

# 16-Bit, Ultra Precise, Fast Settling V<sub>OUT</sub> DAC

# **FEATURES**

- 2µs Settling to 0.0015% for 10V Step
- 1LSB Max DNL and INL Over Industrial Temperature Range
- On-Chip 4-Quadrant Resistors Allow Precise 0V to 10V, 0V to -10V or ±10V Outputs
- Low Glitch Impulse: 2nV•s
- Low Noise: 13nV/√Hz
- 36-Lead SSOP Package
- Power-On Reset
- Asynchronous Clear Pin

LTC1821: Reset to Zero Scale LTC1821-1: Reset to Midscale

### **APPLICATIONS**

- Process Control and Industrial Automation
- Precision Instrumentation
- Direct Digital Waveform Generation
- Software-Controlled Gain Adjustment
- Automatic Test Equipment

### DESCRIPTION

The LTC $^{\circ}$ 1821 is a parallel input 16-bit multiplying voltage output DAC that operates from analog supply voltages of  $\pm 5$ V up to  $\pm 15$ V. INL and DNL are accurate to 1LSB over the industrial temperature range in both unipolar 0V to 10V and bipolar  $\pm 10$ V modes. Precise 16-bit bipolar  $\pm 10$ V outputs are achieved with on-chip 4-quadrant multiplication resistors. The LTC1821 is available in a 36-lead SSOP package and is specified over the industrial temperature range.

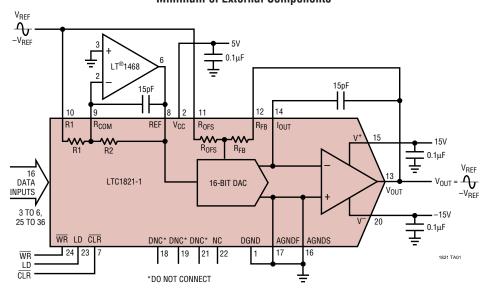
The device includes an internal deglitcher circuit that reduces the glitch impulse to less than 2nV•s (typ). The LTC1821 settles to 1LBS in 2µs with a full-scale 10V step. The combination of fast, precise settling and ultra low glitch make the LTC1821 ideal for precision industrial control applications.

The asynchronous  $\overline{\text{CLR}}$  pin resets the LTC1821 to zero scale and resets the LTC1821-1 to midscale.

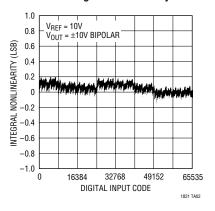
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# TYPICAL APPLICATION

16-Bit, 4-Quadrant Multiplying DAC with a Minimum of External Components



# LTC1821/LTC1821-1 Integral Nonlinearity





## **ABSOLUTE MAXIMUM RATINGS**

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# PACKAGE/ORDER INFORMATION

| DGND 1           | TOP VIEW  36 D4   | ORDER PART<br>NUMBER   |
|------------------|---|--|
| T <sub>JMA</sub> | 35 D5 34 D6 33 D7 32 D8 31 D9 30 D10 29 D11 28 D12 27 D13 26 D14 25 D15 24 WR 23 LD 22 NC 21 DNC* 20 V 19 DNC* 4 DNC* 4 DNC* 5 ONOT CONNECT | LTC1821ACGW<br>LTC1821BCGW<br>LTC1821-1ACGW<br>LTC1821-1BCGW<br>LTC1821AIGW<br>LTC1821BIGW<br>LTC1821-1AIGW<br>LTC1821-1BIGW |

Consult factory for parts specified with wider operating temperature ranges.

### **ELECTRICAL CHARACTERISTICS**

The ullet denotes specifications which apply over the full operating temperature range, otherwise specifications are  $T_A = T_{MIN}$  to  $T_{MAX}$ ,  $V^+ = 15V$ ,  $V^- = -15V$ ,  $V_{CC} = 5V$ ,  $V_{REF} = 10V$ , AGNDF = AGNDS = DGND = 0V.

|          |                              |   |   | LT  | C1821B/- | -1B        | LT  | C1821A/-       | -1A        |                |
|----------|------------------------------|---|---|-----|----------|------------|-----|----------------|------------|----------------|
| SYMBOL   | PARAMETER                    | CONDITIONS  |   | MIN | TYP      | MAX        | MIN | TYP            | MAX        | UNITS          |
| Accuracy |                              |   |   |     |          |            |     |                |            |                |
|          | Resolution                   |   | • | 16  |          |            | 16  |                |            | Bits           |
|          | Monotonicity                 |   | • | 16  |          |            | 16  |                |            | Bits           |
| INL      | Integral Nonlinearity        | T <sub>A</sub> = 25°C (Note 2)<br>T <sub>MIN</sub> to T <sub>MAX</sub>                  | • |     |          | ±2<br>±2   |     | ±0.25<br>±0.35 | ±1<br>±1   | LSB<br>LSB     |
| DNL      | Differential Nonlinearity    | T <sub>A</sub> = 25°C<br>T <sub>MIN</sub> to T <sub>MAX</sub>                           | • |     |          | ±1<br>±1   |     | ±0.2<br>±0.2   | ±1<br>±1   | LSB<br>LSB     |
| GE       | Gain Error                   | Unipolar Mode<br>T <sub>A</sub> = 25°C (Note 3)<br>T <sub>MIN</sub> to T <sub>MAX</sub> | • |     |          | ±16<br>±24 |     | ±5<br>±8       | ±16<br>±16 | LSB<br>LSB     |
|          |                              | Bipolar Mode<br>T <sub>A</sub> = 25°C (Note 3)<br>T <sub>MIN</sub> to T <sub>MAX</sub>  | • |     |          | ±16<br>±24 |     | ±2<br>±5       | ±16<br>±16 | LSB<br>LSB     |
|          | Gain Temperature Coefficient | ∆Gain/∆Temperature (Note 4)   | • |     | 1        | 3          |     | 1              | 3          | ppm/°C         |
|          | Unipolar Zero-Scale Error    | T <sub>A</sub> = 25°C<br>T <sub>MIN</sub> to T <sub>MAX</sub>                           | • |     |          | ±3<br>±6   |     | ±0.25<br>±0.50 | ±2<br>±4   | LSB<br>LSB     |
|          | Bipolar Zero Error           | T <sub>A</sub> = 25°C<br>T <sub>MIN</sub> to T <sub>MAX</sub>                           | • |     |          | ±12<br>±16 |     | ±2<br>±3       | ±8<br>±10  | LSB<br>LSB     |
| PSRR     | Power Supply Rejection Ratio | $V_{CC} = 5V \pm 10\%$<br>V+, V- = ±4.5V to ±16.5V                                      | • |     |          | 2<br>±2    |     | 0.7<br>±0.1    | 2<br>±2    | LSB/V<br>LSB/V |



