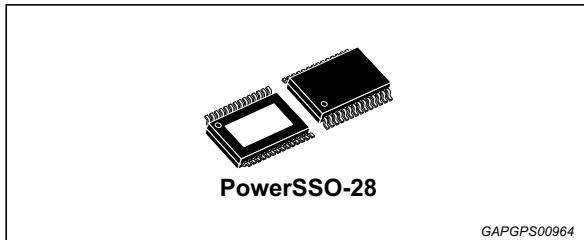


Automotive octal self configuring low/high side driver

Datasheet - production data



Features

- AEC-Q100 (Rev. F) qualified
- Eight independently self configuring low/high drivers
- Supply voltage from 4.5 V to 5.5 V
- $R_{ON(max)} = 0.7 \Omega @ T_j = 25^\circ\text{C}$,
 $R_{ON(max)} = 1.2 \Omega @ T_j = 125^\circ\text{C}$
- Minimum current limit of each output 1 A
- Output voltage clamping min. 40 V in low-side configuration
- Output voltage clamping max. -14 V in high-side configuration
- SPI interface for outputs control and for diagnosis data communication
- Additional PWM inputs for 3 outputs
- Independent thermal shutdown for all outputs open load, short to GND, short to V_b, overcurrent diagnostics in latched or unlatched mode for each channel
- Internal charge pump without need of external capacitor



- Controlled SR for reduced EMC

Description

The L9733 is a highly flexible monolithic, medium current, output driver that incorporates 8 outputs that can be used as either internal low or high-side drives in any combination.

Outputs 1-8 are self-configuring as high or low-side drives. Self-configuration allows a user to connect a high or low-side load to any of these outputs and the L9733 will drive them correctly as well as provide proper fault mode operation with no other needed inputs. In addition, outputs 6, 7 and 8 can be PWM controlled via a external pins (IN6-8).

This device is capable of switching variable load currents over the ambient range of -40 °C to +125 °C. The outputs are MOSFET drivers to minimize V_{dd} current requirements. For low-side configured outputs an internal zener clamp from the drain to gate with a breakdown of 50 V minimum will provide fast turn off of inductive loads. When a high-side configured output is commanded Off after having been commanded On, the source voltage will go to (VGND - 15 V).

An 16 bit SPI input is used to command the 8 output drivers either "On" or "Off", reducing the I/O port requirement of the microcontroller.

Multiple L9733 can be daisy-chained. In addition the SPI output indicates latched fault conditions that may have occurred.

Table 1. Device summary

| Order code | Package | Packing |
|------------|---------------------------|---------------|
| L9733XP | PowerSSO-28 (Exposed pad) | Tube |
| L9733XPTR | PowerSSO-28 (Exposed pad) | Tape and reel |
| L9733CN | PowerSSO-28 (Exposed pad) | Tube |
| L9733CNTR | PowerSSO-28 (Exposed pad) | Tape and reel |

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1 Pin description

Figure 1. Pin connection (top view)

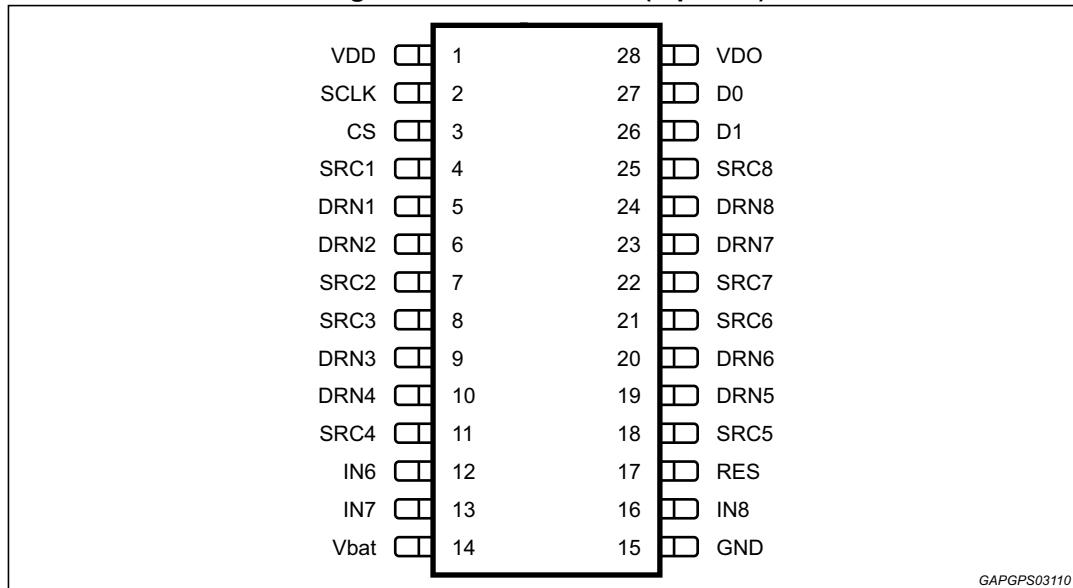


Table 2. Pin description

| Nº | Pin | Function |
|----|------|---|
| 1 | VDD | 5 Volt supply input |
| 2 | SCLK | SPI serial clock input |
| 3 | CS | SPI chip select (active low) |
| 4 | SRC1 | Source pin of configurable driver #1 (0.7 Ω R _{ds_{on}} @ +25 °C) |
| 5 | DRN1 | Drain pin of configurable driver #1 (0.7 Ω R _{ds_{on}} @ +25 °C) |
| 6 | DRN2 | Drain pin of configurable driver #2 (0.7 Ω R _{ds_{on}} @ +25 °C) |
| 7 | SRC2 | Source pin of configurable driver #2 (0.7 Ω R _{ds_{on}} @ +25 °C) |
| 8 | SRC3 | Source pin of configurable driver #3 (0.7 Ω R _{ds_{on}} @ +25 °C) |
| 9 | DRN3 | Drain pin of configurable driver #3 (0.7 Ω R _{ds_{on}} @ +25 °C) |
| 10 | DRN4 | Drain pin of configurable driver #4 (0.7 Ω R _{ds_{on}} @ +25 °C) |
| 11 | SRC4 | Source pin of configurable driver #4 (0.7 Ω R _{ds_{on}} @ +25 °C) |
| 12 | IN6 | Discrete input used to PWM output driver #6 |
| 13 | IN7 | Discrete input used to PWM output driver #7 |
| 14 | Vbat | Battery supply voltage |
| 15 | GND | Analog ground |
| 16 | IN8 | Discrete input used to PWM output driver #8 |
| 17 | RES | Reset input (active low) |
| 18 | SRC5 | Source pin of configurable driver #5 (0.7 Ω R _{ds_{on}} @ +25 °C) |

Table 2. Pin description (continued)

| N° | Pin | Function |
|----|------|--|
| 19 | DRN5 | Drain pin of configurable driver #5 (0.7 Ω $R_{ds_{on}}$ @ +25 °C) |
| 20 | DRN6 | Drain pin of configurable driver #6 (0.7 Ω $R_{ds_{on}}$ @ +25 °C) |
| 21 | SRC6 | Source pin of configurable driver #6 (0.7 Ω $R_{ds_{on}}$ @ +25 °C) |
| 22 | SRC7 | Source pin of configurable driver #7 (0.7 Ω $R_{ds_{on}}$ @ +25 °C) |
| 23 | DRN7 | Drain pin of low-side driver #7 (0.7 Ω $R_{ds_{on}}$ @ +25 °C) |
| 24 | DRN8 | Drain pin of low-side driver #8 (0.7 Ω $R_{ds_{on}}$ @ +25 °C) |
| 25 | SRC8 | Source pin of configurable driver #8 (0.7 Ω $R_{ds_{on}}$ @ +25 °C) |
| 26 | DI | SPI data in |
| 27 | DO | SPI data out |
| 28 | VDO | Microcontroller logic interface voltage |

Note: *The exposed slug must be soldered on the PCB and connected to GND.*

2 Operating conditions

2.1 Operating range

This part may not operate if taken outside the operating range. Once the condition is returned within the specified maximum rating or the power is recycled, the part will recover with no damage or degradation.

Table 3. Operating range

| Symbol | Parameter | Value | Unit |
|-----------------------------|---------------------------------------|------------|------|
| V_{dd} | Supply voltage | 4.5 to 5.5 | V |
| V_{bat} (operative range) | Battery supply voltage | 4.5V to 18 | V |
| V_{bat} @ JSC | | 18 to 27 | |
| V_{bat} @ low battery | | 3.5 to 4.5 | |
| V_{bat} @ load dump | | 27 to 40 | |
| T_j | Thermal junction temperature range | -40 to 150 | °C |
| | Snubbing voltage of DRN1-8 | min 50 | VDC |
| I_{Ox} | Output current 1-8 | max 800 | mA |
| Eso | Maximum clamping energy at switch-off | 20 | mJ |

2.1.1 Functional operative range

$$4.5 \text{ V} \leq V_{bat} \leq 18 \text{ V} \quad (-40 \text{ }^{\circ}\text{C} \leq T_j \leq 150 \text{ }^{\circ}\text{C});$$

All the electrical capabilities are guaranteed by characterization as reported in [Section 3: Electrical performance characteristics](#).

2.1.2 Jump start conditions

$$18 \text{ V} \leq V_{bat} \leq 27 \text{ V} \quad (-40 \text{ }^{\circ}\text{C} \leq T_j \leq 150 \text{ }^{\circ}\text{C});$$

Operation at Jump start condition for a maximum duration of 1 minute.

All outputs are switched according to the commands on the SPI bus or the PWM inputs. The SPI bus and the inputs are functional during the Jump-Start condition.

The over-temperature shutdown and over current protection of the device are not guaranteed to stay functional for Vbat between 18 V and 27 V.

The reliability and the functionality of the L9733XP are not compromised when the Jump-Start condition is not repeated for more than five times.

2.1.3 Operation at low battery condition

$$3.5 \text{ V} \leq V_{\text{bat}} \leq 4.5 \text{ V} \quad (-40 \text{ }^{\circ}\text{C} \leq T_j \leq 150 \text{ }^{\circ}\text{C});$$

All outputs are able to keep the status according to the commands on the SPI bus or the PWM inputs. Switching commands entered via the SPI bus might not be executed by the L9733 at low-battery condition. The SPI bus and the inputs are functional during the Low-Battery condition.

