

# SiGe:C Low Noise Amplifier MMIC for GPS, GLONASS, Galileo and Compass

Rev. 1 — 24 December 2013

Product data sheet

## 1. Product profile

#### 1.1 General description

The BGU8010 is a Low Noise Amplifier (LNA) for GNSS receiver applications, available in a small plastic 6-pin extremely thin leadless package. The BGU8010 requires one external matching inductor and one external decoupling capacitor.

The BGU8010 adapts itself to the changing environment resulting from co-habitation of different radio systems in modern cellular handsets. It has been designed for low power consumption and optimal performance when jamming signals from co-existing cellular transmitters are present. At low jamming power levels it delivers 16.1 dB gain at a noise figure of 0.85 dB. During high jamming power levels, resulting for example from a cellular transmit burst, it temporarily increases its bias current to improve sensitivity.

#### 1.2 Features and benefits

- Covers full GNSS L1 band, from 1559 MHz to 1610 MHz
- Noise figure (NF) = 0.85 dB
- Gain 16.1 dB
- High input 1 dB compression point of –9 dBm
- High out of band IP3<sub>i</sub> of 3 dBm
- Supply voltage 1.5 V to 3.1 V
- Optimized performance at very low supply current of 3.1 mA
- Power-down mode current consumption < 1 μA</p>
- Integrated temperature stabilized bias for easy design
- Requires only one input matching inductor and one supply decoupling capacitor
- Input and output DC decoupled
- ESD protection on all pins (HBM > 2 kV)
- Integrated matching for the output
- Available in a 6-pins leadless package 1.1 mm  $\times$  0.9 mm  $\times$  0.47 mm; 0.4 mm pitch: SOT1230
- 180 GHz transit frequency SiGe:C technology
- Moisture sensitivity level of 1

## 1.3 Applications

■ LNA for GPS, GLONASS, Galileo and Compass (BeiDou) in smart phones, feature phones, tablets, digital still cameras, digital video cameras, RF front-end modules, complete GNSS modules and personal health applications.



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#### 1.4 Quick reference data

Table 1. Quick reference data

f = 1575 MHz;  $V_{CC}$  = 2.85 V;  $P_i$  < -40 dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 6.8 nH inductor, see Figure 1; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
$V_{CC}$	supply voltage			1.5	-	3.1	V
I <sub>CC</sub>	supply current			-	3.2	-	mΑ
Gp	power gain	no jammer		-	16.1	-	dB
NF	noise figure	no jammer	[1]	-	0.85	-	dB
P <sub>i(1dB)</sub>	input power at 1 dB gain compression			-	-9	-	dBm
IP3 <sub>i</sub>	input third-order intercept point		[2]	-	3	-	dBm
			[3]	-	0	-	dBm

<sup>[1]</sup> PCB losses are subtracted.

## 2. Pinning information

Table 2. Pinning

Tubic	z. i iiiiiiig		
Pin	Description	Simplified outline	Graphic symbol
1	GND		
2	V <sub>CC</sub>	4 3	6 2
3	RF_OUT		5—3
4	GND_RF	5 2	<u> </u>
5	RF_IN		1 4 aaa-006408
6	ENABLE	61	
		Transparent top view	

## 3. Ordering information

Table 3. Ordering information

Type number	Package				
	Name	Description	Version		
BGU8010	XSON6	plastic very thin small outline package; no leads; 6 terminals; body 1.1 $\times$ 0.9 $\times$ 0.47 mm	SOT1230		
OM7822	EVB	BGU8010 evaluation board, MMIC only	-		

## 4. Marking

Table 4. Marking codes

Type number	Marking code
BGU8010	В

<sup>[2]</sup>  $f_1 = 1713 \text{ MHz}$ ;  $f_2 = 1851 \text{ MHz}$ ,  $P_i = -20 \text{ dBm per carrier}$ .

<sup>[3]</sup>  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz;  $P_i = -20$  dBm at  $f_1$ ;  $P_i = -65$  dBm at  $f_2$ .

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## 5. Limiting values

#### Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Absolute Maximum Ratings are given as Limiting Values of stress conditions during operation, that must not be exceeded under the worst probable conditions.