# **ELECTRICAL CHARACTERISTICS**

The ullet denotes specifications which apply over the full operating temperature range, otherwise specifications are  $T_A = T_{MIN}$  to  $T_{MAX}$ ,  $V^+ = 15V$ ,  $V^- = -15V$ ,  $V_{CC} = 5V$ ,  $V_{REF} = 10V$ , AGNDF = AGNDS = DGND = 0V.

| SYMBOL                             | PARAMETER                                       | CONDITIONS   |   | MIN           | TYP        | MAX        | UNITS                                  |
|------------------------------------|---|--|---|---------------|------------|------------|--|
| Reference                          | Input   |  |   |               |            |            |  |
| R <sub>REF</sub>                   | DAC Input Resistance (Unipolar)                 | (Note 6)   | • | 4.5           | 6          | 10         | kΩ                                     |
| R1/R2                              | R1/R2 Resistance (Bipolar)                      | (Notes 6, 11)  | • | 9             | 12         | 20         | kΩ                                     |
| R <sub>OFS</sub> , R <sub>FB</sub> | Feedback and Offset Resistances                 | (Note 6)   | • | 9             | 12         | 20         | kΩ                                     |
| AC Perforn                         | nance (Note 4)                                  |  |   |               |            |            |  |
|                                    | Output Voltage Settling Time                    | ΔV <sub>OUT</sub> = 10V (Notes 7, 8)                                 |   |               | 2          |            | μS                                     |
|                                    | Midscale Glitch Impulse                         | (Note 10)  |   |               | 2          |            | nV∙s                                   |
|                                    | Digital-Feedthrough                             | (Note 9)   |   |               | 2          |            | nV∙s                                   |
|                                    | Multiplying Feedthrough Error                   | V <sub>REF</sub> = ±10V, 10kHz Sine Wave (Note 7)                    |   |               | 1          |            | mV <sub>P-P</sub>                      |
|                                    | Multiplying Bandwidth                           | Code = Full Scale (Note 7)   |   |               | 600        |            | kHz                                    |
|                                    | Output Noise Voltage Density                    | 1kHz to 100kHz (Note 7)<br>Code = Zero Scale<br>Code = Full Scale    |   |               | 13<br>20   |            | nV/√ <u>Hz</u><br>nV/√Hz               |
|                                    | Output Noise Voltage                            | 0.1Hz to 10Hz (Note 7)<br>Code = Zero Scale<br>Code = Full Scale     |   |               | 0.45<br>1  |            | μV <sub>RMS</sub><br>μV <sub>RMS</sub> |
|                                    | 1/f Noise Corner                                | (Note 7)   |   |               | 30         |            | Hz                                     |
| Analog Out                         | tputs (Note 4)                                  |  |   |               |            |            |  |
| V <sub>OUT</sub>                   | DAC Output Swing                                | $R_L = 2k, V^+ = 15V, V^- = -15V$<br>$R_L = 2k, V^+ = 5V, V^- = -5V$ | • | ±12.6<br>±2.6 |            |            | V<br>V                                 |
|                                    | DAC Output Load Regulation                      | $V^{+} = 15V, V^{-} = -15V, \pm 5mA \text{ Load}$                    | • |               | 0.02       | 0.2        | LSB/mA                                 |
| I <sub>SC</sub>                    | Short-Circuit Current                           | $V_{OUT} = 0V, V^{+} = 15V, V^{-} = -15V$                            | • | 12            | 40         |            | mA                                     |
| SR                                 | Slew Rate                                       | $R_L = 2k, V^+ = 15V, V^- = -15V$<br>$R_L = 2k, V^+ = 5V, V^- = -5V$ |   |               | 20<br>14   |            | V/µs<br>V/µs                           |
| Digital Inp                        | uts   |  |   |               |            |            |  |
| V <sub>IH</sub>                    | Digital Input High Voltage                      |  | • | 2.4           |            |            | V                                      |
| $V_{IL}$                           | Digital Input Low Voltage                       |  | • |               |            | 0.8        | V                                      |
| I <sub>IN</sub>                    | Digital Input Current                           |  | • |               | 0.001      | ±1         | μΑ                                     |
| C <sub>IN</sub>                    | Digital Input Capacitance                       | (Note 4 ) V <sub>IN</sub> = 0V                                       | • |               |            | 8          | pF                                     |
| Timing Cha                         | aracteristics                                   |  |   |               |            |            |  |
| t <sub>DS</sub>                    | Data to WR Setup Time                           |  | • | 60            | 20         |            | ns                                     |
| t <sub>DH</sub>                    | Data to WR Hold Time                            |  | • | 0             | -12        |            | ns                                     |
| t wr                               | WR Pulse Width                                  |  | • | 60            | 25         |            | ns                                     |
| t <sub>LD</sub>                    | LD Pulse Width                                  |  | • | 110           | 55         |            | ns                                     |
| t <sub>CLR</sub>                   | Clear Pulse Width                               |  | • | 60            | 40         |            | ns                                     |
| t <sub>LWD</sub>                   | WR to LD Delay Time                             |  | • | 0             |            |            | ns                                     |
| Power Sup                          | · ·   |  |   |               |            |            |  |
| I <sub>CC</sub>                    | Supply Current, V <sub>CC</sub>                 | Digital Inputs = 0V or V <sub>CC</sub>                               | • |               | 1.5        | 10         | μΑ                                     |
| I <sub>S</sub>                     | Supply Current, V <sup>+</sup> , V <sup>-</sup> | ±15V<br>±5V  | • |               | 4.5<br>4.0 | 7.0<br>6.8 | mA<br>mA                               |
| $V_{CC}$                           | Supply Voltage                                  |  | • | 4.5           | 5          | 5.5        | V                                      |
| <u>V</u> +                         | Supply Voltage                                  |  | • | 4.5           |            | 16.5       | V                                      |
| <u>V</u> -                         | Supply Voltage                                  |  | • | -16.5         |            | -4.5       | V                                      |