2.1.4 Operation at load dump condition

$$27 \text{ V} \leq V_{\text{bat}} \leq 40 \text{ V} \quad (-40 \text{ }^{\circ}\text{C} \leq T_j \leq 150 \text{ }^{\circ}\text{C})$$

There is not an internal circuit that switches OFF the drivers during load dump condition.

The over-temperature shutdown and over current protection of the device are not guaranteed to stay functional during load dump condition.

2.1.5 Loss of protection against short to battery

When the battery supply voltage, V_{bat} (pin 14), is switched off during a short-to-battery condition at an output in high-side configuration, the protection circuits are no longer functional, and the L9733 may fail with EOS.

2.2 Absolute maximum ratings

This part may be irreparably damaged if taken outside the specified absolute maximum ratings. Operation outside the absolute maximum ratings may also cause a decrease in reliability.

Table 4. Absolute maximum ratings

| Symbol | Parameter | Value | Unit |
|------------------|--|------------------------|------|
| V_{DD} | Supply voltage | -0.3 to 7 | V |
| V_{bat} | Supply voltage | -0.3 to 40 | V |
| - | CS,DI,DO,SCLK,EN,IN6,IN7,IN8,VDO | -0.3 to 7.0 | V |
| - | SRCx pin | min. -24 | VDC |
| - | Max. value of $V_{\text{SRCx}} = \text{Minimum of } \{V_{\text{bat}} + 1\text{ V} \parallel V_{\text{DRNx}} + 0.3 \text{ V} \parallel +40 \text{ V}\}$ | - | - |
| - | DRN1-8 ⁽¹⁾ | -0.3 to 60 | VDC |
| I_{OL} | Current limit of output 1-8 (-40 $^{\circ}\text{C}$) | 2.5 | A |
| I_{OP} | Over current protection at output 1-8 (-40 $^{\circ}\text{C}$) | 3 | A |
| | Maximum clamping energy | 20 | mj |
| ESD | Human body model - All pins | ± 2 ⁽²⁾ | kV |
| | Human body model - Driver outputs | ± 4 ⁽²⁾ | kV |

1. For the DRNx the MAX ASB value is the Max Clamp Voltage (see [Table 6](#) on page 13 - DRNx Clamp voltage).
2. Device is only protected vs. GND.

2.3 Thermal data

Table 5. Thermal data

| Symbol | Parameter | Min | Typ | Max | Unit |
|------------------|---|-----|-----|-----|------|
| T_{amb} | Operating ambient temperature | -40 | - | 125 | °C |
| T_{stg} | Storage temperature | -50 | - | 150 | °C |
| T_j | Maximum operating junction temperature | - | - | 150 | °C |
| R_{th} | Thermal shutdown temperature | 151 | 175 | 200 | °C |
| R_{th-hys} | Thermal shutdown temperature hysteresis | 7 | 10 | 25 | °C |
| $R_{Th\ j-amb}$ | Thermal resistance junction-to-ambient ⁽¹⁾ | - | - | 24 | °C/W |
| $R_{Th\ j-case}$ | Thermal resistance junction-to-case | - | - | 3 | °C/W |

1. With 2s2p PCB thermally enhanced.

3 Electrical performance characteristics

These are the electrical capabilities this part was designed to meet. It is required that every part meets these characteristics.

3.1 DC characteristics

T_{amb} = -40 to 125 °C, V_{dd} = 4.5 to 5.5 Vdc, V_{bat} = 4.5 to 18 Vdc (high-side configuration), unless otherwise specified.

Table 6. DC characteristics

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|---------------------|--------------------|---------------------------|---------|-----|--------|-------|
| IN6v _{ih} | IN6 input voltage | - | - | - | 0.7vdo | V |
| IN6v _{il} | | - | 0.3vdo | - | - | V |
| I _{IN6il} | IN6 input current | IN6 = 0 VDC | - | - | 10 | µA |
| I _{IN6ih} | | IN6 = VDO | 10 | - | 100 | µA |
| IN7v _{ih} | IN7 input voltage | - | - | - | 0.7vdo | V |
| IN7v _{il} | | - | 0.3vdo | - | - | V |
| I _{IN7il} | IN7 input current | IN7 = 0 VDC | - | - | 10 | µA |
| I _{IN7ih} | | IN7 = VDO | 10 | - | 100 | µA |
| IN8v _{ih} | IN8 input voltage | - | - | - | 0.7vdo | V |
| IN8v _{il} | | - | 0.3vdo | - | - | V |
| I _{IN8il} | IN8 input current | IN8 = 0 VDC | - | - | 10 | µA |
| I _{IN8ih} | | IN8 = VDO | 10 | - | 100 | µA |
| CS _{ih} | CS input voltage | - | - | - | 0.7vdo | V |
| CS _{il} | | - | 0.3vdo | - | - | V |
| I _{CSih} | CS input current | CS = VDO | - | - | 10 | µA |
| I _{CSil} | | CS = 0 VDC | 10 | - | 100 | µA |
| SCLK _{ih} | SCLK input voltage | - | - | - | 0.7vdo | V |
| SCLK _{il} | | - | 0.3vdo | - | - | V |
| I _{SCLKih} | SCLK input current | SCLK = VDO | - | - | 10 | µA |
| I _{SCLKil} | | SCLK = 0 VDC | 10 | - | 100 | µA |
| DI _{ih} | DI input voltage | - | - | - | 0.7vdo | V |
| DI _{il} | | - | 0.3vdo | - | - | V |
| I _{DIih} | DI input current | DI = VDO | - | - | 10 | µA |
| I _{DIil} | | DI = 0 VDC | 10 | - | 100 | µA |
| DO _{ol} | DO output voltages | I _{DO} = 2.5 mA | - | - | 0.4 | V |
| DO _{oh} | | I _{DO} = -2.5 mA | vdo-0.6 | - | - | V |

Table 6. DC characteristics (continued)

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|---------------------------|---|---|-------------|-----|-------------|--------------------|
| I_{DOz0l} | DO Tri-state currents | DO = 0 VDC | - | - | $ 10 $ | μA |
| I_{DOz0h} | | DO = VDO | - | - | $ 10 $ | μA |
| RES_{ih} | RES input voltage | - | - | - | $0.7v_{do}$ | V |
| RES_{il} | | - | $0.3v_{do}$ | - | - | V |
| I_{RESil} | RES input current | RES = 0 VDC | 10 | - | 100 | μA |
| I_{RESih} | | RES = VDO | - | - | $ 10 $ | μA |
| POR_{th} | Power on reset threshold | @ -40 °C | 2.8 | - | 4.2 | V |
| | | @ 25 °C | 2.8 | - | 3.7 | |
| | | @ 125 °C | 2 | - | 3.4 | |
| I_{slp} | Vbat sleep current | VDD = SRC1-8 = 0VDC DRN1-DRN8=18VDC, Vb. Sum currents ($T_{amb} > 0$ °C) (T_{amb} @ -40 °C) | - | - | 10 3 | μA μA |
| I_{vbat} | Vbat current | VDD = 5 V All Outputs Commanded On | - | - | 15 | mA |
| I_{VDD} | Max. VDD current | All Outputs Commanded On | - | - | 8.5 | mA |
| I_{VDD} | Min. VDD current | All Outputs Commanded Off | 0.5 | - | | mA |
| $I_{DRN1lk} - I_{DRN8lk}$ | DRN1 - DRN8 leakage currents (low-side) | VDD = 0 VDC: SRC1-8 = 0 VDC DRN1- DRN8 = 16 VDC DRN1- DRN8 = 40 VDC | - | - | 5 10 | μA μA |
| $I_{SRC1lk} - I_{SRC8lk}$ | SRC1 – SRC8 Leakage currents (high-side) | VDD = 0 VDC: SRC1-8 = 0 VDC DRN1- 8 = 16 V DRN1- 8 = 40 VDC | - | - | -5 -10 | μA μA |
| $I_{Drn1-8sink}$ | DRN1 – DRN8 sink current (low-side) | SRC1-8 = GND DI = AC00h $R_{load} \leq 11 \text{ k}\Omega$ $R_{load} \leq 200 \text{ k}\Omega$ | 10 120 | - | 100 280 | μA μA |
| R_{DRN1-8} | Open load detection resistance | VBAT \geq 9 V | 11 | - | 200 | $\text{K}\Omega$ |
| $I_{Drn1-8source}$ | Source current | DRN1-DRN8 = GND | -10 | - | -100 | μA |
| $I_{src1-8sink}$ | SRC1 – SRC8 sink/source current (high-side) | DRN1- 8 = Vb, DI = AC00h SCR1- 8 = Vb | 10 | - | 100 | μA |
| $I_{src1-8source}$ | | SCR1- 8 = GND | -18 | - | -100 | μA |
| $V_{Drn1-8open}$ | DRN1 – DRN8 open load voltage (low-side) | SRC1- 8 = GND, DI = AC00h DRN1- DRN8 = Open VDD=4.9 to 5.1 VDC | 2.7 | - | 3.1 | V |
| | | SRC1- 8 = GND, DI = AC00h DRN1- DRN8 = Open VDD = 4.5 to 5.5 V | 2.5 | - | 3.5 | V |

Table 6. DC characteristics (continued)

