NTB0102

Dual supply translating transceiver; auto direction sensing; 3-state

Rev. 4 — 23 January 2013

Product data sheet

1. General description

The NTB0102 is a 2-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 2-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ($V_{CC(A)}$ and $V_{CC(B)}$). $V_{CC(A)}$ can be supplied at any voltage between 1.2 V and 3.6 V and $V_{CC(B)}$ can be supplied at any voltage between 1.65 V and 5.5 V, making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins An and OE are referenced to $V_{CC(A)}$ and pins Bn are referenced to $V_{CC(B)}$. A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

2. Features and benefits

- Wide supply voltage range:
 - ◆ V_{CC(A)}: 1.2 V to 3.6 V and V_{CC(B)}: 1.65 V to 5.5 V
- I_{OFF} circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
 - ◆ HBM JESD22-A114E Class 2 exceeds 2500 V for A port
 - ◆ HBM JESD22-A114E Class 3B exceeds 15000 V for B port
 - MM JESD22-A115-A exceeds 200 V
 - ◆ CDM JESD22-C101E exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C



Dual supply translating transceiver; auto direction sensing; 3-state

3. Ordering information

Table 1. Ordering information

Type number	Package	Package								
	Temperature range	Name	Description	Version						
NTB0102DP	–40 °C to +125 °C	TSSOP8	plastic thin shrink small outline package; 8 leads; body width 3 mm; lead length 0.5 mm	SOT505-2						
NTB0102GT	–40 °C to +125 °C	XSON8	plastic extremely thin small outline package; no leads; 8 terminals; body 1 \times 1.95 \times 0.5 mm	SOT833-1						
NTB0102GD	–40 °C to +125 °C	XSON8	plastic extremely thin small outline package; no leads; 8 terminals; body $3\times2\times0.5~\text{mm}$	SOT996-2						
NTB0102GF	–40 °C to +125 °C	XSON8	extremely thin small outline package; no leads; 8 terminals; body 1.35 \times 1 \times 0.5 mm	SOT1089						
NTB0102GU	–40 °C to +125 °C	XQFN10	plastic, extremely thin quad flat package; no leads; 10 terminals; body 1.40 \times 1.80 \times 0.50 mm	SOT1160-1						

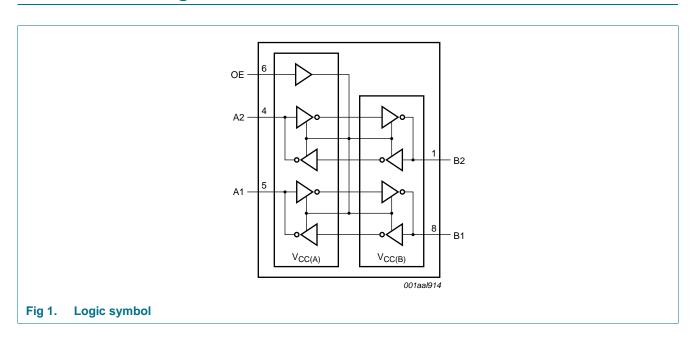
4. Marking

Table 2. Marking

Type number	Marking code ^[1]
NTB0102DP	t02
NTB0102GT	t02
NTB0102GD	t02
NTB0102GF	t2
NTB0102GU	t2

^[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

5. Functional diagram



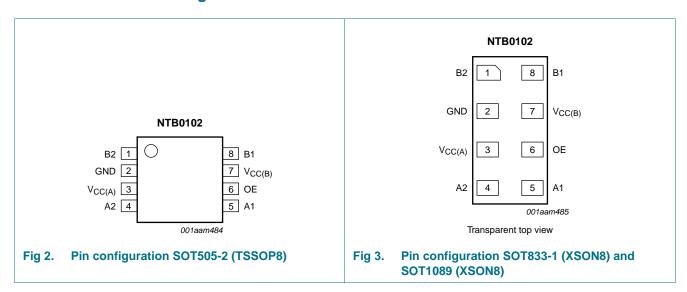
NTB0102

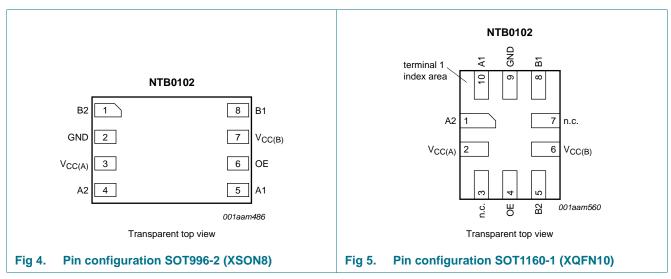
All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state

6. Pinning information

6.1 Pinning





6.2 Pin description

Table 3. Pin description

Symbol	Pin	Description	
	SOT505-2, SOT833-1, SOT1089 and SOT996-2 SOT1160-1		
B2, B1	1, 8	5, 8	data input or output (referenced to $V_{\text{CC(B)}}$)
GND	2	9	ground (0 V)
$V_{CC(A)}$	3	2	supply voltage A
A2, A1	4, 5	1, 10	data input or output (referenced to $V_{\text{CC}(A)}$)

NTB0102

Dual supply translating transceiver; auto direction sensing; 3-state

Table 3. Pin description ... continued

Symbol	Pin		Description
	SOT505-2, SOT833-1, SOT1089 and SOT996-2 SOT1160-1		
OE	6	4	output enable input (active HIGH; referenced to $V_{\text{CC(A)}}$)
$V_{CC(B)}$	7	6	supply voltage B
n.c.	-	3, 7	not connected

7. Functional description

Table 4. Function table[1]

Supply voltage		Input	Input/output		
V _{CC(A)} V _{CC(B)}		OE	An	Bn	
1.2 V to V _{CC(B)}	1.65 V to 5.5 V	L	Z	Z	
1.2 V to V _{CC(B)}	1.65 V to 5.5 V	Н	input or output	output or input	
GND[2]	GND[2]	X	Z	Z	

^[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
V _{CC(B)}	supply voltage B		-0.5	+6.5	V
V_{I}	input voltage		<u>[1]</u> –0.5	+6.5	V
Vo	output voltage	Active mode	[1][2][3] -0.5	$V_{CCO} + 0.5$	V
		Power-down or 3-state mode	<u>[1]</u> –0.5	+6.5	V
I _{IK}	input clamping current	V _I < 0 V	-50	-	mA
I _{OK}	output clamping current	V _O < 0 V	-50	-	mA
Io	output current	$V_O = 0 V \text{ to } V_{CCO}$	<u>[2]</u> _	±50	mA
I _{CC}	supply current	$I_{CC(A)}$ or $I_{CC(B)}$	-	100	mA
I_{GND}	ground current		-100	-	mA
T _{stg}	storage temperature		-65	+150	°C
P _{tot}	total power dissipation	$T_{amb} = -40 ^{\circ}\text{C}$ to +125 $^{\circ}\text{C}$	<u>[4]</u> -	250	mW

^[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

^[2] When either $V_{CC(A)}$ or $V_{CC(B)}$ is at GND level, the device goes into Power-down mode.