# **ELECTRICAL CHARACTERISTICS**

**Note 1:** Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

**Note 2:**  $\pm 1$ LSB =  $\pm 0.0015\%$  of full scale =  $\pm 15.3$ ppm of full scale.

Note 3: Using internal feedback resistor.

Note 4: Guaranteed by design, not subject to test.

Note 5: I<sub>OUT</sub> with DAC register loaded to all 0s.

**Note 6:** Typical temperature coefficient is 100ppm/°C.

Note 7: Measured in unipolar mode.

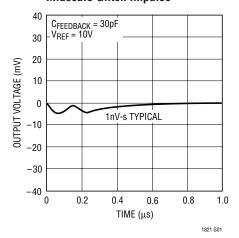
**Note 8:** To 0.0015% for a full-scale change, measured from the rising edge of LD.

**Note 9:** REF = 0V. DAC register contents changed from all 0s to all 1s or all 1s to all 0s. LD low and  $\overline{WR}$  high.

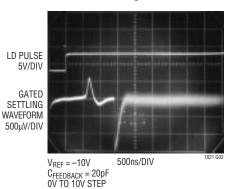
Note 11: R1 and R2 are measured between R1 and R<sub>COM</sub>, REF and R<sub>COM</sub>.

# TYPICAL PERFORMANCE CHARACTERISTICS

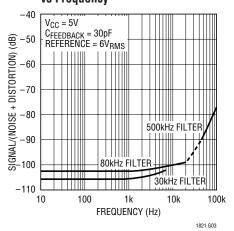
### Midscale Glitch Impulse



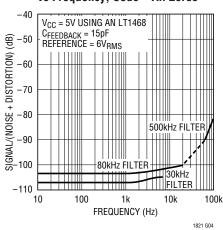
### Full-Scale Setting Waveform



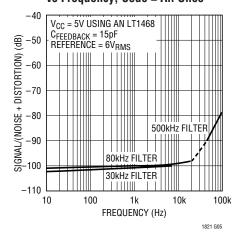
#### Unipolar Multiplying Mode Signal-to-(Noise + Distortion) vs Frequency



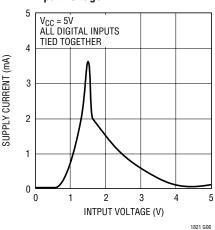
#### Bipolar Multiplying Mode Signal-to-(Noise + Distortion) vs Frequency, Code = All Zeros



Bipolar Multiplying Mode Signal-to-(Noise + Distortion) vs Frequency, Code = All Ones



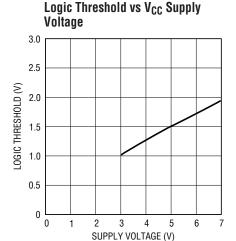
V<sub>CC</sub> Supply Current vs Digital Input Voltage

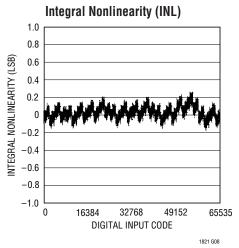


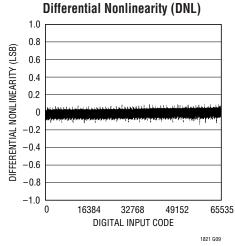


# TYPICAL PERFORMANCE CHARACTERISTICS

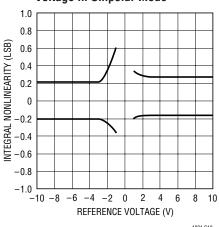
1821 G07



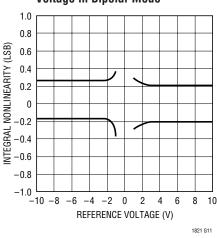




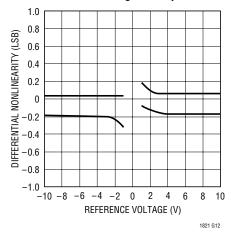
Integral Nonlinearity vs Reference Voltage in Unipolar Mode



