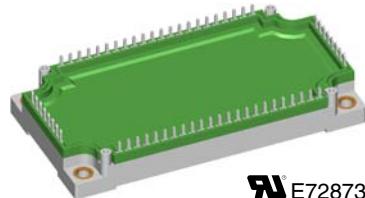
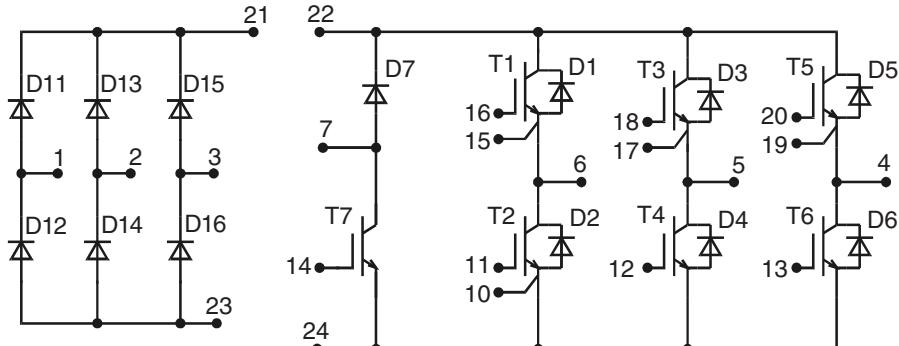
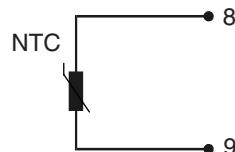


## Converter - Brake - Inverter Module (CBI3)



See outline drawing for pin arrangement

### Preliminary data



Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600 \text{ V}$	$V_{CES} = 600 \text{ V}$	$V_{CES} = 600 \text{ V}$
$I_{FAV} = 90 \text{ A}$	$I_{C25} = 50 \text{ A}$	$I_{C25} = 125 \text{ A}$
$I_{FSM} = 850 \text{ A}$	$V_{CE(sat)} = 1.9 \text{ V}$	$V_{CE(sat)} = 1.9 \text{ V}$

### Input Rectifier D11 - D16

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$		1600		V
$I_{FAV}$	$T_c = 80^\circ\text{C}$ ; sine $180^\circ$	65		A
$I_{DAVM}$	$T_c = 80^\circ\text{C}$ ; rectangular; $d = 1/3$ ; bridge	180		A
$I_{FSM}$	$T_{VJ} = 25^\circ\text{C}$ ; $t = 10 \text{ ms}$ ; sine 50 Hz	850		A
$P_{tot}$	$T_c = 25^\circ\text{C}$	170		W

Symbol	Conditions	Characteristic Values		
		( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_F$	$I_F = 100 \text{ A}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.3 1.3	1.5 V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1	0.05 mA mA
$R_{thJC}$	(per diode)			0.73 K/W

### Application: AC motor drives with

- € Input from single or three phase grid
- € Three phase synchronous or asynchronous motor
- € Electric braking operation

### Features

- € High level of integration - only one power semiconductor module required for the whole drive
- € NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- € Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- € Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- € Temperature sense included

**Output Inverter T1 - T6**

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	600		V
$V_{GES}$	Continuous		$\pm 20$	V
$I_{C25}$	$T_C = 25^\circ\text{C}$	125		A
$I_{C80}$	$T_C = 80^\circ\text{C}$	85		A
<b>RBSOA</b>	$V_{GE} = \pm 15\text{ V}$ ; $R_G = 2.2\text{ }\Omega$ ; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100\text{ }\mu\text{H}$	$I_{CM} = 200$		A
$t_{sc}$ <b>(SCSOA)</b>	$V_{CE} = V_{CES}$ ; $V_{GE} = \pm 15\text{ V}$ ; $R_G = 2.2\text{ }\Omega$ ; $T_{VJ} = 125^\circ\text{C}$ non-repetitive	10		$\mu\text{s}$
$P_{tot}$	$T_C = 25^\circ\text{C}$	410		W

Symbol	Conditions	Characteristic Values		
		( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)	min.	typ.
$V_{CE(sat)}$	$I_C = 100\text{ A}$ ; $V_{GE} = 15\text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.9 2.2	2.5 V V
$V_{GE(th)}$	$I_C = 1.5\text{ mA}$ ; $V_{GE} = V_{CE}$	4.5		6.5 V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.4 1.5	mA mA
$I_{GES}$	$V_{CE} = 0\text{ V}$ ; $V_{GE} = \pm 20\text{ V}$		400	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 300\text{ V}$ ; $I_C = 100\text{ A}$ $V_{GE} = \pm 15\text{ V}$ ; $R_G = 2.2\text{ }\Omega$		25 11 150 30 1.0 2.9	ns ns ns ns mJ mJ
$C_{ies}$			4.3	nF
$Q_{Gon}$			340	nC
$R_{thJC}$	(per IGBT)			0.3 K/W

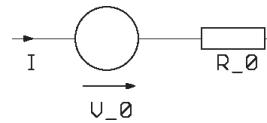
**Output Inverter D1 - D6**

Symbol	Conditions	Maximum Ratings		
$I_{F25}$	$T_C = 25^\circ\text{C}$	140		A
$I_{F80}$	$T_C = 80^\circ\text{C}$	85		A