^[2] V_{CCO} is the supply voltage associated with the output.

^[3] $V_{CCO} + 0.5 \text{ V}$ should not exceed 6.5 V.

^[4] For TSSOP8 package: above 55 °C the value of P_{tot} derates linearly with 2.5 mW/K. For XSON8 packages: above 118 °C the value of P_{tot} derates linearly with 7.8 mW/K. For XQFN10 package: above 128 °C the value of P_{tot} derates linearly with 11.5 mW/K.

Dual supply translating transceiver; auto direction sensing; 3-state

9. Recommended operating conditions

Table 6. Recommended operating conditions[1][2]

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		1.2	3.6	V
V _{CC(B)}	supply voltage B		1.65	5.5	V
VI	input voltage		0	5.5	V
V _O	output voltage	Power-down or 3-state mode; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$			
		A port	0	3.6	V
		B port	0	5.5	V
T _{amb}	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	40	ns/V

^[1] The A and B sides of an unused I/O pair must be held in the same state, both at V_{CCI} or both at GND.

10. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.

Parameter	Conditions	Min	Тур	Max	Unit
HIGH-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$; $I_O = -20 \mu\text{A}$	-	1.1	-	V
LOW-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$; $I_O = 20 \mu\text{A}$	-	0.09	-	V
input leakage current	OE input; $V_I = 0 \text{ V to } 3.6 \text{ V}; V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	-	±1	μА
OFF-state output current	A or B port; $V_O = 0$ V to V_{CCO} ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	<u>[1]</u> -	-	±1	μА
power-off leakage current	A port; V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V	-	-	±1	μА
	B port; V_1 or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V	-	-	±1	μА
supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	[2]			
	$I_{CC(A)}$; $V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	0.05	-	μΑ
	$I_{CC(B)}$; $V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	3.3	-	μΑ
	$I_{CC(A)} + I_{CC(B)}$; $V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	3.5	-	μΑ
input capacitance	OE input; $V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	1.0	-	pF
input/output	A port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	4.0	-	pF
capacitance	B port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	7.5	-	pF
	HIGH-level output voltage LOW-level output voltage input leakage current OFF-state output current power-off leakage current supply current input capacitance input/output	HIGH-level output voltage LOW-level output voltage A port; $V_{CC(A)} = 1.2 \text{ V}$; $I_O = -20 \text{ μA}$ output voltage input leakage current OE input; $V_I = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$ OFF-state output current OFF-state output current A or B port; $V_O = 0 \text{ V to } V_{CC(C)}$; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$ power-off leakage current A port; V_I or $V_O = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(A)} = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(A)} = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(A)} = 0 \text{ V to } 3.6 \text{ V}$ supply current V _I = 0 V or $V_{CC(B)} = 0 \text{ V to } 3.6 \text{ V}$ $I_{CC(A)}$; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V to } 5.5 \text{ V}$ $I_{CC(B)}$; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V to } 5.5 \text{ V}$ $I_{CC(A)} + I_{CC(B)}$; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V to } 5.5 \text{ V}$ input capacitance input/output A port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V to } 5.5 \text{ V to } 5.5 \text{ V}$	HIGH-level output voltage LOW-level output voltage input leakage current OE input; $V_{CC(A)} = 1.2 \text{ V}$; $I_O = 20 \text{ μA}$ - consortance input leakage current A port; $V_{CC(A)} = 1.2 \text{ V}$; $I_O = 20 \text{ μA}$ - consortance input leakage current OE input; $V_I = 0 \text{ V}$ to 3.6 V; $V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V OFF-state output current A or B port; $V_O = 0 \text{ V}$ to $V_{CC(C)}$; $V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V Power-off leakage current A port; $V_I \text{ or } V_O = 0 \text{ V}$ to 3.6 V; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$ to 5.5 V B port; $V_I \text{ or } V_O = 0 \text{ V}$ to 5.5 V; $V_{CC(B)} = 0 \text{ V}$; $V_{CC(A)} = 0 \text{ V}$ to 3.6 V supply current $V_I = 0 \text{ V}$ or $V_{CC(I)} = 0 \text{ A}$ $V_I = 0 \text{ V}$ or $V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V $V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V input capacitance OE input; $V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V - capacitance input/output A port; $V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V - capacitance	HIGH-level output voltage LOW-level output voltage A port; $V_{CC(A)} = 1.2 \text{ V}$; $I_O = -20 \text{ μA}$ - 0.09 LOW-level output voltage input leakage current OE input; $V_I = 0 \text{ V}$ to 3.6 V; $V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V DFF-state output current A or B port; $V_O = 0 \text{ V}$ to $V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V power-off leakage current A port; V_I or $V_O = 0 \text{ V}$ to 3.6 V; $V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$ to 5.5 V B port; V_I or $V_O = 0 \text{ V}$ to 5.5 V; $V_{CC(B)} = 0 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$ to 3.6 V; $V_{CC(B)} = 0 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$; $V_{CC(A)} = 0 \text{ V}$ to 5.5 V supply current $V_I = 0 \text{ V}$ or $V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V $I_{CC(A)} : V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V $I_{CC(A)} : V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V $I_{CC(A)} : V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V $I_{CC(A)} : V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V $I_{CC(A)} : V_{CC(A)} = 1.2 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V $I_{CC(A)} : V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} : V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V $I_{CC(A)} : V_{CC(A)} : V_{CC(A)} = 1.2 \text{ V}$ to 3.6 V; $V_{CC(B)} : V_{CC(B)} : V_{CC(B)} : V_{CC(B)} : V_{CC(B)} : V_{CC(C)} $	HIGH-level output voltage LOW-level output voltage A port; $V_{CC(A)} = 1.2 \text{ V}$; $I_{O} = -20 \text{ μA}$ - 0.09 - 1.1 COFF-state output voltage OFF-state output $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V OFF-state output $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V power-off leakage current A port; $V_{CC(B)} = 0 \text{ V}$ to 5.5 V B port; $V_{I} = 0 \text{ V}$ to 5.5 V B port; $V_{I} = 0 \text{ V}$ to 5.5 V B port; $V_{I} = 0 \text{ V}$ to 5.5 V B port; $V_{I} = 0 \text{ V}$ to 5.5 V B port; $V_{I} = 0 \text{ V}$ to 5.5 V B port; $V_{I} = 0 \text{ V}$ to 5.5 V Supply current $V_{CC(B)} = 0 \text{ V}$ to $V_{CC(B)} = 0 \text{ V}$ to 5.5 V $V_{CC(B)} = 0 \text{ V}$ to $V_{CC(B)} = 0 \text{ V}$ to 5.5 V $V_{CC(B)} = 0 \text{ V}$ to $V_{CC(B)} = 0 \text{ V}$ to 5.5 V $V_{CC(B)} = 0 \text{ V}$ to $V_{CC(A)} = 0 \text{ V}$ to 5.5 V $V_{CC(B)} = 0 \text{ V}$ to $V_{CC(A)} = 0 \text{ V}$ to 0.05 C $V_{CC(B)} = 0 \text{ V}$ to 0.05 C $V_{CC(A)} = 0 \text{ V}$ to 0.05 C $V_{CC(A)} = 0 \text{ V}$ to 0.05 C $V_{CC(B)} = 0 \text{ V}$ to 0.05 C $V_{CC(B)} = 0 \text{ V}$ to 0.05 C $V_{CC(B)} = 0 \text{ V}$ to 0.05 C $V_{CC(B)} = 0 \text{ V}$ to 0.05 C $V_{CC(B)} = 0 \text{ V}$ to 0.05 C $V_{CC(B)} = 0.05 \text{ V}$ $V_$

