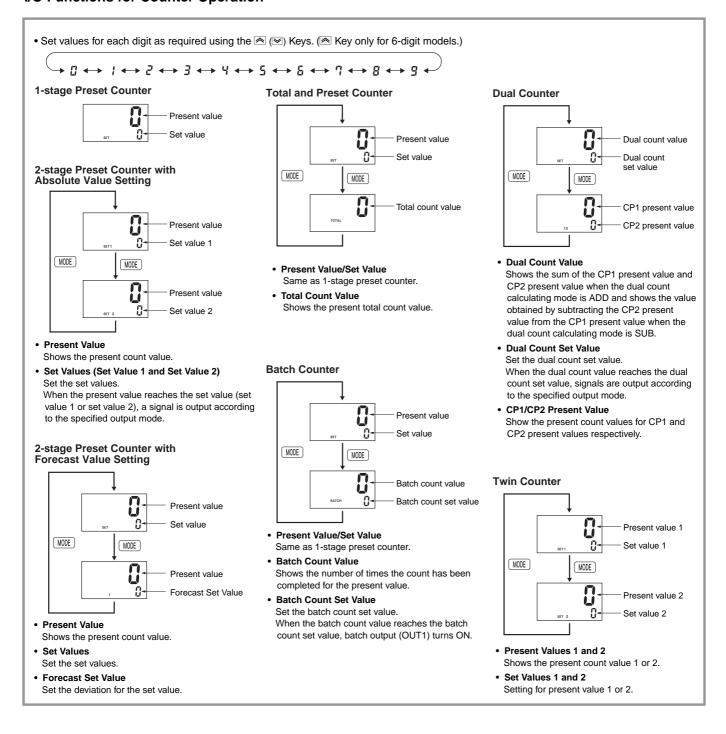
The monitor value is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

ON Count Monitor Values for Outputs 1 and 2 (OUT1 and OUT2) (an IC and and C)

The monitor value for output 1 or 2 is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

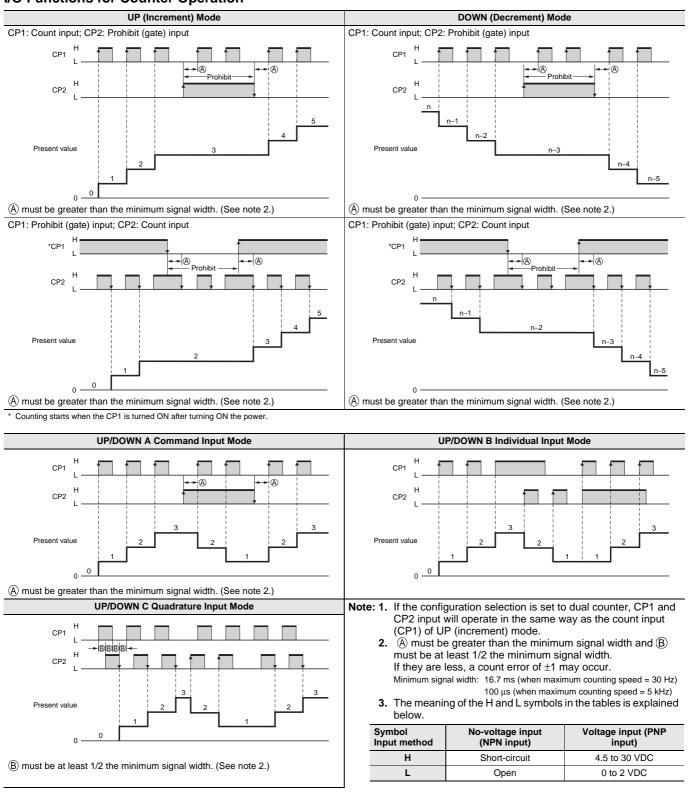
H7CX-A□-N Counter

Operation in Run Mode I/O Functions for Counter Operation



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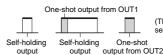
Input Modes and Present Value (See note 1.) I/O Functions for Counter Operation



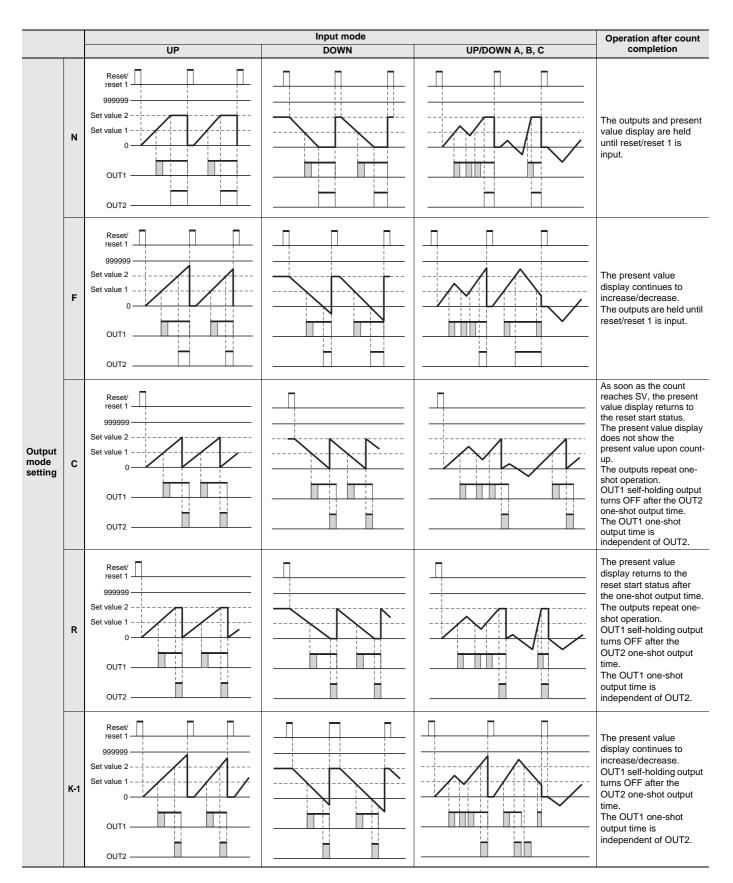
Input/Output Mode Settings

I/O Functions for Counter Operation

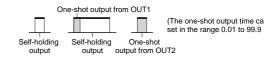
If a 1-stage model or 2-stage model is incorrectly used as twin counter, the operation for output 2 will be performed. When using a 2-stage model as a 1-stage preset counter, total and preset counter, or dual counter, OUT1 and OUT2 turn ON and OFF simultaneously.

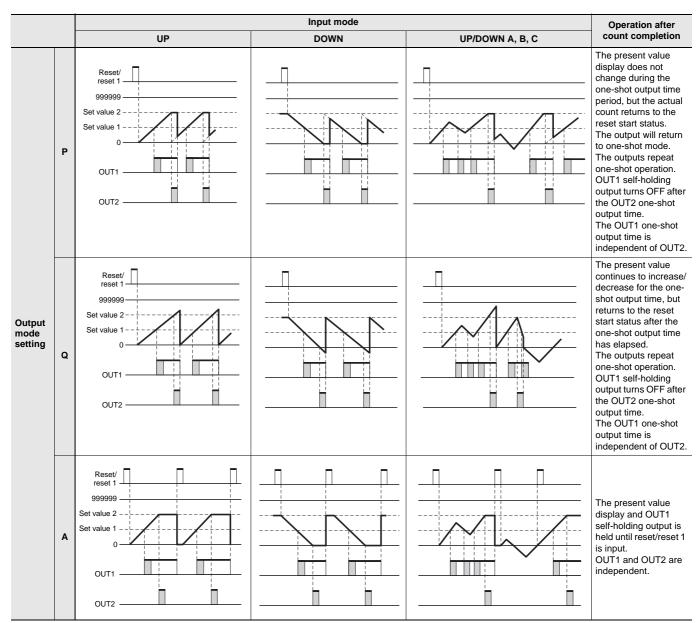


(The one-shot output time can be set in the range 0.01 to 99.99s.) t



H7CX-A -N Counter



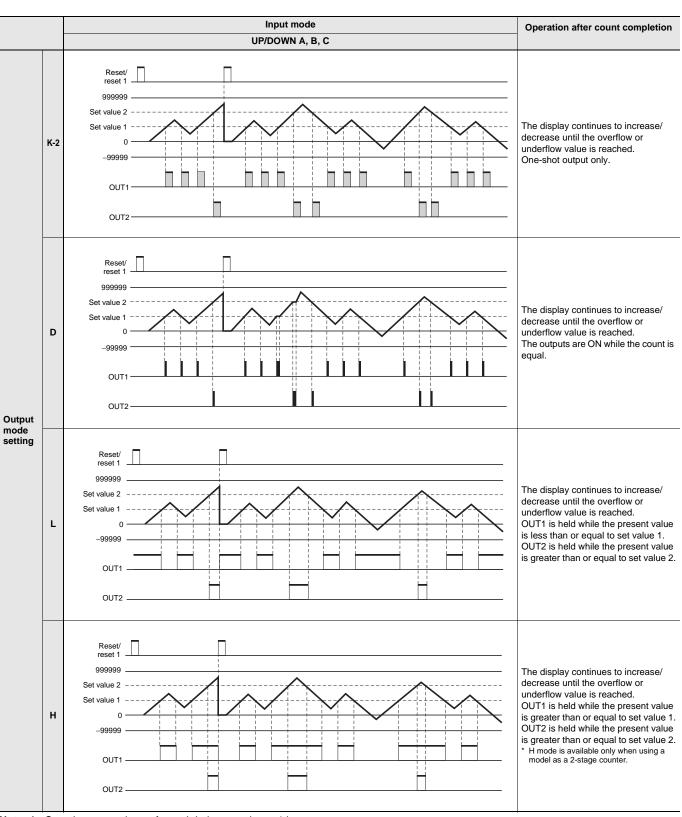


Note: 1. The full scale (FS) for H7CX 4-digit models is 9999.

- 2. When the present value reaches 999999, it returns to 0.
- 3. Counting cannot be performed during reset/reset 1 input.
- 4. If reset/reset 1 is input while one-shot output is ON, one-shot output turns OFF.
- 5. If there is power failure while output is ON, output will turn ON again when the power supply has recovered.
- For one-shot output, output will turn ON again for the duration of the output time setting once the power supply has recovered.
- 6. Do not use the counter function in applications where the count may be completed (again) while one-shot output is ON.
- 7. The setting range is 0 to 999999 (0 to 9999 for 4-digit models).

Self-holding Instantaneous One-shot output (equals) output

(The one-shot output time can be set in the range 0.01 to 99.99s.)



Note: 1. Counting cannot be performed during reset/reset 1 input.

2. If reset/reset 1 is input while one-shot output is ON, one-shot output turns OFF.

3. If there is power failure while output is ON, output will turn ON again when the power supply has recovered.

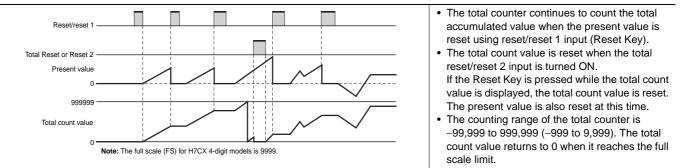
- For one-shot output, output will turn ON again for the duration of the output time setting once the power supply has recovered.
- 4. Do not use the counter function in applications where the count may be completed (again) while one-shot output is ON.

5. The set value is from -99999 to 999999 (-999 to 9999 for 4-digit models).

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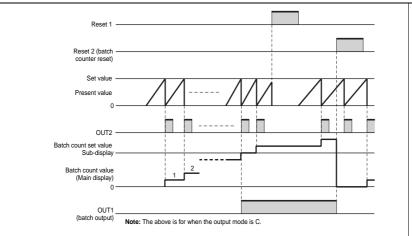
Total and Preset Counter Operation

The H7CX has a total counter, separate from the 1-stage preset counter, for counting the total accumulated value.



