() IDT.

Four Output Differential Buffer for PCI Express

9DB401C

Description

The 9DB401C is a DB400 Version 2.0 Yellow Cover part with PCI Express support. It can be used in PC or embedded systems to provide outputs that have low cycle-to-cycle jitter (50ps), low output-to-output skew (100ps), and are PCI Express gen 1 compliant. The 9DB401C supports a 1 to 4 output configuration, taking a spread or non spread differential HCSL input from a CK410(B) main clock such as 954101 and 932S401, or any other differential HCSL pair. 9DB401C can generate HCSL or LVDS outputs from 50 to 200MHz in PLL mode or 0 to 400Mhz in bypass mode. There are two de-jittering modes available selectable through the HIGH_BW# input pin, high bandwidth mode provides de-jittering for spread inputs and low bandwidth mode provides extra de-jittering for non-spread inputs. The SRC_STOP#, PD#, and OE real-time input pins provide completely programmable power management control.

Output Features

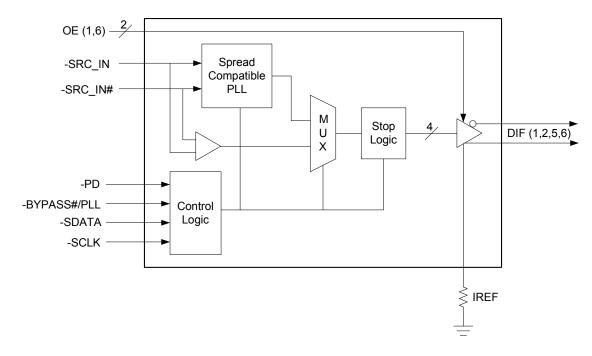
- 4 0.7V HCSL or LVDS differential output pairs
- Supports zero delay buffer mode and fanout mode
- Bandwidth programming available

Features/Benefits

- Spread spectrum modulation tolerant, 0 to -0.5% down spread and +/- 0.25% center spread
- Supports undriven differential outputs in PD# and SRC_STOP# modes for power management.

Key Specifications

- Outputs cycle-cycle jitter: < 50ps
- Outputs skew: < 50ps
- Extended frequency range in bypass mode: Revision B: up to 333.33MHz Revision C: up to 400MHz
- Real-time PLL lock detect output pin
- 28-pin SSOP/TSSOP package
- Available in RoHS compliant packaging

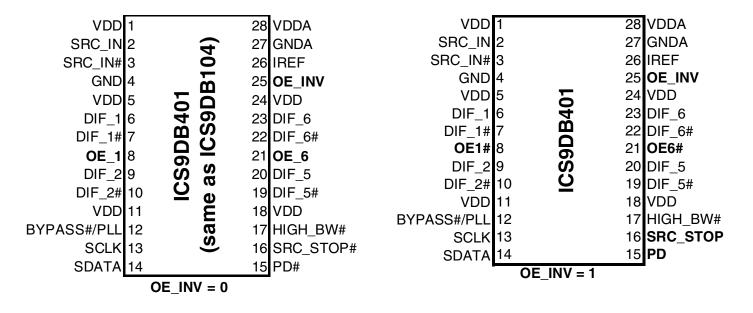


Functional Block Diagram

Note: Polarities shown for $OE_INV = 0$.

IDT[®] Four Output Differential Buffer for PCI Express

Pin Configuration



28-pin SSOP & TSSOP

Polarity Inversion Pin List Table

	OE_INV			
Pins	0	1		
8	OE_1	OE1#		
15	PD#	PD		
16	DIF_STOP#	DIF_STOP		
21	OE_6	OE6#		

Power Groups

Pin N	lumber	Description
VDD	GND	Description
1	4	SRC_IN/SRC_IN#
5,11,18, 24	4	DIF(1,2,5,6)
N/A	27	IREF
28	27	Analog VDD & GND for PLL core

