

- Supports XGA Resolution (Output Pixel Rates Up to 86 MHz)
- Digital Visual Interface (DVI) Specification Compliant<sup>1</sup>
- True-Color, 24 Bit/Pixel, 16.7M Colors at 1 or 2-Pixels Per Clock
- Laser Trimmed Internal Termination Resistors for Optimum Fixed Impedance Matching
- Skew Tolerant Up to One Pixel Clock Cycle
- 4x Over-Sampling
- Reduced Power Consumption – 1.8 V Core Operation With 3.3 V I/Os and Supplies<sup>2</sup>
- Reduced Ground Bounce Using Time Staggered Pixel Outputs
- Lowest Noise and Best Power Dissipation Using TI PowerPAD™ Packaging
- Advanced Technology Using TI 0.18- $\mu$ m EPIC-5™ CMOS Process
- TFP101A Incorporates HSYNC Jitter Immunity<sup>3</sup>

### description

The Texas Instruments TFP101 and TFP101A are TI *PanelBus*™ flat panel display products, part of a comprehensive family of end-to-end DVI 1.0 compliant solutions. Targeted primarily at desktop LCD monitors and digital projectors, the TFP101/101A finds applications in any design requiring high-speed digital interface.

The TFP101/101A supports display resolutions up to XGA in 24-bit true color pixel format. The TFP101/101A offers design flexibility to drive one or two pixels per clock, supports TFT or DSTN panels, and provides an option for time staggered pixel outputs for reduced ground bounce.

PowerPAD™ advanced packaging technology results in best of class power dissipation, footprint, and ultra-low ground inductance.

The TFP101/101A combines *PanelBus*™ circuit innovation with TI's advanced 0.18- $\mu$ m EPIC-5™ CMOS process technology, along with TI PowerPAD™ package technology to achieve a reliable, low-powered, low noise, high-speed digital interface solution.

### AVAILABLE OPTIONS

| PACKAGED DEVICE |                   |
|-----------------|-------------------|
| T <sub>A</sub>  | 100-TQFP<br>(PZP) |
| 0°C to 70°C     | TFP101PZP         |
|                 | TFP101APZP        |



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

1. The Digital Visual Interface Specification, DVI, is an industry standard developed by the Digital Display Working Group (DDWG) for high-speed digital connection to digital displays. The TFP101 and TFP101A are compliant to the DVI Specification Rev. 1.0.
2. The TFP101/101A has an internal voltage regulator that provides the 1.8-V core power supply from the externally supplied 3.3-V supplies.
3. The TFP101A incorporates additional circuitry to create a stable HSYNC from DVI transmitters that introduce undesirable jitter on the transmitted HSYNC signal.

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I<sup>2</sup>C is a licensed bus protocol from Phillips Semiconductor, Inc.

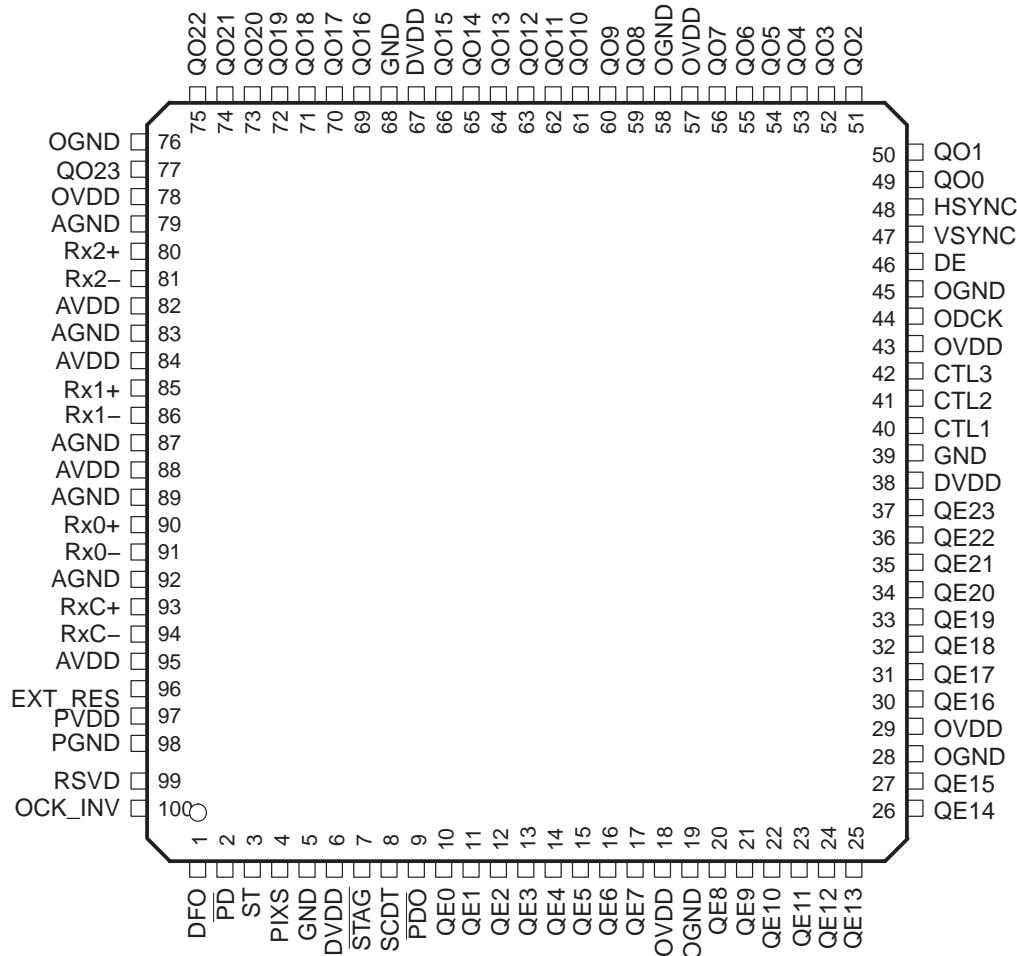
PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

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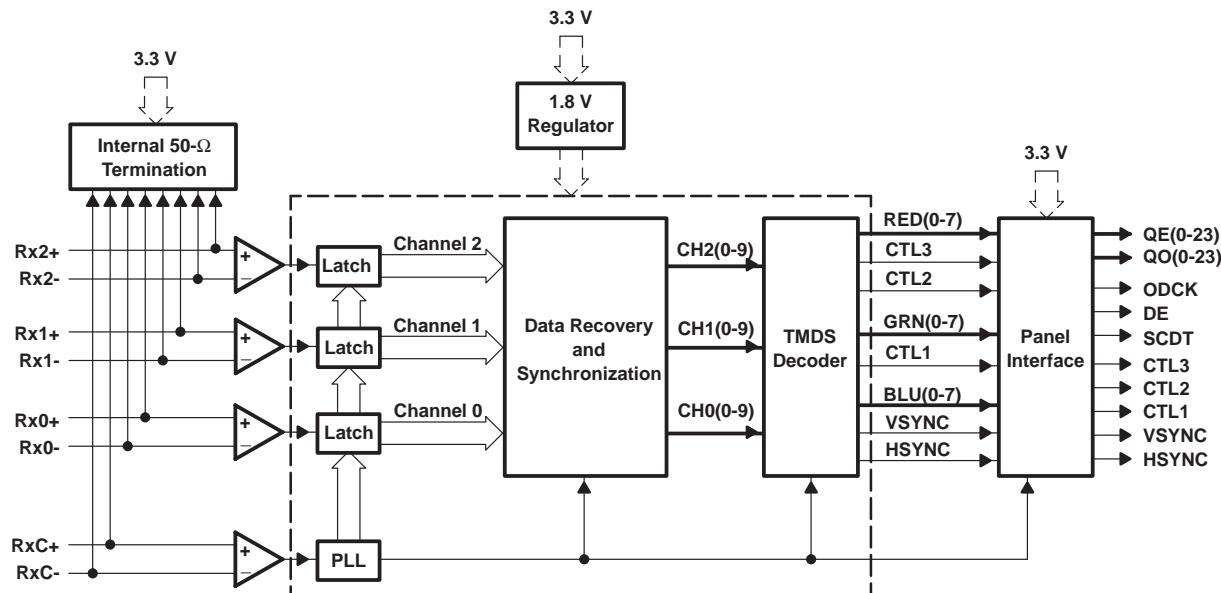
**TFP101, TFP101A**  
**TI PanelBus™ DIGITAL RECEIVER**

