E6D-C

CSM_E6D-C_DS_E_5_1

High-resolution Encoder

- Incremental model
- External diameter of 55 mm.
- Resolution of up to 6,000 ppr.





Be sure to read *Safety Precautions* on page 4.

Ordering Information

Encoders [Refer to Dimensions on page 4.]

| Power supply voltage | Output configuration | Resolution (pulses/rotation) | Model |
|----------------------|-----------------------|------------------------------|---|
| 5 VDC | Voltage output | 1,000 | E6D-CWZ1E (resolution) 0.5M Example: E6D-CWZ1E 1000P/R 0.5M |
| | | 2,000 | |
| | | 3,600 | |
| | | 5,000 | |
| | | 6,000 | |
| 12 VDC | Open-collector output | 1,000 | E6D-CWZ2C (resolution) 0.5M Example: E6D-CWZ2C 1000P/R 0.5M |
| | | 2,000 | |
| | | 3,600 | |
| | | 5,000 | |
| | | 6,000 | |

Note: In addition to the models listed at the left, models with either voltage outputs or open-collector outputs are also available with the following resolutions (pulses/rotation): 720, 800, 1,024, 1,200, 1,500, 1,800, 2,048, 2,500, 3,000, 3,200, and 4,096.

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

| Name | Model | Remarks |
|------------------------|-----------|----------------------------|
| | E69-C06B | Provided with the product. |
| Couplings | E69-C68B | Different end diameter |
| Coupings | E69-C610B | Different end diameter |
| | E69-C06M | Metal construction |
| Servo Mounting Bracket | E69-2 | Provided with the product. |

Refer to Accessories for details.

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Ratings and Specifications

| Item | Model | E6D-CWZ1E | E6D-CWZ2C | | |
|---|---|--|--|--|--|
| Power supply voltage | | 5 VDC ±5%, ripple (p-p): 5% max. 12 VDC ±10%, ripple (p-p): 5% max. | | | |
| Current consumption*1 15 | | 150 mA max. | | | |
| Resolution (pulses/rotation) | | 1,000, 2,000, 3,600, 5,000, 6,000 | | | |
| Output phases | | Phases A, B, and Z | | | |
| Output configuration | | Voltage output | Open-collector output | | |
| Output capacity | | Output resistance: 1 k Ω Sink current: 35 mA max. Residual voltage: 0.7 V max. (at sink current of 10 mA) | Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage: 1 V max. (at sink current of 35 mA) Residual voltage: 0.7 V max. (at sink current of 10 mA) | | |
| Maximum response frequency*2 | | 200 kHz | | | |
| Phase difference between outputs | | 90°±25° between A and B (1/4 T ± 0.07 T) | | | |
| Rise and fall times of output 1 μs max. | | | | | |
| Starting torque | | 9.8 mN·m max. | | | |
| Moment of inertia | | 3 × 10 ⁻⁶ kg⋅m² max. | | | |
| Shaft loading | Radial | 50 N (20 N to maintain accuracy) | | | |
| Shart loading | Thrust | 30 N (10 N to maintain accuracy) | | | |
| Maximum permissible speed | | 12,000 r/min | | | |
| Ambient temperature range | | Operating: -10 to 70°C (with no icing), Storage: -25 to 80°C (with no icing) | | | |
| Ambient humic | dity range | Operating/Storage: 35% to 85% (with no condensation) | | | |
| Insulation resi | stance | Excluded because of capacitor ground. | | | |
| Dielectric strer | ngth | Excluded because of capacitor ground. | | | |
| Vibration resis | tance | Destruction: 10 to 55 Hz, 1.5-mm double amplitude for | 2 hours each in X, Y, and Z directions | | |
| Shock resistar | ice | Destruction: 500 m/s² 3 times each in X, Y, and Z directions | | | |
| Degree of prot | ection*3 | IEC 60529 IP50 | | | |
| Connection me | ethod | Pre-wired Models (Standard cable length: 0.5 m) | | | |
| Material | | Case: Zinc alloy, Main unit: Aluminum, Shaft: SUS303, Mounting Bracket: Galvanized iron | | | |
| Weight (packe | packed state) Approx. 280 g | | | | |
| Accessories | E69-C06B Coupling, E69-2 Servo Mounting Bracket, Hexagonal wrench, Instruction manual | | | | |

| Maximum electrical response speed (rpm) = | Maximum response frequency | |
|---|----------------------------|-------------|
| waxiinum electrical response speed (ipin) = | Resolution | \times 60 |

^{*1.} An inrush current of approximately 2 A will flow for approximately 50 μs when the power is turned ON.
*2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

This means that the Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. *3. No protection is provided against water or oil.

3

I/O Circuit Diagrams

| Model/Output Circuits | Output mode | Connection | |
|---|---|--|--|
| E6D-CWZ1E | E6D-CWZ1E Voltage output | | |
| Brown +5 V Standard Standar | Direction of rotation: CW (as viewed from end of shaft) CCW (as viewed from end of shaft) CCW (360°) CT CW (360°) CT CW (360°) COW (360°) CI CI CI CI CI CI CI CI CI C | Model Color E6D-CWZ1E E6D-CWZ2C | |
| E6D-CWZ2C | E6D-CWZ2C Open-collector output | Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case. 2. The phase A, phase B, and phase Z circuits are all identical. | |
| Brown +12 V Black, white, orange Output (Black: phase A, White: phase B, Orange: phase Z) Shield GND | Direction of rotation: CW (as viewed from end of shaft) (b) (as viewed from end of shaft) (as viewed from end of shaft) (b) (as viewed from end of shaft) (as viewed from end of shaft) (b) (as viewed from end of shaft) (b) (as viewed from end of shaft) (as viewed from end of shaft) (b) (as viewed from end of shaft) (as viewed from end of shaft) (b) (as viewed from end of shaft) (b) (as viewed from end of shaft) (b) (b) (as viewed from end of shaft) (b) (b) (as viewed from end of shaft) (b) (b) (c) (as viewed from end of shaft) (b) (b) (c) (as viewed from end of shaft) (b) (b) (c) (as viewed from end of shaft) (b) (b) (c) (as viewed from end of shaft) (b) (b) (c) (as viewed from end of shaft) (b) (b) (c) (as viewed from end of shaft) (b) (b) (c) (d) (d) (d) (d) (d) (d) (d | 3. Normally, connect GND externally to 0 V or to ground. Peripheral Device Precautions (1) When connecting to a counter, use the 12-VDC Model E6D-CWZC. (2) For counters with voltage inputs, insert pull-up resistance of 4.7 Ω and 1/4 W. | |

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Safety Precautions

Refer to Warranty and Limitations of Liability.



This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

Wiring

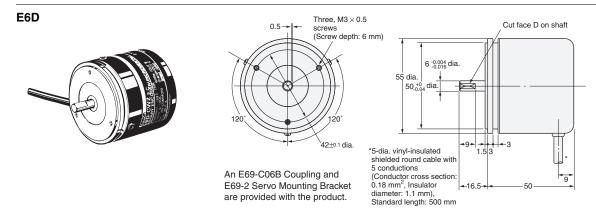
Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)

Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

Encoder



Accessories (Order Separately)

Refer to Accessories for details.

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