Pin Description for OE_INV = 0

PIN #	PIN NAME	PIN TYPE	DESCRIPTION
1	VDD	PWR	Power supply, nominal 3.3V
2	SRC_IN	IN	0.7 V Differential SRC TRUE input
3	SRC_IN#	IN	0.7 V Differential SRC COMPLEMENTARY input
4	GND	PWR	Ground pin.
5	VDD	PWR	Power supply, nominal 3.3V
6	DIF_1	OUT	0.7V differential true clock output
7	DIF_1#	OUT	0.7V differential complement clock output
8	OE_1	IN	Active high input for enabling output 1.
8	UE_1	IIN	0 = tri-state outputs, 1= enable outputs
9	DIF_2	OUT	0.7V differential true clock output
10	DIF_2#	OUT	0.7V differential complement clock output
11	VDD	PWR	Power supply, nominal 3.3V
10			Input to select Bypass(fan-out) or PLL (ZDB) mode
12	BYPASS#/PLL	IN	0 = Bypass mode, 1= PLL mode
13	SCLK	IN	Clock pin of SMBus circuitry, 5V tolerant.
14	SDATA	I/O	Data pin for SMBus circuitry, 5V tolerant.
			Asynchronous active low input pin used to power down the device.
15	PD#	IN	The internal clocks are disabled and the VCO and the crystal are
			stopped.
16	SRC_STOP#	IN	Active low input to stop SRC outputs.
17		INI	3.3V input for selecting PLL Band Width
17	HIGH_BW#	IN	0 = High, 1= Low
18	VDD	PWR	Power supply, nominal 3.3V
19	DIF_5#	OUT	0.7V differential complement clock output
20	DIF_5	OUT	0.7V differential true clock output
21		IN	Active high input for enabling output 6.
21	OE_6	IIN	0 = tri-state outputs, 1= enable outputs
22	DIF_6#	OUT	0.7V differential complement clock output
23	DIF_6	OUT	0.7V differential true clock output
24	VDD	PWR	Power supply, nominal 3.3V
25	OE_INV	IN	This latched input selects the polarity of the OE pins.
25		IIN	0 = OE pins active high, 1 = OE pins active low (OE#)
			This pin establishes the reference current for the differential current-
26	IREF		mode output pairs. This pin requires a fixed precision resistor tied
20		OUT	to ground in order to establish the appropriate current. 475 ohms is
			the standard value.
27	GNDA	PWR	Ground pin for the PLL core.
28	VDDA	PWR	3.3V power for the PLL core.

PIN #	PIN NAME	PIN TYPE	DESCRIPTION
1	VDD	PWR	Power supply, nominal 3.3V
2	SRC_IN	IN	0.7 V Differential SRC TRUE input
3	SRC_IN#	IN	0.7 V Differential SRC COMPLEMENTARY input
4	GND	PWR	Ground pin.
5	VDD	PWR	Power supply, nominal 3.3V
6	DIF_1	OUT	0.7V differential true clock output
7	DIF_1#	OUT	0.7V differential complement clock output
•	051/	INI	Active low input for enabling DIF pair 1.
8	OE1#	IN	1 = tri-state outputs, 0 = enable outputs
9	DIF_2	OUT	0.7V differential true clock output
10	DIF_2#	OUT	0.7V differential complement clock output
11	VDD	PWR	Power supply, nominal 3.3V
10		15.1	Input to select Bypass(fan-out) or PLL (ZDB) mode
12	BYPASS#/PLL	IN	0 = Bypass mode, 1= PLL mode
13	SCLK	IN	Clock pin of SMBus circuitry, 5V tolerant.
14	SDATA	I/O	Data pin for SMBus circuitry, 5V tolerant.
15	PD	IN	Asynchronous active high input pin used to power down the device. The internal clocks are disabled and the VCO is stopped.
16	SRC_STOP	IN	Active high input to stop SRC outputs.
17	HIGH_BW#	IN	3.3V input for selecting PLL Band Width 0 = High, 1= Low
18	VDD	PWR	Power supply, nominal 3.3V
10	DIF_5#	OUT	0.7V differential complement clock output
20	DIF_5	OUT	0.7V differential true clock output
21	OE6#	IN	Active low input for enabling DIF pair 6.
21	OE0#		1 = tri-state outputs, 0 = enable outputs
22	DIF_6#	OUT	0.7V differential complement clock output
23	DIF_6	OUT	0.7V differential true clock output
24	VDD	PWR	Power supply, nominal 3.3V
25	OE_INV	IN	This latched input selects the polarity of the OE pins. 0 = OE pins active high, 1 = OE pins active low (OE#)
26	IREF	OUT	This pin establishes the reference current for the differential current-mode output pairs. This pin requires a fixed precision resistor tied to ground in order to establish the appropriate current. 475 ohms is the standard value.
27	GNDA	PWR	Ground pin for the PLL core.
28	VDDA	PWR	3.3V power for the PLL core.

