## Rugged Rotary Encoder

- Absolute model.
- External diameter of 50 mm .
- Resolution of up to 1,024 (10-bit).
- IP65 (improved oil-proof protection with sealed bearings)
- Optimum angle control possible in combination with PLC or Cam Positioner.



## c $\epsilon$

 page 7.
## Ordering Information

Encoders [Refer to Dimensions on page 8.]

| Power supply voltage | Output configuration | Output code | Resolution (pulses/rotation) | Connection method | Model |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 12 to 24 VDC | Open-collector output (NPN) | Gray | 256, 360, (720) *2 | Pre-wired Connector Model (1 m) | E6C3-AG5C-C (resolution) 1M Example: E6C3-AG5C-C 256P/R 1M |
|  |  |  | 256, 360, 720, 1,024 | ```Pre-wired Model (1 m) *1``` | E6C3-AG5C (resolution) 1M Example: E6C3-AG5C 256P/R 1M |
|  |  | Binary | 32, 40 |  | E6C3-AN5C (resolution) 1M Example: E6C3-AN5C 32P/R 1M |
|  |  | BCD | 6, 8, 12 |  | E6C3-AB5C (resolution) 1M Example: E6C3-AB5C 6P/R 1M |
|  | Open-collector output (PNP) | Gray | 256, 360, 720, 1,024 |  | E6C3-AG5B (resolution) 1M Example: E6C3-AG5B 256P/R 1M |
|  |  | Binary | 32, 40 |  | E6C3-AN5B (resolution) 1M Example: E6C3-AN5B 32P/R 1M |
|  |  | BCD | 6, 8, 12 |  | E6C3-AB5B (resolution) 1M Example: E6C3-AB5B 6P/R 1M |
| 5 VDC | Voltage output | Binary | 256 |  | E6C3-AN1E 256P/R 1M |
| 12 VDC |  |  |  |  | E6C3-AN2E 256P/R 1M |

*1. Standard models are also available with 2-m cables. When ordering, specify the cable length at the end of the model number (example: E6C3-AG5C 360P/R 2M).
*2. When connecting to the H8PS, use the E6C3-AG5C-C 256, 360, 720P/R. (Only a $2-\mathrm{m}$ cable is available for the 720P/R Model.)
For the 360/720 resolutions, 2-m cables are standard in-stock.

## Accessories (Order Separately)

[Dimensions: Refer to Accessories on page 8 for Extension Cable dimensions and Accessories for the dimensions of other accessories.]

| Name | Model |  |  |
| :--- | :--- | :--- | :--- |
| Couplings | E69-C08B |  | Remarks |
|  | E69-C68B | Different end diameter (6 to 8 mm) |  |
| Flanges | E69-FCA03 |  |  |
|  | E69-FCA04 | E69-2 Servo Mounting Bracket provided. |  |
| Servo Mounting Bracket | E69-2 | Provided with E69-FCA04 Flange. |  |
|  | E69-DF5 | 5 m | Applicable to the E6C3-AG5C-C. |
|  | E69-DF10 | 10 m |  |
|  | E69-DF20 | 20 m |  |

Refer to Accessories for details.