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**100-PIN PACKAGE  
(TOP VIEW)**



## functional block diagram



## Terminal Functions

| TERMINAL<br>NAME<br>NO. | I/O | DESCRIPTION   |
|-------------------------|-----|---|
| AGND 79,83,87,<br>89,92 | GND | Analog Ground – Ground reference and current return for analog circuitry.   |
| AVDD 82,84,88,<br>95    | VDD | Analog VDD – Power supply for analog circuitry. Nominally 3.3 V   |
| CTL[3:1] 42,41,40       | DO  | General-purpose control signals – Used for user defined control. CTL1 is not powered-down via PDO.  |
| DE 46                   | DO  | Output data enable – Used to indicate time of active video display versus non-active display or blank time. During blank, only HSYNC, VSYNC, and CTL1-3 are transmitted. During times of active display, or non-blank, only pixel data, QE[23:0] and QO[23:0], is transmitted.<br>High : Active display time<br>Low: Blank time                     |
| DFO 1                   | DI  | Output clock data format – Controls the output clock (ODCK) format for either TFT or DSTN panel support. For TFT support ODCK clock runs continuously. For DSTN support ODCK only clocks when DE is high, otherwise ODCK is held low when DE is low.<br>High : DSTN support/ODCK held low when DE = low<br>Low: TFT support/ODCK runs continuously. |
| DGND 5,39,68            | GND | Digital ground – Ground reference and current return for digital core   |
| DVDD 6,38,67            | VDD | Digital VDD – Power supply for digital core. Nominally 3.3 V  |
| EXT_RES 96              | AI  | Internal impedance matching – The TFP101/101A is internally optimized for impedance matching at 50 Ω. An external resistor tied to this pin will have no effect on device performance.  |
| HSYNC 48                | DO  | Horizontal sync output  |
| RSVD 99                 | DI  | Reserved. Must be tied high for normal operation.   |
| OVDD 18,29,43,<br>57,78 | VDD | Output driver VDD – Power supply for output drivers. Nominally 3.3 V  |
| ODCK 44                 | DO  | Output data clock - Pixel clock. All pixel outputs QE[23:0] and QO[23:0] (if in 2-pixel/clock mode) along with DE, HSYNC, VSYNC and CTL[3:1] are synchronized to this clock.  |

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**Terminal Functions (continued)**

| TERMINAL<br>NAME | NO.                | I/O             | DESCRIPTION  |
|------------------|--------------------|-----------------|--|
| OGND             | 19,28,45,<br>58,76 | GND             | Output driver ground – Ground reference and current return for digital output drivers  |
| OCK_INV          | 100                | DI              | ODCK Polarity – Selects ODCK edge on which pixel data (QE[23:0] and QO[23:0]) and control signals (HSYNC, VSYNC, DE, CTL1-3) are latched<br><br>Normal Mode:<br>High : Latches output data on rising ODCK edge<br>Low : Latches output data on falling ODCK edge   |
| PD               | 2                  | DI              | Power down – An active low signal that controls the TFP101/101A power-down state. During power down all output buffers are switched to a high impedance state. All analog circuits are powered down and all inputs are disabled, except for PD.<br><br>If PD is left unconnected an internal pullup will default the TFP101/101A to normal operation.<br>High : Normal operation<br>Low: Power down  |
| PDO              | 9                  | DI              | Output drive power down – An active low signal that controls the power-down state of the output drivers. During output drive power down, the output drivers (except SCDT and CTL1) are driven to a high impedance state. When PDO is left unconnected, an internal pullup defaults the TFP101/101A to normal operation.<br><br>High : Normal operation/output drivers on<br>Low: Output drive power down.  |
| PGND             | 98                 | GND             | PLL GND – Ground reference and current return for internal PLL   |
| PIXS             | 4                  | DI              | Pixel select – Selects between one or two pixels per clock output modes. During the 2-pixel/clock mode, both even pixels, QE[23:0], and odd pixels, QO[23:0], are output in tandem on a given clock cycle. During 1-pixel/clock, even and odd pixels are output sequentially, one at a time, with the even pixel first, on the even pixel bus, QE[23:0]. (The first pixel per line is pixel-0, the even pixel. The second pixel per line is pixel-1, the odd pixel.)<br><br>High : 2-pixel/clock<br>Low: 1-pixel/clock |
| PV <sub>DD</sub> | 97                 | V <sub>DD</sub> | PLL V <sub>DD</sub> – Power supply for internal PLL  |
| QE[0:7]          | 10-17              | DO              | Even blue pixel output – Output for even and odd blue pixels when in 1-pixel/clock mode. Output for even only blue pixel when in 2-pixel per clock mode. Output data is synchronized to the output data clock, ODCK.<br><br>LSB: QE0/pin 10<br>MSB: QE7/pin 17   |
| QE[8:15]         | 20-27              | DO              | Even green pixel output – Output for even and odd green pixels when in 1-pixel/clock mode. Output for even only green pixel when in 2-pixel/clock mode. Output data is synchronized to the output data clock, ODCK.<br><br>LSB: QE8/pin 20<br>MSB: QE15/pin 27   |
| QE[16:23]        | 30-37              | DO              | Even red pixel output – Output for even and odd red pixels when in 1-pixel/clock mode. Output for even only red pixel when in 2-pixel/clock mode. Output data is synchronized to the output data clock, ODCK.<br><br>LSB: QE16/pin 30<br>MSB: QE23/pin 37  |
| QO[0:7]          | 49-56              | DO              | Odd blue pixel output – Output for odd only blue pixel when in 2-pixel/clock mode. Not used, and held low, when in 1-pixel/clock mode. Output data is synchronized to the output data clock, ODCK.<br><br>LSB: QO0/pin 49<br>MSB: QO7/pin 56   |
| QO[8:15]         | 59-66              | DO              | Odd green pixel output – Output for odd only green pixel when in 2-pixel/clock mode. Not used, and held low, when in 1-pixel/clock mode. Output data is synchronized to the output data clock, ODCK.<br><br>LSB: QO8/pin 59<br>MSB: QO15/pin 66  |
| QO[16:23]        | 69-75,77           | DO              | Odd red pixel output – Output for odd only red pixel when in 2-pixel/clock mode. Not used, and held low, when in 1-pixel/clock mode. Output data is synchronized to the output data clock, ODCK.<br><br>LSB: QO16/pin 69<br>MSB: QO23/pin 77   |