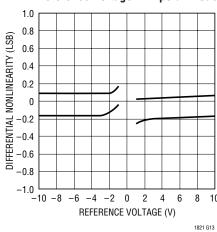
Integral Nonlinearity vs Reference Voltage in Bipolar Mode



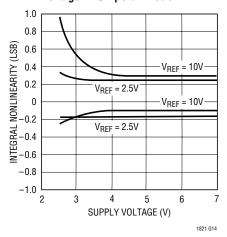
Differential Nonlinearity vs Reference Voltage in Unipolar Mode



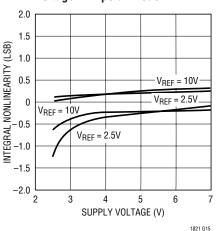
Differential Nonlinearity vs Reference Voltage in Bipolar Mode



Integral Nonlinearity vs V<sub>CC</sub> Supply Voltage in Unipolar Mode

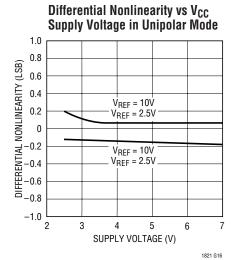


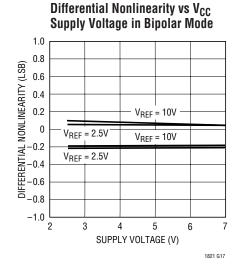
Integral Nonlinearity vs V<sub>CC</sub> Supply Voltage in Bipolar Mode



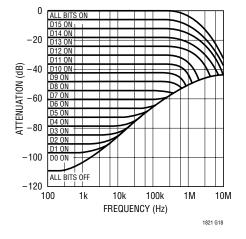


# TYPICAL PERFORMANCE CHARACTERISTICS





#### Unipolar Multiplying Mode Frequency Response vs Digital Code



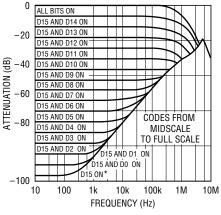
9 10 11 12

30pF

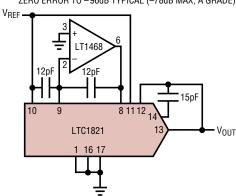
 $V_{OUT}$ 

 $V_{REF}$ 

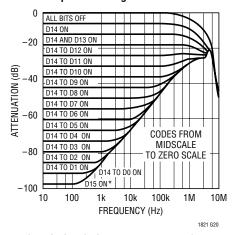
#### Bipolar Multiplying Mode Frequency Response vs Digital Code



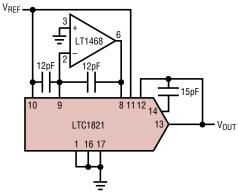
\*DAC ZERO VOLTAGE OUTPUT LIMITED BY BIPOLAR ZERO ERROR TO –96dB TYPICAL (–78dB MAX, A GRADE)



#### Bipolar Multiplying Mode Frequency Response vs Digital Code



\*DAC ZERO VOLTAGE OUTPUT LIMITED BY BIPOLAR ZERO ERROR TO -96db Typical (-78db Max, a grade)





# PIN FUNCTIONS

**DGND (Pin 1):** Digital Ground. Connect to analog ground.

**V<sub>CC</sub>** (**Pin 2**): Positive Supply Input.  $4.5V \le V_{CC} \ge 5.5V$ . Requires a bypass capacitor to ground.

D3 (Pin 3): Digital Input Data Bit 3.

**D2 (Pin 4):** Digital Input Data Bit 2.

D1 (Pin 5): Digital Input Data Bit 1.

**D0 (Pin 6):** LSB or Digital Input Data Bit 0.

**CLR** (**Pin 7**): Digital Clear Control Function for the DAC. When CLR is taken to a logic low, it sets the DAC output and all internal registers to: zero code for the LTC1821 and midscale code for the LTC1821-1.

**REF (Pin 8):** Reference Input and 4-Quadrant Resistor R2. Typically  $\pm 10V$ , accepts up to  $\pm 15V$ . In 2-quadrant mode, tie this pin to the external reference signal. In 4-quadrant mode, this pin is driven by external inverting reference amplifier.

**R<sub>COM</sub>** (**Pin 9**): Center Tap Point of the Two 4-Quadrant Resistors R1 and R2. Normally tied to the inverting input of an external amplifier in 4-quadrant operation. Otherwise this pin is shorted to the REF pin. See Figures 1 and 2.

**R1** (Pin 10): 4-Quadrant Resistor R1. In 2-quadrant operation, short this pin to the REF pin. In 4-quadrant mode, tie this pin to the external reference signal.

**R<sub>OFS</sub>** (**Pin 11**): Bipolar Offset Resistor. Typically swings  $\pm 10V$ , accepts up to  $\pm 15V$ . For 2-quadrant operation, tie this pin to R<sub>FB</sub> and for 4-quadrant operation, tie this pin to R1.

**R<sub>FB</sub> (Pin12):** Feedback Resistor. Normally connected to  $V_{OUT}$ . Typically swings  $\pm 10V$ . The voltage at this pin swings 0 to  $V_{REF}$  in unipolar mode and  $\pm V_{REF}$  in bipolar mode.

 $V_{OUT}$  (Pin 13): DAC Voltage Output. Normally connected to R<sub>FB</sub> and to I<sub>OUT</sub> through a 22pF feedback capacitor in unipolar mode (15pF in bipolar mode). Typically swings  $\pm 10$ V.

 $I_{OUT}$  (Pin 14): DAC Current Output. Normally tied through a 22pF feedback capacitor in unipolar mode (15pF in bipolar mode) to  $V_{OUT}$ .