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|-------------------------------------|---|---|--------|-----|------------|--------|
| $V_{src1-8open}$ | SRC1 – SRC8 open load voltage (High-side) DRN1 - DRN8 | DRN1-8 = Vb, DI = AC00h SCR1-8 = open | 2.0 | - | 2.8 | V |
| $I_{DRN1limit} - I_{DRN8limit}$ | DRN1 - DRN8 current limits (low-side) | DI = ACFFh, DI = AAFFh SRC1 – SRC8 = 0 VDC DRN1 - DRN8 = 4.5 - 16 VDC ($T_{amb} > 0^{\circ}\text{C}$) ($T_{amb} @ -40^{\circ}\text{C}$) | 1 1 | - | 2.2 2.5 | A A |
| $I_{DRN1OVC} - I_{DRN8OVC}$ | DRN1 - DRN8 overcurrent threshold (low-side) | DI = AC00h, DI = AA00h SRC1 – SRC8 = 0 VDC DRN1 - DRN8 = 4.5 - 16 VDC ($T_{amb} > 0^{\circ}\text{C}$) ($T_{amb} - 40^{\circ}\text{C}$) | 1 1 | - | 2.7 3 | A A |
| $I_{SRC1limit} - I_{SRC8limit}$ | SRC1 – SRC8 current limits (high-side) | DI = ACFFh, DI = AAFFh DRN1 - DRN8 = Vb SRC1 – SRC8 = GND ($T_{amb} > 0^{\circ}\text{C}$) ($T_{amb} - 40^{\circ}\text{C}$) | 1 1 | - | 2.2 2.5 | A A |
| $I_{SRC1OVC} - I_{SRC8OVC}$ | Overcurrent threshold (high-side) | DRN1 - DRN8 = Vbat SRC1 – SRC8 = GND ($T_{amb} > 0^{\circ}\text{C}$) ($T_{amb} - 40^{\circ}\text{C}$) | 1 1 | - | 2.7 3 | A A |
| $DRN1_{Cl+} - DRN8_{Cl+}$ | DRN1 - DRN8 Clamp voltages (low-side) | DI = AC00h SRC1-8 = GND, $I_{DRN1-8} = 350\text{ mA}$ | 50 | - | 60 | V |
| $SRC1_{Cl+} - SRC8_{Cl+}$ | SRC1 – SRC8 Clamp voltages (High-side) | DI = AC00h DRN1-8 = Vbat, $I_{SRC1-8} = -350\text{ mA}$ | -24 | - | -14 | V |
| $V_{Drn1-8open} - DRN1-8_{VthGND}$ | Short to GND threshold distance from open load voltage (low-side) | SRC1 – SRC8 = GND: Decrease Drn1 - Drn8 until Faults are "Set" | 0.3 | - | 0.7 | V |
| $DRN1-8_{VthVbat} - V_{Drn1-8open}$ | DRN1 - DRN8 Short to Vbat threshold distance from open load voltage (low-side) | DI = AC00h SRC1 – SRC8 = GND: Increase Drn1 - Drn8 until Faults are "Not Set" | 0.3 | - | 0.7 | V |
| $V_{Drn1-8open} - SRC1-8_{VthGND}$ | SRC1 - SRC8 Short to GND threshold distance from open load voltage (High-side) | DI = AC00h Drn1 – Drn8 = Vb: Decrease SRC1 – SRC8 until Faults are "Not Set" | 0.2 | - | 0.6 | V |
| $SRC1-8_{VthVbat} - V_{Drn1-8open}$ | SRC1 – SRC8 Short to Vbat threshold distance from open load voltage (High-side) | DI = AC00h Drn1 – Drn8 = Vbat: Increase SCR1 - SCR8 until Faults are "Set" | 0.2 | - | 0.6 | V |

Table 6. DC characteristics (continued)

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|-------------------------|----------------------------------|--|-----|-----|-----|-------|
| $R_{dson,Drn1-8}^{(1)}$ | On resistance (Drn to SRC1-8) | @ +125 °C @ $I_{DRN} = 350$ mA | - | - | 1.2 | Ω |
| | | @ +25 °C @ $I_{DRN} = 350$ mA | - | - | 0.7 | Ω |
| | | @ -40 °C @ $I_{DRN} = 350$ mA | - | - | 0.5 | Ω |
| $Drn1-8_{ther}^{(2)}$ | Thermal shutdown temperature | DI = ACFFh, $I_{Drn1-8} = 1$ mA, SRC1 – SRC8 = GND, Increase temperature until $Drn1 - Drn8 > 2$ VDC, Verify DO Bits 0-15 are "Set" | 151 | - | 200 | °C |
| $Drn1-8_{hyst}^{(2)}$ | Hysteresis | $Drn1 - Drn8 < 2$ VDC | 5 | - | 15 | °C |

1. $R_{dson,Drn1-8} \leq 1.2$ Ω; at V_{bat} between 3.5 V and 27 V and T between -40 °C and 150 °C

2. Design Information, not tested.

3.2 AC characteristics

$T_{amb} = -40$ to 125 °C, $V_{dd} = 4.5$ to 5.5 Vdc, $V_{bat} = 4.5$ to 18 Vdc, unless otherwise specified

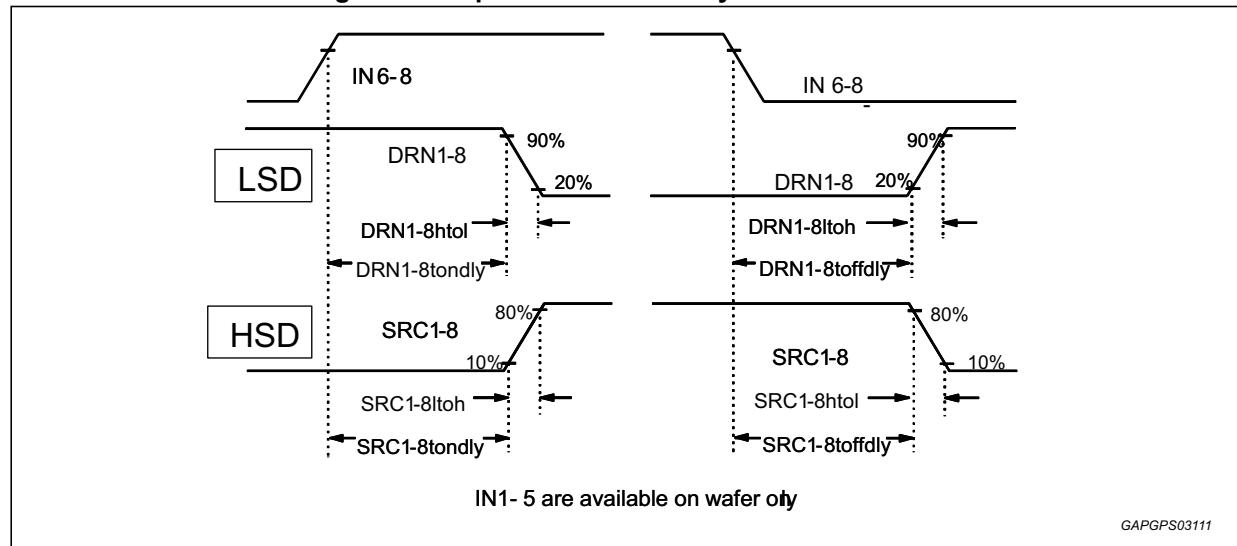
Table 7. AC characteristics

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|-------------------|--|--|------|-----|------|-------|
| $T_{filt,DRN1-8}$ | DRN1 - DRN8 Open load & short to GND filter time (low-side) (Latch mode) | DI = AC00h, DI = A3FFh SRC1 – SRC8 = GND | 300 | - | 900 | μs |
| $T_{filt,SRC1-8}$ | SRC1 - SRC8 Open load & short to Vbat filter time (high-side) (Latch mode) | DI = AC00h, DI = A3FFh DRN1 – DRN8 = Vb | 300 | - | 900 | μs |
| $T_{del,DRN1-8}$ | DRN1 - DRN8 Overcurrent switch off delay (low-side) | DI = ACFFh, DI = AA00h SRC1 – SRC8 = GND | 10 | - | 75 | μs |
| $T_{del,SRC1-8}$ | SRC1 - SRC8 Overcurrent switch off delay (high-side) | DI = ACFFh, DI = AA00h DRN1 – DRN8 = Vb | 10 | - | 75 | μs |
| T_{res} | Restart time after overcurrent switch off time (Int) | DI = ACFFh, DI = AA00h | 120 | - | 450 | ms |
| $Drn1-8_{htol}$ | Slew rate turn on | Outputs loaded as <i>Figure 4</i> See <i>Figure 2</i> | 0.65 | - | 1.95 | V/μs |
| $Drn1-8_{ltoh}$ | Turn off (low-side) | | 0.5 | - | 1.5 | V/μs |

Table 7. AC characteristics (continued)

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|---------------------------|----------------------|--|------|-----|------|-------|
| SRC1-8 _{htol} | Slew rate turn on | Outputs loaded as <i>Figure 4</i> See <i>Figure 2</i> | 0.65 | - | 1.95 | V/μs |
| SRC1-8 _{ltoh} | Turn off (High-side) | | 0.5 | - | 1.5 | V/μs |
| Drn1-8 _{tondly} | Delay time Turn on | Outputs loaded as <i>Figure 4</i> See <i>Figure 2</i> | 2 | - | 20 | μs |
| Drn1-8 _{toffdly} | Turn off (low-side) | | 10 | - | 100 | μs |
| SRC1-8 _{tondly} | Delay time Turn on | Outputs loaded as <i>Figure 4</i> See <i>Figure 2</i> | 2 | - | 20 | μs |
| SRC1-8 _{toffdly} | Turn off (high-side) | | 10 | - | 100 | μs |
| Drn1-8 _{offon} | Delay delta | Drn1-8 _{toffdly} - Drn1-8 _{tondly} | 10 | - | 60 | μs |
| SRC1-8 _{offon} | Delay delta | SRC1-8 _{toffdly} - SRC1-8 _{tondly} | 10 | - | 60 | μs |

Figure 2. Output turn on/off delays and slew rates



3.3 SPI characteristics and timings

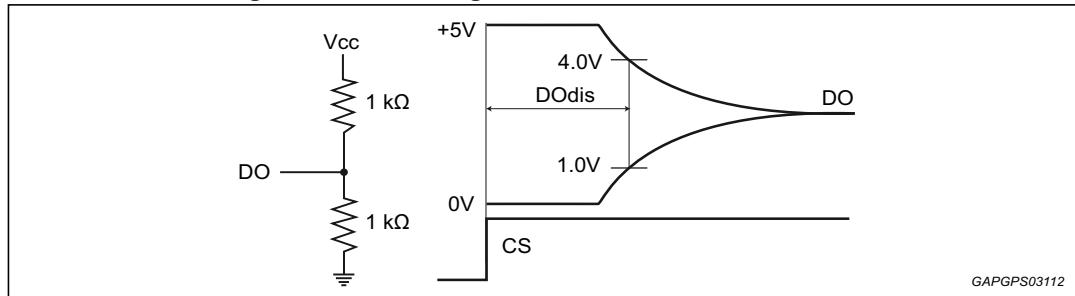
T_{amb} = -40 to 125 °C, V_{dd} = 4.5 to 5.5 Vdc, V_{bat} = 4.5 to 18 Vdc, unless otherwise specified