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## Terminal Functions (continued)

| TERMINAL |     | I/O | DESCRIPTION  |
|----------|-----|-----|--|
| NAME     | NO. |     |  |
| RxC+     | 93  | AI  | Clock positive receiver input – Positive side of reference clock. TMDS low voltage signal differential input pair  |
| RxC-     | 94  | AI  | Clock negative receiver input – Negative side of reference clock. TMDS low voltage signal differential input pair.   |
| Rx0+     | 90  | AI  | Channel-0 positive receiver input – Positive side of channel-0. TMDS low voltage signal differential input pair. Channel-0 receives blue pixel data in active display and HSYNC, VSYNC control signals in blank.   |
| Rx0-     | 91  | AI  | Channel-0 negative receiver input – Negative side of channel-0. TMDS low voltage signal differential input pair.   |
| Rx1+     | 85  | AI  | Channel-1 positive receiver input – Positive side of channel-1 TMDS low voltage signal differential input pair. Channel-1 receives green pixel data in active display and CTL1 control signals in blank.   |
| Rx1-     | 86  | AI  | Channel-1 negative receiver input – Negative side of channel-1 TMDS low voltage signal differential input pair   |
| Rx2+     | 80  | AI  | Channel-2 positive receiver input – Positive side of channel-2 TMDS low voltage signal differential input pair. Channel-2 receives red pixel data in active display and CTL2, CTL3 control signals in blank.   |
| Rx2-     | 81  | AI  | Channel-2 negative receiver input – Negative side of channel-2 TMDS low voltage signal differential input pair.  |
| SCDT     | 8   | DO  | Sync detect – Output to signal when the link is active or inactive. The link is considered to be active when DE is actively switching. The TFP101/101A monitors the state DE to determine link activity. SCDT can be tied externally to PDO to power down the output drivers when the link is inactive.<br><br>High: Active link<br>Low: Inactive link |
| ST       | 3   | DI  | Output drive strength select – Selects output drive strength for high or low current drive. (See dc specifications for $I_{OH}$ and $I_{OL}$ vs ST state.)<br><br>High : High drive strength<br>Low : Low drive strength   |
| STAG     | 7   | DI  | Staggered pixel select – An active low signal used in the 2-pixel/clock pixel mode (PIXS = high). Time staggers the even and odd pixel outputs to reduce ground bounce. Normal operation outputs the odd and even pixels simultaneously.<br><br>High : Normal simultaneous even/odd pixel output<br>Low: Time staggered even/odd pixel output          |
| VSYNC    | 47  | DO  | Vertical sync output   |

**absolute maximum ratings over operating free-air temperature (unless otherwise noted)†**

† Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. Specified with PowerPAD™ bond pad on the backside of the package soldered to a 2 oz. Cu plate PCB thermal plane. Specified at maximum allowed operating temperature, 70°C.  
 2. PowerPAD™ bond pad on the backside of the package is not soldered to a thermal plane. Specified at maximum allowed operating temperature, 70°C.

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**recommended operating conditions**

|   | MIN  | TYP | MAX | UNIT               |
|---|------|-----|-----|--------------------|
| Supply voltage, $V_{DD}$ (DV <sub>DD</sub> , AV <sub>DD</sub> , PV <sub>DD</sub> , OV <sub>DD</sub> ) | 3    | 3.3 | 3.6 | V                  |
| Pixel time, $t_{pix}^{\dagger}$   | 11.6 | 40  | ns  |                    |
| Single ended analog input termination resistance, $R_t$   | 45   | 50  | 55  | $\Omega$           |
| Operating free-air temperature, $T_A$   | 0    | 25  | 70  | $^{\circ}\text{C}$ |

<sup>†</sup>  $t_{pix}$  is the pixel time defined as the period of the RxC clock input. The period of the output clock, ODCK is equal to  $t_{pix}$  when in 1-pixel/clock mode and  $2t_{pix}$  when in 2-pixel/clock mode.

**electrical characteristics over recommended operating free-air temperature range (unless otherwise noted)****dc digital I/O specifications**

| PARAMETER  | TEST CONDITIONS   | MIN | TYP | MAX              | UNIT          |
|--|---|-----|-----|------------------|---------------|
| $V_{IH}$ High level digital input voltage <sup>‡</sup> |   | 2   |     | DV <sub>DD</sub> | V             |
| $V_{IL}$ Low level digital input voltage <sup>‡</sup>  |   | 0   |     | 0.8              | V             |
| $I_{OH}$ High level output drive current <sup>§</sup>  | ST = High, $V_{OH} = 2.4$ V                                   | 5   | 10  | 14               | mA            |
|  | ST = Low, $V_{OH} = 2.4$ V                                    | 3   | 6   | 9                |               |
| $I_{OL}$ Low level output drive current <sup>§</sup>   | ST = High, $V_{OL} = 0.8$ V                                   | 10  | 13  | 19               | mA            |
|  | ST = Low, $V_{OL} = 0.8$ V                                    | 5   | 7   | 11               |               |
| $I_{OZ}$ Hi-Z output leakage current                   | $\overline{PD} = \text{Low}$ or $\overline{PDO} = \text{Low}$ | -1  |     | 1                | $\mu\text{A}$ |

<sup>‡</sup> Digital inputs are labeled DI in I/O column of Terminal Functions Table.

<sup>§</sup> Digital outputs are labeled DO in I/O column of Terminal Functions Table.

**dc specifications**

| PARAMETER   | TEST CONDITIONS               | MIN                   | TYP | MAX                  | UNIT |
|---|-------------------------------|-----------------------|-----|----------------------|------|
| $V_{ID}$ Analog input differential voltage (see Note 3)             |                               | 75                    |     | 1200                 | mv   |
| $V_{IC}$ Analog input common mode voltage (see Note 3)              |                               | AV <sub>DD</sub> -300 |     | AV <sub>DD</sub> -37 | mv   |
| $V_{I(OC)}$ Open circuit analog input voltage                       |                               | AV <sub>DD</sub> -10  |     | AV <sub>DD</sub> +10 | mv   |
| $I_{DD(2PIX)}$ Normal 2-pix/clock power supply current (see Note 4) | ODCK = 43 MHz<br>2-pix/clock  |                       |     | 350                  | mA   |
| $I_{PD}$ Power down current (see Note 5)                            | $\overline{PD} = \text{Low}$  |                       |     | 10                   | mA   |
| $I_{PDO}$ Output drive power down current (see Note 5)              | $\overline{PDO} = \text{Low}$ |                       |     | 35                   | mA   |

NOTES: 3. Specified as dc characteristic with no overshoot or undershoot.

4. Alternating 2-pixel black/2-pixel white pattern. ST = high, STAG = high, QE[23:0] and QO[23:0]  $C_L = 10$  pF.

5. Analog inputs are open circuit (transmitter is disconnected from TFP101/101A).

## electrical characteristics over recommended operating free-air temperature range (unless otherwise noted) (continued)

## ac specifications

| PARAMETER       | TEST CONDITIONS  | MIN  | TYP  | MAX        | UNIT                 |
|-----------------|--|--|------|------------|----------------------|
| $V_{ID(2)}$     | Differential input sensitivity <sup>†</sup>                                    |  | 150  | 1560       | $mV_{p-p}$           |
| $t_{ps}$        | Analog input intra-pair (+ to -) differential skew (see Note 6)                |  |      | 0.4        | $t_{bit}^{\ddagger}$ |
| $t_{ccs}$       | Analog Input inter-pair or channel-to-channel skew (see Note 6)                |  |      | 1          | $t_{pix}^{\$}$       |
| $t_{ijit}$      | Worse case differential input clock jitter tolerance <sup>¶</sup> (see Note 6) |  | 50   |            | ps                   |
| $t_{f1}$        | Fall time of data and control signals <sup>#</sup> ,                           | ST = Low, $C_L=5\text{ pF}$<br>ST = High, $C_L=10\text{ pF}$ |      | 2.4<br>1.9 | ns                   |
| $t_{r1}$        | Rise time of data and control signals <sup>#</sup> ,                           | ST = Low, $C_L=5\text{ pF}$<br>ST = High, $C_L=10\text{ pF}$ |      | 2.4<br>1.9 | ns                   |
| $t_{r2}$        | Rise time of ODCK clock <sup>#</sup>   | ST = Low, $C_L=5\text{ pF}$<br>ST = High, $C_L=10\text{ pF}$ |      | 2.4<br>1.9 | ns                   |
| $t_{f2}$        | Fall time of ODCK clock <sup>#</sup>   | ST = Low, $C_L=5\text{ pF}$<br>ST = High, $C_L=10\text{ pF}$ |      | 2.4<br>1.9 | ns                   |
| $t_{su1}$       | Setup time, data and control signal to falling edge of ODCK (OCK_INV = low)    | ST = Low, $C_L=5\text{ pF}$<br>ST = High, $C_L=10\text{ pF}$ | 3.6  |            | ns                   |
| $t_{h1}$        | Hold time, data and control signal to falling edge of ODCK (OCK_INV = low)     | ST = Low, $C_L=5\text{ pF}$<br>ST = High, $C_L=10\text{ pF}$ | 3.6  |            | ns                   |
| $t_{su2}$       | Setup time, data and control signal to rising edge of ODCK (OCK_INV = high)    | ST = Low, $C_L=5\text{ pF}$<br>ST = High, $C_L=10\text{ pF}$ | 3.6  |            | ns                   |
| $t_{h2}$        | Hold time, data and control signal to rising edge of ODCK (OCK_INV = high)     | ST = Low, $C_L=5\text{ pF}$<br>ST = High, $C_L=10\text{ pF}$ | 3.1  |            | ns                   |
| $f_{ODCK}$      | ODCK frequency   | PIX = Low (1-PIX/CLK)  | 25   | 86         | MHz                  |
|                 |  | PIX = High (2-PIX/CLK)                                       | 12.5 | 43         |                      |
| ODCK duty-cycle |  |  | 40%  | 50%        | 60%                  |
| $t_{pd(PDL)}$   | Propagation delay time from <u>PD</u> low to Hi-Z outputs                      |  |      | 9          | ns                   |
| $t_{pd(PDOL)}$  | Propagation delay time from <u>PDO</u> low to Hi-Z outputs                     |  |      | 9          | ns                   |
| $t_{t(HSC)}$    | Transition time between DE transition to SCDT low <sup>*</sup>                 |  |      | 1e6        | $t_{pix}$            |
| $t_{t(FSC)}$    | Transition time between DE transition to SCDT high <sup>*</sup>                |  |      | 1024       | $t_{pix}$            |
| $t_{d(st)}$     | Delay time, ODCK latching edge to QE[23:0] data output                         | STAG = Low<br>Pixs = High                                    |      | 0.25       | $t_{pix}$            |