Pin Description for OE_INV = 1

Absolute Max

Symbol	Parameter	Min	Max	Units
VDD_A	3.3V Core Supply Voltage		4.6	V
VDD_In	3.3V Logic Supply Voltage		4.6	V
V _{IL}	Input Low Voltage	GND-0.5		V
V _{IH}	Input High Voltage		V_{DD} +0.5V	V
Ts	Storage Temperature	-65	150	°C
Tambient	Ambient Operating Temp	0	70	O°
Tcase	Case Temperature		115	О°
	Input ESD protection			
ESD prot	human body model	2000		V

Electrical Characteristics - Input/Supply/Common Output Parameters T_A = 0 - 70°C; Supply Voltage V_{DD} = 3.3 V +/-5%

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage	V _{IH}	3.3 V +/-5%	2		V _{DD} + 0.3	V	
Input Low Voltage	VIL	3.3 V +/-5%	GND - 0.3		0.8	V	
Input High Current	I _{IH}	$V_{IN} = V_{DD}$ -5			5	uA	
	I _{IL1}	V _{IN} = 0 V; Inputs with no pull- up resistors	-5			uA	
Input Low Current	$I_{\rm IL2}$	V _{IN} = 0 V; Inputs with pull-up resistors	-200			uA	
On eventing Council of Course at	I _{DD3.3PLL}			175	200	mA	
Operating Supply Current	I _{DD3.3ByPass}	Full Active, $C_L = Full load;$		160	175	mA	
Powerdown Current		all diff pairs driven			40	mA	
	I _{DD3.3PD}	all differential pairs tri-stated			4	mA	
Input Frequency	F _{iPLL}	PLL Mode	50		200	MHz	
Input Frequency	F _{iBypass}	Bypass Mode (Revision B/REV ID = 1H)	0		333.33	MHz	
Input Frequency	F _{iBypass}	Bypass Mode (Revision C/REV ID = 2H)	0		400	MHz	
Pin Inductance ¹	L _{pin}				7	nH	1
1	C _{IN}	Logic Inputs	1.5		4	pF	1
Input Capacitance ¹	C _{OUT}	Output pin capacitance			4	pF	1
		PLL Bandwidth when PLL_BW=0	2.4	3	3.4	MHz	1
PLL Bandwidth	BW	PLL Bandwidth when PLL_BW=1	0.7	1	1.4	MHz	1
Clk Stabilization ^{1,2}	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de- assertion of PD# to 1st clock		0.5	1	ms	1,2
Modulation Frequency	fMOD	Triangular Modulation	30		33	kHz	1
Tdrive_SRC_STOP#		DIF output enable after SRC_Stop# de-assertion		10	15	ns	1,3
Tdrive_PD#		DIF output enable after PD# de-assertion			300	us	1,3
Tfall		Fall time of PD# and SRC_STOP#			5	ns	1
Trise		Rise time of PD# and SRC_STOP#			5	ns	2

¹Guaranteed by design and characterization, not 100% tested in production.

²See timing diagrams for timing requirements.

³Time from deassertion until outputs are >200 mV

IDT® Four Output Differential Buffer for PCI Express

9DB401C REV H 01/27/11

Electrical Characteristics - Clock Input Parameters

$T_A = 0.70$ C, Supply Voltage $v_{DD} = 3.5$ V +7-3%						
PARAMETER	SYMBOL	CONDITIONS	MIN	MAX	UNITS	NOTES
Differential Input High Voltage	V _{IHDIF}	Differential inputs (single-ended measurement)	600	1150	mV	1
Differential Input Low Voltage	V _{ILDIF}	Differential inputs (single-ended measurement)	V _{SS} - 300	300	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.4	8	V/ns	2
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}, V_{IN} = GND$	-5	5	uA	1
Input Duty Cycle	d _{tin}	Measurement from differential wavefrom	45	55	%	1
Input SRC Jitter - Cycle to Cycle	$SRCJ_{C2CIn}$	Differential Measurement		125	ps	1

 $T_A = 0 - 70^{\circ}C$; Supply Voltage $V_{DD} = 3.3 \text{ V} \pm -5\%$

¹ Guaranteed by design and characterization, not 100% tested in production.