Batch Counter Operation

The H7CX has a batch counter, separate from the 1-stage preset counter, for counting the number of times the count has been completed.



- · The batch counter continues after count completion.
- Batch output is held until batch counter reset is input.
- · When the batch counter reset input is turned ON, the batch count value is reset, and batch output turns OFF.
- · If the Reset Key is pressed while the batch count value is displayed, the batch count value is reset and batch output turns OFF. The present value is also reset at this time.
- The count value can be incremented and decremented.
- The batch count is only incremented.
- The maximum counting speed for batch counter operation is 5 kHz. The batch counter counts the number of times the count reaches the set value.

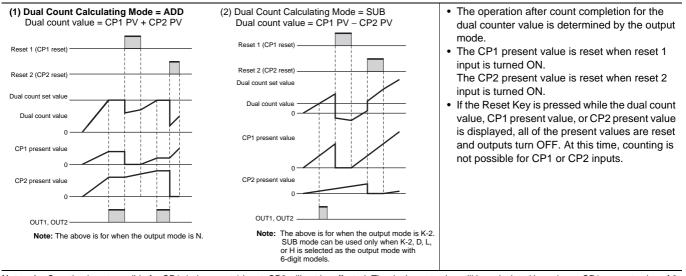
Note: 1

- The batch count value is held at 0 during batch counter reset input. If the batch count set value is 0, batch count will be performed but there will be no batch output. The batch count value returns to 0 when it reaches 999,999 (9,999 for 4-digit models).
- 3
- 4.
- 5. 6.

Once batch count set value is changed from a value that is greater than the batch count value to one that is less, batch output will turn ON. If the batch count set value is changed from a value that is greater than the batch count value to one that is less, batch output will turn ON. After batch output turns ON, the ON state will be held even if the batch count set value is changed to a value greater than the batch count value.

Dual Counter Operation

Using the dual counter allows the count from 2 inputs to be added or subtracted and the result displayed. It is possible to specify a set value for which output turns ON when the set value matches the added or subtracted result.

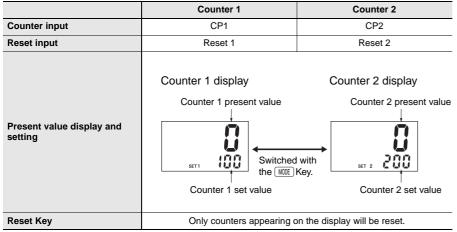


- Counting is not possible for CP1 during reset 1 input. CP2 will not be affected. The dual count value will be calculated based on a CP1 present value of 0. Counting is not possible for CP2 during reset 2 input. CP1 will not be affected. The dual count value will be calculated based on a CP2 present value of 0. The counting range for the dual count value is –99,999 to 999,999 (0 to 9,999 for 4-digit models). The counting ranges for the CP1 present value and CP2 present value are 0 to 999,999 (0 to 9,999 for 4-digit models). If a present value exceeds 999,999 (9,999 for 4-digit models), FFFFF (FFFF for 4-digit models) will be displayed to indicate an overflow, and all counting Note: 1. 3.

will stop.

Twin Counter Operation

Two independent counters are built in.



Note: 1. Only 2-stage models

2. Increment mode only for counters 1 and 2.

3. The settings for prescaling and the decimal point are used by both counter 1 and 2.

Reset Function List I/O Functions for Counter Operation

| Function | 1-stage/2- stage preset counter | Total and preset counter | | Batch counter | | Dual counter | | Twin counter | |
|--------------------------------------|---------------------------------------|---------------------------------------|---|---------------------------------------|---|--|--|-----------------------------------|-----------------------------------|
| Screen dis- played in run mode | Present value/ set value (1, 2) | Present value/set value | Total count value | Present value/set value | Batch count value/batch count set value | Dual count value/dual count set value | CP1 present value/CP2 present value | Present value 1/Set value 1 | Present value 2/Set value 2 |
| Reset/reset 1 | Present value and output reset. | | e and output set. | | e and output set. | | oresent value is set. | Only the CP1 p | |
| Total reset or reset 2 | No effect | Only the total count value is reset. | | | alue and batch reset. | | oresent value is set. | Only the CP2 p res | |
| Reset Key | Present value and output reset. | Present value and output reset. | Present value, total count value, and output reset. | Present value and output reset. | Present value, batch count value, output and batch output reset. | present valu | t value, CP2 e, dual count output reset. | CP1 present value reset | CP2 present value reset |

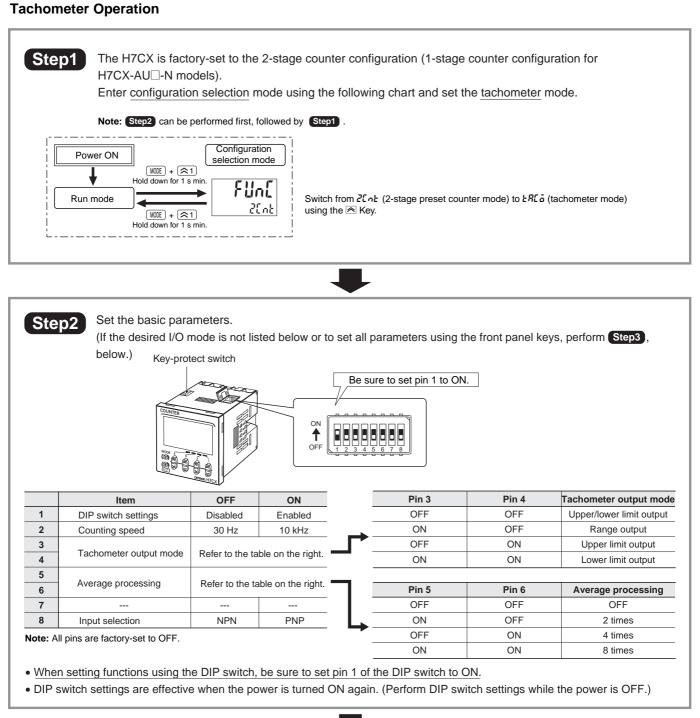
• The following table shows the delay from when the present value passes the set value until the output is produced.

| Actual measurements in N and K-2 modes | (Reference values) |
|--|--------------------|
|--|--------------------|

| Control output type | Max. counting speed | Output delay time |
|---------------------|---------------------|-------------------|
| Contact output | 30 Hz | 16.5 to 24.0 ms |
| Contact output | 5 kHz | 3.7 to 5.6 ms |
| Transistor output | 30 Hz | 12.0 to 20.0 ms |
| Transistor Output | 5 kHz | 0.2 to 0.55 ms |

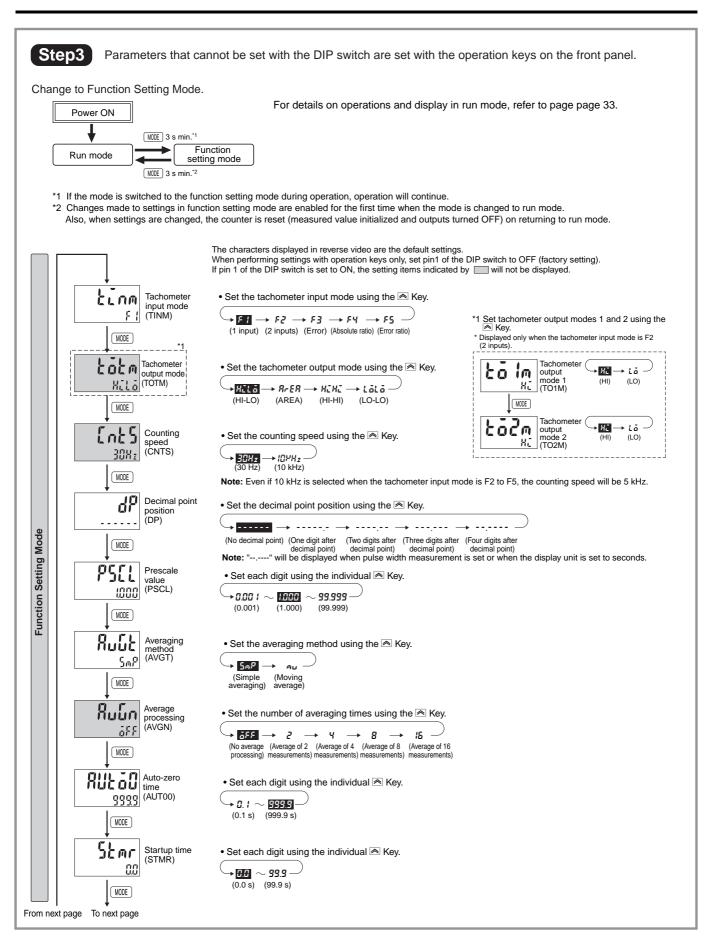
Note: The above times may vary slightly depending on the mode or operating conditions.

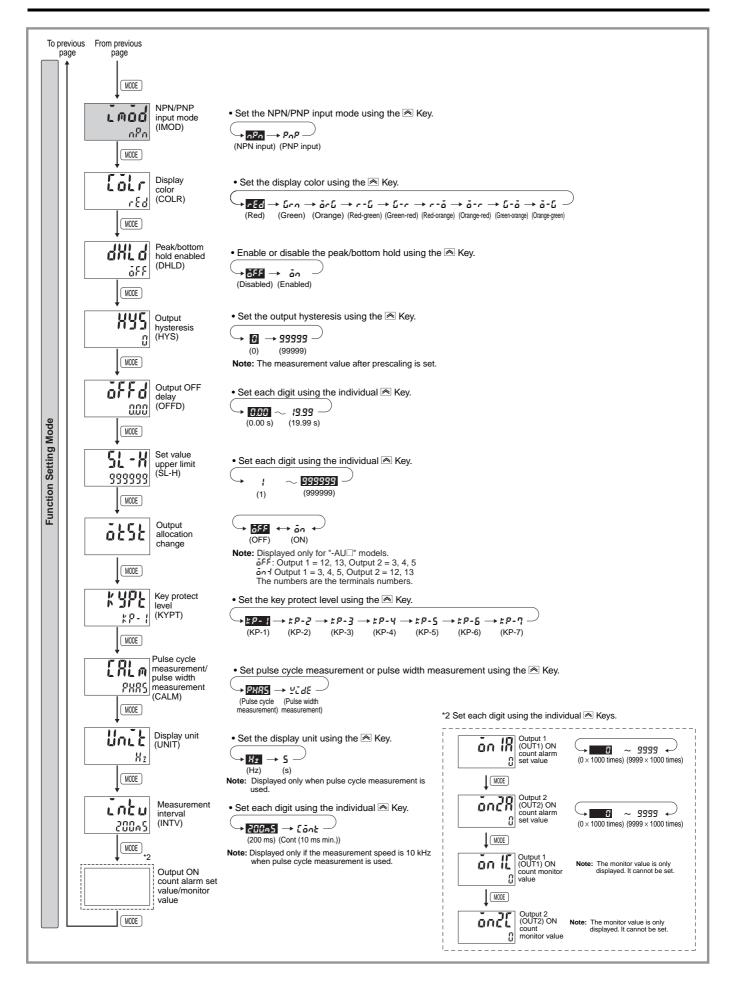
Setting Procedure Guide



After making DIP switch settings for basic operations, advanced functions can be added using the operation keys. For details, refer to page page 28.

H7CX-A□-N Tachometer





Explanation of Functions Tachometer Operation

Items marked with stars \star can be set using the DIP switch.