<sup>†</sup> Specified as ac parameter to include sensitivity to overshoot, undershoot and reflection.<sup>‡</sup>  $t_{bit}$  is 1/10 the pixel time,  $t_{pix}$ <sup>§</sup>  $t_{pix}$  is the pixel time defined as the period of the RxC input clock. The period of ODCK is equal to  $t_{pix}$  in 1-pixel/clock mode or  $2t_{pix}$  when in 2-pixel/clock mode.<sup>¶</sup> Measured differentially at 50% crossing using ODCK output clock as trigger.<sup>#</sup> Rise and fall times measured as time between 20% and 80% of signal amplitude.<sup>||</sup> Data and control signals are : QE[23:0], QO[23:0], DE, HSYNC, VSYNC and CTL[3:1]

★Link active or inactive is determined by amount of time detected between DE transitions. SCDT indicates link activity.

NOTE 6: By characterization

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**PARAMETER MEASUREMENT INFORMATION**

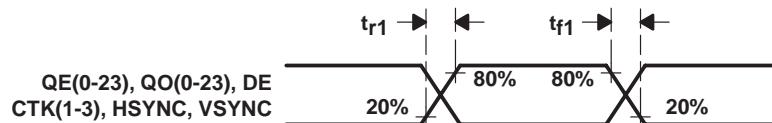


Figure 1. Rise and Fall Time of Data and Control Signals

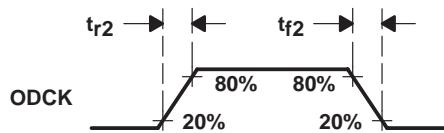


Figure 2. Rise and Fall Time of ODCK

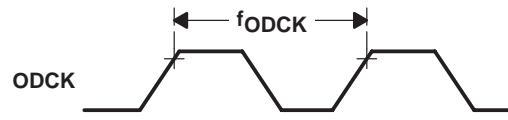


Figure 3. ODCK Frequency

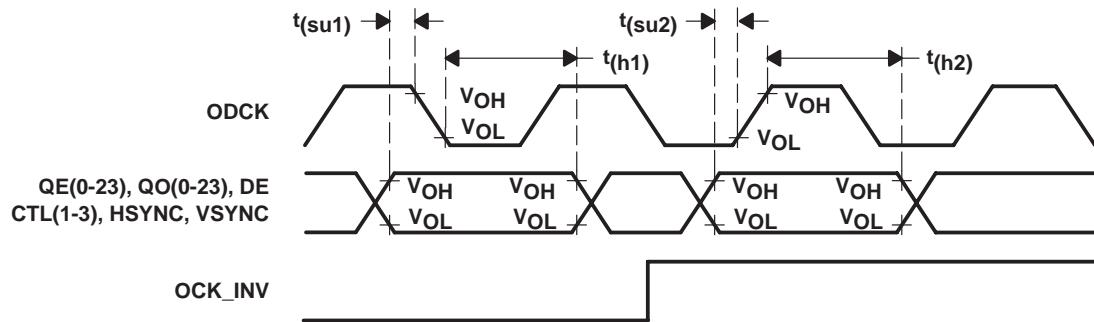


Figure 4. Data Setup and Hold Time to Rising and Falling Edge of ODCK

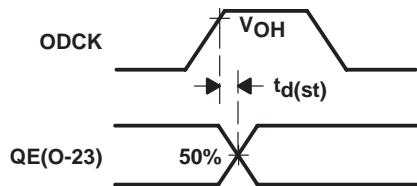


Figure 5. ODCK High to QE[23:0] Staggered Data Output

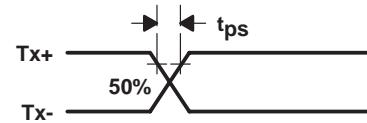


Figure 6. Analog Input Intra-Pair Differential Skew

## PARAMETER MEASUREMENT INFORMATION

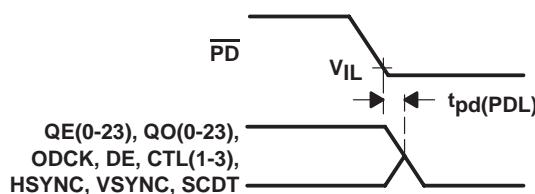
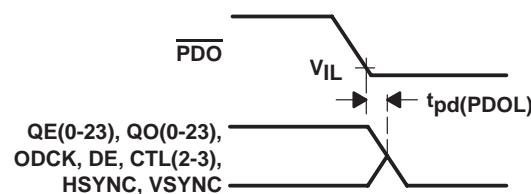
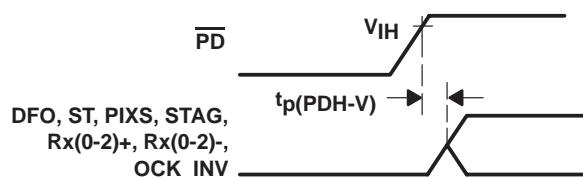
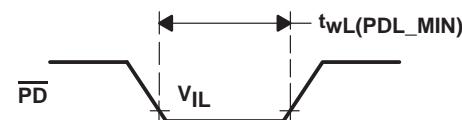
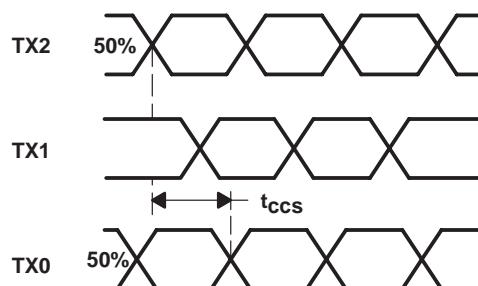
Figure 7. Delay From  $\overline{PD}$  Low to Hi-Z OutputsFigure 8. Delay From  $\overline{PDO}$  Low to Hi-Z OutputsFigure 9. Delay From  $\overline{PD}$  Low to High Before Inputs are ActiveFigure 10. Minimum Time  $\overline{PD}$  Low