**V**<sup>+</sup> (**Pin 15**): Amplifier Positive Supply. Range is 4.5V to 16.5V.

**AGNDS (Pin 16):** Analog Ground Sense. Connect to analog ground.

**AGNDF (Pin 17):** Analog Ground Force. Connect to analog ground.

**DNC (Pin 18, 19, 21):** Connected internally. Do not connect external circuitry to these pins.

 $V^-$  (Pin 20): Amplifier Negative Supply. Range is -4.5V to -16.5V.

NC (Pin 22): No Connection.

**LD (Pin 23):** DAC Digital Input Load Control Input. When LD is taken to a logic high, data is loaded from the input register into the DAC register, updating the DAC output.

 $\overline{WR}$  (Pin 24): DAC Digital Write Control Input. When  $\overline{WR}$  is taken to a logic low, data is written from the digital input pins into the 16-bit wide input reigster.

**D15 (Pins 25):** MSB or Digital Input Data Bit 15.

D14 (Pin 26): Digital Input Data Bit 14.

D13 (Pin 27): Digital Input Data Bit 13.

D12 (Pin 28): Digital Input Data Bit 12.

D11 (Pin 29): Digital Input Data Bit 11.

**D10 (Pin 30):** Digital Input Data Bit 10.

**D9 (Pin 31):** Digital Input Data Bit 9.

**D8 (Pin 32):** Digital Input Data Bit 8.

**D7 (Pin 33):** Digital Input Data Bit 7.

D6 (Pin 34): Digital Input Data Bit 6.

D5 (Pin 35): Digital Input Data Bit 5.

**D4 (Pin 36):** Digital Input Data Bit 4.

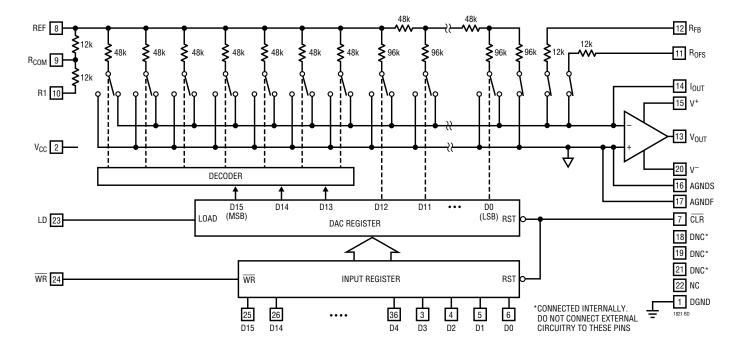


# TRUTH TABLE

### Table 1

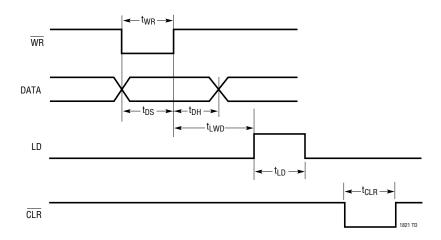
| CONT | CONTROL INPUTS |    |  |
|------|----------------|----|--|
| CLR  | WR             | LD | REGISTER OPERATION   |
| 0    | Χ              | Χ  | Reset Input and DAC Register to All 0s for LTC1821 and Midscale for LTC1821-1 (Asynchronous Operation)   |
| 1    | 0              | 0  | Write Input Register with All 16 Data Bits   |
| 1    | 1              | 1  | Load DAC Register with the Contents of the Input Register  |
| 1    | 0              | 1  | Input and DAC Register Are Transparent   |
| 1    | T              | T  | CLK = LD and WR Tied Together. The 16 Data Bits Are Written Into the Input Register on the Falling Edge of the CLK and Then Loaded Into the DAC Register on the Rising Edge of the CLK |
| 1    | 1              | 0  | No Register Operation  |

# **BLOCK DIAGRAM**





# TIMING DIAGRAM



### APPLICATIONS INFORMATION

### **Description**

The LTC1821 is a 16-bit voltage output DAC with a full parallel 16-bit digital interface. The device can operate from 5V and  $\pm 15$  supplies and provides both unipolar 0V to -10V or 0V to 10V and bipolar  $\pm 10V$  output ranges from a 10V or -10V reference input. Additionally, the power supplies for the LTC1821 can go as low as 4.5V and  $\pm 4.5V$ . In this case for a 2.5V or -2.5V reference, the output range is 0V to -2.5V, 0V to 2.5V and  $\pm 2.5V$ . The LTC1821 has three additional precision resistors on chip for bipolar operation. Refer to the block diagram regarding the following description.

The 16-bit DAC consists of a precision R-2R ladder for the 13 LSBs. The three MSBs are decoded into seven segments of resistor value R. Each of these segments and the R-2R ladder carries an equally weighted current of one eighth of full scale. The feedback resistor  $R_{FB}$  and 4-quadrant resistor  $R_{OFS}$  have a value of R/4. 4-quadrant resistors R1 and R2 have a magnitude of R/4. R1 and R2 together with an external op amp (see Figure 2) inverts the reference input voltage and applies it to the 16-bit DAC input REF, in 4-quadrant operation. The REF pin presents a constant input impedance of R/8 in unipolar mode and R/12 in bipolar mode.

The LTC1821 contains an onboard precision high speed amplifier. This amplifier together with the feedback resistor (RFB) form a precision current-to-voltage converter for the DAC's current output. The amplifier has very low noise, offset, input bias current and settles in less than  $2\mu s$  to 0.0015% for a 10V step. It can sink and source 22mA ( $\pm 15V$ ) typically and can drive a 300pF capacitive load. An added feature of these devices, especially for waveform generation, is a proprietary deglitcher that reduces glitch impulse to below 2nV-s over the DAC output voltage range.