## Ratings and Specifications

| Item | Model | $\begin{gathered} \text { E6C3- } \\ \text { AG5C-C } \end{gathered}$ | E6C3AG5C | E6C3AN5C | E6C3AB5C | $\begin{aligned} & \text { E6C3- } \\ & \text { AG5B } \end{aligned}$ | E6C3AN5B | $\begin{aligned} & \text { E6C3- } \\ & \text { AB5B } \end{aligned}$ | E6C3AN1E | $\begin{aligned} & \hline \text { E6C3- } \\ & \text { AN2E } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power supply voltage |  | 12 VDC $-10 \%$ to 24 VDC $+15 \%$, ripple (p-p): $5 \%$ max. |  |  |  |  |  |  | $\begin{aligned} & \text { 5 VDC } \\ & \pm 5 \% \end{aligned}$ | $\begin{aligned} & \hline 12 \text { VDC } \\ & \pm 10 \% \end{aligned}$ |
| Current consumption*1 |  | 70 mA max. |  |  |  |  |  |  |  |  |
| Resolution*2 (pulses/rotation) |  | $\begin{aligned} & 256,360, \\ & 720 \end{aligned}$ | $\begin{aligned} & 256,360, \\ & 720,1,024 \\ & \hline \end{aligned}$ | 32, 40 | 6, 8, 12 | $\begin{aligned} & \hline 256,360, \\ & 720,1,024 \\ & \hline \end{aligned}$ | 32, 40 | 6, 8, 12 | 256 |  |
| Output code |  | Gray code |  | Binary | BCD | Gray code | Binary | BCD | Binary |  |
| Output configuration |  | NPN open-collector output |  |  |  | PNP open-collector output |  |  | Voltage output |  |
| Output capacity |  | Applied voltage: 30 VDC max. <br> Sink current: 35 mA max. <br> Residual voltage: 0.4 V max. (at sink current of 35 mA ) |  |  |  | Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA ) |  |  | Output resistance: $2.4 \mathrm{k} \Omega$ | Output resistance: $8.2 \mathrm{k} \Omega$ |
|  |  | Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA ) |  |  |  |
| Rise and fall times of output |  |  |  |  |  | $1 \mu \mathrm{~s} \mathrm{max}$. (Cable length: 2 m , Sink current: 35 mA ) |  |  |  |  |  |  | Rise: $3 \mu \mathrm{~s}$ max., Fall: $1 \mu \mathrm{~s}$ max. | Rise: $10 \mu \mathrm{~s}$ max. <br> Fall: $1 \mu \mathrm{~s}$ max. |
| Maximum response frequency*3 |  | 20 kHz |  |  |  |  |  |  | 10 kHz |  |
| Logic |  | Negative logic (high = 0, low = 1) |  |  |  | Positive logic (high = 1, low =0) |  |  |  |  |
| Direction of rotation*4 |  | Output code increases for CW (as viewed from end of shaft). |  |  |  |  |  |  | Switched using rotation direction input. |  |
| Strobe signal |  | None |  | Supported |  | None | Supported |  | None |  |
| Positioning sig | gnal | None |  |  | Supported | None |  | Supported | None |  |
| Parity signal |  | None |  | Supported (even) | None |  | Supported (even) | None |  |  |
| Starting torque |  | $10 \mathrm{mN} \cdot \mathrm{m}$ max. at room temperature, $30 \mathrm{mN} \cdot \mathrm{m}$ max. at low temperature |  |  |  |  |  |  |  |  |
| Moment of inertia |  | $2.3 \times 10^{-6} \mathrm{~kg} \cdot \mathrm{~m}^{2}$ |  |  |  |  |  |  |  |  |
| Shaft loading | Radial | 80 N |  |  |  |  |  |  |  |  |
|  | Thrust | 50 N |  |  |  |  |  |  |  |  |
| Maximum permissible speed |  | 5,000 r/min |  |  |  |  |  |  |  |  |
| Ambient temperature range |  | Operating: -10 to $70^{\circ} \mathrm{C}$ (with no icing), Storage: -25 to $85^{\circ} \mathrm{C}$ (with no icing) |  |  |  |  |  |  |  |  |
| Ambient humidity range |  | Operating/Storage: $35 \%$ to $85 \%$ (with no condensation) |  |  |  |  |  |  |  |  |
| Insulation resistance |  | $20 \mathrm{M} \Omega \mathrm{min}$. (at 500 VDC ) between current-carrying parts and case |  |  |  |  |  |  |  |  |
| Dielectric strength |  | $500 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}$ for 1 min between current-carrying parts and case |  |  |  |  |  |  |  |  |
| Vibration resistance |  | Destruction: 10 to $500 \mathrm{~Hz}, 150 \mathrm{~m} / \mathrm{s}^{2}$ or 2-mm double amplitude for 11 min 3 times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |  |  |  |  |  |
| Shock resistance |  | Destruction: $1,000 \mathrm{~m} / \mathrm{s}^{2} 3$ times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |  |  |  |  |  |
| Degree of protection |  | IEC 60529 IP65, in-house standards: oilproof |  |  |  |  |  |  |  |  |
| Connection method |  | Connector Models *6 | Pre-wired Models (Standard cable length: 1 m ) |  |  |  |  |  |  |  |
| Material |  | Case: Aluminum, Main unit: Aluminum, Shaft: SUS303 |  |  |  |  |  |  |  |  |
| Weight (packed state) |  | Approx. 300 g |  |  |  |  |  |  |  |  |
| Accessories |  | Instruction manual Note: Coupling, mounting bracket and hex-head spanner are sold separately. |  |  |  |  |  |  |  |  |

*1. An inrush current of approximately 6 A will flow for approximately 0.8 ms when the power is turned ON
*2. The code is as follows:

| Output <br> code | Resolu- <br> tion | Code No. |
| :--- | :--- | :--- |
| Binary | 32 | 1 to 32 |
|  | 40 | 1 to 40 |
|  | 256 | 0 to 255 |
| BCD | 6 | 0 to 5 |
|  | 8 | 0 to 7 |
|  | 12 | 0 to 11 |
|  | 256 | 0 to 255 |
|  | 360 | 76 to 435 (gray after 76 ) |
|  | 720 | 152 to 871 (gray after 152 ) |
|  | 1,024 | 0 to 1,023 |