^[1] V_{CCO} is the supply voltage associated with the output.

NTB0102

All information provided in this document is subject to legal disclaimers.

^[2] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$.

^[2] V_{CCI} is the supply voltage associated with the input.

Dual supply translating transceiver; auto direction sensing; 3-state

Table 8. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.

V _{CC(A)}	V _{CC(B)}								Unit
	1.8	3 V	2.5	2.5 V		3 V	5.0 V		
	I _{CC(A)}	I _{CC(B)}							
1.2 V	10	10	10	10	10	20	10	1050	nA
1.5 V	10	10	10	10	10	10	10	650	nA
1.8 V	10	10	10	10	10	10	10	350	nA
2.5 V	-	-	10	10	10	10	10	40	nA
3.3 V	-	-	-	-	10	10	10	10	nA

Table 9. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		-40 °C to	+85 °C	-40 °C to	+125 °C	Unit
				Min	Max	Min	Max	
V_{IH}	HIGH-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		0.65V _{CCI}	-	0.65V _{CCI}	-	V
V_{IL}	LOW-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	0.35V _{CCI}	-	0.35V _{CCI}	V
V_{OH}	HIGH-level	$I_{O} = -20 \mu A$	[2]					
	output voltage	A port; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V}$		$V_{CCO}-0.4$	-	$V_{CCO}-0.4$	-	V
		B port; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		$V_{CCO}-0.4$	-	$V_{CCO}-0.4$	-	V
V_{OL}	LOW-level	I _O = 20 μA	[2]					
	output voltage	A port; V _{CC(A)} = 1.4 V to 3.6 V		-	0.4	-	0.4	V
		B port; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	0.4	-	0.4	V
I _I	input leakage current	OE input; $V_I = 0 \text{ V to } 3.6 \text{ V};$ $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	±2	-	±5	μА
I _{OZ}	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	[2]	-	±2	-	±10	μА
I _{OFF}	power-off leakage	A port; V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V		-	±2	-	±10	μА
(current	B port; V_1 or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V		-	±2	-	±10	μΑ

Dual supply translating transceiver; auto direction sensing; 3-state

Table 9. Static characteristics ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		–40 °C t	:o +85 °C	–40 °C to	+125 °C	Unit
				Min	Max	Min	Max	
I _{CC}	supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	<u>[1]</u>					'
	$I_{CC(A)}$ $OE = LOW;$ $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	I _{CC(A)}						
		3	-	15	μΑ			
		OE = HIGH; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	3	-	20	μΑ
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	2	-	15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$		-	-2	-	-15	μΑ
		I _{CC(B)}						
		OE = LOW; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	5	-	15	μА
		OE = HIGH; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	5	-	20	μΑ
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	-2	-	-15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$		-	2	-	15	μΑ
		$I_{CC(A)} + I_{CC(B)}$						
		$V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	8	-	40	μΑ

^[1] V_{CCI} is the supply voltage associated with the input.

11. Dynamic characteristics

Table 10. Typical dynamic characteristics for temperature 25 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for waveforms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions				Unit		
				1.8 V	2.5 V	3.3 V	5.0 V	
$V_{CC(A)} = 1$	1.2 V; T _{amb} = 25 °C							
t_{pd}	propagation delay	A to B		5.9	4.8	4.4	4.2	ns
		B to A		5.6	4.8	4.5	4.4	ns
t _{en}	enable time	OE to A, B		0.5	0.5	0.5	0.5	μS
t _{dis}	disable time	OE to A; no external load	[2]	6.9	6.9	6.9	6.9	ns
		OE to B; no external load	[2]	9.5	8.6	8.5	8.0	ns
		OE to A		81	69	83	68	ns
		OE to B		81	69	83	68	ns
t _t	transition time	A port		4.0	4.0	4.1	4.1	ns
		B port		2.6	2.0	1.7	1.4	ns

NTB0102

^[2] V_{CCO} is the supply voltage associated with the output.