Tachometer Input Mode (とこつの)

Set the count input mode to one of the following: 1 input (F 1), 2 inputs (F2), error (F3), absolute ratio (F4), or error ratio (F5).

| Input mode | Input | Internal processing | Application |
|-------------------|---|---|--|
| 1 input | Count 1 | None | Operation with only one input. |
| 2 inputs | 2 inputs Counts 1 and 2 None | | Operation with two independent inputs. |
| Error | ror Counts 1 and 2 Count 1 input – Count 2 input | | Measuring the difference between two inputs (error in number of revolutions). |
| Absolute ratio | Counts 1 and 2 | | Measuring the ratio of two inputs (ratio of number of revolutions). |
| Error ratio | Counts 1 and 2 | (Count 1 input – Count 2 input) ÷ Count 2 input | Measuring the ratio of error for two inputs (measuring the error ratio of number of revolutions). |

Tachometer Output Mode (とãと∩)★

Set the output method for control output based on the comparison value. Upper and lower limit (HI-LO), area (AREA), upper limit (HI-HI), and lower limit (LO-LO) can be set.

(For details on the output modes, refer to *Output Mode Settings and Operation* on page page 34.)

Counting Speed (Lot 5)★

Set the maximum counting speed (30 Hz/10 kHz) for CP1 input. If contacts are used for input signals, set the counting speed to 30 Hz. Processing to eliminate chattering is performed for this setting.

Decimal Point Position (dP)

Decide the decimal point position for the measurement value, OUT1 set value, and OUT2 set value.

Prescale Value (PSEL)

It is possible to display the rate of rotation or the speed of a device or machine to which the H7CX is mounted by converting input pulses to a desired unit.

If this prescaling function is not used, the input frequency (Hz) will be displayed.

It is also possible to specify time (seconds) as the display value. Refer to *Display Unit* on page page 31 for details.

The relationship between display and input is determined by the following equation. Set the prescale value according to the unit to be displayed.

Displayed value = f $\times \alpha$

f: Input pulse frequency (number of pulses in 1 second) α : Prescale value

(1) Displaying Rotation Rate

| Display unit | Prescale value (α) |
|--------------|--------------------|
| rpm | 1/N × 60 |
| rps | 1/N |

N: Number of pulses per revolution

Example: To display the rate of rotation for a machine that outputs 5 pulses per revolution in the form $\Box\Box\Box$ rpm:

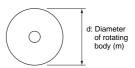
1. Set the decimal point position to 1 decimal places.

2. Using the formula, set the prescale value (a) to 1/N \times 60 = 60/5 = 12.

(2) Displaying Speed

| Display unit | Prescale value (α) |
|--------------|----------------------------|
| m/min | $\pi d 	imes 1/N 	imes 60$ |
| m/s | $\pi d \times 1/N$ |

N: Number of pulses per revolution d: Diameter of rotating body (m) π d: Circumference (m)



• Observe the following points when setting a prescale value.

Set the set value to a value less than {Maximum countable value – Prescale value}.

Example: If the prescale value is 1.25 and the counting range is 0.000 to 999.999, set the set value to a value less than 998.749 (= 999.999 - 1.25).

If the set value is set to a value greater than this, output will not turn ON.

* Output will turn ON, however, if a present value overflow occurs (FFFFFF or FFFF).

Note: If the prescale value setting is incorrect, a counting error will occur. Check that the settings are correct before using this function.

Averaging Method (Rule) (Only for Tachometer Operation)

A simple average or moving average can be selected for the averaging. With the moving average method, the average of the measurement values is displayed each sampling cycle, in contrast to a simple average, with which the the average of the set number of samples is displayed.

Number of Averaging Times (ສິມພິກ)★

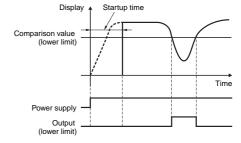
Flickering display and output chattering can be prevented using average processing. Average processing can be set to one of four levels: no average processing, 2 times (i.e., the average of 2 measurement values), 4 times, 8 times, or 16 times. The measurement cycle will be equal to the sampling cycle multiplied by the average processing setting (i.e., the number of times). Average processing enables stable displays even for fluctuating input signals. Set the optimum number of times for the application.

Auto-zero Time (RUL al)

The display can be force-set to 0 if there is no pulse for a certain period of time. This time is called the auto-zero time. Set the auto-zero time to a time slightly longer than the estimated interval between input pulses. Accurate measurement is not possible if the auto-zero time is set to a time shorter than the input pulse cycle. Setting a time that is too long may also result in problems, such as a time-lag between rotation stopping and the alarm turning ON. The auto-zero time is not applied to pulse width measurements.

Startup Time (52mr)

To prevent undesired outputs resulting from unstable inputs immediately after the power supply is turned ON, it is possible to prohibit measurement for a set period of time, the startup time. It can also be used to stop measurements and disable outputs until the rotating body reaches the normal rate of rotation, after the power supply to the H7CX and rotating body are turned ON at the same time.



NPN/PNP Input Mode (⊾ักอัd)★

Select either NPN input (no-voltage input) or PNP input (voltage input) as the input format.

When using a two-wire sensor, select NPN input. The same setting is used for all external inputs.

For details on input connections, refer to *Input Connections* on page page 9.

Display Color (Lalr)

Set the color used for the measurement value.

| | Control output OFF | Control output ON | |
|------------|--|---|--|
| rEd | Red (fixed) | | |
| <u>Gen</u> | Green (fixed) | | |
| ŏr ū | Orange | e (fixed) | |
| r-6 *1 | Measured value is displayed in red when both control outputs 1 and 2 are OFF. | Measured value is displayed in green when either control output 1 or control output 2 is ON. | |
| 5-r *2 | Measured value is displayed in green when both control outputs 1 and 2 are OFF. | Measured value is displayed in red when either control output 1 or control output 2 is ON. | |
| r-ā*3 | Measured value is displayed in red when both control outputs 1 and 2 are OFF. | Measured value is displayed in orange when both control outputs 1 and 2 are OFF. | |
| ō-r *4 | Measured value is displayed in orange when both control outputs 1 and 2 are OFF. | Measured value is displayed in red when both control outputs 1 and 2 are OFF. | |
| ũ-ă *5 | Measured value is displayed in green when both control outputs 1 and 2 are OFF. | Measured value is displayed in orange when both control outputs 1 and 2 are OFF. | |
| ō-ŭ *6 | Measured value is displayed in orange when both control outputs 1 and 2 are OFF. | Measured value is displayed in green when both control outputs 1 and 2 are OFF. | |

*1. If the tachometer output mode is set to AREA, however, the measured value is displayed in red when control output 1 is OFF and in green when control output 1 is ON.

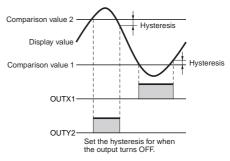
- *2. If the tachometer output mode is set to AREA, however, the measured value is displayed in green when control output 1 is OFF and in red when control output 1 is ON.
- *3. If the tachometer output mode is set to AREA, however, the measured value is displayed in red when control output 1 is OFF and in orange when control output 1 is ON.
- *4. If the tachometer output mode is set to AREA, however, the measured value is displayed in orange when control output 1 is OFF and in red when control output 1 is ON.
- *5. If the tachometer output mode is set to AREA, however, the measured value is displayed in green when control output 1 is OFF and in orange when control output 1 is ON.
- *6. If the tachometer output mode is set to AREA, however, the measured value is displayed in orange when control output 1 is OFF and in green when control output 1 is ON.

Peak/bottom Hold Enabled (dHLd)

This function records the peak and bottom (i.e., minimum) after counting starts (after turning ON the power supply or changing the configuration selection mode or function setting). The peak value is also held when the power supply is interrupted.

Output Hysteresis (서날5)

This setting can be used to prevent output chattering if the measurement value fluctuates slightly near the set value. The measurement value after prescaling is set.



Output OFF Delay (aFFd)

This function delays the timing for turning OFF comparative output by a certain time.

The ON time can be held for the set time if the comparative result changes in a short time.

Operation will continue and outputs will not change when holding the value.

Set Value Upper Limit (PL - H)

Set the upper limit for the set value when it is set in run mode. The limit can be set to between 1 and 999999.

Output Allocation (a252)

When using an H7CX-AU \Box -N model as 2-stage counter, each output can be flexibly allocated to either stage 1 or 2.

The transistor output can be allocated to SV1 and the contact output to SV2 or vice verse, as in the following tables.

H7CX-AU-N/-AUD1-N

| | Output 1 | Output 2 |
|-----------|--------------------|--------------------|
| öff | Transistor (12-13) | Contact (3, 4, 5) |
| <u>ăn</u> | Contact (3, 4, 5) | Transistor (12-13) |

H7CX-AUSD1-N

| | Output 1 | Output 2 | |
|-----|---------------------------------|---------------------------------|--|
| 8FF | Transistor (12-13) | Transistor with diode (3, 4, 5) | |
| ŏn | Transistor with diode (3, 4, 5) | Transistor (12-13) | |

Key Protect Level (# 날무논)

Set the key protect level.

Refer to Key Protect Level on page page 36.

Pulse Cycle Measurement/Pulse Width Measurement ([RLm)

Set the measurement mode to pulse cycle measurement or pulse width measurement.

With pulse cycle measurement, the number of pulse cycles that occur in 1 s is measured.

With pulse width measurement, the ON time for one pulse is measured.

An input OFF period of at least 20 ms is required for pulse width measurement.

If there is no input pulse during pulse width measurement, the previously measured value will be held.

Display Unit (じっこと)

When pulse cycle measurement is used, set the display unit to Hz (hertz) or s (seconds).

Counting Interval (interval)

If the measurement speed is 10 kHz when pulse cycle measurement is used, set the measurement interval to 200 ms or Cont (10 ms min.).

ON Count Alarm Set Values for Outputs 1 and 2 (OUT1 and OUT2) ($an \ B$ and $an \ B$)

Set the ON count alarm values for the outputs 1 and 2.

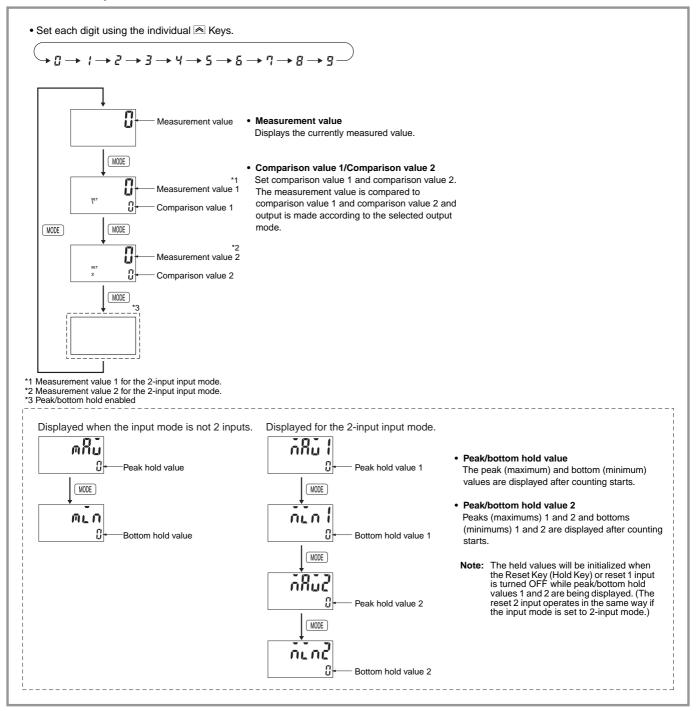
The limit can be set to between $\underline{0} \times 1000$ (0 times) and $\underline{9999} \times 1000$ (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of instantaneous output 1 or 2 exceeds the alarm set value, E3 will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to *Self-diagnostic Function* on page page 36 for information on the E3 display.