Symbol	Parameter	Conditions		Min	Max	Unit
$V_{CC}$	supply voltage		<u>[1]</u>	-0.5	+5.0	V
V <sub>I(ENABLE)</sub>	input voltage on pin ENABLE	V <sub>I(ENABLE)</sub> < V <sub>CC</sub> + 0.6 V	[1][2]	-0.5	+5.0	V
V <sub>I(RF_IN)</sub>	input voltage on pin RF_IN	DC, $V_{I(RF_IN)} < V_{CC} + 0.6 V$	[1][2][3]	-0.5	+5.0	V
V <sub>I(RF_OUT)</sub>	input voltage on pin RF_OUT	DC, $V_{I(RF\_OUT)} < V_{CC} + 0.6 V$	[1][2][3]	-0.5	+5.0	V
Pi	input power	f =1575 MHz	<u>[1]</u>	-	10	dBm
P <sub>tot</sub>	total power dissipation	$T_{sp} \le 130  ^{\circ}C$		-	55	mW
T <sub>stg</sub>	storage temperature			-65	+150	°C
Tj	junction temperature			-	150	°C
V <sub>ESD</sub>	electrostatic discharge voltage	Human Body Model (HBM) According to ANSI/ESDA/JEDEC standard JS-001		-	±2	kV
		Charged Device Model (CDM) According to JEDEC standard JESD22-C101		-	±1	kV

<sup>[1]</sup> Stressed with pulses of 200 ms in duration, with application circuit as in Figure 1.

## 6. Recommended operating conditions

Table 6. Operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{CC}$	supply voltage		1.5	-	3.1	V
T <sub>amb</sub>	ambient temperature		-40	+25	+85	°C
V <sub>I(ENABLE)</sub>	input voltage on pin ENABLE	OFF state	-	-	0.3	V
		ON state	8.0	-	-	V

#### 7. Thermal characteristics

Table 7. Thermal characteristics

Symbol	Parameter	Conditions	Тур	Unit
$R_{th(j-sp)}$	thermal resistance from junction to solder point		225	K/W

<sup>[2]</sup> Warning: due to internal ESD diode protection, the applied DC voltage shall not exceed V<sub>CC</sub> + 0.6 V and shall not exceed 5.0 V in order to avoid excess current.

<sup>[3]</sup> The RF input and RF output are AC coupled through internal DC blocking capacitors.

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#### 8. Characteristics

Table 8. Characteristics at  $V_{CC} = 1.8 \text{ V}$ 

f = 1575 MHz;  $V_{CC}$  = 1.8 V;  $V_{I(ENABLE)} \ge 0.8$  V;  $P_i$  < -40 dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 8.2 nH inductor, see Figure 1; unless otherwise specified.

Symbol	Parameter	Conditions	ı	Min	Тур	Max	Unit
I <sub>CC</sub>	supply current	$V_{I(ENABLE)} \ge 0.8 \text{ V}$					
		$P_i < -40 \text{ dBm}$		-	3.1	-	mΑ
		$P_i = -20 \text{ dBm}$		-	5.0	-	mΑ
		$V_{I(ENABLE)} \le 0.3 \text{ V}$		-	-	1	μΑ
G <sub>p</sub>	power gain	no jammer		-	15.8	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$		-	15.0	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$		-	16.5	-	dB
RLin	input return loss	$P_i < -40 \text{ dBm}$		-	12	-	dB
		$P_i = -20 \text{ dBm}$		-	14	-	dB
RL <sub>out</sub>	output return loss	$P_i < -40 \text{ dBm}$		-	12	-	dB
		$P_i = -20 \text{ dBm}$		-	12	-	dB
ISL	isolation			-	24	-	dB
NF	noise figure	$P_i = -40$ dBm, no jammer	<u>[1]</u> .	-	0.85	-	dB
		P <sub>i</sub> = -40 dBm, no jammer	[2]	-	0.90	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	[2]	-	1.3	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	[2]	-	1.5	-	dB
$P_{i(1dB)} \\$	input power at 1 dB gain compression		-	-	-12	-	dBm
IP3 <sub>i</sub>	input third-order		[3]	-	1	-	dBm
	intercept point		[4]	-	0	-	dBm
t <sub>on</sub>	turn-on time	time from $V_{I(\mbox{\footnotesize{ENABLE}})}$ ON, to 90 % of the gain	-	-	-	2	μS
t <sub>off</sub>	turn-off time	time from $V_{I(\mbox{\footnotesize{ENABLE}})}$ OFF, to 10 % of the gain	•	•	-	1	μS

<sup>[1]</sup> PCB losses are subtracted

<sup>[2]</sup> Including PCB losses

<sup>[3]</sup>  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz,  $P_i = -20$  dBm per carrier.