### **Digital Section**

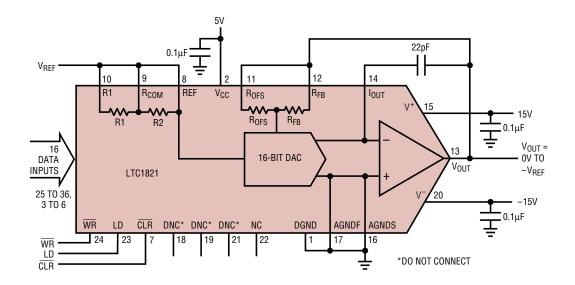
The LTC1821 has a 16-bit wide full parallel data bus input. The device is double-buffered with two 16-bit registers. The double-buffered feature permits the update of several DACs simultaneously. The input register is loaded directly from a 16-bit microprocessor bus when the  $\overline{WR}$  pin is brought to a logic low level. The second register (DAC register) is updated with the data from the input register when the LD signal is brought to a logic high. Updating the DAC register updates the DAC output with the new data. To make both registers transparent in flowthrough mode, tie  $\overline{WR}$  low and LD high. However, this defeats the deglitcher operation and output glitch impulse may increase. The deglitcher is activated on the rising edge of the LD pin. The



versatility of the interface also allows the use of the input and DAC registers in a master slave or edge-triggered configuration. This mode of operation occurs when  $\overline{WR}$  and LD are tied together. The asynchronous clear pin resets the LTC1821 to zero scale and the LTC1821-1 to midscale.  $\overline{CLR}$  resets both the input and DAC registers. These devices also have a power-on reset. Table 1 shows the truth table for the LTC1821.

# Unipolar Mode (2-Quadrant Multiplying, $V_{OUT} = 0V \text{ to } - V_{REF}$ )

The LTC1821 can be used to provide 2-quadrant multiplying operation as shown in Figure 1. With a fixed -10V reference, the circuit shown gives a precision unipolar 0V to 10V output swing.



#### **Unipolar Binary Code Table**

| DIGITAL INPUT<br>BINARY NUMBER<br>IN DAC REGISTER |                              |                              | R                            | ANALOG OUTPUT<br>Vout   |
|---|------------------------------|------------------------------|------------------------------|---|
| MSB   |                              |                              | LSB                          |   |
| 1111<br>1000<br>0000<br>0000                      | 1111<br>0000<br>0000<br>0000 | 1111<br>0000<br>0000<br>0000 | 1111<br>0000<br>0001<br>0000 | -V <sub>REF</sub> (65,535/65,536)<br>-V <sub>REF</sub> (32,768/65,536) = -V <sub>REF</sub> /2<br>-V <sub>REF</sub> (1/65,536)<br>0V |

1821 F01

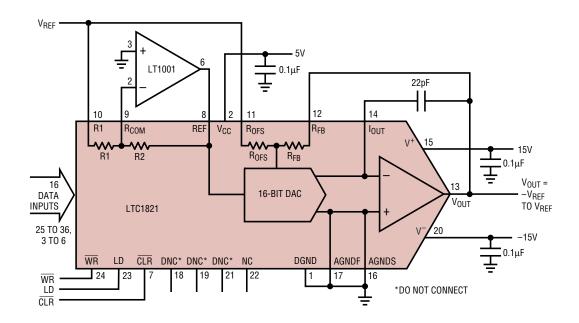
Figure 1. Unipolar Operation (2-Quadrant Multiplication)  $V_{OUT} = 0V$  to  $-V_{REF}$ 



# Bipolar Mode (4-Quadrant Multiplying, $V_{OUT} = -V_{REF}$ to $V_{REF}$ )

The LTC1821 contains on chip all the 4-quadrant resistors necessary for bipolar operation. 4-quadrant multiplying

operation can be achieved with a minimum of external components—a capacitor and a single op amp, as shown in Figure 2. With a fixed 10V reference, the circuit shown gives a precision bipolar –10V to 10V output swing.



### **Bipolar Offset Binary Code Table**

| В    | INARY | L INPU<br>Numbe<br>Registi | ANALOG OUTPUT<br>V <sub>out</sub> |                                  |
|------|-------|----------------------------|-----------------------------------|----------------------------------|
| MSB  |       |                            | LSB                               |                                  |
| 1111 | 1111  | 1111                       | 1111                              | V <sub>REF</sub> (32,767/32,768) |
| 1000 | 0000  | 0000                       | 0001                              | V <sub>REF</sub> (1/32,768)      |
| 1000 | 0000  | 0000                       | 0000                              | 0V                               |
| 0111 | 1111  | 1111                       | 1111                              | -V <sub>REF</sub> (1/32,768)     |
| 0000 | 0000  | 0000                       | 0000                              | -V <sub>REF</sub>                |

1821 F02

Figure 2. Bipolar Operation (4-Quadrant Multiplication)  $V_{OUT} = -V_{REF}$  to  $V_{REF}$ 



### **Precision Voltage Reference Considerations**

Because of the extremely high accuracy of the 16-bit LTC1821, careful thought should be given to the selection of a precision voltage reference. As shown in the section describing the basic operation of the LTC1821, the output voltage of the DAC circuit is directly affected by the voltage reference; thus, any voltage reference error will appear as a DAC output voltage error.

There are three primary error sources to consider when selecting a precision voltage reference for 16-bit applications: output voltage initial tolerance, output voltage temperature coefficient (TC), and output voltage noise.