²Slew rate measured through Vswing centered around differential zero

Electrical Characteristics - DIF 0.7V Current Mode Differential Pair

 $T_A = 0 - 70^{\circ}C; V_{DD} = 3.3 V + -5\%; C_L = 2pF, R_S = 33.2\Omega, R_P = 49.9\Omega, I_{REF} = 475\Omega$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Current Source Output Impedance	Zo ¹	$V_{O} = V_{x}$	3000			Ω	1
Voltage High	VHigh	Statistical measurement on single ended signal using oscilloscope	660		850	mV	1,3
Voltage Low	VLow	math function.	-150		150	ΠV	1,3
Max Voltage	Vovs	Measurement on single ended			1150	mV	1
Min Voltage	Vuds	signal using absolute value.	-300			IIIV	1
Crossing Voltage (abs)	Vcross(abs)		250		550	mV	1
Crossing Voltage (var)	d-Vcross	Variation of crossing over all edges			140	mV	1
Long Accuracy	ppm	see Tperiod min-max values			0	ppm	1,2
Rise Time	t _r	$V_{OL} = 0.175V, V_{OH} = 0.525V$	175		700	ps	1
Fall Time	t _f	$V_{OH} = 0.525 V V_{OL} = 0.175 V$	175		700	ps	1
Rise Time Variation	d-t _r				125	ps	1
Fall Time Variation	d-t _f				125	ps	1
Duty Cycle	d _{t3}	Measurement from differential wavefrom	45		55	%	1
Skew	t _{sk3}	$V_{T} = 50\%$			50	ps	1
Jitter, Cycle to cycle	t _{jcyc-cyc}	PLL mode, Measurement from differential wavefrom			50	ps	1
		BYPASS mode as additive jitter			50	ps	1

¹Guaranteed by design and characterization, not 100% tested in production.

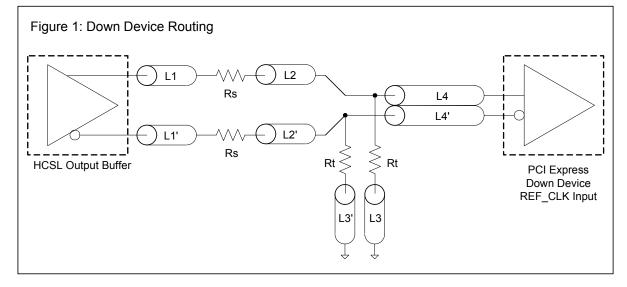
² All Long Term Accuracy and Clock Period specifications are guaranteed with the assumption that the input clock complies with CK409/CK410 accuracy requirements

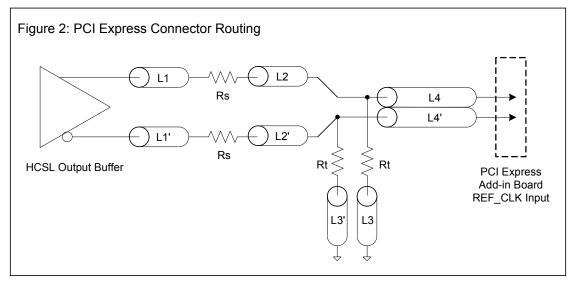
 ${}^{3}I_{REF} = V_{DD}/(3xR_{R})$. For $R_{R} = 475\Omega$ (1%), $I_{REF} = 2.32mA$. $I_{OH} = 6 \times I_{REF}$ and $V_{OH} = 0.7V @ Z_{O} = 50\Omega$.

SRC Reference Clock						
Common Recommendations for Differential Routing	Dimension or Value	Unit	Figure			
L1 length, route as non-coupled 50ohm trace	0.5 max	inch	1			
L2 length, route as non-coupled 50ohm trace	0.2 max	inch	1			
L3 length, route as non-coupled 50ohm trace	0.2 max	inch	1			
Rs	33	ohm	1			
Rt	49.9	ohm	1			

Down Device Differential Routing			
L4 length, route as coupled microstrip 100ohm differential trace	2 min to 16 max	inch	1
L4 length, route as coupled stripline 100ohm differential trace	1.8 min to 14.4 max	inch	1

Differential Routing to PCI Express Connector			
L4 length, route as coupled microstrip 100ohm differential trace	0.25 to 14 max	inch	2
L4 length, route as coupled stripline 100ohm differential trace	0.225 min to 12.6 max	inch	2