*3. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

Maximum electrical response speed $(r p m)=$ Maximum response frequency $\times 60$
Resolution
This means that the Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed
*4. For the E6C3-AN1E and E6C3-AN2E, the rotation direction input (wire color: pink) can be connected to high (Vcc) to increase the output code for CW rotation and connected to low ( 0 V ) to decrease the output code for CW rotation. E6C3-AN1E: High $=1.5$ to 5 V , Low $=0$ to 0.8 V

E6C3-AN2E: $\mathrm{High}=2.2$ to 12 V , Low $=0$ to 1.2 V

Read the code $10 \mu$ s or more after the LSB $\left(2^{0}\right)$ of the code changes for the E6C3-AN1E or E6C3-AN2E.
*5. The minimum address of the absolute code is output when cut face D on the shaft and the cable connection direction are as shown in the diagram at the right (output position range: $\pm 15^{\circ}$ ).

*6. Resolution of 360 or 720: Standard cable
length: 2 m
Resolution of 256: Standard cable length: 1 m

## I/O Circuit Diagrams

| Model | E6C3-AG5C/-AG5C-C ${ }^{\text {E6C3-AG5B }}$ | E6C3-AN5C E6C3-AN5B |
| :---: | :---: | :---: |
| Output Circuits | Note: The circuit is the same for all bit outputs. Each E6C3-A Rotary Encoder has one main circuit. <br> Note: The circuit is the same for all bit outputs. Each E6C3-A Rotary Encoder has one main circuit. | Note: The circuit is the same for all bit outputs. Each E6C3-A Rotary Encoder has one main circuit. <br> Note: The circuit is the same for all bit outputs. Each E6C3-A Rotary Encoder has one main circuit. |
| Output mode | Direction of rotation: CW (as viewed from the end of the shaft) | Direction of rotation: CW (as viewed from the end of the shaft) Resolution/40 |

## Connection Specifications

## Connector Models

| ModelPin No. | E6C3-AG5C-C |  |  |
| :---: | :---: | :---: | :---: |
|  | Output signal |  |  |
|  | 8-bit (256) | 9-bit (360) | 10-bit (720) |
| 1 | $\}$ Connected | Not connected | $2^{9}$ |
| 2 | $\}$ internally | $2^{8}$ | $2^{8}$ |
| 3 | $2^{5}$ | $2^{5}$ | $2^{5}$ |
| 4 | $2^{1}$ | $2^{1}$ | $2^{1}$ |
| 5 | $2^{0}$ | $2^{0}$ | $2^{0}$ |
| 6 | $2^{7}$ | $2^{7}$ | $2^{7}$ |
| 7 | $2^{4}$ | $2^{4}$ | $2^{4}$ |
| 8 | $2^{2}$ | $2^{2}$ | $2^{2}$ |
| 9 | $2^{3}$ | $2^{3}$ | $2^{3}$ |
| 10 | $2^{6}$ | $2^{6}$ | $2^{6}$ |
| 11 |  | Shield (ground) |  |
| 12 |  | 12 to 24 VDC |  |
| 13 |  | 0 V (common) |  |

[^0]Pre-wired Models

| Model | E6C3-AG5C/E6C3-AG5B |  |  |
| :---: | :---: | :---: | :---: |
|  | Output signal |  |  |
| Brown | 8-bit (256) | 9-bit (360) | 10-bit (720 or <br> $\mathbf{1 , 0 2 4 )}$ |
| Orange | $2^{0}$ | $2^{0}$ | $2^{0}$ |
| Yellow | $2^{2}$ | $2^{1}$ | $2^{1}$ |
| Green | $2^{3}$ | $2^{2}$ | $2^{2}$ |
| Blue | $2^{4}$ | $2^{3}$ | $2^{3}$ |
| Purple | $2^{5}$ | $2^{4}$ | $2^{4}$ |
| Gray | $2^{6}$ | $2^{5}$ | $2^{5}$ |
| White | $2^{7}$ | $2^{6}$ | $2^{6}$ |
| Pink | Not connected | $2^{7}$ | $2^{7}$ |
| Light blue | Not connected | Not connected | $2^{8}$ |
| --- | Shield (ground) |  |  |
| Red | 12 to 24 VDC |  |  |
| Black | 0 V (common) |  |  |