ON Count Monitor Values for Outputs 1 and 2 (OUT1 and OUT2) (בֿה اנ and בֿהבנ)

The monitor value for output 1 or 2 is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

Operation in Run Mode Tachometer Operation



Output Mode Setting and Operation

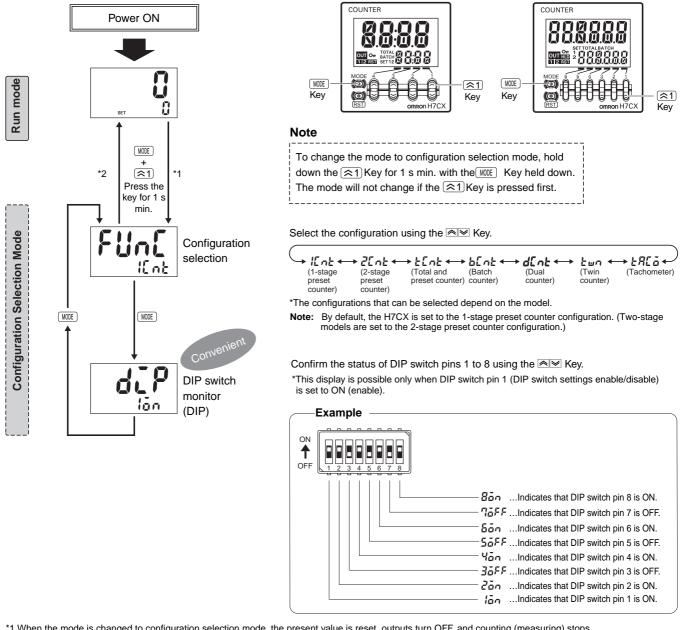
Tachometer Operation

| Input mode setting | Output mode setting | ר Operation | | | | | |
|---|-------------------------------------|---|--|--|--|--|--|
| 1 input Error Absolute ratio Error ratio | Upper and lower limit (HI-LO) | (Upper-limit) Comparison value 2 Measurement value (Lower-limit) Comparison value 1 OUT1 OUT2 OUT2 | | | | | |
| | | Comparison value 2 Condition Comparison value 1 ≤ Comparison value 2 Measurement value 1 > Comparison value 2 Measurement value 0 0 0 0 | | | | | |
| | Area (AREA) | Comparison value 1 ON condition for OUT1 Comparison value 1 ≤ Measurement value ≤ Comparison value 2 Comparison value 2 ≤ Measurement value ≤ Comparison value 1 | | | | | |
| | | OUT1 ON condition for OUT2 Measurement value < Comparison value 1 or Measurement value > Comparison value 2 Measurement value < Comparison value 2 or Measurement value > Comparison value 2 OUT2 OUT2 Measurement value > Comparison value 2 Measurement value > Comparison value 2 | | | | | |
| | Upper limit (HI-HI) | (Upper-limit) Comparison value 2 Measurement value (Lower-limit) Comparison value 1 OUT1 OUT2 OUT2 OUT2 | | | | | |
| | Lower limit (LO-LO) | (Upper-limit) Comparison value 2 Measurement value (Lower-limit) Comparison value 1 OUT1 OUT1 OUT2 OUT2 OUT2 OUT2 | | | | | |
| 2 inputs | Upper limit (HI) | Output 1 Output 2 | | | | | |
| | | Comparison value 1 CP1 display value OUT1 OUT1 OUT2 OUT2 OUT2 OUT2 OUT2 OUT2 OUT2 OUT2 OUT2 | | | | | |
| | | ON condition for output 2: CP2 present value (display value) ≥ Comparison value 2 Output 1 Output 2 | | | | | |
| | Lower limit (LO) | CP1 display value Comparison value 1 OUT1 OUT1 OUT2 OU | | | | | |

Switching between Preset Counter, Total and Preset Counter, Batch Counter, Dual Counter, Twin Counter, and Tachometer Operation

Select which H7CX configuration is used (i.e., preset counter, total and preset counter, batch counter, dual counter, twin counter, or tachometer) in configuration selection mode.

The H7CX is also equipped with a DIP switch monitor function, a convenient function that enables the settings of the DIP switch pins to be confirmed using the display on the front of the H7CX.



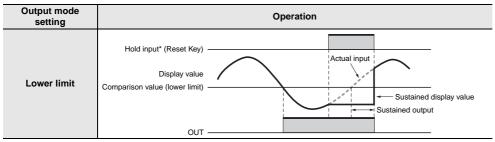
*1 When the mode is changed to configuration selection mode, the present value is reset, outputs turn OFF, and counting (measuring) stops. *2 Setting changes made in configuration selection mode are enabled when the mode is changed to run mode. If the configuration is changed, the

set value (or set value 1 and set value 2), comparison value 1 and comparison value 2 are initialized.

Hold Function

The measurement value (display value) and output are sustained while the hold input is ON. **Note:** The output will maintain the current status when the hold key is pressed.

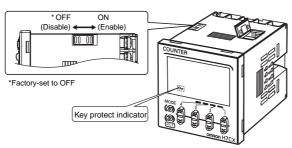
Example:



Key Protect Level

It is possible to prevent setting errors by prohibiting the use of certain operation keys by specifying the key protect level (KP-1 to KP-7) when the key-protect switch is set to ON.

The key protect level is set in the function setting mode. The key protect indicator is lit when the key-protect switch is ON.



| | | Details | | | |
|---------------------------|----------------------------------|-----------------|---------------------------------------|-----------|--------------|
| Level | Description | Changing modes* | Switching display during operation | Reset Key | Up/Down Keys |
| KP-1 (default setting) | | Invalid | Valid | Valid | Valid |
| KP-2 | MODE | Invalid | Valid | Invalid | Valid |
| KP-3 | MODE CO EST OTRION H7CX | Invalid | Valid | Valid | Invalid |
| KP-4 | MODE CONTROL H7CX | Invalid | Valid | Invalid | Invalid |
| KP-5 | MODE CELE OTRION H7CX | Invalid | Invalid | Invalid | Invalid |
| KP-6 | MODE CONTROL H7CX | Invalid | Invalid | Valid | Valid |
| KP-7 | | Invalid | Invalid | Invalid | Valid |

* Changing mode to configuration selection mode or function setting mode.

Self-diagnostic Function

The following displays will appear if an error occurs.

| Main display | Sub-display | Description | Output status | Correction method | Set value after reset |
|----------------------------------|-------------|---------------------------|---------------|---|-----------------------|
| ()*1*5 | No change | Present value underflow*3 | No change | Either press the Reset Key or turn ON reset input. | No change |
| FFFFF (FFFF)*1*5 | No change | Present value overflow*4 | No change | Either press the Reset Key or turn ON reset input.*6 | No change |
| E I | Not lit | CPU error | OFF | Either press the Reset Key or reset the power supply. | No change |
| 53 | Not lit | Memory error (RAM) | OFF | Turn ON the power again. | No change |
| 53 | SUm | Memory error (EEPROM)*2 | OFF | Reset Key | Factory setting |
| E3*8 | No change | Output Counter Overflow | No change | Reset Key*7 | No change |

*1. Displays for 4-digit models are given in parentheses.

This includes times when the life of the EEPROM has expired. *2.

*3. This occurs if the present value or total count value falls below -99999

(-999 for 4-digit models).

*4. This occurs in the following conditions if the present value (i.e., measurement value) exceeds 999999 (9999 for 4-digit models). • For Output Modes K-2, D, L, or H

• Dual counter or tachometer operation is used. *5. Display flashes.(1-second cycles)

*6. This does not apply when tachometer operation is used.

exceeded if a model with two outputs is used. The total ON count will not be cleared by using the Reset Key. *8. The normal display and £3 will appear alternately. When the Reset Key is pressed, £3 will not be displayed even if the alarm

*7. This is displayed if the alarm value setting for either of the two outputs is

set value is exceeded.

(Monitoring is possible, however, because the counter will continue without the output ON count being cleared.)

H7CX-R -N Tachometer

- Tachometer-only model (DIN 48×48) for the H7CX (Supports display and alarm outputs for numbers of rotations, speed, and flow rate.)
- Socket design allows either flush or surface mounting.
- "-W" models added to provide two sets of measurement controls. *
- Operation in any of the four following modes is possible with the same Unit: Upper and lower limit, upper limit, lower limit, and area.
- Equipped with auto-zero time, average processing, and startup time functions.

*The prescale value and auto-zero time settings are one.

For the most recent information on models that have been certified for safety standards, refer to your OMRON website.

Specifications

Ratings

| | Classification | | | Tacho | meter | | | |
|---|--|--|---|--|------------------------|---|--|--|
| ltem | Model | | H7CX- | R11□-N | | H7CX-R11W□-N | | |
| Input mod | le | 1 input only | | | | 2 inputs only | | |
| • | Power supply volt- | • 100 to 240 VAC, 50/60 Hz | | | | | | |
| | age ^{*1} | • 12 to 24 VDC or 2 | | | | | | |
| Ratings | Operating voltage | 85% to 110% of rate | ed supply voltage (90% | 6 to 110% at 12 to 24 | VDC) | | | |
| | fluctuation range Power consumption | Approx 94 VA at 1 | 00 to 240 VAC Appro | x 7 2 VA/4 7 W at 24 | VAC/12 to 24 VDC | Approx. 3.7 W at 12 to 24 VDC | | |
| Mounting | | Flush mounting or s | , , , , | | | | | |
| - | connections | 11-pin socket | anacomounting | | | | | |
| | protection | | pe 4 (indoors) for pan | el surface only and wh | en Y92S-29 Watero | roof Packing is used | | |
| Input sign | | Count and hold | | | | Count 1 and count 2 | | |
| | asurement method | | cycle measurement) | AMD-compatible mo measurement) | de (continuous | Tachometer mode (cycle measurement) | | |
| Maximum counting speed | | 30 Hz (minimum pulse width: 16.7 ms) | 10 kHz (minimum pulse width: 0.05 ms) | - | | 30 Hz (minimum pulse width: 16.7 ms) or 5 kHz (minimum pulse width: 0.1 ms) (selectable) | | |
| Minimum | input signal width | | | 10 ms | 1 ms | | | |
| Measuring | g ranges | 0.001 Hz to 30.00Hz | 0.001 Hz to 10 kHz | 0.026 to 999999 s | 0.003 to 999999 s | 0.01 to 5k Hz | | |
| Sampling | cycle | 200 ms min. | | Continuous measure interval of 10 ms) | ement (minimum | 200 ms min. | | |
| Display refresh cycle | | Input pulse of 5 Hz min. Averaging not used: 200 ms Averaging used: 200 multiplied by the averaging setting (ms) Input pulse of less than 5 Hz Averaging not used: Two times the maximum input pulse cycle Using averaging: Two times the maximum of the input pulse cycle multiplied by the averaging setting. | | | | | | |
| Measuring | g accuracy | ±0.1% FS ±1 digit max. (at 23 ±5°C) | | | | | | |
| Output mo | | HI-LO, AREA, HI-HI, LO-LO | | | | | | |
| Auto-zero | | 0.1 to 999.9 s (in Tachometer Mode) | | | | | | |
| Startup tir | | 0.0 to 99.9 s | | | | | | |
| Averaging | | Simple averaging/moving averaging selectable, Number of times: OFF, 2, 4, or 8 times | | | | | | |
| | g function | 0.001 to 99.999 (in Tachometer Mode) | | | | | | |
| | oint adjustment | Rightmost 3 digits | | | | | | |
| | aiting time | 290 ms max. (Control output is turned OFF and no input is accepted during sensor waiting time.) | | | | | | |
| Input method Input method $ \begin{array}{c} Los index (control output) output) output is decepted daming sensor watching times is decepted daming sensor watching sensor watching times is decepted daming sensor watching times is daming sensor watching times is daming sensor watching tin te$ | | | | | | | | |
| | Hold input | Minimum input signal width: 20 ms | | | | | | |
| External p | oower supply | 12 VDC (±10%), 100 mA * Refer to Safety Precautions (Common) on page page 52 for details. | | | | | | |
| Control or | utput | Contact output: 3 A at 250 VAC/30 VDC, resistive load (coso=1) Minimum applied load:10 mA at 5 VDC (failure level: P, reference value) | | | | | | |
| Display*2 | | 7-segment, negative transmissive LCD Character height Present value: 10 mm (red), comparison value: 6 mm (green) | | | | | | |
| Digits | | 6 digits (0 to 999999 | 9) | | | | | |
| Memory b | ackup | EEPROM (overwrite | es: 100,000 times min. |) that can store data for | or 10 years min. | | | |
| Operating | temperature range | -10 to 55°C (-10 to | 50°C if Counter/Tach | ometers are mounted | side by side) (with no | icing or condensation) | | |
| Storage te | emperature range | | icing or condensation | | | . , | | |
| - | humidity range | 25% to 85% | <u> </u> | | | | | |
| Case colo | | Black (N1.5) | | | | | | |
| | | | supply. The ripple mu | st be 20% maximum fo | or CC power | | | |

*2. The display is lit only when the power is ON. Nothing is displayed when power is OFF.