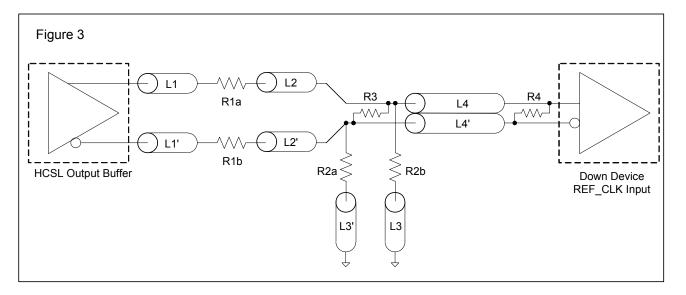


9DB401C Four Output Differential Buffer for PCI Express

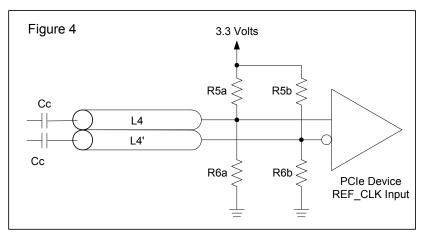
Alternative Termination for LVDS and other Common Differential Signals (figure 3)								
Vp-p	Vcm	R1	R2	R3	R4	Note		
0.22v	1.08	33	150	100	100			
0.28	0.6	33	78.7	137	100			
0.40	0.6	33	78.7	none	100	ICS874003i-02 input compatible		
0.3	1.2	33	174	140	100	Standard LVDS		
	0.22v 0.28 0.40	0.22v 1.08 0.28 0.6 0.40 0.6 0.3 1.2	0.22v 1.08 33 0.28 0.6 33 0.40 0.6 33 0.3 1.2 33	0.22v 1.08 33 150 0.28 0.6 33 78.7 0.40 0.6 33 78.7 0.3 1.2 33 174	0.22v 1.08 33 150 100 0.28 0.6 33 78.7 137 0.40 0.6 33 78.7 none 0.3 1.2 33 174 140	0.22v 1.08 33 150 100 100 0.28 0.6 33 78.7 137 100 0.40 0.6 33 78.7 none 100 0.3 1.2 33 174 140 100		

R1a = R1b = R1

R2a = R2b = R2



Cable Connected AC Coupled Application (figure 4)							
Component	Value	Note					
R5a, R5b	8.2K 5%						
R6a, R6b	1K 5%						
Сс	0.1 µF						
Vcm	0.350 volts						



General SMBus serial interface information for the 9DB401C

How to Write:

- Controller (host) sends a start bit.
- Controller (host) sends the write address DC (h)
- IDT clock will *acknowledge*
- Controller (host) sends the begining byte location = N
- IDT clock will *acknowledge*
- Controller (host) sends the data byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N + X -1
- IDT clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

How to Read:

- Controller (host) will send start bit.
- Controller (host) sends the write address DC (h)
- IDT clock will acknowledge
- Controller (host) sends the begining byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit.
- Controller (host) sends the read address DD (h)
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N + X -1
- IDT clock sends Byte 0 through byte X (if X_(h) was written to byte 8).
- Controller (host) will need to acknowledge each byte
- Controllor (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

Ind	Index Block Write Operation							
Cor	ntroller (Host)		IDT (Slave/Receiver)					
Т	starT bit							
Slave	e Address DC _(h)							
WR	WRite							
		ACK						
Begi	nning Byte = N							
			ACK					
Data	Byte Count = X							
			ACK					
Begir	ning Byte N							
			ACK					
	\$	fe						
	\diamond	X Byte	\$					
	\$	×	\$					
		1	\$					
Byte	e N + X - 1	1						
			ACK					
Р	stoP bit							

Ind	ex Block Rea	ad	Operation	
Con	troller (Host)	ID	T (Slave/Receiver)	
Т	starT bit			
Slave	e Address DC _(h)			
WR	WRite			
			ACK	
Beginning Byte = N				
			ACK	
RT	Repeat starT			
Slave	e Address DD _(h)			
RD	ReaD			
			ACK	
		Data Byte Count = X		
	ACK			
			Beginning Byte N	
	ACK			
		X Byte	\diamond	
	\diamond	B	\diamond	
	\diamond	$ \times $	\diamond	
	\diamond			
			Byte N + X - 1	
N	Not acknowledge			
Р	stoP bit			