## I/O Circuit Diagrams



## Connection Specifications

## Pre-wired Models

| Wire color Model | E6C3-AN5C/-AN5B | E6C3-AB5C/-AB5B |  | E6C3-AN1E/-AN2E |
| :---: | :---: | :---: | :---: | :---: |
|  | Output signal | Output signal |  | Output signal |
|  | 6-bit (32 or 40) | 3-bit (6 or 8) | 5-bit (12) | 8-bit (256) |
| Brown | $2^{0}$ | $2^{0}$ | $2^{0}$ | $2^{0}$ |
| Orange | $2^{1}$ | $2^{1}$ | $2^{1}$ | $2^{1}$ |
| Yellow | $2^{2}$ | $2^{2}$ | $2^{2}$ | $2^{2}$ |
| Green | $2^{3}$ | Not connected | $2^{3}$ | $2^{3}$ |
| Blue | $2^{4}$ | Not connected | $2^{0} \times 10$ | $2^{4}$ |
| Purple | $2^{5}$ | Not connected | Not connected | $2^{5}$ |
| Gray | Parity | Positioning | Positioning | $2^{6}$ |
| White | Strobe | Strobe | Strobe | $2^{7}$ |
| Pink | Not connected | Not connected | Not connected | Rotation Direction Input |
| Light blue | Not connected | Not connected | Not connected | Not connected |
| --- | Shield (ground) |  |  |  |
| Red | 12 to 24 VDC |  |  | 5 or 12 VDC |
| Black | 0 V (common) |  |  |  |

[^1]
## Connection Example

H8PS Cam Positioner Connection Example


Specifications

| Rated voltage | 24 VDC |
| :---: | :---: |
| Cam precision | $0.5^{\circ}$ (for 720 resolution), $1^{\circ}$ (for 256/360 resolution) |
| No. of output points | 8-point output type: <br> 8 cam outputs, 1 RUN output, 1 pulse output <br> 16-point output type: <br> 16 cam outputs, 1 RUN output, 1 pulse output <br> 32-point output type: <br> 32 cam outputs, 1 RUN output, 1 pulse output |
| Encoder response | RUN mode, test mode: <br> 256/360 resolution ..... 1,600 r/min max. (1,200 r/min when advance compensation is set for four cams or more) 720 resolution ............ $800 \mathrm{r} / \mathrm{min}$ max. ( $600 \mathrm{r} / \mathrm{min}$ when advance compensation is set for four cams or more) |
| Additional functions | - Origin compensation (zeroing) <br> - Rotation direction switching <br> - Angle display switching <br> - Teaching <br> - Pulse output <br> - Angle/number of rotations display switching <br> - Puncture * <br> - Angle advance <br> - Number of rotations alarm output <br> - Setting with support software (order separately) * |

* For 16-point and 32-point output types only


## Programmable Controller Connection Example

## Connection to the CPM1A

(720 Resolution)


Ladder Programming Example

Wiring between the E6C3-AG5C and CPM1A

| E6C3-AG5C out- <br> put signal | CPM1A input <br> signal |
| :---: | :---: |
| Brown $\left(2^{0}\right)$ | 00000 |
| Orange $\left(2^{1}\right)$ | 00001 |
| Yellow $\left(2^{2}\right)$ | 00002 |
| Green $\left(2^{3}\right)$ | 00003 |
| Blue $\left(2^{4}\right)$ | 00004 |
| Purple $\left(2^{5}\right)$ | 00005 |
| Gray $\left(2^{6}\right)$ | 00006 |
| White $\left(2^{7}\right)$ | 00007 |
| Pink $\left(2^{8}\right)$ | 00008 |
| Light blue $\left(2^{9}\right)$ | 00009 |

Output Timing



| DM6200 | 0000 | $\left[\begin{array}{l} \text { Lower limit } 1 \\ \text { Upper limit } 1 \end{array}\right] \text { Bit CIO } 20300$ |  |
| :---: | :---: | :---: | :---: |
| 6201 | 0540 |  |  |
| 6202 | 0090 | $\left[\begin{array}{l} \text { Lower limit 2 } \\ \text { Upper limit 2 } 2 \end{array}\right] \text { Bit CIO } 20301$ |  |
| 6203 | 0360 |  |  |
| 6204 | 0180 | $\left[\begin{array}{l}\text { Lower limit } 3 \\ \text { Upper limit } 3\end{array}\right]$ Bit CIO 20302 |  |
| 6205 | 0659 |  |  |
| 6206 | 0000 | Lower limit 4 |  |
|  |  |  | Not used in this example. |
| 6231 | 0000 | Upper limit 16 |  |

CPM1A For details, refer to the SYSMAC C200HX/HG/HE/C200H/C200HS/CQM1/CPM1A/SRM1 Command Reference Manual (SCCC-304).