37

Characteristics

| Insulation re | sistance | 100 M Ω min. (at 500 VDC) between current-carrying terminal and exposed non- | | | | |
|-----------------------|---------------|--|--|--|--|--|
| | | current-carrying metal parts, and between non-continuous contacts | | | | |
| | | 2,000 VAC, 50/60 Hz for 1 min between current-carrying metal parts and non-current- | | | | |
| | | carrying metal parts | | | | |
| D ¹ | | 2,000 VAC (for 100 to 240 VAC), 50/60 Hz for 1 min between power supply and input | | | | |
| Dielectric str | ength | circuit (1,000 VAC for 24 VAC/12 to 24 VDC) | | | | |
| | | 2,000 VAC 50/60 Hz for 1 min between control output, power supply, and input circuit | | | | |
| | | 1,000 VAC, 50/60 Hz for 1 min between non-continuous contacts | | | | |
| | | 3.0 kV (between power terminals) for 100 to 240 VAC, 1.0 kV for 24 VAC/12 to 24 VDC | | | | |
| Impulse with | stand voltage | 4.5 kV (between current-carrying terminal and exposed non-current-carrying metal | | | | |
| impuloo inti | otana vonago | parts) for 100 to 240 VAC, 1.5 kV for 24 VAC/12 to 24 VDC | | | | |
| | | ±1.5 kV (between power terminals) | | | | |
| | | | | | | |
| Noise immu | nity | ±600 V (between input terminals) | | | | |
| | | Square-wave noise by noise simulator (pulse width: 100 ns/1 μ s, 1-ns rise) | | | | |
| Static immu | nity | Destruction: 15 kV, Malfunction: 8 kV | | | | |
| Vibration | Destruction | 10 to 55 Hz with 0.75-mm single amplitude, each in three directions for 2 hours | | | | |
| resistance | Malfunction | 10 to 55 Hz with 0.35-mm single amplitude, each in three directions for 10 min | | | | |
| Shock re- | Destruction | 300m/s ² each in three directions, three cycles | | | | |
| sistance Malfunction | | 100m/s ² each in three directions, three cycles | | | | |
| Life expectancy | | Mechanical: 10,000,000 operations min. | | | | |
| | | Electrical: 100,000 operations min. (3 A at 250 VAC, resistive load, ambient | | | | |
| | | temperature condition: 23°C) * | | | | |
| Weight | | Approx. 110 g (Tachometer only) | | | | |

* See Life-test Curve (Reference Values) on the right.

Applicable Standards

| Approved | cULus (or cURus): UL508/CSA C22 | 2.2 No. 14* | | | | | |
|-----------|--|-------------------|--|--|--|--|--|
| safety | Conforms to EN 61010-1 (IEC 6101 | 0-1): Pollution d | egree 2/overvoltage category II, B300 PILOT DUTY, | | | | |
| standards | ndards 1/4 HP 120 VAC, 1/3 HP, 240 VAC, 3-A resistive load | | | | | | |
| | (EMI) | EN61326 | | | | | |
| | Emission Enclosure: | EN55011 Grou | ip 1 classA | | | | |
| | Emission AC mains: | EN55011 Grou | ip 1 classA | | | | |
| | (EMS) | EN61326 | | | | | |
| | Immunity ESD: | EN61000-4-2: | 4 kV contact discharge (level 2); | | | | |
| | - | | 8 kV air discharge (level 3) | | | | |
| | Immunity RF-interference: | EN61000-4-3: | 10 V/m (Amplitude-modulated, 80 MHz to 1 GHz) | | | | |
| EMC | - | | (level 3); | | | | |
| | | | 10 V/m (Pulse-modulated, 900 MHz ±5 MHz) (level 3) | | | | |
| | Immunity Conducted Disturbance: | EN61000-4-6: | 10 V (0.15 to 80 MHz) (level 3) | | | | |
| | Immunity Burst: | EN61000-4-4: | 2 kV power-line (level 3); | | | | |
| | - | | 1 kV I/O signal-line (level 4) | | | | |
| | Immunity Surge: | EN61000-4-5: | 1 kV line to lines (power and output lines) (level 2); | | | | |
| | | | 2 kV line to ground (power and output lines) (level 3) | | | | |
| | Immunity Voltage Dip/Interruption: | EN61000-4-11: | 0.5 cycle, 100% (rated voltage) | | | | |

* The following safety standards apply to the H7CX-R11□. cUL (Listing): Applicable when an OMRON P2CF(-E) Socket is used. cUR (Recognition): Applicable when any other socket is used.

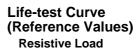
I/O Functions

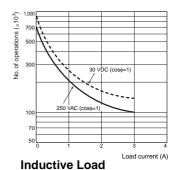
| Inputs | Count, count 1, count 2 | Reads counting signals. |
|---------|-------------------------------|--|
| | Hold | Holds the measurement value and outputs.The hold indicator is lit during hold.* |
| Outputs | OUT | Outputs signals according to the specified output mode when a comparison value is reached. |

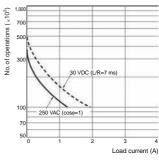
* Refer to page page 50 for details on the hold function.

• The following table shows the delay from when the reset signal is input until the output is turned OFF. (Reference values)

| Minimum reset signal width | Output delay time | | |
|----------------------------|-------------------|--|--|
| 1 ms | 0.8 to 1.2 ms | | |
| 20 ms | 15 to 25 ms | | |







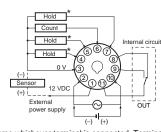
A current of 0.15 A max. can be switched at 125 VDC (cos¢=1) (Life expectancy: 100,000 operations) A current of 0.1 A max. can be switched if L/R=7 ms. (Life expectancy: 100,000 operations)

H7CX-R□-N

Connections

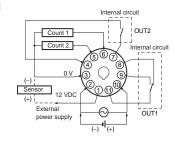
Terminal Arrangement

H7CX-R11-N H7CX-R11D1-N

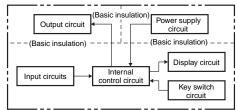


* The hold function is the same whichever terminal is connected. Terminals are not connected internally, and so do not use them for cross-over wiring.

H7CX-R11W-N H7CX-R11WD1-N

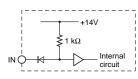


Block Diagram



Input Circuits Count and Hold Inputs

No-voltage Inputs (NPN Inputs)



Voltage Inputs (PNP Inputs)

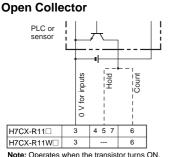
| Approx. 4.7 kΩ |
|----------------|
| IN Q-W-Circuit |
| |

Input Connections

The inputs of the H7CX-R are no-voltage (short-circuit or open) inputs or voltage inputs. They are set for use as voltage inputs at the time of delivery.

Contact Input

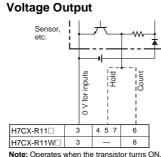
No-voltage Inputs (NPN Inputs)



No-voltage Input Signal Levels

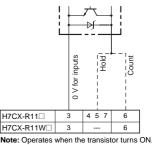
No-contact

input



0 V for inputs Per Count H7CX-R11□ 3 4 5 7 6 H7CX-R11W 3 6 Note: Operate when the contact turns ON

DC Two-wire Sensor



Applicable Two-wire Sensor

- Leakage current: 1.5 mA max.
- Switching capacity: 5 mA min.
- Residual voltage: 3 VDC max.
- Operating voltage: 10 VDC

Open level (Transistor OFF) • Impedance when OFF: 100 kΩ min. Contact in-Use contacts which can adequately switch 5 mA at 10 V. put Note: The DC voltage must be 30 VDC max.

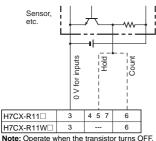
Short-circuit level (Transistor ON)

• Impedance when ON: 1 k Ω max.

(The leakage current is approx. 12 mA when the impedance is 0 Ω .)

• Residual voltage: 3 V max.

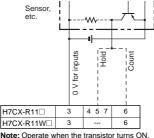
Voltage Inputs (PNP Inputs) **No-contact Input (NPN Transistor)**



Voltage Input Signal Levels

High level (Input ON): 4.5 to 30 VDC Low level (Input OFF): 0 to 2 VDC

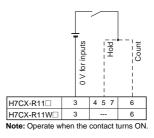
No-contact Input (PNP Transistor)



Note: Operate when the transistor turns ON

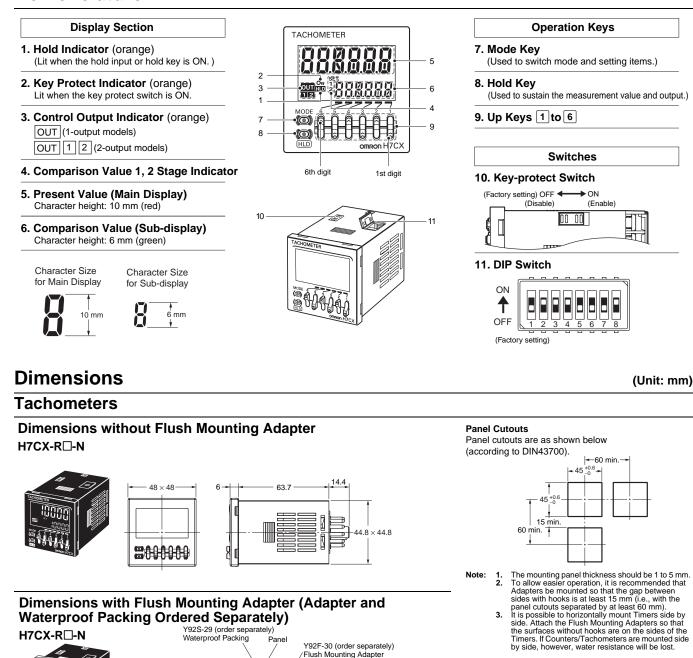
Note: 1. The DC voltage must be 30 VDC max. **2.** Input resistance: Approx. 4.7 k Ω

Contact Input

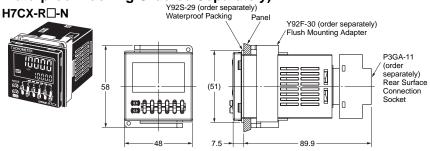


H7CX-R

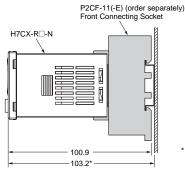
Nomenclature



Waterproof Packing Ordered Separately)



Dimensions with Front Connecting Socket H7CX-R□-N



* These dimensions vary with the kind of DIN track (reference value).

n side by side mounting

Α

A=(48n-2.5) +1

 $A=\{48n-2.5+(n-1)\times4\}^{+1}_{-0}$ With Y92A-48 attached. A=(51n-5.5) +1 -0

With Y92A-48F1 attached.