<sup>[4]</sup>  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz;  $P_i = -20$  dBm at  $f_1$ ;  $P_i = -65$  dBm at  $f_2$ .

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Table 9. Characteristics at V<sub>CC</sub> = 2.85 V

f = 1575 MHz;  $V_{CC}$  = 2.85 V;  $V_{I(ENABLE)} \ge 0.8$  V;  $P_i < -40$  dBm;  $T_{amb}$  = 25 °C; input matched to 50  $\Omega$  using a 8.2 nH inductor, see Figure 1; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
I <sub>CC</sub>	supply current	$V_{I(ENABLE)} \ge 0.8 \text{ V}$					
		$P_i < -40 \text{ dBm}$		-	3.2	-	mΑ
		$P_i = -20 \text{ dBm}$		-	5.0	-	mΑ
		V <sub>I(ENABLE)</sub> ≤ 0.3 V		-	-	1	μΑ
G <sub>p</sub>	power gain	no jammer		-	16.1	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$		-	15.2	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$		-	16.5	-	dB
$RL_{in}$	input return loss	$P_i < -40 \text{ dBm}$		-	13	-	dB
		$P_i = -20 \text{ dBm}$		-	15	-	dB
RLout	output return loss	$P_i < -40 \text{ dBm}$		-	12	-	dB
		$P_i = -20 \text{ dBm}$		-	12	-	dB
ISL	isolation			-	24	-	dB
NF	noise figure	P <sub>i</sub> = −40 dBm, no jammer	[1]	-	0.85	-	dB
		P <sub>i</sub> = -40 dBm, no jammer	[2]	-	0.90	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	[2]	-	1.3	-	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	[2]	-	1.5	-	dB
$P_{i(1dB)}\\$	input power at 1 dB gain compression			-	-9	-	dBm
IP3 <sub>i</sub>	input third-order		[3]	-	3	-	dBm
	intercept point		[4]	-	0	-	dBm
t <sub>on</sub>	turn-on time	time from $V_{I(\mbox{\footnotesize{ENABLE}})}$ ON, to 90 % of the gain		-	-	2	μS
t <sub>off</sub>	turn-off time	time from $V_{I(\mbox{\footnotesize{ENABLE}})}$ OFF, to 10 % of the gain		-	-	1	μS

<sup>[1]</sup> PCB losses are subtracted

<sup>[2]</sup> Including PCB losses

<sup>[3]</sup>  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz,  $P_i = -20$  dBm per carrier.

<sup>[4]</sup>  $f_1 = 1713$  MHz;  $f_2 = 1851$  MHz;  $P_i = -20$  dBm at  $f_1$ ;  $P_i = -65$  dBm at  $f_2$ .

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## 9. Application information

#### 9.1 GNSS LNA

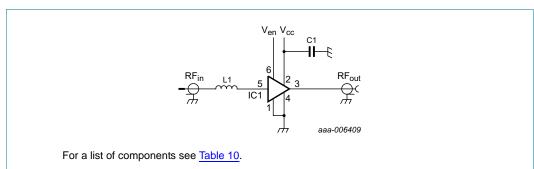


Fig 1. Schematics GNSS LNA evaluation board

Table 10. List of components

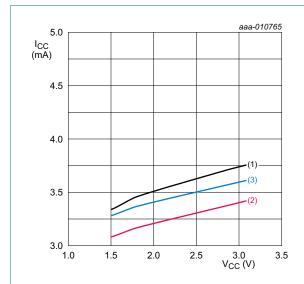
For schematics see Figure 1.