NTB0102 NXP Semiconductors

Dual supply translating transceiver; auto direction sensing; 3-state

Table 10. Typical dynamic characteristics for temperature 25 °C[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for waveforms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions		V _{CC(B)}			
			1.8 V	2.5 V	3.3 V	5.0 V	
t _{sk(o)}	output skew time	between channels [3]	0.2	0.2	0.2	0.2	ns
t _W	pulse width	data inputs	15	13	13	13	ns
f _{data}	data rate		70	80	80	80	Mbps

^[1] t_{pd} is the same as t_{PLH} and t_{PHL} . ten is the same as tPZL and tPZH. t_{dis} is the same as t_{PLZ} and t_{PHZ} . t_{t} is the same as t_{THL} and t_{TLH}

Table 11. Dynamic characteristics for temperature range -40 °C to +85 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ±	0.15 V	2.5 V	± 0.2 V	3.3 V	± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{CC(A)} =$	$1.5 \text{ V} \pm 0.1 \text{ V}$											
t _{pd}	propagation	A to B		1.4	12.9	1.2	10.1	1.1	10.0	8.0	9.9	ns
	delay	B to A		0.9	14.2	0.7	12.0	0.4	11.7	0.3	13.7	ns
t _{en}	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t _{dis}	disable time	OE to A; no external load	[2]	1.0	11.9	1.0	11.9	1.0	11.9	1.0	11.9	ns
		OE to B; no external load	[2]	1.0	16.9	1.0	15.2	1.0	14.1	1.0	13.8	ns
		OE to A		-	320	-	260	-	260	-	280	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t _t	transition	A port		0.9	5.1	0.9	5.1	0.9	5.1	0.9	5.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t _{sk(o)}	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t _W	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f _{data}	data rate			-	40	-	40	-	40	-	40	Mbps
V _{CC(A)} =	1.8 V ± 0.15 V											
t _{pd}	propagation	A to B		1.6	11.0	1.4	7.7	1.3	6.8	1.2	6.5	ns
	delay	B to A		1.5	12.0	1.3	8.4	1.0	7.6	0.9	7.1	ns
t _{en}	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t _{dis}	disable time	OE to A; no external load	[2]	1.0	11.0	1.0	11.0	1.0	11.0	1.0	11.0	ns
		OE to B; no external load	[2]	1.0	15.4	1.0	13.5	1.0	12.4	1.0	12.1	ns
		OE to A		-	260	-	230	-	230	-	230	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t _t	transition	A port		8.0	4.1	8.0	4.1	8.0	4.1	8.0	4.1	ns
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns

^[2] Delay between OE going LOW and when the outputs are actually disabled.

^[3] Skew between any two outputs of the same package switching in the same direction.

Dual supply translating transceiver; auto direction sensing; 3-state

Table 11. Dynamic characteristics for temperature range -40 °C to +85 °C[1] ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 8</u>; for wave forms see <u>Figure 6</u> and <u>Figure 7</u>.

Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ±	0.15 V	2.5 V =	± 0.2 V		± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
t _{sk(o)}	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t _W	pulse width	data inputs		20	-	17	-	17	-	17	-	ns
f _{data}	data rate			-	49	-	60	-	60	-	60	Mbps
V _{CC(A)} =	2.5 V ± 0.2 V											
t _{pd}	propagation	A to B		-	-	1.1	6.3	1.0	5.2	0.9	4.7	ns
	delay	B to A		-	-	1.2	6.6	1.1	5.1	0.9	4.4	ns
t _{en}	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t _{dis}	disable time	OE to A; no external load	[2]	-	-	1.0	9.2	1.0	9.2	1.0	9.2	ns
		OE to B; no external load	[2]	-	-	1.0	11.9	1.0	10.7	1.0	10.2	ns
		OE to A		-	-	-	200	-	200	-	200	ns
		OE to B		-	-	-	200	-	200	-	200	ns
t _t tra	transition	A port		-	-	0.7	3.0	0.7	3.0	0.7	3.0	ns
	time	B port		-	-	0.7	3.2	0.5	2.5	0.4	2.7	ns
t _{sk(o)}	output skew time	between channels	[3]	-	-	-	0.5	-	0.5	-	0.5	ns
t _W	pulse width	data inputs		-	-	12	-	10	-	10	-	ns
f _{data}	data rate			-	-	-	85	-	100	-	100	Mbps
V _{CC(A)} =	3.3 V ± 0.3 V											
t _{pd}	propagation	A to B		-	-	-	-	0.9	4.7	8.0	4.0	ns
	delay	B to A		-	-	-	-	1.0	4.9	0.9	3.8	ns
t _{en}	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t _{dis}	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.2	1.0	9.2	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	10.1	1.0	9.6	ns
		OE to A		-	-	-	-	-	260	-	260	ns
		OE to B		-	-	-	-	-	200	-	200	ns
t _t	transition	A port		-	-	-	-	0.7	2.5	0.7	2.5	ns
	time	B port		-	-	-	-	0.5	2.5	0.4	2.7	ns
t _{sk(o)}	output skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
t _W	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f _{data}	data rate			-	-	-	-	-	100	-	100	Mbps

 $[\]begin{array}{ll} \text{[1]} & t_{pd} \text{ is the same as } t_{PLH} \text{ and } t_{PHL}. \\ & t_{en} \text{ is the same as } t_{PZL} \text{ and } t_{PZH}. \end{array}$

NTB0102

 t_{dis} is the same as t_{PLZ} and $t_{\text{PHZ}}.$

 t_{t} is the same as t_{THL} and $t_{\text{TLH}}.$

^[2] Delay between OE going LOW and when the outputs are actually disabled.

^[3] Skew between any two outputs of the same package switching in the same direction.

NTB0102 NXP Semiconductors

Dual supply translating transceiver; auto direction sensing; 3-state

Table 12. Dynamic characteristics for temperature range –40 °C to +125 °C[1] Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 8</u>; for wave forms see <u>Figure 6</u> and <u>Figure 7</u>.

Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ±	0.15 V	2.5 V ±	Ŀ 0.2 V	3.3 V =	Ŀ 0.3 V	5.0 V ±	Ŀ 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
V _{CC(A)} =	1.5 V ± 0.1 V			'		•		•				'
t _{pd}	propagation	A to B		1.4	15.9	1.2	13.1	1.1	13.0	8.0	12.9	ns
	delay	B to A		0.9	17.2	0.7	15.0	0.4	14.7	0.3	16.7	ns
t _{en}	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t _{dis}	disable time	OE to A; no external load	[2]	1.0	12.5	1.0	12.5	1.0	12.5	1.0	12.5	ns
		OE to B; no external load	[2]	1.0	18.1	1.0	16.2	1.0	14.9	1.0	14.6	ns
		OE to A		-	340	-	280	-	280	-	300	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t _t	transition	A port		0.9	7.1	0.9	7.1	0.9	7.1	0.9	7.1	ns
	time	B port		0.9	6.5	0.6	5.2	0.5	4.8	0.4	4.7	ns
t _{sk(o)}	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t _W	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f _{data}	data rate			-	40	-	40	-	40	-	40	Mbp
	1.8 V ± 0.15 V											
t _{pd} propagation delay	A to B		1.6	14.0	1.4	10.7	1.3	9.8	1.2	9.5	ns	
	B to A		1.5	15.0	1.3	11.4	1.0	10.6	0.9	10.1	ns	
t _{en}	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t _{dis}	disable time	OE to A; no external load	[2]	1.0	11.5	1.0	11.5	1.0	11.5	1.0	11.5	ns
		OE to B; no external load	[2]	1.0	16.5	1.0	14.5	1.0	13.3	1.0	12.7	ns
		OE to A		-	280	-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t _t	transition	A port		0.8	6.2	0.8	6.1	0.8	6.1	0.8	6.1	ns
	time	B port		0.9	5.8	0.6	5.2	0.5	4.8	0.4	4.7	ns
t _{sk(o)}	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t _W	pulse width	data inputs		22	-	19	-	19	-	19	-	ns
f _{data}	data rate			-	45	-	55	-	55	-	55	Mbp:
	2.5 V ± 0.2 V											
t _{pd}	propagation	A to B		-	-	1.1	9.3	1.0	8.2	0.9	7.7	ns
	delay	B to A		-	-	1.2	9.6	1.1	8.1	0.9	7.4	ns
t _{en}	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t _{dis}	disable time	OE to A; no external load	[2]	-	-	1.0	9.6	1.0	9.6	1.0	9.6	ns
		OE to B; no external load	[2]	-	-	1.0	12.6	1.0	11.4	1.0	10.8	ns
		OE to A		-	-	-	220	-	220	-	220	ns
		OE to B		-	-	-	220	-	220	-	220	ns
t _t	transition	A port		-	-	0.7	5.0	0.7	5.0	0.7	5.0	ns
time		•										

All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state

Table 12. Dynamic characteristics for temperature range -40 °C to +125 °C[1] ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 8</u>; for wave forms see <u>Figure 6</u> and <u>Figure 7</u>.

					· ·							_
Symbol	Parameter	meter Conditions					Vcc	C(B)				Unit
				1.8 V ±	0.15 V	2.5 V ±	± 0.2 V	3.3 V :	± 0.3 V	5.0 V =	0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
t _{sk(o)}	output skew time	between channels	[3]	-	-	-	0.5	-	0.5	-	0.5	ns
t _W	pulse width	data inputs;		-	-	14	-	13	-	10	-	ns
f _{data}	data rate			-	-	-	75	-	80	-	100	Mbps
V _{CC(A)} =	3.3 V ± 0.3 V											
t _{pd}	propagation delay	A to B		-	-	-	-	0.9	7.7	8.0	7.0	ns
		B to A		-	-	-	-	1.0	7.9	0.9	6.8	ns
t _{en}	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t _{dis}	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.5	1.0	9.5	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	10.7	1.0	9.6	ns
		OE to A		-	-	-	-	-	280	-	280	ns
		OE to B		-	-	-	-	-	220	-	220	ns
t _t	transition	A port		-	-	-	-	0.7	4.5	0.7	4.5	ns
	time	B port		-	-	-	-	0.5	4.1	0.4	4.7	ns
t _{sk(o)}	output skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
t _W	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f _{data}	data rate			-	-	-	-	-	100	-	100	Mbps

^[1] t_{pd} is the same as t_{PLH} and t_{PHL} .

 t_{en} is the same as t_{PZL} and $t_{\text{PZH}}.$

 t_{dis} is the same as t_{PLZ} and t_{PHZ} .

 t_t is the same as t_{THL} and $t_{\text{TLH.}}$

^[2] Delay between OE going LOW and when the outputs are actually disabled.

^[3] Skew between any two outputs of the same package switching in the same direction.

Dual supply translating transceiver; auto direction sensing; 3-state

Table 13. Typical power dissipation capacitance

Voltages are referenced to GND (ground = 0 V).[1][2]

Symbol	Parameter	Conditions				$V_{CC(A)}$				Unit
			1.2 V	1.2 V	1.5 V	1.8 V	2.5 V	2.5 V	3.3 V	
			V _{CC(B)}							
				5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V	
$T_{amb} = 2$	5 °C									
C _{PD}	power	outputs enabled; $OE = V_{CC(A)}$								
	dissipation capacitance	A port: (direction A to B)	5	5	5	5	5	5	5	pF
		A port: (direction B to A)	8	8	8	8	8	8	8	pF
		B port: (direction A to B)	18	18	18	18	18	18	18	рF
		B port: (direction B to A)	13	16	12	12	12	12	13	pF
		outputs disabled; OE = GND								
		A port: (direction A to B)	0.12	0.12	0.04	0.05	0.08	0.08	0.07	pF
		A port: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction A to B)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction B to A)	0.07	0.09	0.07	0.07	0.05	0.09	0.09	pF

[1] C_{PD} is used to determine the dynamic power dissipation (P_D in μW).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where:

 f_i = input frequency in MHz;

fo = output frequency in MHz;

C_L = load capacitance in pF;

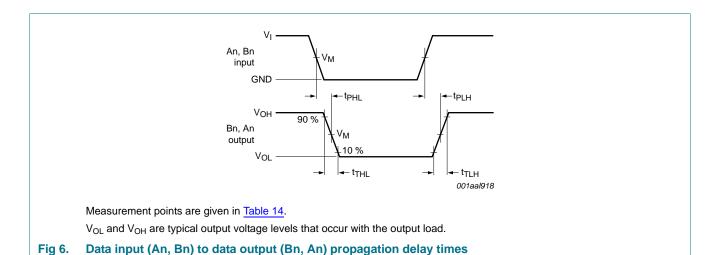
V_{CC} = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o)$ = sum of the outputs.

[2] f_i = 10 MHz; V_I = GND to V_{CC} ; t_f = t_f = 1 ns; C_L = 0 pF; R_L = ∞ Ω .