Accessories (Order Separately)

Note: Depending on the operating environment, the condition of resin or rubber products may deteriorate, or they may shrink or become harder. Therefore, it is recommended that resin products be replaced regularly.

Soft Cover

Y92A-48F1



Protecting the Timer in Environments Subject to Oil

The H7CX's panel surface is water-resistive (conforming to IP \Box 6, UL Type 4X) and so even if drops of water penetrate the gaps between the keys, there will be no adverse effect on internal circuits. If, however, there is a possibility of oil being present on the operator's hands, use the Soft Cover. The Soft Cover ensures protection equivalent to IP54 against oil. Do not, however, use the H7CX in locations where it would come in direct contact with oil.

Hard Cover

Y92A-48



Flush Mounting Adapter

Y92F-30

Order a Flush Mounting Adapter separately if the product is to be flush-mounted.



Waterproof Packing Y92S-29



Y92F-45

Use this Adapter to install the Counter/Tachometer in a cutout previously made for a DIN 72 \times 72 mm device (panel cutout: 68 \times 68 mm).



Order the Waterproof Packing separately if it is lost or damaged. The Waterproof Packing can be used to achieve protection equivalent to IP66.

(The Waterproof Packing will deteriorate, harden, and shrink depending on the application environment. To ensure maintaining the NEMA4 waterproof level, periodically replace the Waterproof Packing. The periodic replacement period will depend on the application environment. You must confirm the proper replacement period. Use 1 year or less as a guideline. If the Waterproof Packing is not replaced periodically, the waterproof level will not be maintained.) It is not necessary to mount the Waterproof Packing if waterproof construction is not required.

Connection Sockets

Refer to Connection Sockets on page page 13 for details.

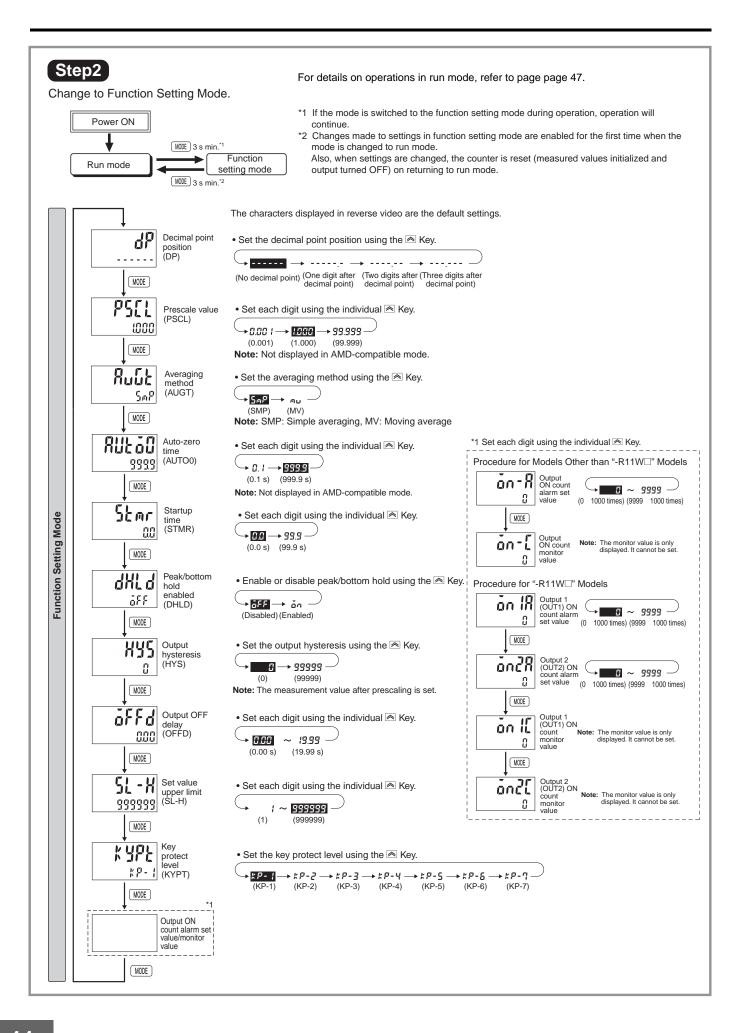
Optional Products for Track Mounting

Refer to Optional Products for Track Mounting on page page 14 for details.

Operating Procedures

Parameters must be set using both the DIP switch and the operation keys on the front panel. Refer to the following for the detailed procedure.

| Step1 | | | | | | | | |
|--|--|----------------------------------|--------------------|---------------|----------------|-----------|----------------------|---|
| Set the basic parameters. | | | | | | | | |
| ANOMETER ON Image: State of the sta | | | | | | | | |
| | Item | OFF | ON | | Pin 1 | Pin 2 | Input mode | Counting speed/ minimum input signal width |
| 1 | Input mode ^{*1} | Refer to the tat | le on the right | | OFF | OFF | Tachometer | 30 Hz |
| 2 | Counting speed/ Minimum input signal width | | | | ON | OFF | AMD compatible | 10 ms |
| 3 | | | | - | OFF | ON | Tachometer | 10 kHz ^{*3} |
| 4 | Output mode*2 | Refer to the tal | ble on the right. | | ON | ON | AMD compatible | 1 ms |
| 5 | | | | | | | | |
| 6 | Average processing | Refer to the table on the right. | | 11 | Pin 6 | Pin 4 | Output mo | ode |
| 7 | | | | 11 | OFF | OFF | Upper and low | er limit |
| 8 | NPN/PNP input mode | NPN | PNP | Ш. | ON | OFF | Area | |
| Note: Th | ne characters displayed in rever | se video are the | default settings. | | OFF | ON | Upper lim | iit |
| | | | <u>j</u> | I . | ON | ON | Lower lim | hit |
| Tho sot | tings made using the DIP s | witch can be d | pockod in the | I . | | | | |
| | itch monitor mode. | witch can be c | | I . | Pin 5 | Pin 6 | Average proc | essing |
| | ion monitor mode. | | | I . | OFF | OFF | OFF (no average p | processing) |
| | | | | | ON | OFF | 2 times | |
| | | | | | OFF | ON | 4 times | |
| | | | | | ON | ON | 8 times | |
| *1. The s *2. For th | etting of Pin 1 is disabled (OFF) e H7CX-R11W□. | for the H7CX-R1 | 1W□. | | | | | |
| | Item | OFF | ON | | Pin | 3 | Output mode | |
| 3 | Output 1 mode | Refer to the tab | - | . | OFI | - | Upper limit | |
| 4 | Output 2 mode | Refer to the tab | | -→ | ON Lower limit | | | |
| Note: T | | | | | | | | |
| | he characters displayed in reve | | - | | Pin | 4 | Output mode | |
| | he H7CX-R11W, the counting lected. | speed will be 5 k | Hz even if 10 kHz | | OFI | | Upper limit | |
| 13 30 | | | | \rightarrow | ON | | Lower limit | |
| | witch cottings are offective wh | on the new or it | | Dorf | | witch co | | Norio OFE) |
| - DIP SI | witch settings are effective wh | ien nie power is | s turneu Oiv agair | i. (Perfo | אוט וווינ | SWITCH SE | sungs writte the pol | Nel IS UFF.) |



Explanation of Functions

Basic Functions

Input Mode

The mode can be switched between tachometer mode and AMD-compatible mode.

Tachometer Mode

Use this mode to measure the pulse frequency (Hz).

AMD-compatible Mode

Use this mode to measure the pulse cycle (s).



Counting Speed

Set the maximum counting speed (30 Hz/10 kHz) for input. If contacts are used for input signals, set the counting speed to 30 Hz. Processing to eliminate chattering is performed for this setting.

Output Mode

Set the output method for control output based on the comparison value.

Upper and lower limit (HI-LO), area (AREA), upper limit (HI), and lower limit (LO) can be set. For the H7CX-RW, the upper limit (HI-HI) and lower limit (LO-LO) can be set. (For details on the operation of the output modes, refer to *Output Mode Settings* on page page 49.)

Averaging Method (ສິມມິະ)

Simple averaging (SMP) or a moving average (MV) can be selected for the averaging method.

With a moving average, the average measurement value is displayed every sampling cycle or pulse cycle, in contrast to simple averaging, for which the average value is displayed for the set number of samples.

Number of Averaging Times

Flickering display and output chattering can be prevented using average processing. Average processing can be set to one of four levels: no average processing, 2 times (i.e., the average of 2 measurement values), 4 times, or 8 times.

For a measurement frequency of 5 Hz or higher using a tachometer, the average will be equal to the sampling cycle (200 ms) multiplied by the averaging setting (i.e., the number of times).

For less than 5 Hz, the frequency will be measured when the input pulse comes. Average processing produces a stable display even for fluctuating input signals. Set the optimum number of times for the application.

If AMD-compatible mode is used, the measurement cycle will be measured when the input pulse is received. The output will change, however, when the comparison value is exceeded even if averaging is enabled.

NPN/PNP Input Mode

Select either NPN input (no-voltage input) or PNP input (voltage input) as the input format. When using a two-wire sensor, select NPN input.

The same setting is used for all external inputs.

For details on input connections, refer to *Input Connections* on page page 40.

Advanced Functions

Decimal Point Position (d^p)

Decide the decimal point position for the measurement value and comparison value.

Prescale Value (P5[I)

It is possible to display the rate of rotation or the speed of a device or machine to which the H7CX is mounted by converting input pulses to a desired unit.

If the default prescaling value (1,000) is used, the input frequency (Hz) will be displayed.

The relationship between display and input is determined by the following equation. Set the prescale value according to the unit to be displayed.

Displayed value = f $\times \, \alpha$

f: Input pulse frequency (number of pulses in 1 second) α : Prescale value

(1) Displaying Rotation Rate

| Display unit | Prescale value (α) | | |
|--------------|--------------------|--|--|
| rpm | 1/N × 60 | | |
| rps | 1/N | | |

N: Number of pulses per revolution

Example: In order to display the rate of rotation for a machine that outputs 5 pulses per revolution in the form $\Box \Box \Box$ rpm: 1. Set the decimal point position to 1 decimal places. 2. Using the formula, set the prescale value (α) to $1/N \times 60 = 60/5 = 12$.

(2) Displaying Speed

 π d: Circumference (m)

| Display unit | Prescale value (α) |
|-----------------------------------|----------------------------|
| m/min | $\pi d 	imes 1/N 	imes 60$ |
| m/s | $\pi d \times 1/N$ |
| N. Number of pulses per revolutio | n <u> </u> |

d: Diameter of rotating body (m)

d: Diameter of rotating body (m)

• Observe the following points when setting a prescale value.

Set the set value to a value less than {Maximum countable value – Prescale value}.

Example: If the prescale value is 1.25 and the counting range is 0.000 to 999.999, set the set value to a value less than 998.749 (= 999.999 - 1.25).