Figure 11. Analog Input Channel-to-Channel Skew

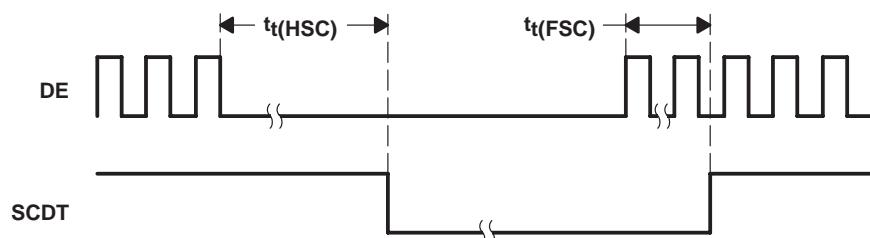


Figure 12. Time Between DE Transitions to SCDT Low and SCDT High

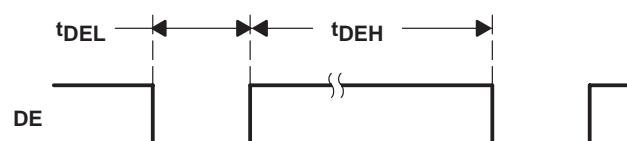


Figure 13. Minimum DE Low and Maximum DE High

# **TFP101, TFP101A**

## **TI PanelBus™ DIGITAL RECEIVER**

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### **detailed description**

#### **fundamental operation**

The TFP101/101A is a digital visual interface (DVI) compliant TMDS digital receiver that is used in digital flat panel display systems to receive and decode TMDS encoded RGB pixel data streams. In a digital display system a host, usually a PC or workstation, contains a TMDS compatible transmitter that receives 24 bit pixel data along with appropriate control signals and encodes them into a high-speed low-voltage differential serial bit stream fit for transmission over a twisted-pair cable to a display device. The display device, usually a flat-panel monitor, will require a TMDS compatible receiver like the TI TFP101/101A to decode the serial bit stream back to the same 24 bit pixel data and control signals that originated at the host. This decoded data can then be applied directly to the flat panel drive circuitry to produce an image on the display. Since the host and display can be separated by distances up to 5 meters or more, serial transmission of the pixel data is preferred. To support modern display resolutions up to SXGA a high bandwidth receiver with good jitter and skew tolerance is required.

#### **TMDS pixel data and control signal encoding**

TMDS stands for transition minimized differential signaling. Only one of two possible TMDS characters for a given pixel will be transmitted at a given time. The transmitter keeps a running count of the number of ones and zeros previously sent and transmits the character that will minimize the number of transitions and approximate a dc balance of the transmission line.

Three TMDS channels are used to receive RGB pixel data during active display time, DE = high. The same three channels also receive control signals, HSYNC, VSYNC, and user defined control signals CTL[3:1]. These control signals are received during inactive display or blanking-time. Blanking-time is when DE = low. The following table maps the received input data to appropriate TMDS input channel in a DVI compliant system.

| RECEIVED PIXEL DATA<br>ACTIVE DISPLAY DE = HIGH | INPUT CHANNEL       | OUTPUT PINS<br>(VALID FOR DE = HIGH) |
|---|---------------------|--------------------------------------|
| Red[7:0]  | Channel – 2 (Rx2 ±) | QE[23:16] QO[23:16]                  |
| Green[7:0]                                      | Channel – 1 (Rx1 ±) | QE[15:8] QO[15:8]                    |
| Blue[7:0]                                       | Channel – 0 (Rx0 ±) | QE[7:0] QO[7:0]                      |
| RECEIVED CONTROL DATA<br>BLANKING DE = LOW      | INPUT CHANNEL       | OUTPUT PINS<br>(VALID FOR DE = LOW)  |
| CTL[3:2]  | Channel – 2 (Rx2 ±) | CTL[3:2]                             |
| CTL[1: 0] (see Note 6)                          | Channel – 1 (Rx1 ±) | CTL1                                 |
| HSYNC, VSYNC                                    | Channel – 0 (Rx0 ±) | HSYNC, VSYNC                         |

NOTE 7: Some TMDS transmitters transmit a CTL0 signal. The TFP101/101A decodes and transfers CTL[3:1] and ignores CTL0 characters. CTL0 is not available as a TFP101/101A output.

The TFP101/101A discriminates between valid pixel TMDS characters and control TMDS characters to determine the state of active display versus blanking, i.e., state of DE.

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## **detailed description (continued)**

### **TFP101/101A clocking and data synchronization**

The TFP101/101A receives a clock reference from the DVI transmitter that has a period equal to the pixel time, Tpix. The frequency of this clock is also referred to as the pixel rate. Since the TMDS encoded data on Rx[2:0] contains 10 bits per 8 bit pixel it follows that the Rx[2:0] serial bit rate is 10 times the pixel rate. For example, the required pixel rate to support an XGA resolution with 60 Hz refresh rate is 65 MHz. The TMDS serial bit rate is 10x the pixel rate or 650 Mb/s. Due to the transmission of this high-speed digital bit stream, on three separate channels (or twisted-pair wires) of long distances (3-5 meters), phase synchronization between the data streams and the input reference clock is not guaranteed. In addition, skew between the three data channels is common. The TFP101/101A uses a 4x oversampling scheme of the input data streams to achieve reliable synchronization with up to 1-Tpix channel-to-channel skew tolerance. Accumulated jitter on the clock and data lines due to reflections and external noise sources is also typical of high speed serial data transmission, hence the TFP101/101A's design for high jitter tolerance.

The input clock to the TFP101/101A is conditioned by a phase-locked-loop (PLL) to remove high frequency jitter from the clock. The PLL provides four 10x clock outputs of different phase to locate and sync the TMDS data streams (4x oversampling). During active display the pixel data is encoded to be transition minimized, whereas in blank, the control data is encoded to be transition maximized. A DVI compliant transmitter is required to transmit in blank for a minimum period of time, 128-Tpix, to ensure sufficient time for data synchronization when the receiver sees a transition maximized code. Synchronization during blank, when the data is transition maximized, ensures reliable data bit boundary detection. Phase synchronization to the data streams is unique for each of the three input channels and is maintained as long as the link remains active.

### **TFP101/101A TMDS input levels and input impedance matching**

The TMDS inputs to the TFP101/101A receiver have a fixed single-ended termination to AV<sub>DD</sub>. The TFP101/101A is internally optimized using a laser trim process to precisely fix the impedance at 50 Ω. The device will function normally with or without a resistor on the EXT\_RES pin, so it remains drop-in compatible with current sockets. The fixed impedance eliminates the need for an external resistor while providing optimum impedance matching to standard 50-Ω DVI cables.

Figure 14 shows a conceptual schematic of a DVI transmitter and TFP101/101A receiver connection. A transmitter drives the twisted pair cable via a current source, usually achieved with an open drain type output driver. The internal resistor, which is matched to the cable impedance, at the TFP101/101A input provides a pullup to AV<sub>DD</sub>. Naturally, when the transmitter is disconnected and the TFP101/101A DVI inputs are left unconnected, the TFP101/101A receiver inputs pullup to AV<sub>DD</sub>. The single ended differential signal and full differential signal is shown in Figure 15. The TFP101/101A is designed to respond to differential signal swings ranging from 150 mV to 1.56 V with common mode voltages ranging from (AV<sub>DD</sub>-300 mV) to (AV<sub>DD</sub>-37 mV).