12. Waveforms



NTB0102

Dual supply translating transceiver; auto direction sensing; 3-state

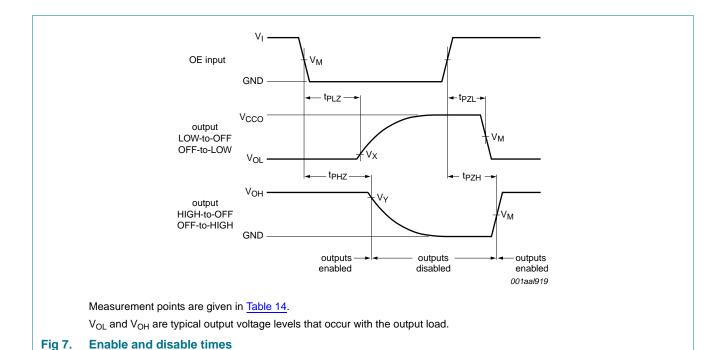
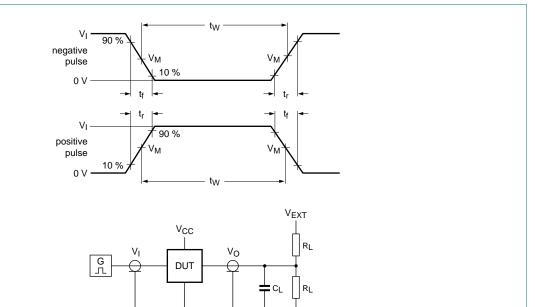


Table 14. Measurement points[1]

Supply voltage	Input	Output		
V _{CCO}	V _M	V _M	V _X	V _Y
1.2 V	0.5V _{CCI}	0.5V _{CCO}	$V_{OL} + 0.1 V$	$V_{OH} - 0.1 V$
1.5 V ± 0.1 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.1 V	V _{OH} – 0.1 V
1.8 V ± 0.15 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.15 V	V _{OH} – 0.15 V
$2.5~\text{V}\pm0.2~\text{V}$	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.15 V	V _{OH} – 0.15 V
$3.3~V\pm0.3~V$	0.5V _{CCI}	0.5V _{CCO}	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$
$5.0~\text{V} \pm 0.5~\text{V}$	0.5V _{CCI}	0.5V _{CCO}	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$

^[1] V_{CCI} is the supply voltage associated with the input and V_{CCO} is the supply voltage associated with the output.

Dual supply translating transceiver; auto direction sensing; 3-state



Test data is given in Table 15.

All input pulses are supplied by generators having the following characteristics: PRR \leq 10 MHz; Z_{O} = 50 Ω ; $dV/dt \geq$ 1.0 V/ns.

R_L = Load resistance.

 C_L = Load capacitance including jig and probe capacitance.

 V_{EXT} = External voltage for measuring switching times.

Fig 8. Test circuit for measuring switching times

Table 15. Test data

Supply voltage	је	Input		Load		V _{EXT}		
V _{CC(A)}	V _{CC(B)}	۷ _ا نا	Δt/ΔV	CL	R _L [2]	t_{PLH} , t_{PHL}	t_{PZH}, t_{PHZ}	t _{PZL} , t _{PLZ} [3]
1.2 V to 3.6 V	1.65 V to 5.5 V	V_{CCI}	\leq 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V _{CCO}

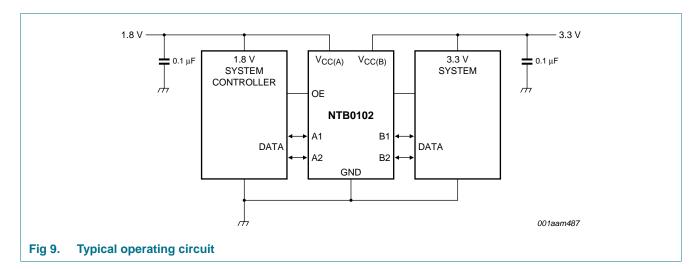
- [1] V_{CCI} is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements, $R_L = 1 \text{ M}\Omega$; for measuring enable and disable times, $R_L = 50 \text{ k}\Omega$.
- [3] V_{CCO} is the supply voltage associated with the output.

Dual supply translating transceiver; auto direction sensing; 3-state

13. Application information

13.1 Applications

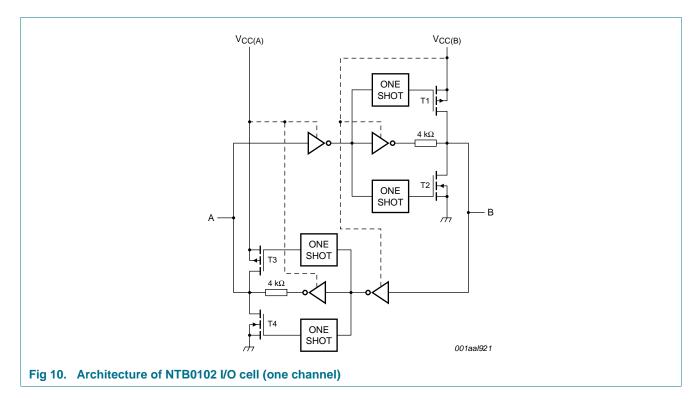
Voltage level-translation applications. The NTB0102 can be used to interface between devices or systems operating at different supply voltages. See <u>Figure 9</u> for a typical operating circuit using the NTB0102.



Dual supply translating transceiver; auto direction sensing; 3-state

13.2 Architecture

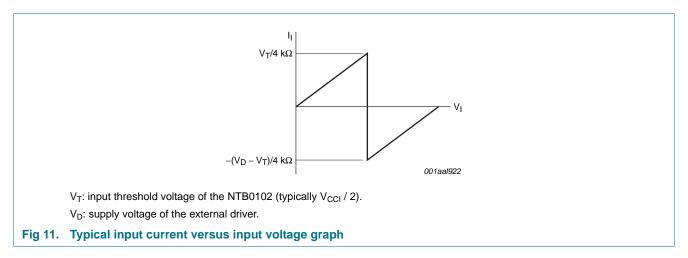
The architecture of the NTB0102 is shown in Figure 10. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NTB0102 can maintain a defined output level, but the output architecture is designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output of one-shot circuits detect rising or falling edges on the A or B ports. During a rising edge, the one-shot circuits turn on the PMOS transistors (T1, T3) for a short duration, accelerating the LOW-to-HIGH transition. Similarly, during a falling edge, the one-shot circuits turn on the NMOS transistors (T2, T4) for a short duration, accelerating the HIGH-to-LOW transition. During output transitions the typical output impedance is 70 Ω at $V_{\rm CCO}$ = 1.2 V to 1.8 V, 50 Ω at $V_{\rm CCO}$ = 1.8 V to 3.3 V and 40 Ω at $V_{\rm CCO}$ = 3.3 V to 5.0 V.



Dual supply translating transceiver; auto direction sensing; 3-state

13.3 Input driver requirements

For correct operation, the device driving the data I/Os of the NTB0102 must have a minimum drive capability of ± 2 mA See Figure 11 for a plot of typical input current versus input voltage.