Component	Description	Value	Remarks
C1	decoupling capacitor	1 nF	
IC1	BGU8010	-	NXP
L1	high quality matching inductor	8.2 nH	Murata LQW15A

See application note AN11336 for details.

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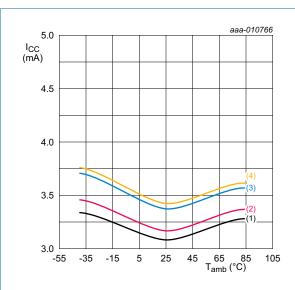
#### 9.2 Graphs



 $P_i = -45 \text{ dBm}.$ 

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

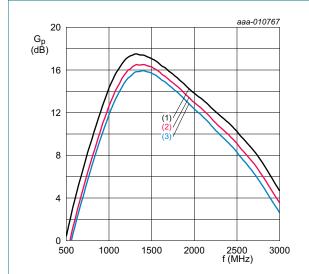




 $P_i = -45 \text{ dBm}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

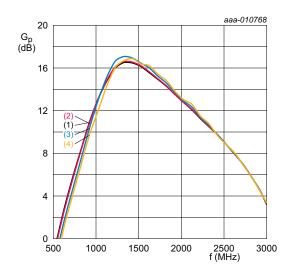
Fig 3. Supply current as a function of ambient temperature; typical values



 $P_i = -45 \text{ dBm}$ ;  $V_{CC} = 1.8 \text{ V}$ .

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 4. Power gain as a function of frequency; typical values

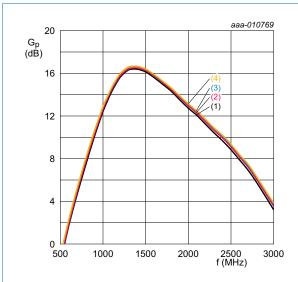


 $T_{amb} = 25 \, ^{\circ}C; \, V_{CC} = 1.8 \, V.$ 

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

Fig 5. Power gain as a function of frequency; typical values

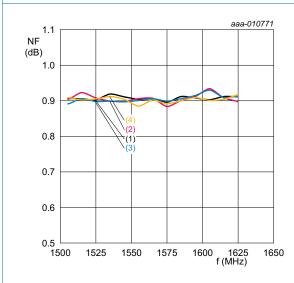
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 $P_i = -45 \text{ dBm}; T_{amb} = 25 \text{ }^{\circ}\text{C}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

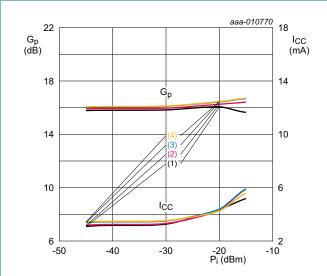
Fig 6. Power gain as a function of frequency; typical values



T<sub>amb</sub> = 25 °C; no jammer, including PCB losses.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

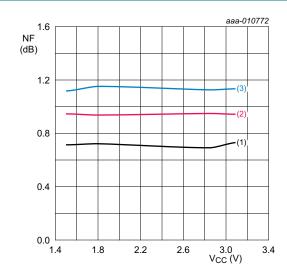
Fig 8. Noise figure as a function of frequency; typical values



f = 1575 MHz;  $T_{amb} = 25 \,^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 7. Power gain and supply current as function of input power; typical values

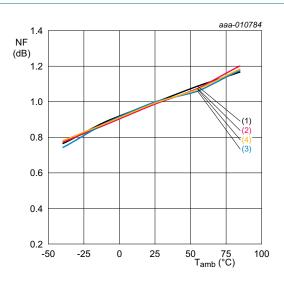


f = 1575 MHz, no jammer, including PCB losses.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 9. Noise figure as a function of supply voltage; typical values

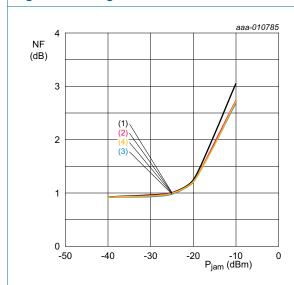
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f = 1575 MHz; no jammer, including PCB losses.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