Table 8. SPI characteristics and timings

| Symbol | Parameter | Conditions | Min | Typ | Max | Units |
|--------------|-------------------------------|--|-----|-----|-----|-------|
| $DINC_{in}$ | Input capacitance | - | - | - | 20 | pF |
| $SCLK_{Cin}$ | | | - | - | 20 | pF |
| DO_{rise} | Output data (do) rise time | 50 pF from DO to Ground See <i>Figure 5</i> | - | - | 70 | ns |
| DO_{fall} | Output data (do) fall time | See <i>Figure 5</i> | - | - | 70 | ns |
| DO_a | Access time | See <i>Figure 6</i> | - | - | 350 | ns |
| DO_{sum} | Set up time | See <i>Figure 6</i> | 20 | - | - | ns |
| DO_{hm} | Hold time | See <i>Figure 6</i> | 10 | - | - | ns |
| DO_{dis} | Output data (DO) disable time | No Capacitor on DO, See <i>Figure 5</i> | - | - | 400 | ns |
| tth_{Filt} | Filter time | All Fault bits are "Set" | 5 | - | 20 | μs |
| $SCLKwid$ | SCLK width | See <i>Figure 5</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | 185 | - | - | ns |
| $SCLKlm$ | SCLK low time | See <i>Figure 5</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | 58 | - | - | ns |
| $SCLKhm$ | SCLK high time | See <i>Figure 5</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | 58 | - | - | ns |
| $SCLKrise$ | SCLK rise time | See <i>Figure 5</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | - | - | 21 | ns |
| $SCLKfall$ | SCLK fall time | See <i>Figure 5</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | - | - | 21 | ns |
| $CSrise$ | Channel select (CS) rise time | See <i>Figure 5</i> (1) | - | - | 100 | ns |
| $CSfall$ | Channel select (CS) fall time | See <i>Figure 5</i> (1) | - | - | 100 | ns |
| $CSlead$ | Channel select (CS) lead time | See <i>Figure 6</i> (1) | 455 | - | - | ns |
| $CSlag$ | Channel select (CS) lag time | See <i>Figure 6</i> (1) | 50 | - | - | ns |
| $DIrise$ | Input data (DI) rise time | See <i>Figure 5</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | - | - | 30 | ns |
| $DIfall$ | Input data (DI) fall time | See <i>Figure 5</i> @ f_{SCLK} = 5.4MHz ⁽¹⁾ | - | - | 30 | ns |
| $DIus$ | Input data (DI) set-up time | See <i>Figure 6</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | 15 | - | - | ns |
| $DIhs$ | Input data (DI) hold time | See <i>Figure 6</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | 10 | - | - | ns |
| $CS2SCLK$ | CS rise to SCLK rise | See <i>Figure 6</i> , @ f_{SCLK} = 5.4MHz ⁽¹⁾ | 40 | - | 300 | ns |

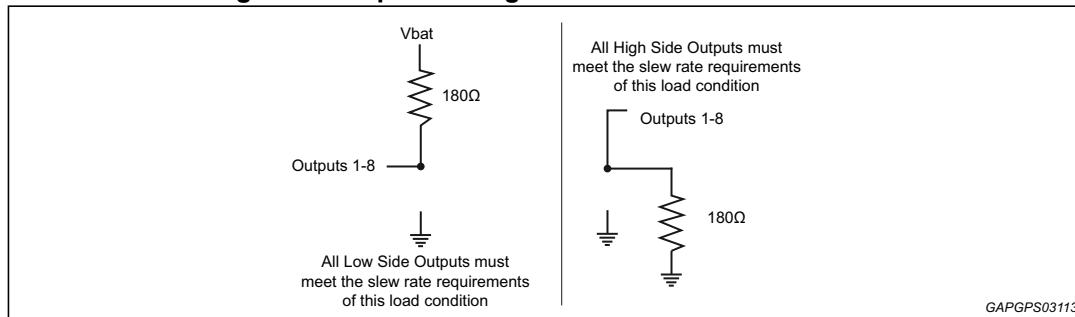
1. Guaranteed by design.

Figure 3. DO loading for disable time measurement



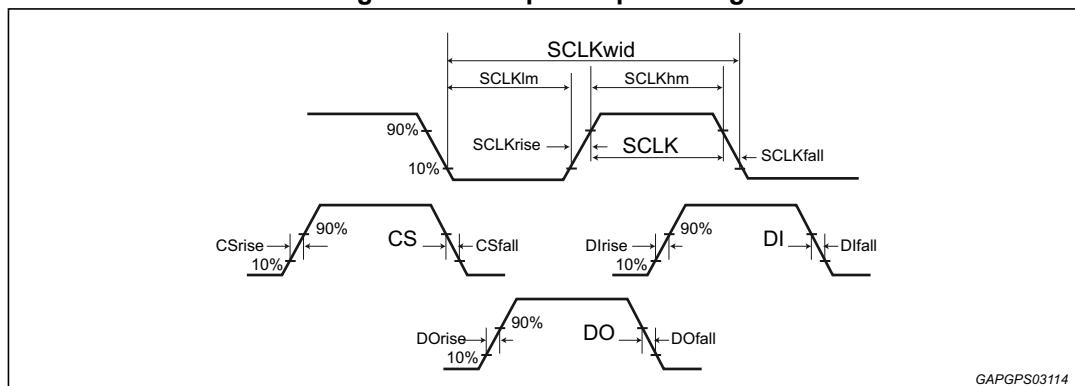
GAPGPS03112

Figure 4. Output loading for slew rate measurements



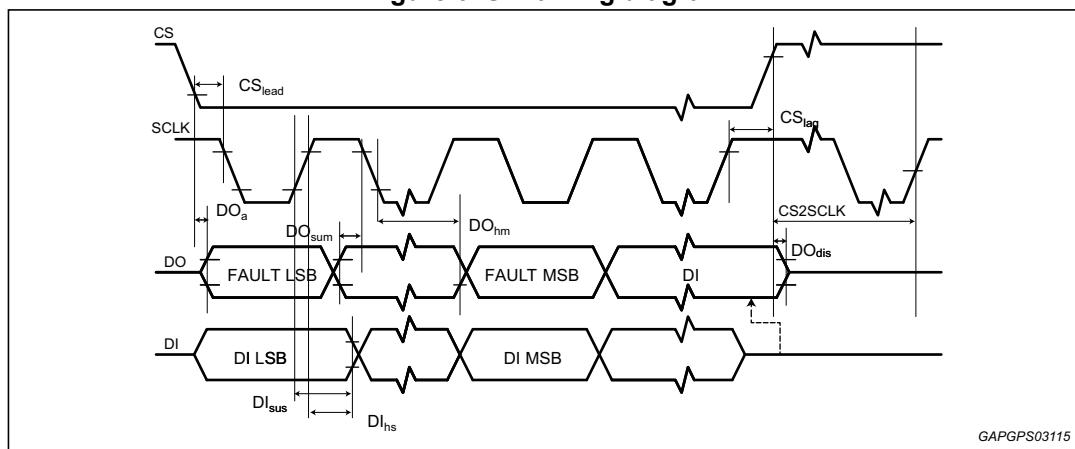
GAPGPS03113

Figure 5. SPI input/output timings



GAPGPS03114

Figure 6. SPI timing diagram



GAPGPS03115

4 Functional description

L9733 integrates 8 self-configuring outputs (OUT1-8) which are able to drive either incandescent lamps, inductive loads (non-pwm'd, in pwm an external diode to reduce flyback power dissipation is necessary), or resistive loads biased to Vbat (low-side configuration) or to GND (high-side configuration). These outputs can be enabled and disabled via the SPI bus. Each of these outputs has a short circuit protection (with 0.8-2.4 Amps threshold) selectable via SPI bus between a filtered switching OFF overcurrent protection or a linear current limitation (default condition after power ON is switching OFF protection enabled).

An over-temperature protection as described in [Section 2.1](#) is available for each output. When a high-side configured output is commanded OFF after having been commanded ON, the source voltage will go to (VGND - 15 V). This is due to the design of the circuitry and the transconductance of the MOSFET. When a low-side configured output is commanded OFF after having been commanded ON, the output voltage will rise to the internal zener clamp voltage (50 VDC minimum) due to the flyback of the inductive load.

Outputs 1-8 are able to drive any combination of inductive loads or lamps at one time. Inductive loads for the L9733 can range from 35 mH to a maximum of 325 mH. The recommended worst-case solenoid loads (at -40 °C) are calculated using a minimum resistance of 40 Ω for each output. The maximum single pulse inductive load energy the L9733 output is able to be safely handled is 20 mJ at -40 °C to 125 °C (Worst-case load of 325 mH and 40 Ω).

4.1 Configurations for outputs 1-8

The drain and source pins for each output must be connected in one of the two following configurations (see [Figure 7](#)).

4.1.1 Low-side drivers

When any combination of outputs 1-8 are connected in a low-side drive configuration the source of the applicable output (Src1-8) shall be connected to ground. The drain of the applicable output (Drn1-8) shall be connected to the low-side of the load.

4.1.2 High-side drivers

When any combination of outputs 1-8 are connected in a high-side drive configuration the drain of the applicable output (Drn1-8) shall be connected to Vbat. The source of the applicable output (Src1-8) shall be connected to the high-side of the load.

4.2 Outputs 1-5

These five outputs can be used as either high or low-side drives. The room temperature $R_{DS(on)}$ of these outputs is 0.7 Ω A current limited (100 μA max) voltage generator is connected to Src 1-5 for open load and short to GND detection when a low-side configured output is commanded OFF. Another current limited (100 μA max if $V_{Drn\ 1-5} > 60\% V_{bat}$, 280 μA max if $V_{Drn\ 1-5} < 60\% V_{bat}$) voltage generator is connected to Drn 1-5 for open load and short to V bat detection when a high-side configured output is commanded OFF.