Initial reference output voltage tolerance, if uncorrected, generates a full-scale error term. Choosing a reference with low output voltage initial tolerance, like the LT1236 ( $\pm 0.05\%$ ), minimizes the gain error due to the reference; however, a calibration sequence that corrects for system zero- and full-scale error is always recommended.

A reference's output voltage temperature coefficient affects not only the full-scale error, but can also affect the circuit's INL and DNL performance. If a reference is chosen with a loose output voltage temperature coefficient, then the DAC output voltage along its transfer characteristic will be very dependent on ambient conditions. Minimizing the error due to reference temperature coefficient can be achieved by choosing a precision reference with a low output voltage temperature coefficient and/or tightly controlling the ambient temperature of the circuit to minimize temperature gradients.

As precision DAC applications move to 16-bit and higher performance, reference output voltage noise may contribute a dominant share of the system's noise floor. This in turn can degrade system dynamic range and signal-to-noise ratio. Care should be exercised in selecting a voltage

reference with as low an output noise voltage as practical for the system resolution desired. Precision voltage references, like the LT1236, produce low output noise in the 0.1Hz to 10Hz region, well below the 16-bit LSB level in 5V or 10V full-scale systems. However, as the circuit bandwidths increase, filtering the output of the reference may be required to minimize output noise.

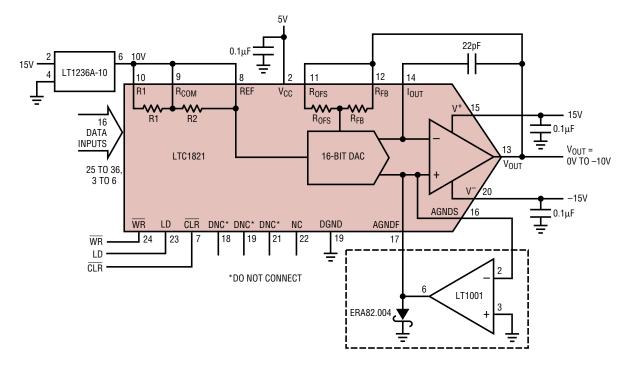
### Grounding

As with any high resolution converter, clean grounding is important. A low impedance analog ground plane and star grounding should be used. AGNDF and AGNDS must be tied to the star ground with as low a resistance as possible. When it is not possible to locate star ground close to AGNDF and AGNDS, separate traces should be used to route these pins to the star ground. This minimizes the voltage drop from these pins to ground due to the code dependent current flowing into the ground plane. If the resistance of these separate circuit board traces exceeds  $1\Omega$ , the circuit of Figure 3 eliminates this code dependent voltage drop error for high resistance traces.

To calculate PC track resistance in squares, divide the length of the PC track by the width and multiply this result by the sheet resistance of copper foil. For 1 oz copper ( $\approx 1.4$  mils thick), the sheet resistance is  $0.045\Omega$  per square.

Table 2. Partial List of LTC Precision References Recommended for Use with the LTC1821, with Relevant Specifications

| ,                        |                      |                      |                        |  |  |
|--------------------------|----------------------|----------------------|------------------------|--|--|
| REFERENCE                | INITIAL<br>Tolerance | TEMPERATURE<br>DRIFT | 0.1Hz to 10Hz<br>NOISE |  |  |
| LT1019A-5,<br>LT1019A-10 | ±0.05%               | 5ppm/°C              | 12μV <sub>P-P</sub>    |  |  |
| LT1236A-5,<br>LT1236A-10 | ±0.05%               | 5ppm/°C              | 3μV <sub>P-P</sub>     |  |  |
| LT1460A-5,<br>LT1460A-10 | ±0.075%              | 10ppm/°C             | 20μV <sub>P-P</sub>    |  |  |
| LT1790A-2.5              | ±0.05%               | 10ppm/°C             | 12μV <sub>P-P</sub>    |  |  |



#### ALTERNATE AMPLIFIER FOR OPTIMUM SETTLING TIME PERFORMANCE

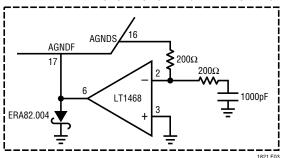
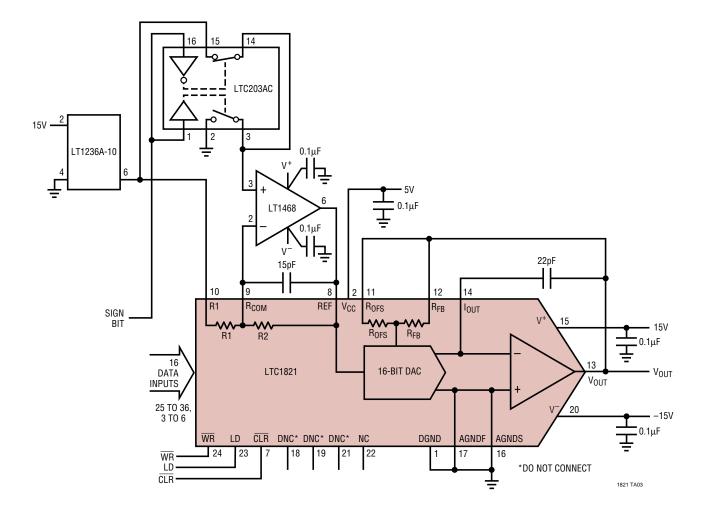


Figure 3. Driving AGNDF and AGNDS with a Force/Sense Amplifier

# TYPICAL APPLICATION

17-Bit Sign Magnitude Output Voltage DAC with Bipolar Zero Error of 140 $\mu$ V (0.92LSB at 17 Bits)