# TFP101, TFP101A

## TI PanelBus™ DIGITAL RECEIVER

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### TFP101/101A TMDS input levels and input impedance matching (continued)

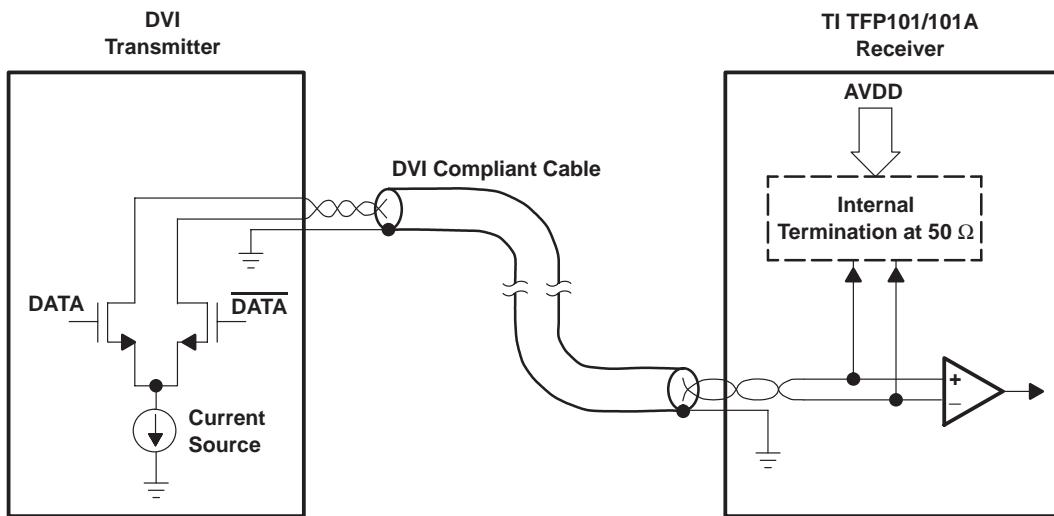


Figure 14. TMDS Differential Input and Transmitter Connection



Figure 15. TMDS Inputs

### TFP101A incorporates HSYNC jitter immunity

Several DVI transmitters available in the market introduce jitter on the transmitted HSYNC and VSYNC signals during the TMDS encryption process. The HSYNC signal can shift by one pixel position (one clock) from nominal in either direction, resulting in up to two cycles of HSYNC shift. This jitter carries through to the DVI receiver, and if the position of HSYNC shifts continuously, the receiver can lose track of the input timing and pixel noise will occur on the display. For this reason, a DVI compliant receiver with HSYNC jitter immunity should be used in all displays that could be connected to host PCs with transmitters that have this HSYNC jitter problem.

The TFP101A integrates HSYNC regeneration circuitry that provides a seamless interface to these noncompliant transmitters. The position of the data enable (DE) signal is always fixed in relation to data, irrespective of the location of HSYNC. The TFP101A receiver uses the DE and clock signals recreate stable vertical and horizontal sync signals. The circuit filters the HSYNC output of the receiver, and HSYNC is shifted to the nearest eighth bit boundary, producing a stable output with respect to data, as shown in Figure 16. This will ensure accurate data synchronization at the input of the display timing controller.

This HSYNC regeneration circuit is transparent to the monitor and need not be removed even if the transmitted HSYNC is stable. For example, the PanelBus line of DVI 1.0 compliant transmitters, such as the TFP6422 and TFP420, do not have the HSYNC jitter problem. The TFP101A will operate correctly with either compliant or noncompliant transmitters. In contrast, the TFP101 is ideal for customers who have control over the transmit portion of the design such as bundled system manufacturers and for internal monitor use (the DVI connection between monitor and panel modules).

## TFP101A incorporates HSYNC jitter immunity (continued)

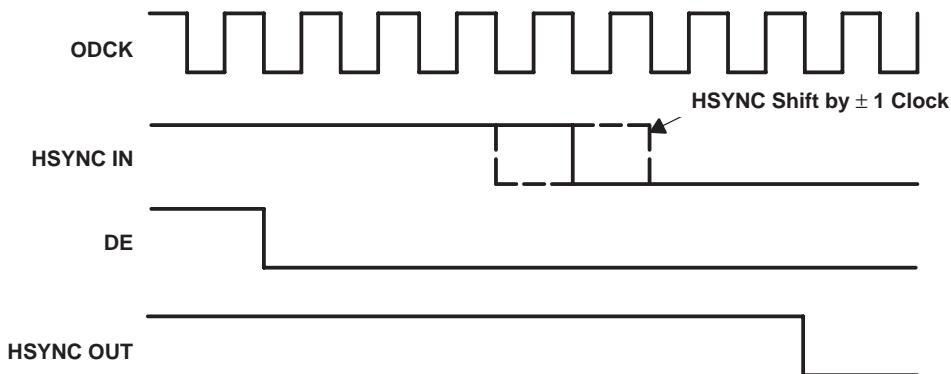


Figure 16. HSYNC Regeneration Timing Diagram

## TFP101/101A modes of operation

The TFP101/101A provides systems design flexibility and value by providing the system designer with configurable options or modes of operation to support varying system architectures. The following table outlines the various panel modes that can be supported along with appropriate external control pin settings.

| PANEL              | PIXEL RATE  | ODCK LATCH EDGE | ODCK      | DFO | PIXS | OCLK_INV |
|--------------------|-------------|-----------------|-----------|-----|------|----------|
| TFT or 16-bit DSTN | 1 pix/clock | Falling         | Free run  | 0   | 0    | 0        |
| TFT or 16-bit DSTN | 1 pix/clock | Rising          | Free run  | 0   | 0    | 1        |
| TFT                | 2 pix/clock | Falling         | Free run  | 0   | 1    | 0        |
| TFT                | 2 pix/clock | Rising          | Free run  | 0   | 1    | 1        |
| 24-bit DSTN        | 1 pix/clock | Falling         | Gated low | 1   | 0    | 0        |
| NONE               | 1 pix/clock | Rising          | Gated low | 1   | 0    | 1        |
| 24-bit DSTN        | 2 pix/clock | Falling         | Gated low | 1   | 1    | 0        |
| 24-bit DSTN        | 2 pix/clock | Rising          | Gated low | 1   | 1    | 1        |

## TFP101/101A output driver configurations

The TFP101/101A provides flexibility by offering various output driver features that can be used to optimize power consumption, ground-bounce and power-supply noise. The following sections outline the output driver features and their effects.

**Output driver power down** (PDO = low), Pulling PDO low will place all the output drivers, except CTL1 and SCDT, into a high-impedance state. The SCDT output which indicates link-disabled or link-inactive can be tied directly to the PDO input to disable the output drivers when the link is inactive or when the cable is disconnected. An internal pullup on the PDO pin will default the TFP101/101A to the normal nonpower down output drive mode if left unconnected.

**Drive Strength** (ST = high for high drive strength, ST=low for low drive strength.) The TFP101/101A allows for selectable output drive strength on the data, control and ODCK outputs. See the dc specifications table for the values of  $I_{OH}$  and  $I_{OL}$  current drives for a given ST state. The high output strength offers approximately two times the drive as the low output drive strength.

# TFP101, TFP101A

## TI *PanelBus*<sup>TM</sup> DIGITAL RECEIVER

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### TFP101/101A output driver configurations (continued)

**Time Staggered Pixel Output.** This option works only in conjunction with the 2-pixel/clock mode (PIXS = high). Setting STAG = low will time stagger the even and odd pixel output so as to reduce the amount of instantaneous current surge from the power supply. Depending on the PCB layout and design this can help reduce the amount of system ground bounce and power supply noise. The time stagger is such that in 2-pixel/clock mode the even pixel is delayed from the latching edge of ODCK by 0.25 Tcip. (Tcip is the period of ODCK. The ODCK period is 2Tpix when in 2-pixel/clock mode.)

Depending on system constraints of output load, pixel rate, panel input architecture and board cost the TFP101/101A drive strength and staggered pixel options allow flexibility to reduce system power-supply noise, ground bounce and EMI.

**Power Management.** The TFP101/101A offers several system power management features.

The output driver power down (PDO = low) is an intermediate mode which offers several uses. During this mode, all output drivers except SCDT and CTL1 are driven to a high impedance state while the rest of the device circuitry remains active

The TFP101/101A power down (PD = low) is a complete power down in that it powers down the digital core, the analog circuitry, and output drivers. All output drivers are placed into a Hi-z state. All inputs are disabled except for the PD input. The TFP101/101A will not respond to any digital or analog inputs until PD is pulled high.

Both PDO and PD have internal pullups so if left unconnected they will default the TFP101/101A to normal operating modes.