Drain pins of outputs 1-5 (Drn1-5) are connected to the drains of the N channel MOSFET transistors. Source pins of outputs 1-5 (Src1-5) are connected to the sources of the N-channel MOSFET transistors.

4.3 Outputs 6-8

These three self-configuring outputs can be used to drive either high or low-side loads. In addition to being controlled by the SPI BUS these outputs can also be enabled and disabled via the IN6 & IN7 & IN8 inputs. The IN6, IN7 and IN8 inputs are logically OR'd with the SPI commands to allow either the IN6 & IN7 & IN8 inputs or the SPI commands to activate these outputs. The use of the IN6 & IN7 & IN8 pins for PWM control on these outputs should only be done with non-inductive loads if an external flyback diode is not present. The room temperature $R_{DS(on)}$ of these four outputs is $0.7\ \Omega$. A current limited (100 μA max) voltage generator is connected to Src 6-8 for open load and short to GND detection when a low-side configured output is commanded OFF. Another current limited (100 μA max if $V_{Drn\ 6-8} > 60\%V_{bat}$, 280 μA max if $V_{Drn\ 6-8} < 60\%V_{bat}$) voltage generator is connected to Drn 6-8 for open load and short to Vbat detection when a high-side configured output is commanded OFF.

Drain pins of Outputs 6-8 (Drn6-8) are connected to the drains of the N channel MOSFET transistors. Source pins of Outputs 6-8 (Src6-8) are connected to the sources of the N channel MOSFET transistors.

4.4 Drn1-8 susceptibility to negative voltage transients

All outputs connected in the low-side configuration must have a ceramic chip capacitor of 0.01 μF to 0.1 μF connected from drain to ground. This is needed to prevent potential problems with the device operation due to the presence of fast negative transient(s) on the drain(s) of the device. Adequate de-coupling capacitors from the Drain (VBAT) to ground shall be provided for high-side configured outputs.

4.5 Supply pins

4.5.1 Main power input (Vdd)

An external $+5.0 \pm 0.5$ VDC supply provided from an external source is the primary power source to the L9733. This supply is used as the power source for all of its internal logic circuitry and other miscellaneous functions.

4.5.2 Battery supply (Vbat)

This input is the supply for the on board charge pump. This input shall be connected directly to battery. If this input is not connected to the same supply, without additional voltage drops, of the drains of any high-side connected outputs, then the $R_{DS(on)}$ of that given output will be higher than the specified maximum.

4.5.3 Discrete inputs voltage supply (VDO)

This pin is used to supply the discrete input stages of L9733 and must be connected to the same voltage used to supply the peripherals of the processor interfaced to L9733.

4.6 Discrete inputs

4.6.1 Output 6-8 enable input (In6, In7, In8)

This input allows Output 6 (or Output 7, or Output 8) to be enabled via this external pin without the use of the SPI. The SPI command and the In6-7 input are logically OR'd together. A logic "1" on this input (In6, In7 or In8) is enable the corresponding output no matter what the status of the SPI command register is. A logic "0" on this input will disable this output if the SPI command register is not commanding this output on. This pins (In6, In7 or In8) can be left "open" if the internal output device is being controlled only via the SPI. This input has a nominal 100 kΩ resistor connected from this pin to ground, which will pull this pin to ground if an open circuit condition occurs. This input is ideally suited for non-inductive loads that are pulse width modulated (PWM'd). This allows PWM control without the use of the SPI inputs.

4.6.2 Reset input (RES)

When this input goes low it resets all the internal registers and switches off all the output stages. This input has a nominal 100 kΩ resistor connected from this pin to VDD, which will pull this pin to VDD if an open circuit condition occurs.

5 Serial peripheral interface (SPI)

The L9733 has a serial peripheral interface consisting of Serial Clock (SCLK), Data Out (DO), Data In (DI), and Chip Select (CS). All outputs will be controlled via the SPI. The input pins CS, SCLK, and DI, thanks to VDO pin, have level input voltages allowing proper operation from microcontrollers that are using 5.0 or 3.3 volts for their Vdd supply. The design of the L9733 allows a "daisy-chaining" of multiple L9733's to further reduce the need for controller pins.

5.1 Serial data output (DO)

This output pin is in a tri-state condition when CS is a logic '1'. When CS is a logic '0', this pin transmits 16 bits of data from the fault register to the digital controller. After the first 16 bits of DO fault data are transmitted (after a CS transition from a logic '1' to a logic '0'), then the DO output sequentially transmits the digital data that was just received (16 SCLK cycles earlier) on the DI pin. The DO output continues to transmit the 16 SCLK delayed bit data from the DI input until CS eventually transitions from a logic '0' to a logic '1'. DO data changes state 10 nsec or later, after the falling edge of SCLK. The LSB is the first bit of the byte transmitted on DO and the MSB is the last bit of the byte transmitted on DO, once CS transitions from a logic '1' to a logic '0'.

5.2 Serial data input (DI)

This input takes data from the digital controller while CS is low. The L9733 accepts a 16 bit byte to command the outputs on or off. The L9733 also serially wraps around the DI input bits to the DO output after the DO output transmits its 16 fault flag bits. The LSB is the first bit of each byte received on DI and the MSB is the last bit of each byte received on DI, once CS transitions from a logic '1' to a logic '0'. The last 4 bits (b15-b12) of the first 16 bit byte are used as key-word. The 4 bits (b11-b8) of the first 16 bits byte are used to select writing mode between OUT8-1 status and diagnosis operating mode . The DI input has a nominal 100 kΩ resistor connected from this pin to the VDO pin, which pulls this pin to VDO if an open circuit condition occurs.

5.3 Chip select (CS)

This is the chip select input pin. On the falling edge of CS, the DO pin is released from tri-state mode. While CS is low, register data are shifted in and shifted out the DI pin and DO pin, respectively, on each subsequent SCLK. On the rising edge of CS, the DO pin is tri-stated and the fault register is "Cleared" if a valid DI byte has been received. A valid DI byte is defined as such:

- a multiple of 16 bits was received;
- a valid key-word was received.

The fault data is not cleared unless all of the 2 previous conditions have been met. The CS input has a nominal 100 kΩ resistor connected from this pin to the VDO pin, which pulls this pin to VDO if an open circuit condition occurs.

5.4 Serial clock (SCLK)

This is the clock signal input for synchronization of serial data transfer. DI data is shifted into the DI input on the rising edge of SCLK and DO data changes on the falling edge of SCLK. The SCLK input has a nominal 100 kΩ resistor connected from this pin to the VDO pin, which pulls this pin to VDO if an open circuit condition occurs.

5.5 Initial input command register and fault register SPI cycle

After initial application of Vdd to the L9733, the input command register and the fault register are "Cleared" by the POR circuitry and that means that the default condition for the output status is Off, the default diagnostic mode is No Latch and the switching OFF overcurrent protection is enable. During the initial SPI cycle, and all subsequent cycles, valid fault data will be clocked out of DO (fault bits).

5.6 Input command register

An input byte (16 bits) is routed to the Command Register. The content of this Command Register is given in *Table 10*. Additional DI data will continue to be wrapped around the DO pin. If CS should happen to go high before complete reception of the current byte, this just transmitted byte shall be ignored (invalid).

Table 9. Bit command register definition

| Key word | | Writing mode: output | | | | | | | | Output status | | | | | | | |
|------------|-----|-----------------------|-----|-----|-----|----|----|--------|--------|-------------------------------|--------|--------|--------|--------|--------|------------|--|
| MSB | | | | | | | | | | | | | | | | LSB | |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 0 | OUT 8 | OUT 7 | OUT 6 | OUT 5 | OUT 4 | OUT 3 | OUT 2 | OUT 1 | | |
| b15 | b14 | b13 | b12 | b11 | b10 | b9 | b8 | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 | | |
| Key word | | Writing mode: diag | | | | | | | | Driver diag mode | | | | | | | |
| MSB | | | | | | | | | | | | | | | | LSB | |
| 1 | 0 | 1 | 0 | 0 | 0 | 1 | 1 | Diag 8 | Diag 7 | Diag 6 | Diag 5 | Diag 4 | Diag 3 | Diag 2 | Diag 1 | | |
| b15 | b14 | b13 | b12 | b11 | b10 | b9 | b8 | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 | | |
| Key word | | Writing mode: protect | | | | | | | | Driver overcurrent protection | | | | | | | |
| MSB | | | | | | | | | | | | | | | | LSB | |
| 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | Ilim 8 | Ilim 7 | Ilim 6 | Ilim 5 | Ilim 4 | Ilim 3 | Ilim 2 | Ilim 1 | | |
| b15 | b14 | b13 | b12 | b11 | b10 | b9 | b8 | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 | | |

Table 10. Command register logic definition

| Bit | State | Status | Writing mode |
|-------|-------|--|--------------|
| b0-b7 | 0 | OUT1 - OUT8 are commanded off | Output |
| b0-b7 | 1 | OUT1 - OUT8 are commanded on | Output |
| b0-b7 | 0 | OUT1 - OUT8 diagnostic is No Latch Mode | Diag |
| b0-b7 | 1 | OUT1 - OUT8 diagnostic is Latch Mode | Diag |
| b0-b7 | 0 | OUT1 - OUT8 switching OFF overcurrent protection | Protection |
| b0-b7 | 1 | OUT1 - OUT8 linear overcurrent protection | Protection |

6 Other L9733 features

6.1 Charge pump usage

In order to provide low $R_{DS(on)}$ values when connected in a high-side configuration, a charge pump to drive the internal gate voltage(s) above V_{BAT} is implemented. The charge pump used on the L9733 doesn't need external capacitor. The L9733 uses a common charge pump and oscillator for all the 8 configurable output channels. The charge pump uses the V_{BAT} supply connected directly to the V_B pin. The normal range of the V_{BAT} voltage is 10 to 18V18V. However, the L9733 is functional with V_{BAT} voltages as low as 4.5 V DC with eventually a degradation of $R_{DS(on)}$.