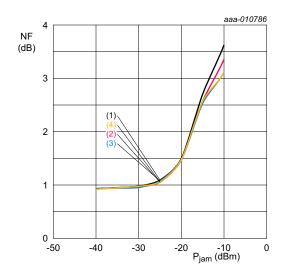
Fig 10. Noise figure as a function of ambient temperature; typical values



 $f_{jam}$  = 850 MHz;  $T_{amb}$  = 25 °C; f = 1575 MHz; including PCB losses.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 11. Noise figure as a function of jamming power; typical values

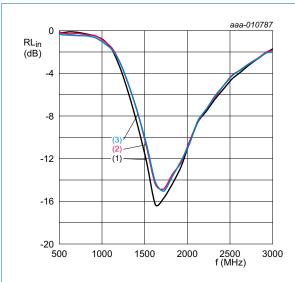


 $f_{jam}$  = 1850 MHz;  $T_{amb}$  = 25 °C; f = 1575 MHz; including PCB losses.

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 12. Noise figure as a function of jamming power; typical values

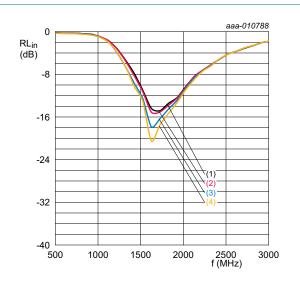
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$$P_i = -45 \text{ dBm}; V_{CC} = 1.8 \text{ V}.$$

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

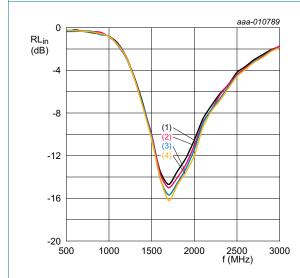
Fig 13. Input return loss as a function of frequency; typical values



$$T_{amb} = 25 \, ^{\circ}C; \, V_{CC} = 1.8 \, V.$$

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

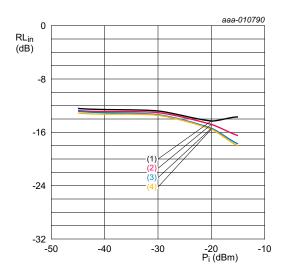
Fig 14. Input return loss as a function of frequency; typical values



 $P_i = -45 \text{ dBm}$ ;  $T_{amb} = 25 \text{ }^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 15. Input return loss as a function of frequency; typical values

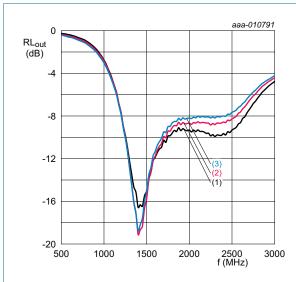


 $f = 1575 \text{ MHz}; T_{amb} = 25 \,^{\circ}\text{C}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 16. Input return loss as a function of input power; typical values

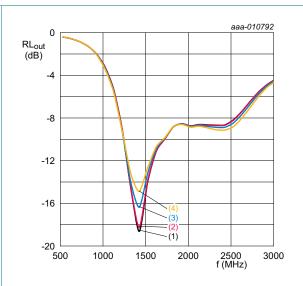
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 $P_i = -45 \text{ dBm}; V_{CC} = 1.8 \text{ V}.$ 

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

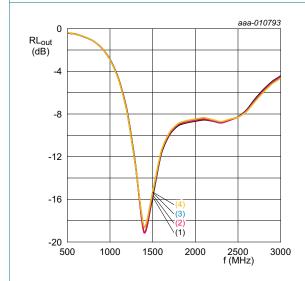
Fig 17. Output return loss as a function of frequency; typical values



 $T_{amb} = 25 \, ^{\circ}C; \, V_{CC} = 1.8 \, V.$ 

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

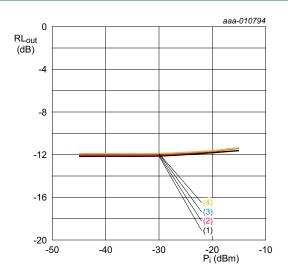
Fig 18. Output return loss as a function of frequency; typical values



 $P_i = -45 \text{ dBm}; T_{amb} = 25 \,^{\circ}\text{C}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 19. Output return loss as a function of frequency; typical values