## Safety Precautions

Refer to Warranty and Limitations of Liability.

| \$ WARNING |
| :--- |
| This product is not designed or rated for ensuring |
| safety of persons either directly or indirectly. |
| Do not use it for such purposes. |

## Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

## - Wiring

## Connections

Cable Extension Characteristics

- Conditions will change according to frequency, noise, and other factors. As a guideline, use a cable length of $10 \mathrm{~m}^{*}$ or less.
* Recommended Cable

Conductor cross section: $0.2 \mathrm{~mm}^{2}$
Spiral shield
Conductor resistance: $92 \Omega / \mathrm{km}$ max. $\left(20^{\circ} \mathrm{C}\right)$
Insulation resistance: $5 \Omega / \mathrm{km} \mathrm{min}$. $\left(20^{\circ} \mathrm{C}\right)$

- The output waveform startup time changes not only according to the length of the cable, but also according to the load resistance and the cable type.
- Extending the cable length not only changes the startup time, but also increases the output residual voltage.


## - Connection

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

Dimensions Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

## Encoder

E6C3-A $\square \square \square$
E6C3-AN $\square \mathrm{E}$


Note: The E69-C08B Coupling is sold separately.

 conductors (Conductor cross section: $0.2 \mathrm{~mm}^{2}$. Insulator diameter: 1.1 mm ), Standard length: 1 m

E6C3-AG5C-C


Note: The E69-C08B Coupling is sold separately.



6-dia. oil-resistant PVC-insulated shielded cable with 12
conductors (Conductor cross section: $0.2 \mathrm{~mm}^{2}$, Insulato
diameter: 1.1 mm ), Standard length: 1 m , Standard length for resolution of 360 or 720 : 2 m

## Accessories (Order Separately)

## Extension Cable

## E69-DF5


*1. 6-dia. oil-resistant PVC-insulated shielded cable with 12 conductors (Conductor cross section: $0.2 \mathrm{~mm}^{2}$, Insulator diameter: 1.1 mm ), Standard length: 5 m
Connects to connector on E6C3-AG5C-C
*3. Connects to H8PS Cam Positioner
Note: 1. The E69-DF5 (5 m) is also available with the following cable lengths: $10 \mathrm{~m}, 15 \mathrm{~m}, 20 \mathrm{~m}$, and 98 m
2. Cable can be extended to 100 m when the H8PS Cam Positioner is connected

| Couplings | Flanges |
| :--- | :--- |
| E69-C08B | E69-FCA03 |
| E69-C68B | E69-FCA04 |

## Servo Mounting Bracket <br> E69-2

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Omron:
E6C3-AB5C 12P/R 1M E6C3-AB5C 12P/R 2M E6C3-AB5C 6P/R 1M E6C3-AB5C 6P/R 2M E6C3-AB5C 8P/R 1M E6C3-AB5C 8P/R 2M E6C3-AG5B 1024P/R 1M E6C3-AG5B 1024P/R 2M E6C3-AG5B 256P/R 1M E6C3-AG5B 256P/R 2M E6C3-AG5B 360P/R 1M E6C3-AG5B 360P/R 2M E6C3-AG5B 720P/R 1M E6C3-AG5B 720P/R 2M E6C3-AG5C 1024P/R 1M E6C3-AG5C 1024P/R 2M E6C3-AG5C 256P/R 1M E6C3-AG5C 256P/R 2M E6C3-AG5C 360P/R 1M E6C3-AG5C 360P/R 2M E6C3-AG5C 720P/R 1M E6C3-AG5C 720P/R 2M E6C3-AG5C-C 256P/R 1M E6C3-AG5C-C 256P/R 2M E6C3-AG5C-C 360P/R 1M E6C3-AG5C-C 360P/R 2M E6C3-AN1E 256P/R 1M E6C3AN1E 256P/R 2M E6C3-AN5B 32P/R 1M E6C3-AN5B 32P/R 2M E6C3-AN5C 32P/R 1M E6C3-AN5C 32P/R 2M E6C3-AN5C 40P/R 1M E6C3-AN5C 40P/R 2M E6C3-AG5C 360P/R 5M


[^0]:    Connector: RP13A-12PD-13SC (Hirose Electric Co., Ltd.)
    Note: Normally connect GND to 0 V or to an external ground.

[^1]:    Note: Normally connect GND to 0 V or to an external ground.