**Sync Detect.** The TFP101/101A offers an output, SCDT to indicate link activity. The TFP101/101A monitors activity on DE to determine if the link is active. When 1 million (1e6) pixel clock periods pass without a transition on DE, the TFP101/101A considers the link inactive and SCDT is driven low. While SCDT is low, if two DE transitions are detected within 1024 pixel clock periods, the link will be considered active and SCDT is pulled high.

SCDT can be used to signal a system power management circuit to initiate a system power down when the link is considered inactive. The SCDT can also be tied directly to the TFP101/101A PDO input to power down the output drivers when the link is inactive. It is not recommended to use the SCDT to drive the PD input since, once in complete power-down, the analog inputs are ignored and the SCDT state will not change. An external system power management circuit to drive PD is preferred.

**TI PowerPAD™ 100-TQFP package**

The TFP101/101A is packaged in TI's thermally enhanced PowerPAD™ 100TQFP packaging. The PowerPAD™ package is a 14 mm × 14 mm × 1 mm TQFP outline with 0.5mm lead-pitch. The PowerPAD™ package has a specially designed die mount pad that offers improved thermal capability over typical TQFP packages of the same outline. The TI 100-TQFP PowerPAD™ package offers a back-side solder plane that connects directly to the die mount pad for enhanced thermal conduction. Soldering the back side of the TFP101/101A to the application board is not required thermally as the device power dissipation is well within the package capability when not soldered.

Soldering the back side of the device to the PCB ground plane is recommended for elctrical considerations. Since the die pad is electrically connected to the chip substrate and hence chip ground, connection of the PowerPAD back side to a PCB ground plane will help to improve EMI, ground bounce, and power supply noise performance.

Table 1 outlines the thermal properties of the TI 100-TQFP PowerPAD™ package. The 100-TQFP non-PowerPAD™ package is included only for reference.

**Table 1. TI 100-TQFP (14 × 14 × 1 mm)/0.5 mm Lead Pitch**

| PARAMETER                      | WITHOUT<br>PowerPAD™ | PowerPAD™<br>NOT CONNECTED TO PCB<br>THERMAL PLANE | PowerPAD™<br>CONNECTED TO PCB<br>THERMAL PLANET |
|--------------------------------|----------------------|--|---|
| Theta-JA†,‡                    | 45°C/W               | 27.3°C/W   | 17.3°C/W  |
| Theta-JC†,‡                    | 3.11°C/W             | 0.12°C/W   | 0.12°C/W  |
| Maximum power dissipation†,‡,§ | 1.6 W                | 2.7 W  | 4.3 W   |

† Specified with 2 oz. Cu PCB plating.

‡ Airflow is at 0 LFM (no airflow)

§ Measured at ambient temperature,  $T_A = 70^\circ\text{C}$ .

**PACKAGING INFORMATION**

| Orderable Device | Status<br>(1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan<br>(2)         | Lead/Ball Finish<br>(6) | MSL Peak Temp<br>(3) | Op Temp (°C) | Device Marking<br>(4/5) | Samples |
|------------------|---------------|--------------|-----------------|------|-------------|-------------------------|-------------------------|----------------------|--------------|-------------------------|---------|
| TFP101APZP       | NRND          | HTQFP        | PZP             | 100  | 90          | Green (RoHS & no Sb/Br) | NIPDAU                  | Level-3-260C-168 HR  | 0 to 70      | TFP101APZP              |         |

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

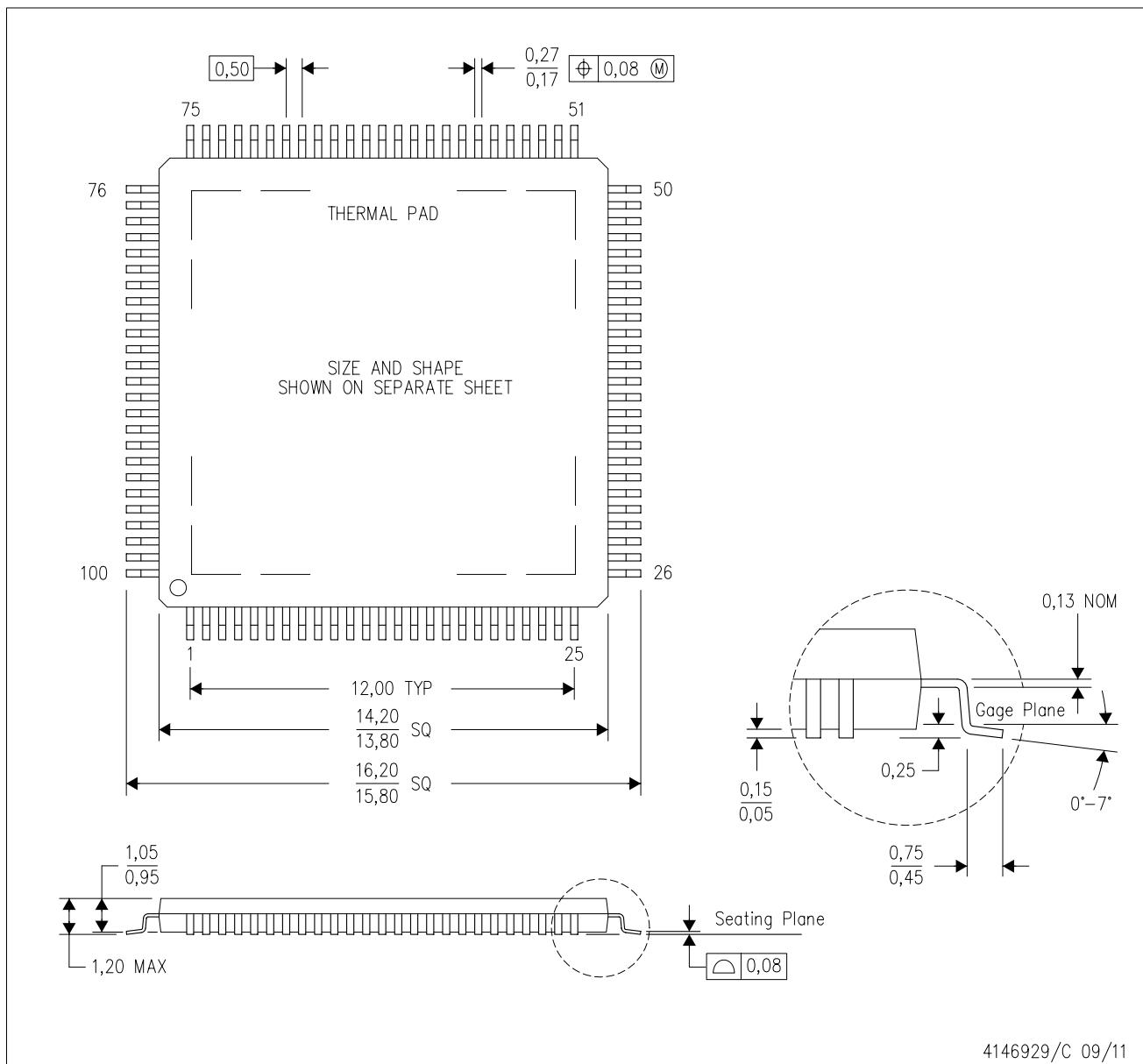
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## MECHANICAL DATA

PZP (S-PQFP-G100)

## PowerPAD™ PLASTIC QUAD FLATPACK



4146929/C 09/11

NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
- F. Falls within JEDEC MS-026

PowerPAD is a trademark of Texas Instruments.