The frequency range of this charge pump is from 3.6 to 7.6 MHz. The frequency is above 1.8 MHz in order to be above the AM radio band and below 8.0 MHz so that harmonics do not get within the FM radio band.

6.2 Waveshaping

Both the turn on and the turn off slew rates on all outputs (OUT1-8) are limited to between 10 μ s and 100 μ s for both rise and fall times (10 to 90 %, and vice versa), to reduce conducted EMC energy in the vehicle's wiring harness. The characteristics of the turn-on and turn-off voltage is linear, with no discontinuities, during the output driver state transition.

6.3 POR register initialization

When the L9733 wakes up, the V_{DD} supply to the L9733 is allowed from 0 to 5 VDC in 0.3 to 3ms. The L9733 has a POR circuit, which monitors the V_{DD} voltage. When the V_{DD} voltage reaches an internal threshold, and remains above this trip level for at least 5 to 20 μ s, the Command and Fault registers are "cleared". Before V_{DD} reaches this trip level, none of the eight outputs are allowed to momentarily glitch on.

6.4 Thermal shutdown

Each of the eight outputs has independent thermal protection circuitry that disables each output driver once the local N-Channel MOSFET's device temperature reaches between +151 and +200 °C. A filter is present to validate the thermal fault (5 μ s to 20 μ s). There is a 5 to 15 °C hysteresis between the enable and disable temperature levels. The faulted channel will periodically turn off and on until the fault condition is cleared, the ambient temperature is decreased sufficiently or the output is commanded off. If a thermal shutdown, of one or more output drivers, is active during the falling edge of the chip select (CS) signal all the bits of the Fault Register are "set" to "1" (thermal shutdown is not latched and could be read only in the moment it is present). The thermal fault is cleared on the rising edge of Chip Select if a valid DI byte is received.

Note: *Due to the design of the L9733 each output's thermal limit "may not" be truly independent to the extent that if one output is shorted, it may impact the operation of other outputs (due to lateral heating in the die).*

7 Fault operation

The fault diagnostic capability consists of one internal 16 bits shift register and 2 bits are used for each output. The diagnostic information is: no fault present, overcurrent, open load and short circuit.

For L9733XP all of the faults will be cleared on the rising edge of chip select if a valid DI byte is received.

For L9733CN the OVC register are cleared when the end of the diagnosis restart time T_{res} is reached or by the input signal (IN) in low state. The other faults are cleared on the rising edge of chip select if a valid DI byte is received.

Table 11. Fault register definition

| OUT 8 | | OUT 7 | | OUT6 | | OUT5 | | OUT4 | | OUT3 | | OUT2 | | OUT1 | |
|------------|-----|-------|-----|------|-----|------|----|------|----|------|----|------|----|------|------------|
| MSB | | | | | | | | | | | | | | | LSB |
| D1 | D0 | D1 | D0 | D1 | D0 | D1 | D0 | D1 | D0 | D1 | D0 | D1 | D0 | D1 | D0 |
| b15 | b14 | b13 | b12 | b11 | b10 | b9 | b8 | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |

Table 12. Fault logic definition

| D1 | | D0 | | Fault status | | | |
|----|---|--|--|--------------|--|--|--|
| 0 | 0 | No fault is present | | | | | |
| 0 | 1 | Open load | | | | | |
| 1 | 0 | Short circuit to GND (low-side) or short circuit to Vbat (high-side) | | | | | |
| 1 | 1 | Overcurrent | | | | | |

If all the bits b0-b15 of the fault register have value '1' it means that a thermal fault, at least on one of the eight independent Outputs, occurred.

7.1 Low-side configured output fault operation

The diagnostic circuitry verifies for the low-side configured output the following condition: Normal operation, open load, short circuit to GND and overcurrent (only if the switching OFF protection, selectable for each channel via SPI bus, is active).

The diagnostic circuitry operates in two different modes, selected for each channel by SPI: no latch mode and latch mode. The fault priority is overcurrent and then open load or short circuit to GND, this means that if an overcurrent occurs the fault register is always overwritten and following open load or short to GND faults that happen before that the register is cleared will be ignored.

7.1.1 No latch mode

This diagnostic operating mode doesn't latch open load and short to GND faults.

1. Open load

The diagnostic of open load is detected only in OFF condition sensing the Drn1-8 output voltage. This fault is detected on the falling edge of the CS input if the power drain voltage is inside the voltage range limited by the two thresholds **Vth_Vbat** and **Vth_GND**. An internal current limited voltage regulator fixes the drain voltage inside the described range when no load is connected.

2. Short circuit to GND

The diagnostic of short circuit to GND is detected only in OFF condition sensing the Drn1-8 output voltage. This fault is detected on the falling edge of the CS input if the power drain voltage is lower than the **Vth_GND** threshold.

3. Overcurrent

The diagnostic of overcurrent is detected only in ON condition, if the switching OFF protection of the channel is enabled (default), sensing the current level of the output power transistor. If the output current has been above the short threshold **lovc** for the filtering time **Tdel** the output power is switched off and at the same time an overcurrent fault is written in the fault register.

There are three possibilities to restart one output after the fault has occurred:

- Automatically after a time **Tres**
- On the rising edge of CS if two valid DI bytes have been received and first the Output Status in the command register is written with logic '0' and then with a logic "1" in the following SPI cycle
- On the rising edge (low to high transition) at the corresponding parallel input pin (only for Outputs 6-8).
- If the switching OFF protection is not active the On phase overcurrent protection is a linear current limitation and no diagnosis is available.

The use of the IN6-8 pins for PWM control on the outputs 6-8 could generate bad diagnostic behavior when the falling edge of CS happens a short time after the falling edge of IN6-8 during the power MOS transient. Software filtering may be needed to ignore fault signals during Drn6-8 transient after falling edge of IN6-8.

7.1.2 Latch mode

This diagnostic operating mode latches all faults when they happen.

1. Open load

The diagnostic of open load is detected only in OFF condition sensing the Drn1-8 output voltage. This fault is detected if the power drain voltage is inside the voltage range limited by the two thresholds **Vth_Vbat** and **Vth_GND** for the filtering time **Tfilt**. An internal current limited voltage regulator fixes the drain voltage inside the described range when no load is connected.

2. Short circuit to GND

The diagnostic of short circuit to GND is detected only in OFF condition sensing the Drn1-8 output voltage. This fault is detected if the power drain voltage is lower than the **Vth_GND** threshold for the filtering time **Tfilt**.

3. Overcurrent

The diagnostic of overcurrent is detected only in ON condition, if the switching OFF protection of the channel is enabled (default), sensing the current level of the output power transistor. If the output current has been above the short threshold **lovc** for the

filtering time T_{del} the output power is switched off and at the same time an overcurrent fault is written in the fault register. If the switching OFF protection is not active the On phase overcurrent protection is a linear current limitation and no diagnosis is available. There are three possibilities to restart one output after the fault has occurred:

- Automatically after a time **Tres**
- On the rising edge of CS if two valid DI bytes have been received and first the Output Status in the command register is written with logic '0' and then with a logic '1' in the following SPI cycle
- On the rising edge (low to high transition) at the corresponding parallel input pin (only for Outputs 6-8).

If the power MOS transient, after a switching-off command, is longer than T_{del} filtering time, a bad diagnostic behavior happens and software filtering may be needed.

7.2 High-side configured output fault operation

The diagnostic circuitry verifies for the high-side configured output the following condition: Normal operation, open load, short circuit to V_{bat} and overcurrent (only if the switching OFF protection, selectable for each channel via SPI bus, is active).

The diagnostic circuitry operates in two different modes, selected for each channel by SPI: no latch mode and latch mode. The fault priority is overcurrent and then open load or short circuit to V_b , this means that if an overcurrent occurs the fault register is always overwritten and following open load or short to V_{bat} faults that happen before that the register is cleared will be ignored.

7.2.1 No latch mode

This diagnostic operating mode doesn't latch open load and short to V_{bat} faults.

1. Open load

The diagnostic of open load is detected only in OFF condition sensing the $Src1-8$ output voltage. This fault is detected on the falling edge of the CS input if the power drain voltage is inside the voltage range limited by the two thresholds $V_{th_V_{bat}}$ and V_{th_GND} . An internal current limited voltage regulator fixes the drain voltage inside the described range when no load is connected.

2. Short Circuit to V_b

The diagnostic of short circuit to V_{bat} is detected only in OFF condition sensing the $Src1-8$ output voltage. This fault is detected on the falling edge of the CS input if the power drain voltage is higher than the **$V_{th_V_{bat}}$** threshold.

3. Overcurrent

The diagnostic of overcurrent is detected only in ON condition, if the switching OFF protection of the channel is enabled (default), sensing the current level of the output power transistor. If the output current has been above the short threshold Io_{vc} for the filtering time T_{del} the output power is switched off and at the same time an overcurrent fault is written in the fault register.

There are three possibilities to restart one output after the fault has occurred:

- Automatically after a time **Tres**
- On the rising edge of CS if two valid DI bytes have been received and first the Output Status in the command register is written with logic '0' and then with a logic '1' in the following SPI cycle

- On the rising edge (low to high transition) at the corresponding parallel input pin (only for Outputs 6-8).
- If the switching OFF protection is not active the On phase overcurrent protection is a linear current limitation and no diagnosis is available.
The use of the IN6-8 pins for PWM control on the outputs 6-8 could generates bad diagnostic behavior when the falling edge of CS happens a short time after the falling edge of IN6-8 during the power MOS transient. Software filtering may be needed to ignore fault signals during Drn6-8 transient after falling edge of IN6-8.

7.2.2 Latch mode

This diagnostic operating mode latches all faults when they happen.

1. Open load

The diagnostic of open load is detected only in OFF condition sensing the Src1-8 output voltage. This fault is detected if the power drain voltage is inside the voltage range limited by the two thresholds **Vth_Vbat** and **Vth_GND** for the filtering time **Tfilt**. An internal current limited voltage regulator fixes the drain voltage inside the described range when no load is connected.

2. Short Circuit to Vb

The diagnostic of short circuit to Vbat is detected only in OFF condition sensing the Src1-8 output voltage. This fault is detected if the power drain voltage is higher than the **Vth_Vbat** threshold for the filtering time **Tfilt**.