13.4 Power-up

During operation $V_{CC(A)}$ must never be higher than $V_{CC(B)}$, however during power-up $V_{CC(A)} \ge V_{CC(B)}$ does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTB0102 includes circuitry that disables all output ports when either $V_{CC(A)}$ or $V_{CC(B)}$ is switched off.

13.5 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time (t_{dis} with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time (t_{en}) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

13.6 Pull-up or pull-down resistors on I/O lines

As mentioned previously the NTB0102 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistors used must be above 50 k Ω . For this reason the NTB0102 is not recommended for use in open drain driver applications such as 1-Wire or I²C-bus. For these applications, the NTS0102 level translator is recommended.

Dual supply translating transceiver; auto direction sensing; 3-state

14. Package outline

TSSOP8: plastic thin shrink small outline package; 8 leads; body width 3 mm; lead length 0.5 mm SOT505-2

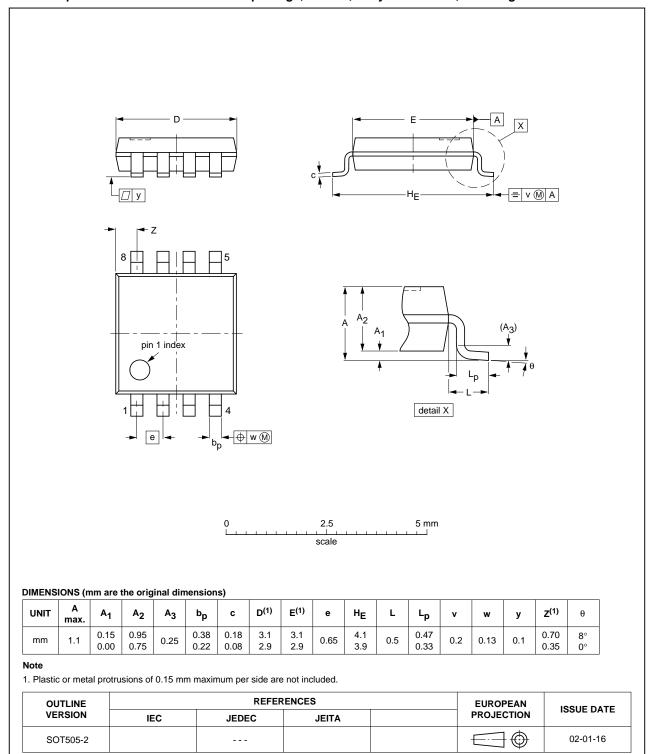


Fig 12. Package outline SOT505-2 (TSSOP8)

B0102 All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state

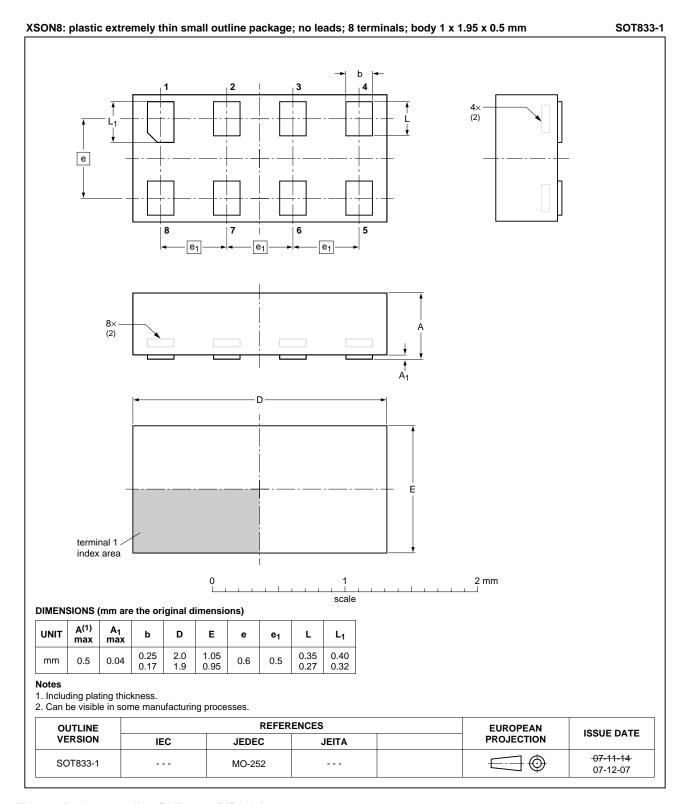


Fig 13. Package outline SOT833-1 (XSON8)

NTB0102 All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state

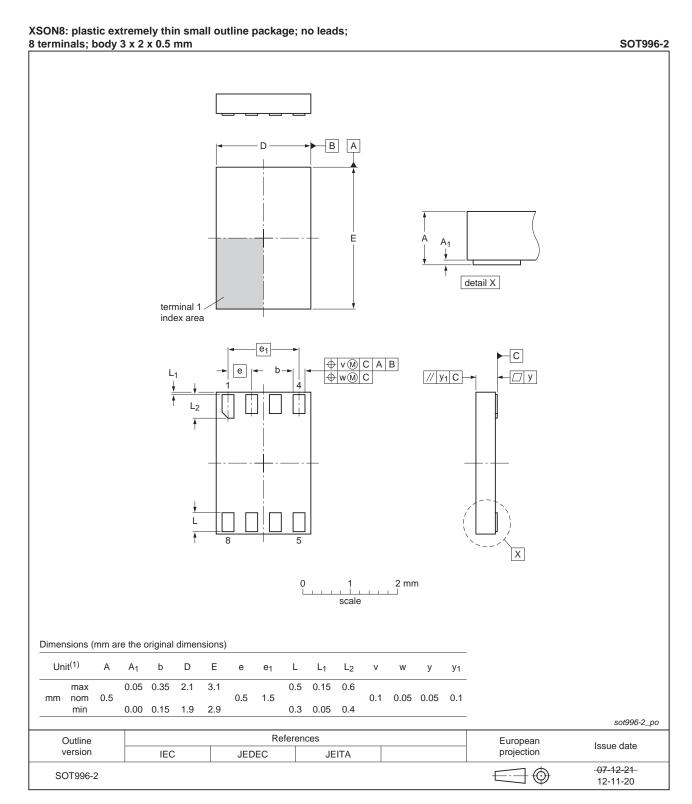


Fig 14. Package outline SOT996-2 (XSON8)