# THERMAL PAD MECHANICAL DATA

PZP (S-PQFP-G100)

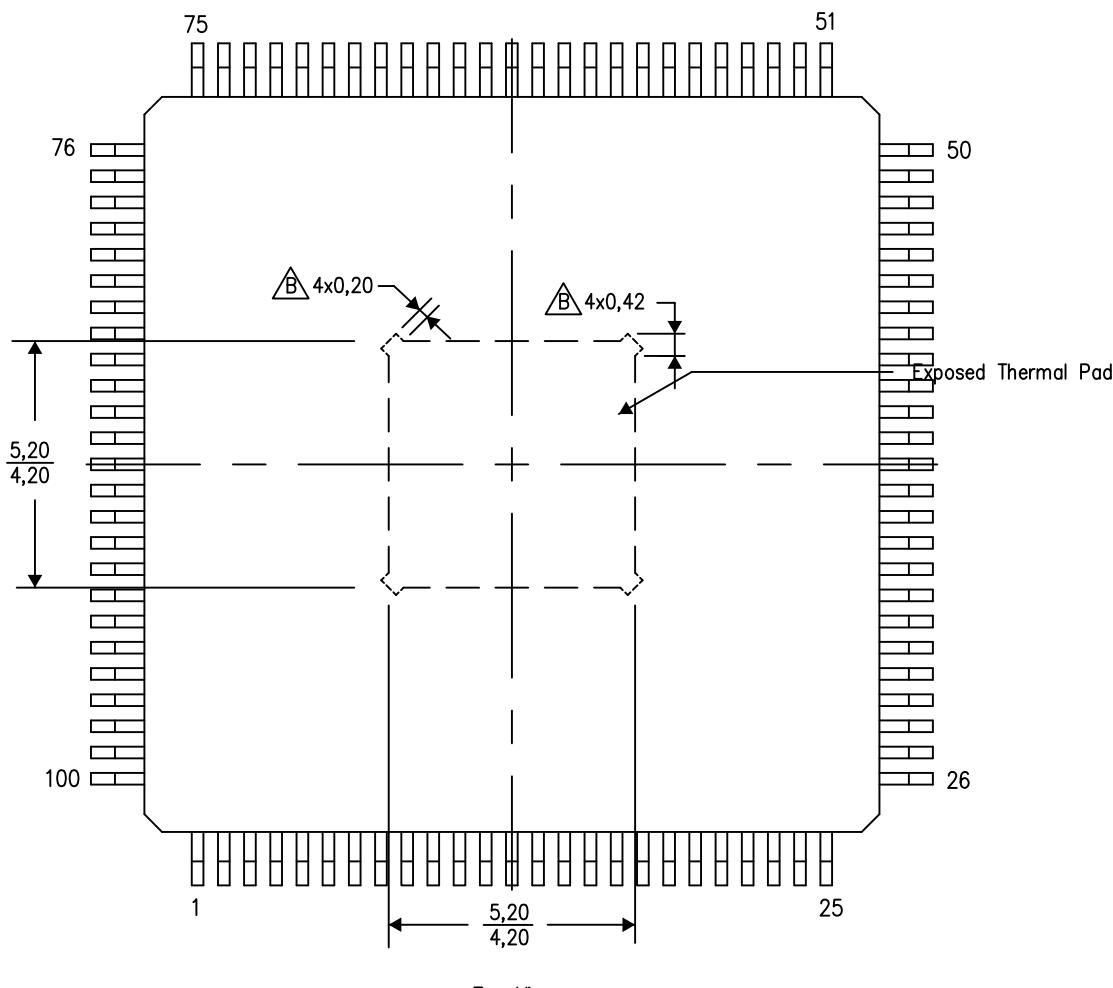
PowerPAD™ PLASTIC QUAD FLATPACK

## THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at [www.ti.com](http://www.ti.com).

The exposed thermal pad dimensions for this package are shown in the following illustration.



NOTE: A. All linear dimensions are in millimeters

 Tie strap features may not be present.

PowerPAD is a trademark of Texas Instruments

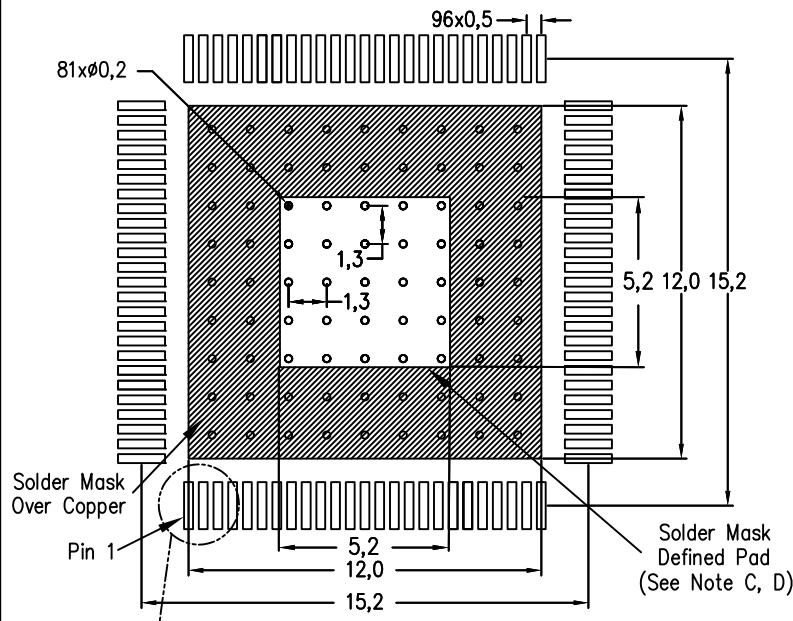
4206333-2/L 05/14

## LAND PATTERN DATA

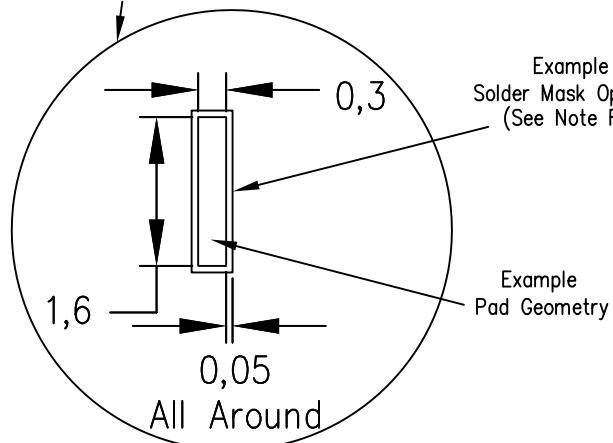
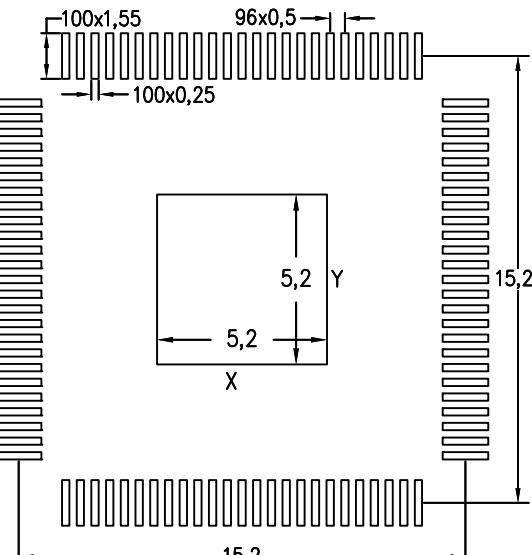
PZP (S-PQFP-G100)

PowerPAD™ PLASTIC QUAD FLATPACK

Example Board Layout  
Via pattern and copper area under solder mask  
may vary depending on layout constraints



Stencil Openings based on a stencil  
thickness of .127mm (.005inch).  
Reference table below for other  
solder stencil thicknesses



| Center Power Pad Solder Stencil Opening |     |     |
|---|-----|-----|
| Stencil Thickness                       | X   | Y   |
| 0.1mm                                   | 5.6 | 5.6 |
| 0.127mm                                 | 5.2 | 5.2 |
| 0.152mm                                 | 4.9 | 4.9 |
| 0.178mm                                 | 4.6 | 4.6 |

4209826-5/C 01/13

- NOTES:
- All linear dimensions are in millimeters.
  - This drawing is subject to change without notice.
  - Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
  - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>. Publication IPC-7351 is recommended for alternate designs.
  - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
  - Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

PowerPAD is a trademark of Texas Instruments.

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