3. Overcurrent

The diagnostic of overcurrent is detected only in ON condition, if the switching OFF protection of the channel is enabled (default), sensing the current level of the output power transistor. If the output current has been above the short threshold **lovc** for the filtering time **Tdel** the output power is switched off and at the same time an overcurrent fault is written in the fault register.

There are three possibilities to restart one output after the fault has occurred:

- Automatically after a time **Tres**
- On the rising edge of CS if two valid DI bytes have been received and first the Output Status in the command register is written with logic '0' and then with a logic "1" in the following SPI cycle
- On the rising edge (low to high transition) at the corresponding parallel input pin (only for Outputs 6-8).

If the switching OFF protection is not active the On phase overcurrent protection is a linear current limitation and no diagnosis is available.

If the power MOS transient, after a switching-off command, is longer than **Tdel** filtering time, a bad diagnostic behavior happens and software filtering may be needed.

Figure 7. Application schematic

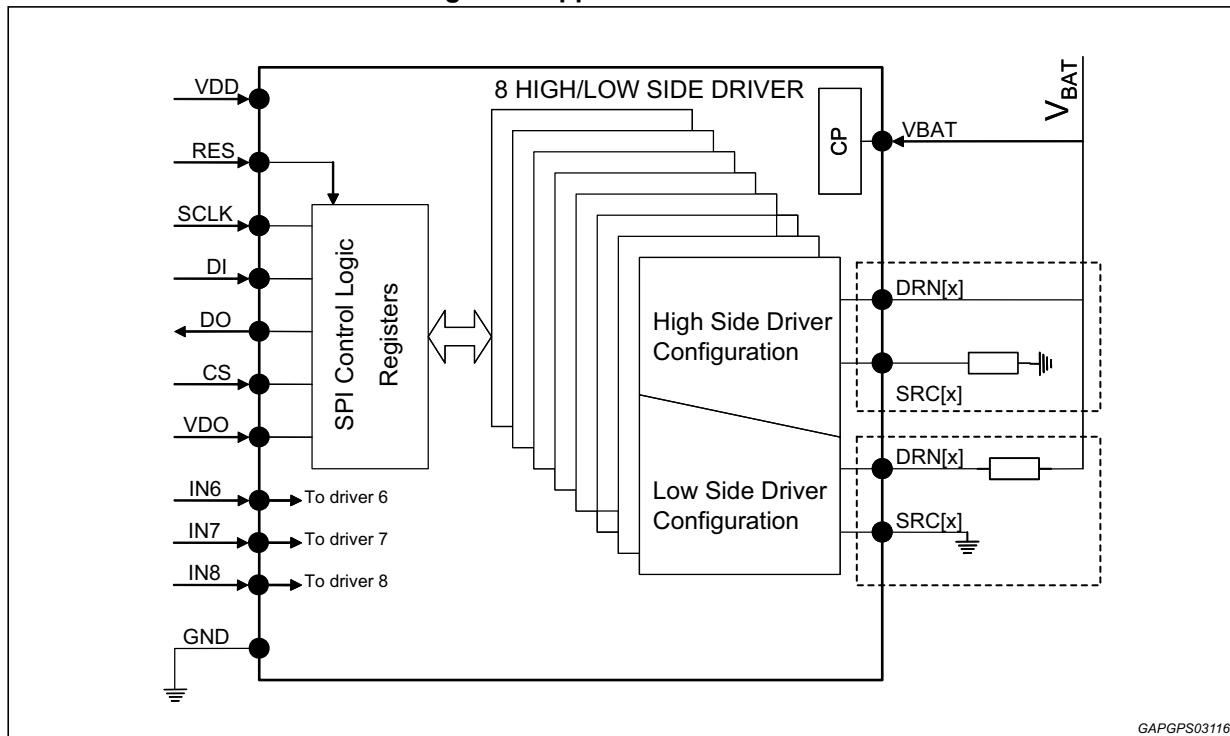


Figure 8. HVAC applicative examples

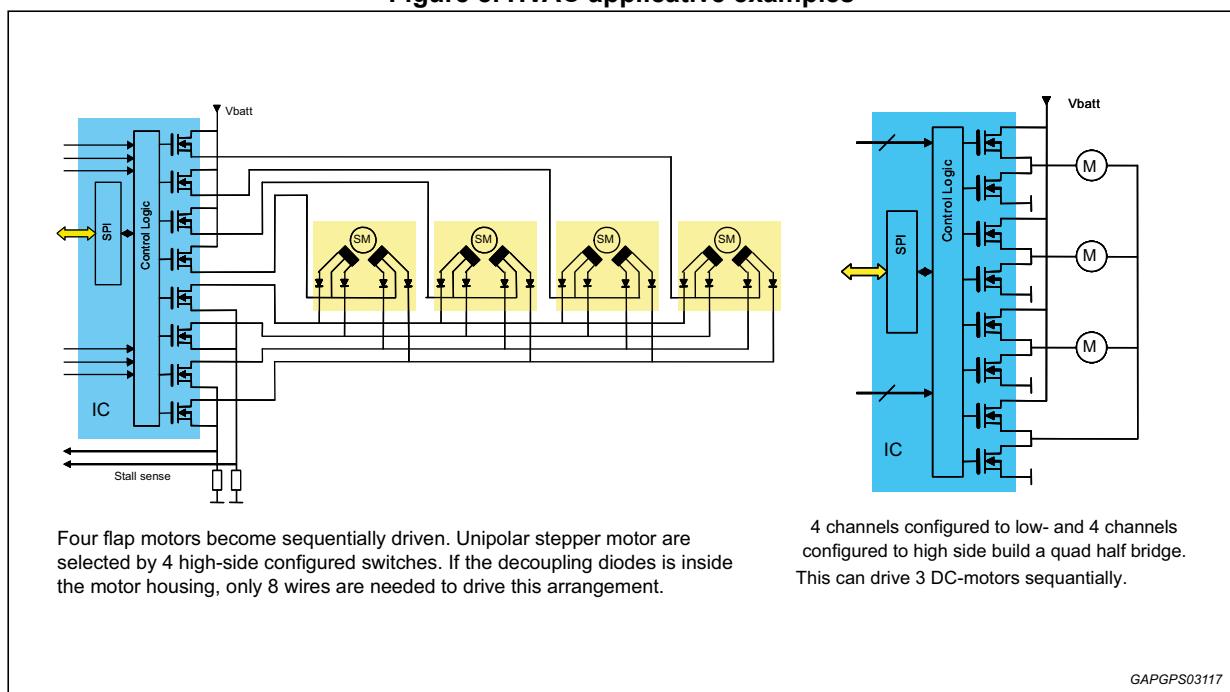
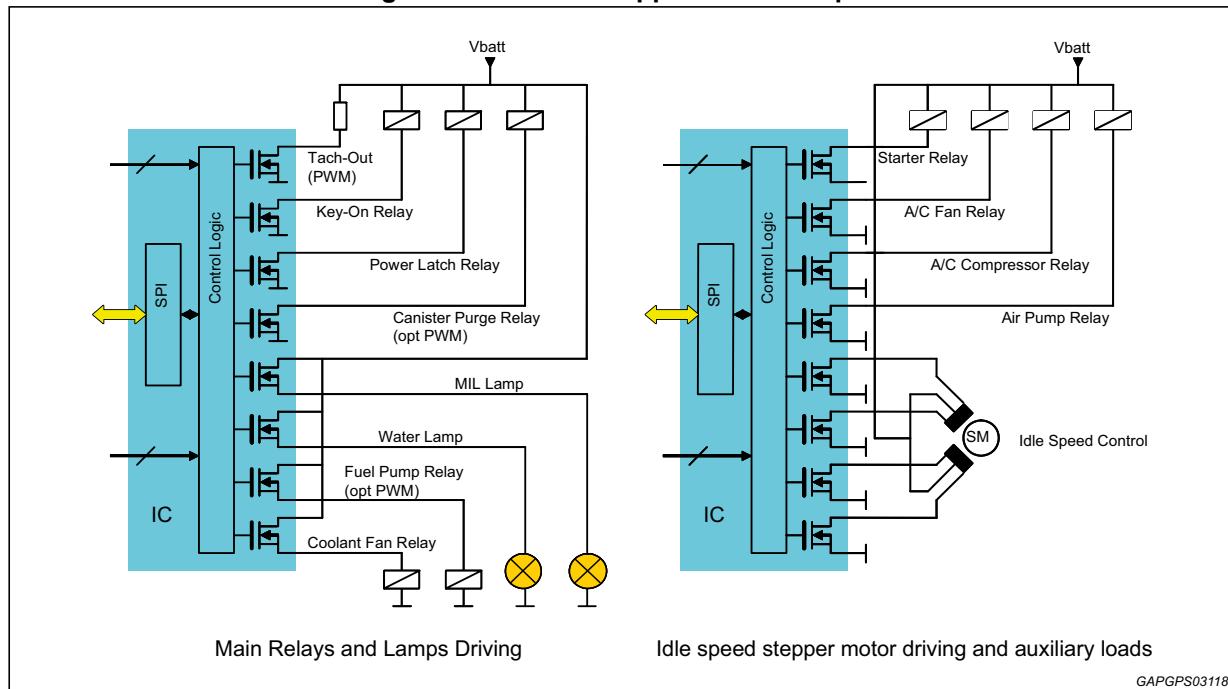
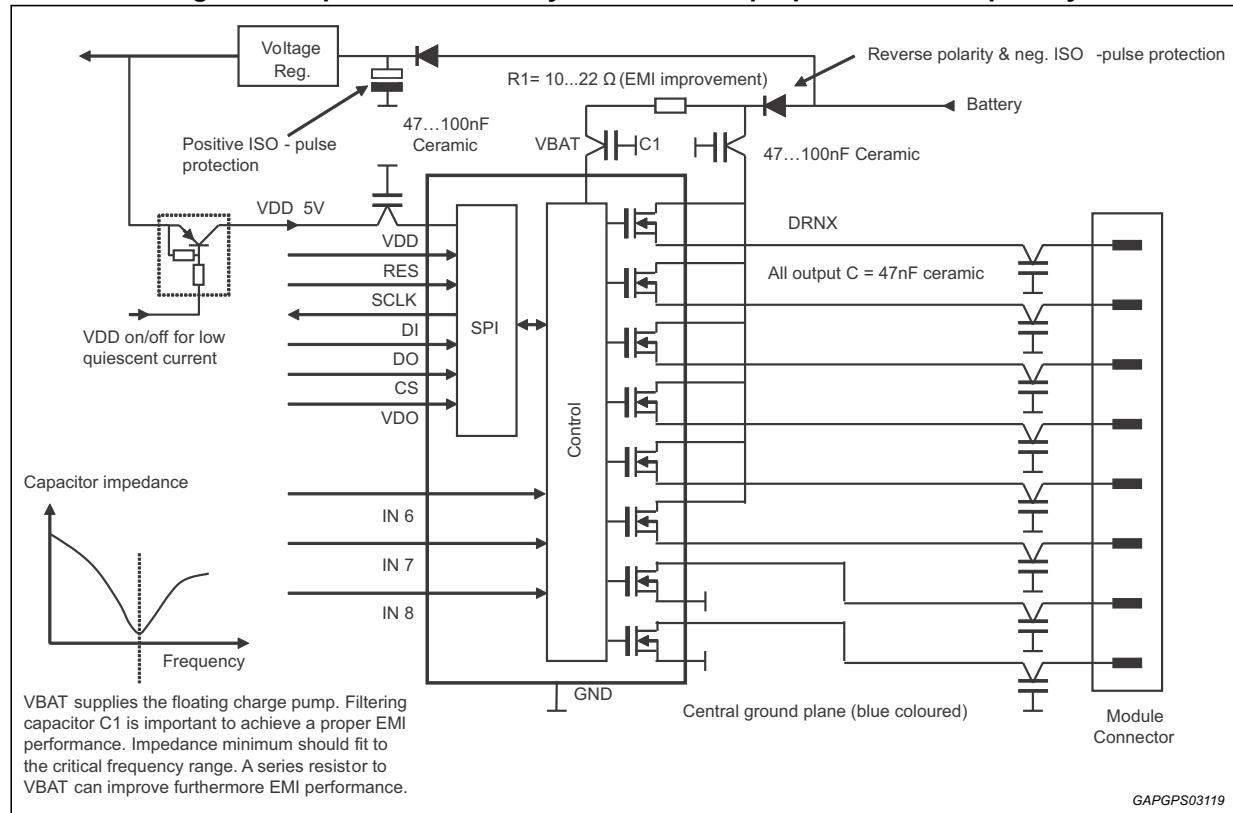