NTB0102 All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state

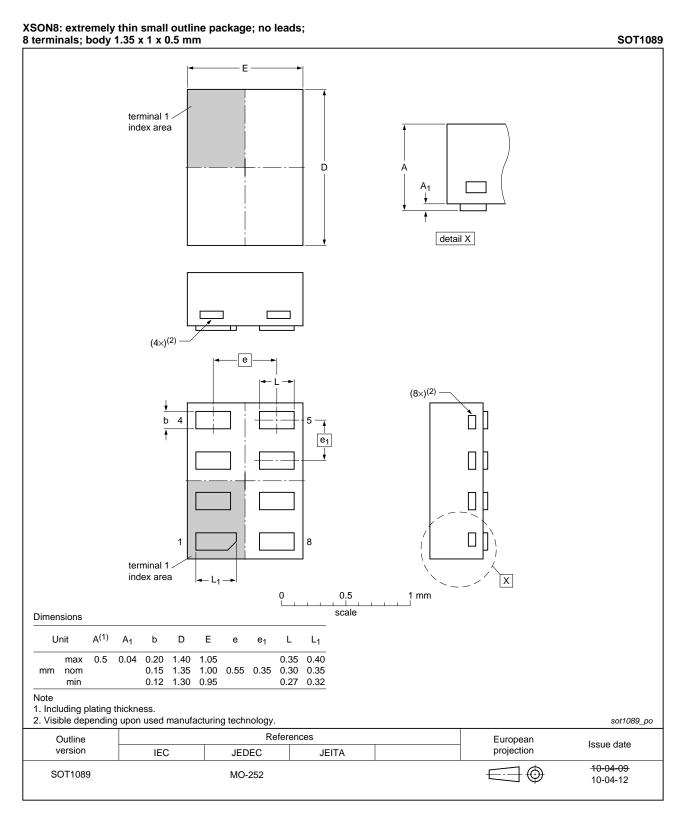


Fig 15. Package outline SOT1089 (XSON8)

NTB0102 All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state

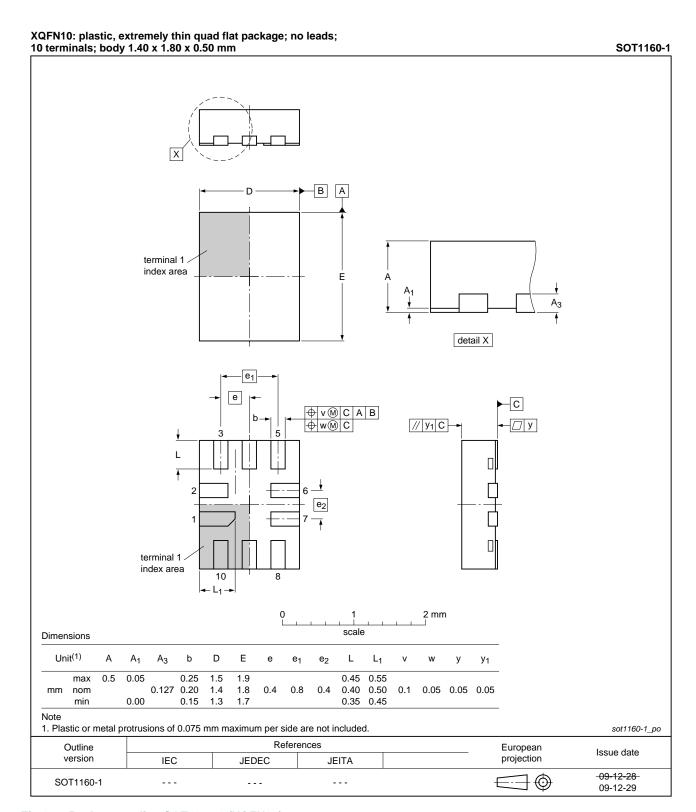


Fig 16. Package outline SOT1160-1 (XQFN10)

NTB0102

All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state

15. Abbreviations

Table 16. Abbreviations

Acronym	Description
CDM	Charged Device Model
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MM	Machine Model
NMOS	N-type Metal Oxide Semiconductor
PMOS	P-type Metal Oxide Semiconductor
PRR	Pulse Repetition Rate

16. Revision history

Table 17. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
NTB0102 v.4	20130123	Product data sheet	-	NTB0102 v.3
Modifications:	 For type num 	nber NTB0102GD XSON8U ha	as changed to XSON8.	
NTB0102 v.3	20111110	Product data sheet	-	NTB0102 v.2
Modifications:	 Legal pages 	updated.		
NTB0102 v.2	20110428	Product data sheet	-	NTB0102 v.1
NTB0102 v.1	20100922	Product data sheet	-	-

Dual supply translating transceiver; auto direction sensing; 3-state

17. Legal information

17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

17.2 Definitions

Draft — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

Product specification — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

17.3 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the *Terms and conditions of commercial sale* of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

Terms and conditions of commercial sale — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at http://www.nxp.com/profile/terms, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

No offer to sell or license — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

NTB0102

Dual supply translating transceiver; auto direction sensing; 3-state

Export control — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Non-automotive qualified products — Unless this data sheet expressly states that this specific NXP Semiconductors product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. NXP Semiconductors accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without NXP Semiconductors' warranty of the

product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond NXP Semiconductors' specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies NXP Semiconductors for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond NXP Semiconductors' standard warranty and NXP Semiconductors' product specifications.

17.4 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

18. Contact information

For more information, please visit: http://www.nxp.com

For sales office addresses, please send an email to: salesaddresses@nxp.com

Dual supply translating transceiver; auto direction sensing; 3-state

19. Contents

1	General description	1
2	Features and benefits	1
3	Ordering information	2
4	Marking	2
5	Functional diagram	2
6	Pinning information	3
6.1	Pinning	
6.2	Pin description	
7	Functional description	4
8	Limiting values	4
9	Recommended operating conditions	5
10	Static characteristics	5
11	Dynamic characteristics	7
12	Waveforms	2
13	Application information	5
13.1	Applications	5
13.2	Architecture 1	6
13.3	Input driver requirements	7
13.4		7
13.5		7
13.6	Pull-up or pull-down resistors on I/O lines 1	7
14	Package outline	8
15	Abbreviations	23
16	Revision history	23
17	Legal information	24
17.1	-	24
17.2	Definitions	24
17.3	Disclaimers	24
17.4	Trademarks2	25
18	Contact information	25
40	Contonto	

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP B.V. 2013.

All rights reserved.

For more information, please visit: http://www.nxp.com For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 23 January 2013 Document identifier: NTB0102

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

NXP:

NTB0102GD,125 NTB0102DP,125 NTB0102GT,115 NTB0102GF,115 NTB0102DP-Q100H NTB0102GD-Q100H