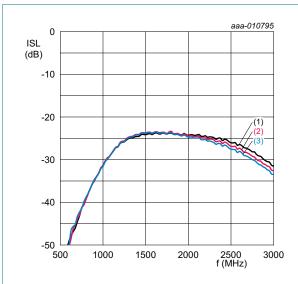


 $f = 1575 \text{ MHz}; T_{amb} = 25 \,^{\circ}\text{C}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 20. Output return loss as a function of input power; typical values

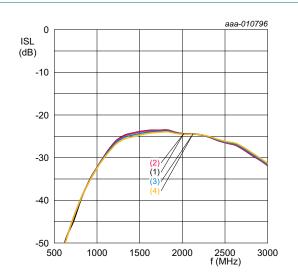
#### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass



$$P_i = -45 \text{ dBm}; V_{CC} = 1.8 \text{ V}.$$

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

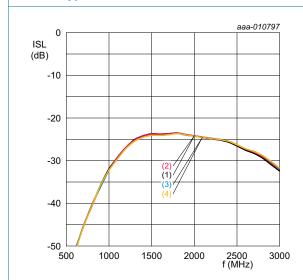
Fig 21. Isolation as a function of frequency; typical values



$$T_{amb} = 25 \, ^{\circ}C; \, V_{CC} = 1.8 \, V.$$

- (1)  $P_i = -45 \text{ dBm}$
- (2)  $P_i = -30 \text{ dBm}$
- (3)  $P_i = -20 \text{ dBm}$
- (4)  $P_i = -15 \text{ dBm}$

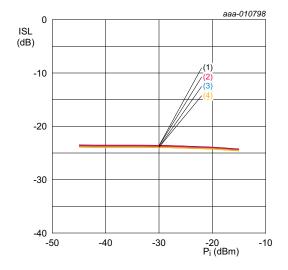
Fig 22. Isolation as a function of frequency; typical values



 $P_i = -45 \text{ dBm}$ ;  $T_{amb} = 25 \text{ }^{\circ}\text{C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 23. Isolation as a function of frequency; typical values

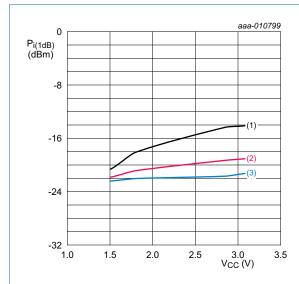


 $f = 1575 \text{ MHz}; T_{amb} = 25 \,^{\circ}\text{C}.$ 

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 24. Isolation as a function of input power; typical values

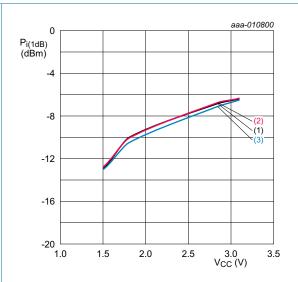
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f = 850 MHz.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

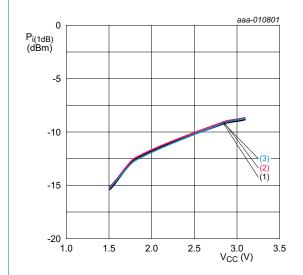
Fig 25. Input power at 1 dB gain compression as a function of supply voltage; typical values



f = 1850 MHz.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

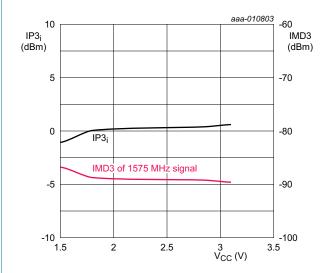
Fig 26. Input power at 1 dB gain compression as a function of supply voltage; typical values



f = 1575 MHz.

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

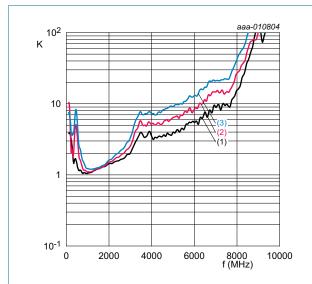
Fig 27. Input power at 1 dB gain compression as a function of supply voltage; typical values



 $f_1$  = 1713 MHz;  $f_2$  = 1851 MHz;  $P_i$  = -20 dBm at  $f_1$ ;  $P_i$  = -65 dBm at  $f_2$ ;  $T_{amb}$  = 25 °C.