If the set value is set to a value greater than this, output will not turn ON.

| r | | ۰. |
|---|--|----|
| L | Note: If the prescale value setting is incorrect, a counting error will | L |
| L | occur. Check that the settings are correct before using this | L |
| L | function. | L |
| L | | L |
| L | | 4 |

Auto-zero Time (RULaD)

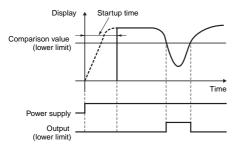
It is possible to make the settings so that the frequency will be forceset to 0 if there is no pulse for a specified period of time. This time is called the auto-zero time.

Note: Set the auto-zero time to a time slightly longer than the estimated interval between input pulses. It will not be possible to make accurate measurements if the auto-zero time is set to a time shorter than the input pulse cycle. Setting a time that is too long may also result in problems, such as a time-lag between rotation stopping and the alarm turning ON.

Startup Time (52 mc)

In order to prevent undesired output resulting from unstable input immediately after the power supply is turned ON, measurement can be prohibited for a set time at startup.

It can also be used to stop measurement and disable output until the rotating body reaches the normal rate of rotation, after the power supply to the H7CX and rotating body are turned ON at the same time.



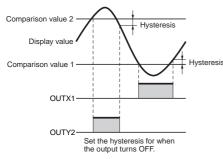
Peak/bottom Hold Enabled (dHLd)

This function records the peak and bottom (i.e., minimum) values after counting starts (after turning ON the power supply or changing the configuration selection mode or function setting).

The peak value is also held when the power supply is interrupted.

Output Hysteresis (서날5)

This setting can be used to prevent output chattering if the measurement value fluctuates slightly near the set value. In Thachometer Mode, the measurement value after prescaling is set.



Output OFF Delay (aFFd)

This function delays the timing for turning OFF comparative output by a certain time.

The ON time can be held for the set time if the comparative result changes in a short time.

Operation will continue and outputs will not change while holding the value.

Set Value Upper Limit (5L - H)

Set the upper limit for the set value when it is set in run mode.

Key Protect Level (3Pt)

Set the key protect level.

Refer to Key Protect Level on page page 48.

Output ON Count Alarm Set Value (an-R)

Set the alarm value for the output ON count.

The limit can be set to between $\underline{0} \times 1000$ (0 times) and $\underline{9999} \times 1000$ (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of the output exceeds the alarm set value, $\xi 3$ will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to *Self-diagnostic Function* on page page 48 for information on the $\xi 3$ display.

ON Count Alarm Set Values for Outputs 1 and 2 (OUT1 and OUT2) (an IR and an 2R)

Set the ON count alarm values for the outputs 1 and 2. The limit can be set to between 0×1000 (0 times) and 9999×1000

(9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of instantaneous output 1 or 2 exceeds the alarm set value, $\mathcal{E}3$ will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to *Self-diagnostic Function* on page page 48 for information on the $\mathcal{E}3$ display.

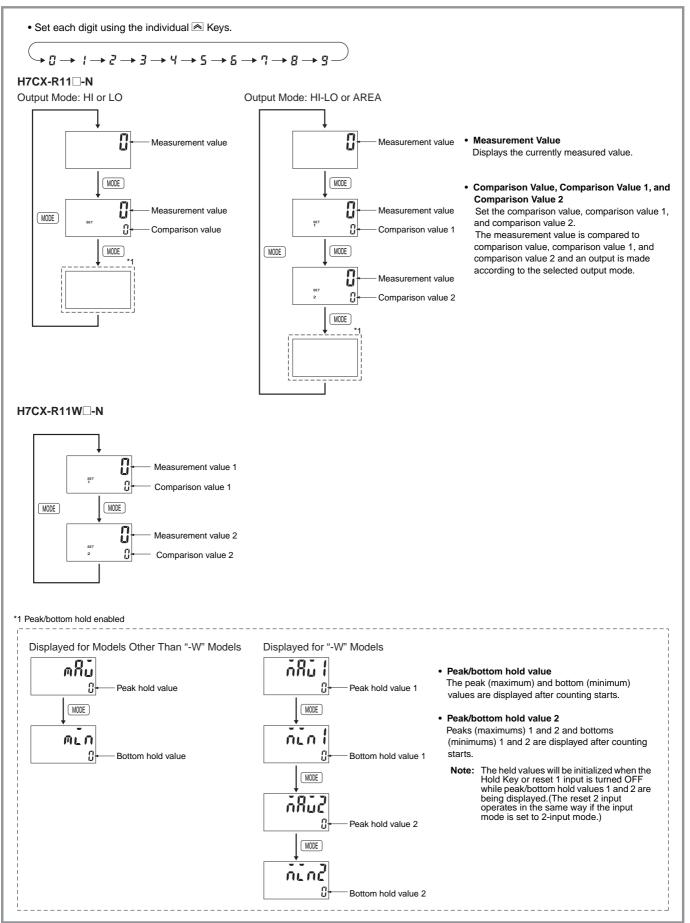
Output ON Count Monitor Value (an-L)

The monitor value is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

ON Count Monitor Values for Outputs 1 and 2 (OUT1 and OUT2) ($\delta \alpha \in \mathbb{Z}$ and $\delta \alpha \in \mathbb{Z}$)

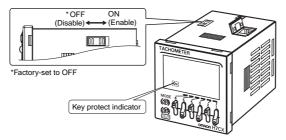
The monitor value for output 1 or 2 is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

Operation in Run Mode



Key Protect Level

When the key-protect switch is set to ON, it is possible to prevent setting errors by prohibiting the use of certain operation keys by specifying the key protect level (KP-1 to KP-7). The key protect level is set in the function setting mode. The key protect indicator is lit when the key-protect switch is ON.



| | | Details | | | | | |
|---------------------------|---------|----------------|---------------------------------------|----------|---------|--|--|
| Level | Meaning | Changing mode* | Switching display during operation | Hold Key | Uр Кеу | | |
| KP-1 (default setting) | | Invalid | Valid | Valid | Valid | | |
| KP-2 | MODE | Invalid | Valid | Invalid | Valid | | |
| KP-3 | | Invalid | Valid | Valid | Invalid | | |
| KP-4 | MODE | Invalid | Valid | Invalid | Invalid | | |
| KP-5 | | Invalid | Invalid | Invalid | Invalid | | |
| KP-6 | | Invalid | Invalid | Valid | Valid | | |
| KP-7 | | Invalid | Invalid | Invalid | Valid | | |

* Changing mode to DIP switch monitor mode or function setting mode.

Self-diagnostic Function

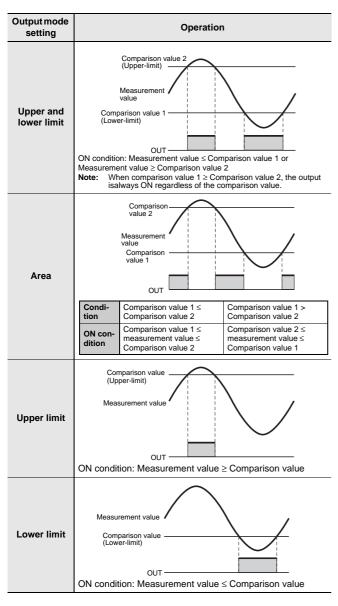
The following displays will appear if an error occurs.

| Main display Sub-display | | Error | Output status | Correction method | Set value after reset |
|--------------------------|--|-------------------------|---------------|--|--------------------------|
| FFFFFF *3 | FFFFFF *3 No change Measurement value overflow*2 | | No change | Measurement value ≤ 999999 | No change |
| El | E I Not lit CPU | | OFF | Either press the hold key or reset the power supply. | No change |
| E2 Not lit Memory | | Memory error (RAM) | OFF | Turn ON the power again. | No change |
| 23 | SUm | Memory error (EEP)*1 | OFF | Hold Key | Factory setting |
| E3 *4 | No change | Output Counter Overflow | No change | Hold Key | No change |

*1. This includes times when the life of the EEPROM has expired.

Cocurs when the measurement value caches 999,999.
 Occurs when the measurement value caches 999,999.
 Display flashes (1-second cycles).
 The normal display and £3 will appear alternately. When the Hold Key is pressed, £3 will not be displayed even if the alarm set value is exceeded. (Monitoring is possible, however, because the counter will continue without clearing the output ON count.)

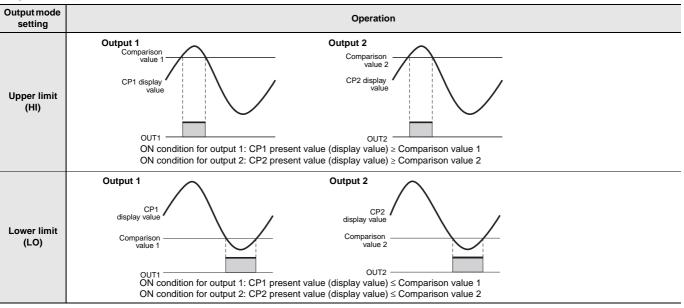
Output Mode Settings Models Other Than H7CX-R11W in Tachometer Mode



Output mode Operation setting Comparison (Upper-limit) Measurement value Comparison value (Lower-limit) Upper and lower limit OUT ON condition: Measurement value < Comparison value 1 or Measurement value ≥ Comparison value 2 When comparison value $1 \ge$ comparison value 2, the output isalways ON regardless of the comparison value. Note: Comparison value 2 Meas value Comparisor value 1 Area OUT Condi-Comparison value 1 ≤ Comparison value 1 tion Comparison value 2 Comparison value 2 Comparison value 1 ≤ Comparison value 2 ≤ ON con-dition measurement value < measurement value < Comparison value 2 Comparison value 1 Comparison value (Upper-limit) Measurement valu Upper limit OUT ON condition: Measurement value ≥ Comparison value Lower limit Comparison (Lower-limit) OUT ON condition: Measurement value < Comparison value Note:

If time "a" is exceeded during operation, the output will turn ON. If time "b" is exceeded during operation, the output will turn OFF. (If average processing is enabled, the output operation will be performed when the time is exceeded once.)

H7CX-R11W



Models Other Than H7CX-R11W in AMD-compatible Mode

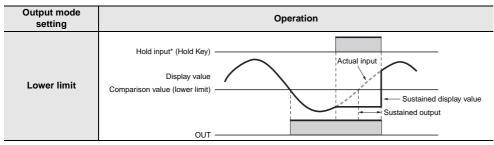
Precautions for the H7CX-R

In upper and lower limit output mode, if the comparison value setting is such that comparison value $1 \ge$ comparison value 2, the output will always be ON.

Hold Function

The measurement value (display value) and output are sustained while the hold input is ON. **Note:** The output will maintain the current status when the hold key is pressed.

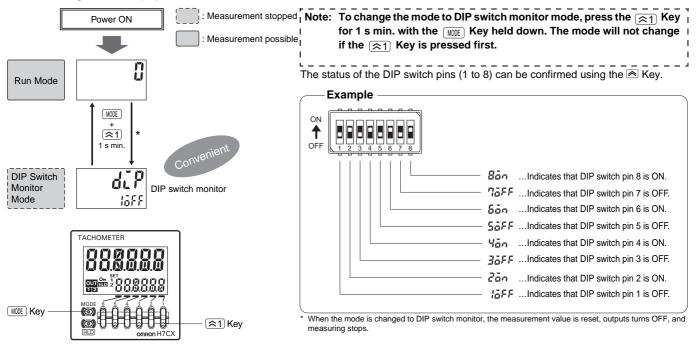
Example:



* The H7CX-R11W -N does not have a hold input.