Figure 9. Powertrain applicative examples



8 Application circuit

Figure 10. Optimized circuit layout to achieve proper EMI/ESD capability



9 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com.

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9.1 PowerSSO-28 (exposed pad) package information

Figure 11. PowerSSO-28 (exposed pad) package outline

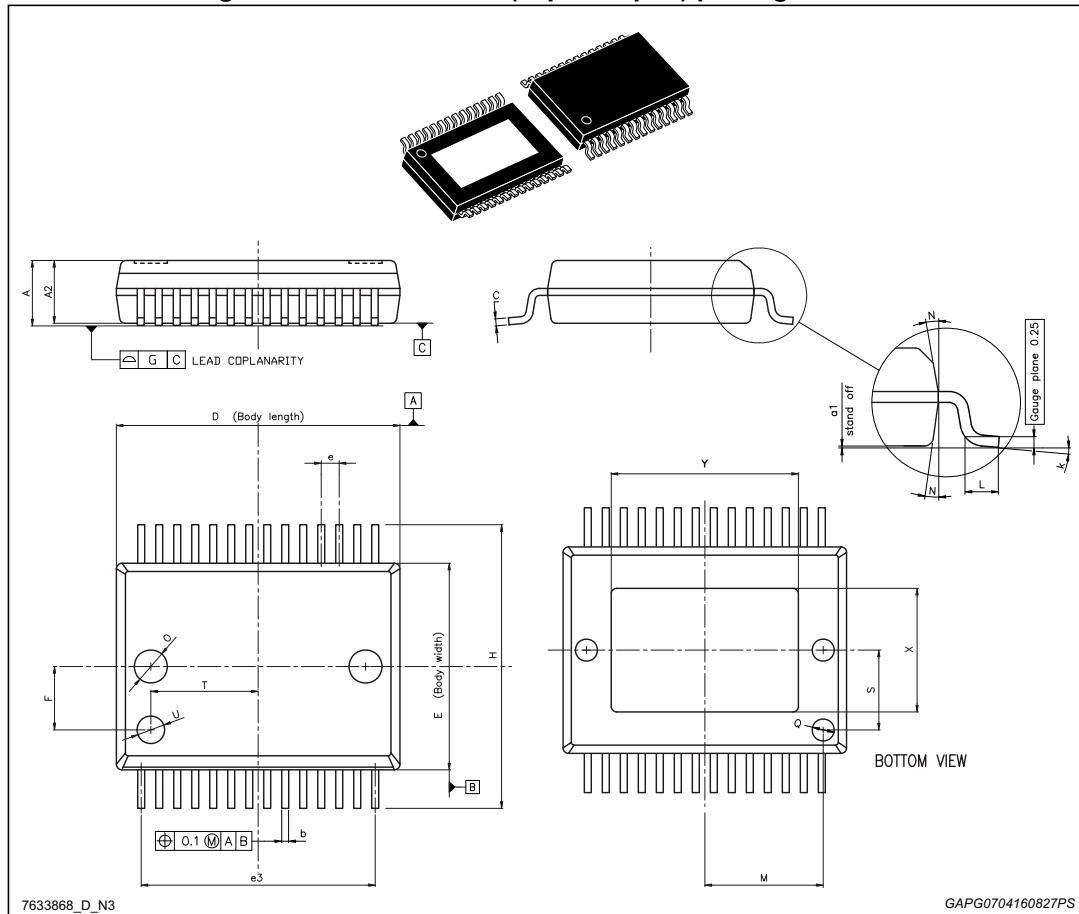


Table 13. PowerSSO-28 (exposed pad) package mechanical data

| Ref | Dimensions | | | | | |
|------------------|-------------|------|-------|-----------------------|--------|--------|
| | Millimeters | | | Inches ⁽¹⁾ | | |
| | Min. | Typ. | Max. | Min. | Typ. | Max. |
| A | 2.15 | - | 2.45 | 0.0846 | - | 0.0965 |
| A2 | 2.15 | - | 2.35 | 0.0846 | - | 0.0925 |
| a1 | - | - | 0.1 | - | - | 0.0039 |
| b | 0.18 | - | 0.36 | 0.0071 | - | 0.0142 |
| c | 0.23 | - | 0.32 | 0.0091 | - | 0.0126 |
| D ⁽²⁾ | 10.1 | - | 10.50 | 0.3976 | - | 0.4134 |
| E ⁽²⁾ | 7.4 | - | 7.6 | 0.2913 | - | 0.2992 |
| e | - | 0.65 | - | - | 0.0256 | - |
| e3 | - | 8.45 | - | - | 0.3327 | - |
| F | - | 2.3 | - | - | 0.0906 | - |
| G | - | - | 0.1 | - | - | 0.0039 |
| G1 | - | - | 0.06 | - | - | 0.0024 |
| H | 10.1 | - | 10.5 | 0.3976 | - | 0.4134 |
| h | - | - | 0.4 | - | - | 0.0157 |
| k | 5° (Typ.) | | | | | |
| L | 0.6 | - | 1 | 0.0236 | - | 0.0394 |
| M | - | 4.3 | - | - | 0.1693 | - |
| N | 10° (Max.) | | | | | |
| O | - | 1.2 | - | - | 0.0472 | - |
| Q | - | 0.8 | - | - | 0.0315 | - |
| S | - | 2.9 | - | - | 0.1142 | - |
| T | - | 3.65 | - | - | 0.1437 | - |
| U | - | 1 | - | - | 0.0394 | - |
| X | 4.2 | - | 4.8 | 0.1654 | - | 0.1890 |
| Y | 6.6 | - | 7.2 | 0.2598 | - | 0.2835 |

1. Values in inches are converted from mm and rounded to 4 decimal digits.
2. "D" and "E" do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side (0.006").

10 Revision history

Table 14. Document revision history

| Date | Revision | Changes |
|-------------|----------|--|
| 13-Apr-2005 | 1 | Initial release. |
| 15-Jun-2006 | 2 | Changed only look and feel. |
| 08-Aug-2006 | 3 | Modified Table 9: Bit command register definition on page 22 . |
| 28-May-2007 | 4 | Changed the min. value of the CSlead parameter on the Table 8 . |
| 17-Jul-2007 | 5 | Updated Table 6 and Table 7 . Added new Figure 4 . Changed the status from Preliminary data to Datasheet. |
| 03-Aug-2007 | 6 | Updated in Table 4 the ESD parameter. |
| 12-Jun-2008 | 7 | Added order codes in Table 1: Device summary on page 1 . Added “CS2SCLK” parameter in Table 8: SPI characteristics and timings . Updated Figure 6: SPI timing diagram . |
| 02-Dec-2008 | 8 | Updated Table 1: Device summary on page 1 . Removed all references to the SO-28 package. Updated Section 2.1: Operating range and Section 2.2: Absolute maximum ratings . Added Section 2.1.1: Functional operative range , Section 2.1.2: Jump start conditions , Section 2.1.3: Operation at low battery condition and Section 2.1.4: Operation at load dump condition . Added Section 8: Application circuit . Added “POR _{th} ” parameter in Table 6: DC characteristics . |
| 13-May-2009 | 9 | Updated Table 1: Device summary on page 1 . Updated Figure 11: PowerSSO28 mechanical data and package dimensions . |
| 27-Jul-2010 | 10 | Updated Table 1: Device summary on page 1 . Updated Section 7: Fault operation on page 25 . |
| 19-Sep-2013 | 11 | Updated Disclaimer. |
| 02-May-2016 | 12 | Modified in cover page the title and added “AEC-Q100 (Rev. F) qualified” in Features bullet. Updated Section 9: Package information . |

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