Byt	te 0	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7		-	PD_Mode	PD# drive mode	RW	driven	Hi-Z	0
Bit 6		-	STOP_Mode	SRC_Stop# drive mode	RW	driven	Hi-Z	0
Bit 5		-	PD_SRC_INV	Power Down and SRC Invert	RW	Normal	Invert	0
Bit 4		-	Reserved	Reserved	RW	Res	erved	Х
Bit 3		-	Reserved	Reserved	RW	Res	erved	Х
Bit 2		-	PLL_BW#	Select PLL BW	RW	High BW	Low BW	1
Bit 1		-	BYPASS#	BYPASS#/PLL	RW	fan-out	ZDB	1
Bit 0		-	SRC_DIV#	SRC Divide by 2 Select	RW	x/2	1x	1

SMBus Table: Frequency Select Register, READ/WRITE ADDRESS (DC/DD)

SMBus Table: Output Control Register

Byt	te 1	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7		-	Reserved	Reserved	RW	Res	erved	Х
Bit 6	22	,23	DIF_6	Output Control	RW	Disable	Enable	1
Bit 5	19	,20	DIF_5	Output Control	RW	Disable	Enable	1
Bit 4		-	Reserved	Reserved	RW	Res	erved	Х
Bit 3		-	Reserved	Reserved	RW	Res	erved	Х
Bit 2	9,	10	DIF_2	Output Control	RW	Disable	Enable	1
Bit 1	6	,7	DIF_1	Output Control	RW	Disable	Enable	1
Bit 0		-	Reserved	Reserved	RW	Res	erved	Х

SMBus Table: Output Control Register

Byt	te 2	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7		-	Reserved	Reserved	RW	Res	erved	Х
Bit 6	22	,23	DIF_6	Output Control	RW	Free-run	Stoppable	0
Bit 5	19	,20	DIF_5	Output Control	RW	Free-run	Stoppable	0
Bit 4		-	Reserved	Reserved	RW	Reserved		Х
Bit 3		-	Reserved	Reserved	RW	Res	erved	Х
Bit 2	9,	10	DIF_2	Output Control	RW	Free-run	Stoppable	0
Bit 1	6	i,7	DIF_1	Output Control	RW	Free-run	Stoppable	0
Bit 0		-	Reserved	Reserved	RW	Res	erved	Х

SMBus Table: Output Control Register

Byt	e 3	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7				Reserved	RW	Reserved		Х
Bit 6			Reserved RW Reserved		erved	Х		
Bit 5			Reserved RW Reserved		erved	Х		
Bit 4			Reserved		RW	Reserved		Х
Bit 3			Reserved		RW	Reserved		Х
Bit 2				Reserved		Reserved		Х
Bit 1			Reserved		RW	Reserved		Х
Bit 0			Reserved		RW	Reserved		Х

Byt	te 4	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7		-	RID3		R	-	-	Х
Bit 6		-	RID2	REVISION ID	R	-	-	Х
Bit 5		-	RID1	REVISIONID	R	-	-	Х
Bit 4		-	RID0		R	-	-	Х
Bit 3		-	VID3		R	-	-	0
Bit 2		-	VID2	VENDOR ID	R	-	-	0
Bit 1		-	VID1	VENDORID	R	-	-	0
Bit 0		-	VID0		R	-	-	1

SMBus Table: Vendor & Revision ID Register

SMBus Table: DEVICE ID

Byt	te 5	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7	Bit 7 -		Dev	Device ID 7 (MSB)		Reserved		0
Bit 6	Bit 6 - Device ID 6		Device ID 6	RW	Reserved		1	
Bit 5	Bit 5 -		Γ	Device ID 5	RW	Res	erved	0
Bit 4	t4 -		Device ID 4		RW	Reserved		0
Bit 3	3 -		Γ	Device ID 3		Reserved		0
Bit 2	2 -		Ξ	Device ID 2		Reserved		0
Bit 1		-	[Device ID 1	RW	Res	erved	0
Bit 0) - [[Device ID 0	RW	Res	erved	1

SMBus Table: Byte Count Register

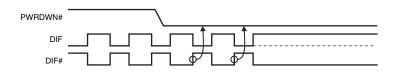
Byt	te 6	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7		-	BC7		RW	-	-	0
Bit 6		-	BC6		RW	-	-	0
Bit 5		-	BC5	Writing to this register	RW	-	-	0
Bit 4		-	BC4	Writing to this register configures how many bytes	RW	-	-	0
Bit 3		-	BC3	will be read back.	RW	-	-	0
Bit 2		-	BC2	will be read back.	RW	-	-	1
Bit 1		-	BC1		RW	-	-	1
Bit 0		-	BC0		RW	-	-	1

PD#

The PD# pin cleanly shuts off all clocks and places the device into a power saving mode. PD# must be asserted before shutting off the input clock or power to insure an orderly shutdown. PD is asynchronous active-low input for both powering down the device and powering up the device. When PD# is asserted, all clocks will be driven high, or tri-stated (depending on the PD# drive mode and Output control bits) before the PLL is shut down.