Operation in DIP Switch Monitor Mode

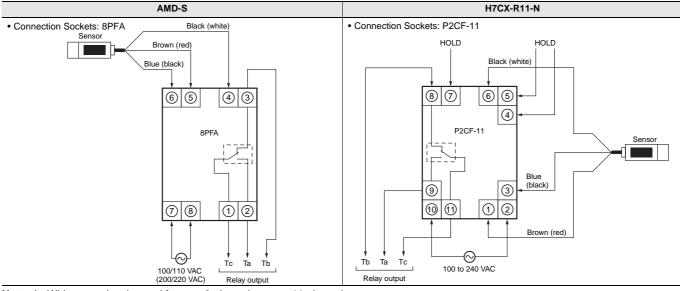
The H7CX-R is also equipped with a DIP switch monitor function, a convenient function that enables the settings of the DIP switch pins to be confirmed using the front display.



Precautions on Replacing the AMD-S

The H7CX-R11-N is the recommended model for replacing the AMD-S-series Motion Detector. Refer to the following precautions before replacing the AMD-S.

Terminal Arrangement and Wiring Connections



Note: 1. Wiring must be changed from an 8-pin socket to an 11-pin socket.

- 2. Take into consideration the length of the wires and the terminal numbers.
 - 3. Order the P2CF-11Connecting Socket separately.

Setting Procedure

Perform the following settings to achieve the functions of the AMD-S using the H7CX-R11-N.

DIP Switch Settings

| Model | | H7CX-R11-N | |
|----------------------------|---|--|----------------|
| ltem | AMD-S | DIP switch pin status * | Set value |
| Measuring ranges | 0.01 to 0.1 s (AMD-S□1), 0.1 to 1 s (AMD- S□2), 1 to 10 s (AMD-S□3) | Set DIP switch pin 1 to ON for AMD-compatible mode. | 1 ms 10 ms |
| Output | Rotation increase detection (AMD-SU□) | | Lower limit |
| mode | Rotation decrease detection (AMD-SL□) | | Upper limit |
| Average process- ing | None | | OFF |
| Input mode | Voltage Input | | PNP |

Note: The characters displayed in reverse video are the default settings.

* Refer to page page 43 for information on DIP switch settings.

Operation Key Settings

| Model | AMD-S | H7CX-R11-N | | |
|-----------------|---------------------|-----------------|--|--------------|
| Item | | Parameter s | Setting range | Set value |
| Startup time | Fixed (0.1 to 10 s) | 52 mr (STMR) | 0.0 ~ 99.9 (0.0 s) (99.9 s) | 0.0 |

Note: The characters displayed in reverse video are the default settings.

Characteristics

| Model | AMD-S | H7CX-R11-N | |
|------------------------------------|--|---|--|
| Item | AMD-5 | | |
| Supply voltage | -100 to 110 VAC -200 to 220 VAC | -100 to 240 VAC | |
| Input method | Voltage input (high: 4 to 14 V, low: 0 to 1 V) | No-voltage input/voltage input (high: 4.5 to 30 V, low: 0 to 2 V) | |
| External pow- er supply | 12 VDC ±1 V, 12 mA | 12 VDC (±10%), 100 mA | |
| Relay output | 5 A at 200 VAC (resistive load) | 3 A at 250 VAC/30 VDC (resistive load) | |
| Output mode | Rotation increase (AMD- SU□) Rotation decrease (AMD- SL□) | HI-LO, AREA, HI-HI, LO-LO (Set using DIP switch.) | |
| Setting meth- od | Input pulse interval (s) | Input pulse interval (s) * | |
| Detection rota- tion rate range | 6 to 6,000 rpm (for 1 pulse/rotation) | 0.00006 to 20,000 rpm * (for 1 pulse/rotation) | |
| Startup time | Always from 0.1 to 10 s (Always 10 s if not specified.) | Setting range: 0.0 to 99.9 s | |
| Life expectan- cy | Output relay electrical operations of 500,000 min. | Output relay electrical operations of 100,000 min. | |
| Memory back- up | None | EEPROM (overwrites: 100,000 times min.) | |

* When set to AMD mode.

Safety Precautions for All H7CX Series (Common)

Do not allow pieces of metal, wire clippings, or fine metallic shavings or fillings from installation to enter the product. Doing so may occasionally result in electric shock, fire, or malfunction.



Minor injury due to explosion may occasionally occur. Do not use the Counter where subject to flammable or explosive gas.



Fire may occasionally occur. Tighten the terminal screws to the rated torque. H7CX terminals: 6.55 to 7.97 lb-in (0.74 to 0.90 N·m) P2CF Socket terminals: 4.4 lb-in (0.5 N·m)



Minor injury due to electric shock may occasionally occur. Do not touch any of the terminals while power is being supplied. Be sure to mount the terminal cover after wiring.

The life expectancy of the output relay varies considerably according to its usage. Use the output relay within its rated load and electrical life

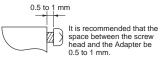
expectancy. If the output relay is used beyond its life expectancy, its contacts may become fused or there may be a risk of fire. Also, be sure that the load current does not exceed the rated load current and when using a heater, be sure to use a thermal switch in the load circuit.

Minor electric shock, fire, or malfunction may occasionally occur. Do not disassemble, modify, or repair the Counter or touch internal components.



Precautions for Safe Use

• The panel surface of the H7CX-A/-R is water-resistant (conforming to NEMA4, IP66, UL Type 4X (Indoor Use Only). To protect the internal circuits from water penetration through the space between the H7CX and operating panel, waterproof packing is included. Attach the Y92F-30 Adapter with sufficient pressure with the reinforcing screws so that water does not penetrate the panel.



- When mounting the Counter to a panel, tighten the two mounting screws alternately, a little at a time, so as to keep them at an equal tightness. If the panel screws are tightened unequally, water may enter the panel.
- Store the Counter at the specified temperature. If the Counter has been stored at a temperature of less than

 -10°C, allow the Counter to stand at room temperature for at least
- 3 hours before use.Mounting the Counter side-by-side may reduce the life
- expectancies of internal components.
- Use the Counter within the specified ranges for the ambient operating temperature and humidity.
- Do not use in the following locations:
 - Locations subject to sudden or extreme changes in temperature.
- Locations where high humidity may result in condensation.
 Do not use the Counter outside of the rated ranges for vibration, shock, water exposure, and oil exposure.
- Do not use this Counter in dusty environments, in locations where corrosive gasses are present, or in locations subject to direct sunlight.
- Install the Counter well away from any sources of static electricity, such as pipes transporting molding materials, powders, or liquids.

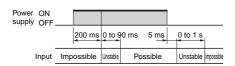
- Internal elements may be destroyed if a voltage outside the rated voltage range is applied.
- Be sure that polarity is correct when wiring the terminals.
- Separate the Counter from sources of noise, such as devices with input signals from power lines carrying noise, and wiring for I/O signals.
- Do not connect more than two crimp terminals to the same terminal.
- Up to two wires of the same size and type can be inserted into a single terminals.
- Use the specified wires for wiring. Applicable Wires: AWG 18 to AWG 22, solid or twisted, copper
- Install a switch or circuit breaker that allows the operator to immediately turn OFF the power, and label it to clearly indicate its function.
- When the Counter is operated with no-voltage input (NPN input), approximately 14 V is output from the input terminals. Use a sensor that contains a diode.



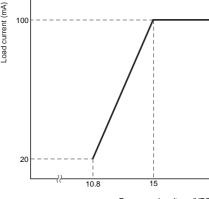
- Use a switch, relay, or other contact so that the rated power supply voltage will be reached within 0.1 seconds. If the power supply voltage is not reached quickly enough, the Counter may malfunction or outputs may be unstable.
- Use a switch, relay, or other contact to turn the power supply OFF instantaneously. Outputs may malfunction and memory errors may occur if the power supply voltage is decreased gradually.
- When changing the set value during operation, because the H7CX uses a constant read-in system, output will turn ON if the set value is equal to the present value.
- When changing the comparison value during operation, because the H7CX uses a constant read-in system, the output status will change if the comparison value is changed to a value on the other side of the present value. (when using as a tachometer)
- If the set value and present value are both 0, the output will turn ON for the default setting. The output will turn OFF during a reset operation. (when using as a counter)
- When the power is turned ON using the factory settings, the output will turn ON after 999.9 s if no pulses are received as count input.
- Do not use organic solvents (such as paint thinners or benzine), strong alkali, or strong acids. They will damage the external finish.
- Confirm that indications are working normally, including the backlight LED, and LCD. The indicator LEDs, LCD, and resin parts may deteriorate more quickly depending on the application environment, preventing normal indications. Periodic inspection and replacement are required.
- The waterproof packing may deteriorate, shrink, or harden depending on the application environment. Periodic inspection and replacement are required.

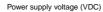
Precautions for Correct Use

- H7CX models with a 12 to 24-VDC power supply use a transformer-free power supply method in which the power supply terminals are not isolated from the signal input terminals. If a nonisolating DC power supply is used, unwanted current paths may occasionally burn or destroy internal components depending on the wiring. Always check the wiring sufficiently before use.
- An inrush current of approx. 10 A will flow for a short time when the power supply is turned ON. If the capacity of the power supply is not sufficient, the Counter may not start. Be sure to use a power supply with sufficient capacity.
- Maintain voltage fluctuations in the power supply within the specified operating voltage range.
- When turning the power ON and OFF, input signal reception is possible, unstable, or impossible as shown in the diagram below.



- Inrush current generated by turning ON or OFF the power supply may deteriorate contacts on the power supply circuit. Turn ON or OFF to a device with the rated current of more than 10 A.
- The capacity of the external power supply is 100 mA at 12 V. When using a 24 VAC/12 to 24 VDC power supply, reduce the load with the power supply voltage, as shown in the following diagram (DC power supplies only).

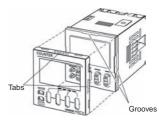




- If the prescale value setting is incorrect, a counting error will occur. Check that the settings are correct before using this function.
- Make sure that all settings are appropriate for the application. Unexpected operation resulting in property damage or accidents may occur if the settings are not appropriate.
- Do not leave the Counter for long periods at a high temperature with output current in the ON state. Doing so may result in the premature deterioration of internal components (e.g., electrolytic capacitors).
- EEPROM is used as backup memory when the power is interrupted. The write life of the EEPROM is 100,000 writes. The EEPROM is written at the following times:
 - · When the power supply is turned OFF
 - When switching from Configuration Selection Mode or Function Setting Mode to Run Mode
- · Dispose of the product according to local ordinances as they apply.

• Attach the front panel when using the Counter. The tabs in the middle of each of four sides secure the front panel to the main body. To remove the panel, widen the four tabs and pull the panel toward you.

To mount the panel, fit all four tabs correctly into the grooves on the main body.



Conformance to EN/IEC Standards

- When conforming to EMC standards, refer to the information provided in this datasheet for cable selection and other conditions.
- This is a class A product. In residential areas it may cause radio interference, in which case the user may be required to take adequate measures to reduce interference.
- H7CX-A
 -N: Basic insulation is provided between power supply and input terminals, between power supply and output terminals, and between input and output terminals. (However, no insulation is provided between the power supply and input terminals for the H7CX-A
 -D-N.)
- H7CX-R
 -N: Basic insulation is provided between power supply and input terminals and between input and output terminals.
- When double insulation or reinforced insulation is required, apply double insulation or reinforced insulation as defined in IEC 60664 that is suitable for the maximum operating voltage with clearances or solid insulation.
- Connect the input and output terminals to devices that do not have any exposed charged parts.

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 H7CX-R11D1-N

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 H7CX-AWS-N AC100-240

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 H7CX-A11-N AC100-240
 H7CX-A4W-N-AC100-240

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