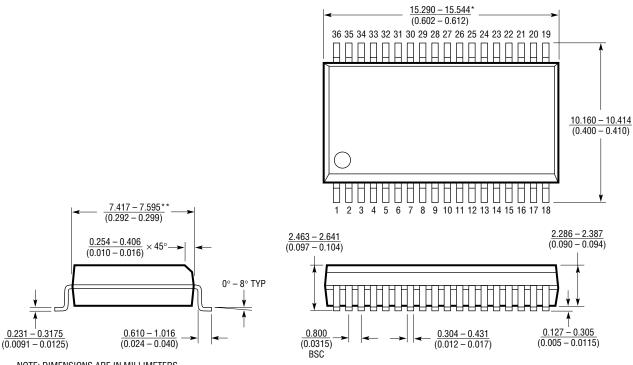


# PACKAGE DESCRIPTION

Dimensions in inches (millimeters) unless otherwise noted.

# GW Package 36-Lead Plastic SSOP (Wide 0.300)

(LTC DWG # 05-08-1642)





<sup>\*</sup>DIMENSION DOES NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED 0.152mm (0.006") PER SIDE

GW36 SSOP 1098

<sup>\*\*</sup>DIMENSION DOES NOT INCLUDE INTERLEAD FLASH. INTERLEAD FLASH SHALL NOT EXCEED 0.254mm (0.010") PER SIDE

# **RELATED PARTS**

| PART NUMB  | ER               | DESCRIPTION   | COMMENTS   |
|------------|------------------|---|--|
| ADCs       | LTC1417          | Low Power 400ksps, 14-Bit ADC                             | 20mW, Single or ±5V, Serial I/O                              |
|            | LTC1418          | 14-Bit, 200ksps, Single 5V ADC                            | 15mW, Serial/Parallel ±10V                                   |
|            | LTC1604/LTC1608  | 16-Bit, 333ksps/500ksps, ±5V ADC                          | 90dB SINAD, 100dB THD, ±2.5V Inputs                          |
|            | LTC1605/LTC1606  | 16-Bit, 100ksps/250ksps, Single 5V ADC                    | ±10V Inputs, 55mW/75mW, Byte or Parallel I/O                 |
|            | LTC1609          | 16-Bit, 200ksps, Single 5V ADC                            | ±10V Inputs, 65mW, Serial I/O                                |
|            | LTC2400          | 24-Bit, Micropower $\Delta\Sigma$ ADC in SO-8             | 0.3ppm Noise, 4ppm INL, 10ppm Total Unadjusted Error, 200μA  |
|            | LTC2410          | 24-Bit, Fully Differential, No Latency $\Delta\Sigma$ ADC | 0.16ppm Noise, 2ppm INL, 10ppm Total Unadjusted Error, 200µA |
| DACs       | LTC1591/LTC1597  | Parallel 14-/16-Bit Current Output DACs                   | On-Chip 4-Quadrant Resistors                                 |
|            | LTC1595/LTC1596  | Serial 16-Bit Current Output DACs in SO-8/S16             | Low Glitch, ±1LSB Maximum INL, DNL                           |
|            | LTC1599          | Parallel 2 Byte 16-Bit Current Output DAC                 | On-Chip 4-Quadrant Resistors                                 |
|            | LTC1650          | Serial 16-Bit ±5V Voltage Output DAC                      | Low Noise and Low Glitch Rail-to-Rail V <sub>OUT</sub>       |
|            | LTC1654          | Dual 14-Bit Rail-to-Rail V <sub>OUT</sub> DAC             | Programmable Speed/Power, 3.5μs/750μA, 8μs/450μA             |
|            | LTC1655/LTC1655L | Serial 5V/3V 16-Bit Voltage Output DAC in SO-8            | Low Power, Deglitched, Rail-to-Rail V <sub>OUT</sub>         |
|            | LTC1657/LTC1657L | Parallel 5V/3V 16-Bit Voltage Output DAC                  | Low Power, Deglitched, Rail-to-Rail V <sub>OUT</sub>         |
|            | LTC1658          | Serial 14-Bit Voltage Output DAC                          | Low Power, 8-Lead MSOP Rail-to-Rail V <sub>OUT</sub>         |
| Op Amps    | LT1001           | Precision Operational Amplifier                           | Low Offset, Low Drift  |
|            | LT1468           | 90MHz, 22V/µs, 16-Bit Accurate Op Amp                     | Precise, 1µs Settling to 0.0015%                             |
| References | LT1019           | Bandgap Reference   | ±0.05% Initial Tolerance, 5ppm/°C                            |
|            | LT1236           | Precision Buried Zener Reference                          | ±0.05% Initial Tolerance, Low Noise 3μV <sub>P-P</sub>       |
|            | LT1460           | Micropower Bandgap Reference                              | ±0.075% Initial Tolerance, 10ppm/°C                          |
|            | LT1790           | SOT-23 Micropower, Low Dropout Reference                  | ±0.05% Initial Tolerance, 10ppm/°C                           |

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LTC1821-1ACGW#TRPBF LTC1821-1BIGW#PBF LTC1821-1AIGW#TR LTC1821ACGW LTC1821-1AIGW
LTC1821ACGW#TR LTC1821-1BIGW#TR LTC1821BIGW LTC1821BIGW#TRPBF LTC1821-1BCGW#TR
LTC1821AIGW#PBF LTC1821-1ACGW LTC1821BIGW#PBF LTC1821-1BCGW LTC1821ACGW#TRPBF LTC1821-1ACGW#PBF LTC1821AIGW#TR LTC1821-1BCGW#TRPBF LTC1821-1BIGW
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