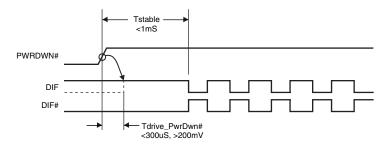
PD# Assertion

When PD# is sampled low by two consecutive rising edges of DIF#, all DIF outputs must be held High, or tri-stated (depending on the PD# drive mode and Output control bits) on the next High-Low transition of the DIF# outputs. When the PD# drive mode bit is set to '0', all clock outputs will be held with DIF driven High with 2 x I_{REF} and DIF# tri-stated. If the PD# drive mode bit is set to '1', both DIF and DIF# are tri-stated.



PD# De-assertion

Power-up latency is less than 1 ms. This is the time from de-assertion of the PD# pin, or VDD reaching 3.3V, or the time from valid SRC_IN clocks until the time that stable clocks are output from the device (PLL Locked). If the PD# drive mode bit is set to '1', all the DIF outputs must driven to a voltage of >200 mV within 300 ms of PD# de-assertion.



Note: Polarities in timing diagrams are shown OE_INV = 0. They are similar to OE_INV = 1.

SRC_STOP#

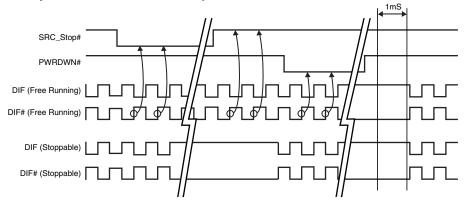
The SRC_STOP# signal is an active-low asynchronous input that cleanly stops and starts the DIF outputs. A valid clock must be present on SRC_IN for this input to work properly. The SRC_STOP# signal is de-bounced and must remain stable for two consecutive rising edges of DIF# to be recognized as a valid assertion or de-assertion.

SRC_STOP# - Assertion (transition from '1' to '0')

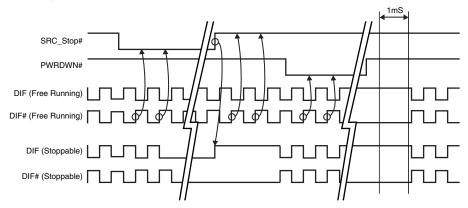
Asserting SRC_STOP# causes all DIF outputs to stop after their next transition (if the control register settings allow the output to stop). When the SRC_STOP# drive bit is '0', the final state of all stopped DIF outputs is DIF = High and DIF# = Low. There is no change in output drive current. DIF is driven with $6x_{REF}$ DIF# is not driven, but pulled low by the termination. When the SRC_STOP# drive bit is '1', the final state of all DIF output pins is Low. Both DIF and DIF# are not driven.

All stopped differential outputs resume normal operation in a glitch-free manner. The de-assertion latency to active outputs is 2-6 DIF clock periods, with all DIF outputs resuming simultaneously. If the SRC_STOP# drive control bit is '1' (tri-state), all stopped DIF outputs must be driven High (>200 mV) within 10 ns of de-assertion.

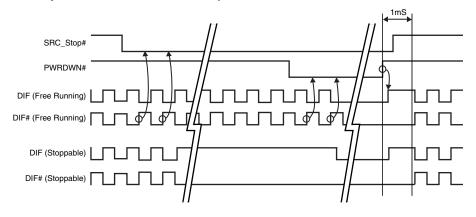
SRC_STOP_1 (SRC_Stop = Driven, PD = Driven)



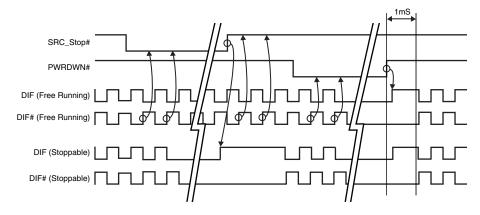
SRC_STOP_2 (SRC_Stop =Tristate, PD = Driven)

