







DTCs Analog Rockers have been developed to provide the reliability required in demanding environmental conditions such as multifunction grips, dashboards or armrest controls for heavy duty industrial applications.

The unique sensing design makes the rocker module an ideal proportional function solution for 'off-road' machinery.

DTCs Analog Rockers have been designed to be integrated into standard and custom designed grips, panels and electronic controls.

Main Features

- Contactless sensing Hall effect
- Life greater than 2 million cycles
- One sensor optional second sensor for redundancy
- Integrated temperature compensation
- Short circuit protection

Electrical Data			
Supply Ratings	Voltage range DC current	8.5V 30V or 5.0 V ± 10° 50 mA at 24V	
Voltage Output	Output 1 Output 2*	0.5V 4.5V 4.5V 0.5V	
Total error		< 10%	
Output current		max. 1 mA	
Other electrical Characteristics	EMI	> 100 V/m	
Mechanical Data			
Life		> 2 million cycles	
Operating temperate - Storage - Working	ure	- 40°C to 85°C - 35°C to 70°C	
Operating force		4-6 N	
Vertical load maxim	um	30 N	
Protection Level		IP 65 (from above when mounted)	
Rocker deflection angle		± 30°	
* for redundant vers	sion		

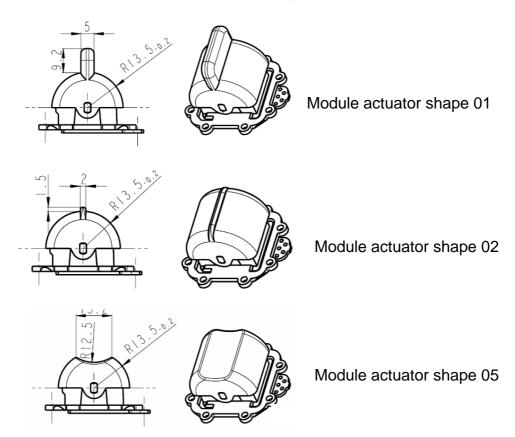
for redundant version

Custom modifications

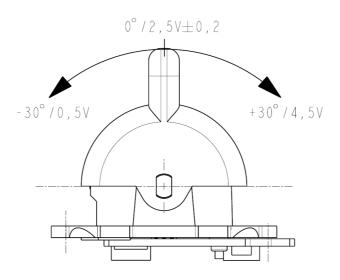
- Output characteristics
- Actuator colour

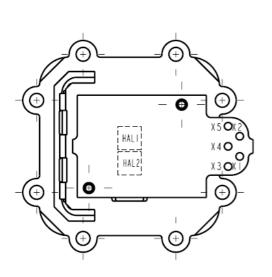


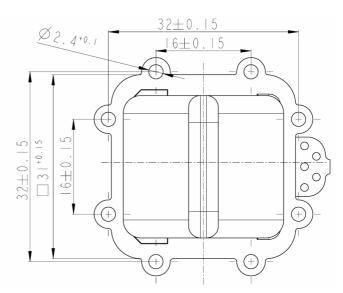
	rdering code		1	2	3	1	5	4	T 7	8	9
Р	idering code	Evenuele	ADOC	- 2		20/20		6	 	2	
H		Example	AR3S	01	ĻĢΥ	30/30	4 <u>N</u>	0	<u>, v</u>		00
1	Туре	AR3 = analog rocker 3	l I	Ī		1		I	Ť	Î	T T
		S = varnished PCB	Ш								
		N = non varnished PCB									
2	Actuator Shape	01 = long lever									
	-	02 = short lever									
		05 = thumb lever									
3	Actuator Colour	GY = grey	1								
١	Actuator colour	or = grey									
1	Actuator Angle	30/30 = left 30° / right 30°									
4	Actuator Angle	30/30 = left 30 / right 30									
F	One median Ferre	4N Javanahana 01	ł								
5	Operation Force	4N = lever shape 01									
		5N = lever shape 02									
		6N = lever shape 05									
	operation force depends on actu	ator shape									
6	Electrical supply	0 = voltage 8.5 30 V									
		$1 = 5 V \pm 10\%$									
7	Output	V = voltage									
8	Sensors	1 = 1 sensor	1								
Γ		2 = 2 sensors (for redundancy)									
9	Output Voltage Co	00 = output 1 / 0.5V 4.5V; 1mA	1								
ľ	calput voltage oo	output 2 / 4.5V 0.5V; 1mA									
		•									
		02 = output 1 / 0.5V 4.5V; 1mA									
L		03 = output 1 / 4.5V 0.5V; 1mA									











Pin assignment:

PIN	ALLOCATION	FUNCTION (8,5-30V)	FUNCTION (5V)
X5	OUT 1	OUTPUT 1 (HAL1)	OUTPUT 1 (HAL1)
X4	OUT 2	OUTPUT 2 (HAL2) *	OUTPUT 2 (HAL2) *
Х3	V	RESERVED	5V±10%
X2	GND IN 1	REFERENCE GROUND	REFERENCE GROUND
X1	U BAT	VOLTAGE SUPPLY 8,5-30V	NOT CONNECTED

^{*} FOR REDUNDANT VERSION ONLY



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