Fig 28. Input third order intercept point and third order intermodulation distortion as function of supply voltage; typical values

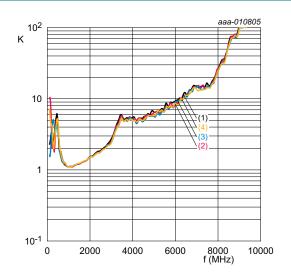
#### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass



 $P_i = -45 \text{ dBm}$ ;  $V_{CC} = 1.8 \text{ V}$ .

- (1)  $T_{amb} = -40 \, ^{\circ}C$
- (2)  $T_{amb} = +25 \, ^{\circ}C$
- (3)  $T_{amb} = +85 \, ^{\circ}C$

Fig 29. Rollett stability factor as a function of frequency; typical values



 $P_i = -45 \text{ dBm}$ ;  $T_{amb} = 25 \text{ °C}$ .

- (1)  $V_{CC} = 1.5 \text{ V}$
- (2)  $V_{CC} = 1.8 \text{ V}$
- (3)  $V_{CC} = 2.85 \text{ V}$
- (4)  $V_{CC} = 3.1 \text{ V}$

Fig 30. Rollett stability factor as a function of frequency; typical values

### SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

## 10. Package outline

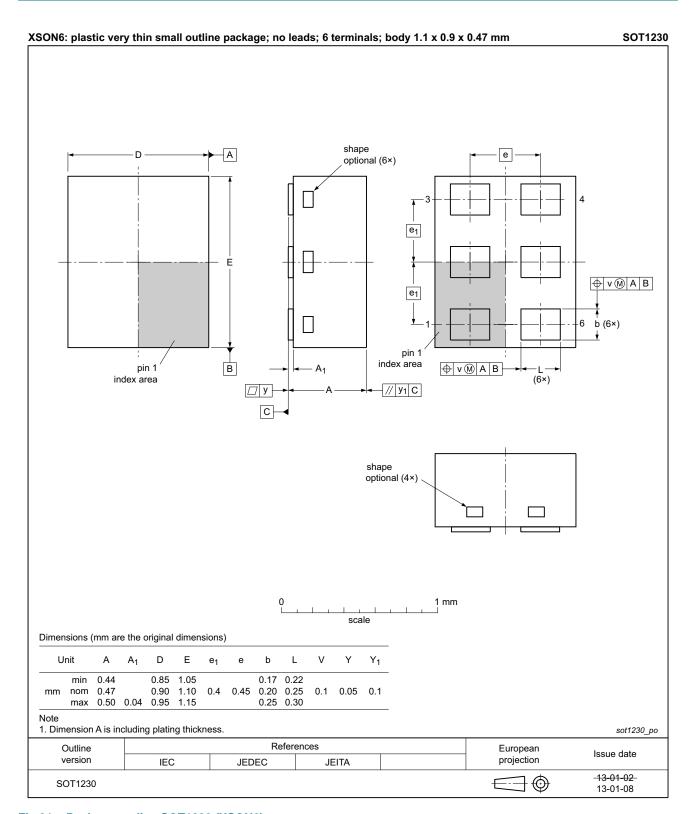


Fig 31. Package outline SOT1230 (XSON6)

#### SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

## 11. Handling information

#### **CAUTION**



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the ANSI/ESD S20.20, IEC/ST 61340-5, JESD625-A or equivalent standards.

## 12. Abbreviations

Table 11. Abbreviations

Acronym De	escription
ESD EI	lectroStatic Discharge
GLONASS GI	LObal NAvigation Satellite System
GNSS GI	lobal Navigation Satellite System
GPS GI	lobal Positioning System
HBM Hu	uman Body Model
MMIC Mo	lonolithic Microwave Integrated Circuit
PCB Pr	rinted-Circuit Board
SiGe:C Sil	ilicon Germanium Carbon

## 13. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
BGU8010 v.1	20131224	Product data sheet	-	-

#### SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

## 14. Legal information

#### 14.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
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