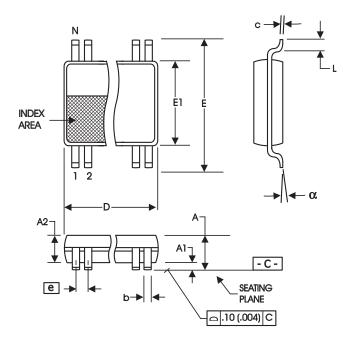


SRC_STOP_3 (SRC_Stop = Driven, PD = Tristate)



SRC_STOP_4 (SRC_Stop = Tristate, PD = Tristate)





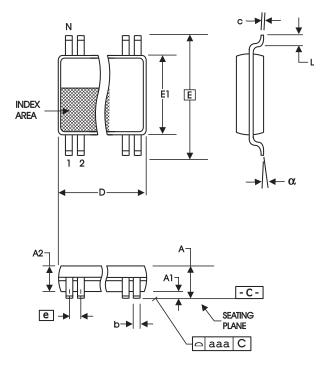
		209 mil SSC)P		
	In Mill	imeters	In Inches		
SYMBOL	COMMON [DIMENSIONS	COMMON [DIMENSIONS	
	MIN	MAX	MIN	MAX	
А		2.00		.079	
A1	0.05		.002		
A2	1.65	1.85	.065	.073	
b	0.22	0.38	.009	.015	
С	0.09	0.25	.0035	.010	
D	SEE VARIATIONS		SEE VA	RIATIONS	
E	7.40	8.20	.291	.323	
E1	5.00	5.60	.197	.220	
е	0.65	BASIC	0.0256	6 BASIC	
L	0.55	0.95	.022	.037	
N	SEE VARIATIONS		SEE VARIATIONS		
α	0°	8°	0°	8°	

VARIATIONS

N	Dr	nm.	D (inch)		
IN	MIN	MAX	MIN	MAX	
28	9.90	10.50	.390	.413	

Reference Doc.: JEDEC Publication 95, MO-150

10-0033



	(173 mil)	(25.6 mil)		
	In Millimeters		In Inches	
SYMBOL	COMMON DIMENSIONS		COMMON DIMENSIONS	
	MIN	MAX	MIN	MAX
A		1.20		.047
A1	0.05	0.15	.002	.006
A2	0.80	1.05	.032	.041
b	0.19	0.30	.007	.012
С	0.09	0.20	.0035	.008
D	SEE VARIATIONS		SEE VARIATIONS	
E	6.40 BASIC		0.252 BASIC	
E1	4.30	4.50	.169	.177
е	0.65 BASIC		0.0256 BASIC	
L	0.45	0.75	.018	.030
N	SEE VARIATIONS		SEE VARIATIONS	
а	0°	8°	0°	8°
aaa		0.10		.004

4.40 mm. Body, 0.65 mm. Pitch TSSOP

Ν	D mm.		D (inch)	
	MIN	MAX	MIN	MAX
28	9.60	9.80	.378	.386

Reference Doc.: JEDEC Publication 95, MO-153

10-0035

Ordering Information

Part / Order Number	Shipping Packaging	Package	Temperature
9DB401CGLF	Tubes	28-pin TSSOP	0 to +70°C
9DB401CGLFT	Tape and Reel	28-pin TSSOP	0 to +70°C
9DB401CFLF	Tubes	28-pin SSOP	0 to +70°C
9DB401CFLFT	Tape and Reel	28-pin SSOP	0 to +70°C

"LF" denotes Pb Configuration, RoHS compliant.

"C" is the device revision designator (will not correlate to the datasheet revision)

Revision History

Rev.	Issue Date	Description	Page #
0.1	4/21/2005	Changed Ordering Information from"LN" to "LF".	
		1. Updated LF Ordering Information to RoHS Compliant.	
Α	8/15/2005	2. Release to web.	14-15
В	9/7/2006	Updated Electrical Characteristics.	Various
С	5/22/2007	Updated Polarity Inversion Table.	2
D	2/28/2008	Added Input Clock Specs	6
E	3/18/2008	Fixed typo in clock Input Parameters	6
		1. Updated Electrical Characteristics to add propagation delay and phase	
		noise information.	
		2. Added SMBus electrical characteristics	
		3. Added foot note about DIF input running in order for the SMBus	
		interface to work	
		4. Added foot note to Byte 1 about functionality of OE bits and OE pins.	
F	9/5/2008	5. Updated Block Diagram to correctly indicate the OE pins.	Various
G	11/18/2010	Updated Block Diagram	1
Н	1/27/2011	Updated Termination Figure 4	8

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