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 100\text{ A}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.9 1.4	2.2 V V
$I_{RM}$ $t_{rr}$	$I_F = 60\text{ A}$ ; $di_F/dt = -500\text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^\circ\text{C}$ $V_R = 300\text{ V}$ ; $V_{GE} = 0\text{ V}$		28 100	A ns
$R_{thJC}$				0.61 K/W

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**Equivalent Circuits for Simulation****Conduction**IGBT (typ. at  $V_{GE} = 15\text{ V}$ ;  $T_J = 125^\circ\text{C}$ )  
T1-T6

$$V_0 = 1.05\text{ V}; R_0 = 11.5\text{ m}\Omega$$

T7

$$V_0 = 1.05\text{ V}; R_0 = 21.5\text{ m}\Omega$$

Diode (typ. at  $T_J = 125^\circ\text{C}$ )

D1-D6

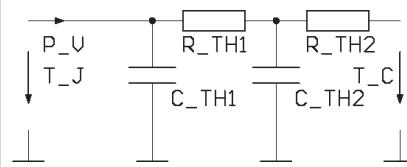
$$V_0 = 1.15\text{ V}; R_0 = 2.5\text{ m}\Omega$$

D7

$$V_0 = 1.15\text{ V}; R_0 = 12.5\text{ m}\Omega$$

D11-D16

$$V_0 = 0.85\text{ V}; R_0 = 4\text{ m}\Omega$$

**Thermal Response**

IGBT (typ.)

T1-T6

$$C_{th1} = 0.232\text{ J/K}; R_{th1} = 0.223\text{ K/W}$$

$$C_{th2} = 1.504\text{ J/K}; R_{th2} = 0.077\text{ K/W}$$

T7

$$C_{th1} = 0.123\text{ J/K}; R_{th1} = 0.419\text{ K/W}$$

$$C_{th2} = 0.944\text{ J/K}; R_{th2} = 0.131\text{ K/W}$$

Diode (typ.)

D1-D6

$$C_{th1} = 0.138\text{ J/K}; R_{th1} = 0.48\text{ K/W}$$

$$C_{th2} = 0.957\text{ J/K}; R_{th2} = 0.13\text{ K/W}$$

D7

$$C_{th1} = 0.038\text{ J/K}; R_{th1} = 1.74\text{ K/W}$$

$$C_{th2} = 0.435\text{ J/K}; R_{th2} = 0.36\text{ K/W}$$

D11-D16

$$C_{th1} = 0.112\text{ J/K}; R_{th1} = 0.568\text{ K/W}$$

$$C_{th2} = 0.745\text{ J/K}; R_{th2} = 0.162\text{ K/W}$$

**Brake Chopper T7**

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	600		V
$V_{GES}$	Continuous	$\pm 20$		V
$I_{C25}$	$T_C = 25^\circ\text{C}$	75		A
$I_{C80}$	$T_C = 80^\circ\text{C}$	50		A
<b>RBSOA</b>	$V_{GE} = \pm 15 \text{ V}$ ; $R_G = 22 \Omega$ ; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 100$ $V_{CEK} \leq V_{CES}$		A
<b>t<sub>sc</sub> (SCSOA)</b>	$V_{CE} = V_{CES}$ ; $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 22 \Omega$ ; $T_{VJ} = 125^\circ\text{C}$ non-repetitive	10	$\mu\text{s}$	
$P_{tot}$	$T_C = 25^\circ\text{C}$	225		W

Symbol	Conditions	Characteristic Values		
		( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 50 \text{ A}$ ; $V_{GE} = 15 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.9 2.1	2.3 V	V
$V_{GE(th)}$	$I_C = 1 \text{ mA}$ ; $V_{GE} = V_{CE}$	4.5		6.5 V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.5	0.5 mA
$I_{GES}$	$V_{CE} = 0 \text{ V}$ ; $V_{GE} = \pm 20 \text{ V}$		200	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 300 \text{ V}$ ; $I_C = 50 \text{ A}$ $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 22 \Omega$	50 55 300 30 2.3 1.7		ns ns ns ns mJ mJ
$C_{ies}$ $Q_{Gon}$		2.8 120		nF nC
$R_{thJC}$			0.55	K/W

**Brake Chopper D7**

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	600		V
$I_{F25}$	$T_C = 25^\circ\text{C}$	35		A
$I_{F80}$	$T_C = 80^\circ\text{C}$	24		A
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$V_F$	$I_F = 50 \text{ A}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	2.2 1.8	2.5 V	V
$I_R$	$V_R = V_{RRM}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.1	0.1	mA
$I_{RM}$ $t_{rr}$	$I_F = 15 \text{ A}$ ; $dI_F/dt = -400 \text{ A}/\mu\text{s}$ ; $T_{VJ} = 125^\circ\text{C}$ $V_R = 300 \text{ V}$	13 90		A ns
$R_{thJC}$			2.1	K/W

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## Temperature Sensor NTC

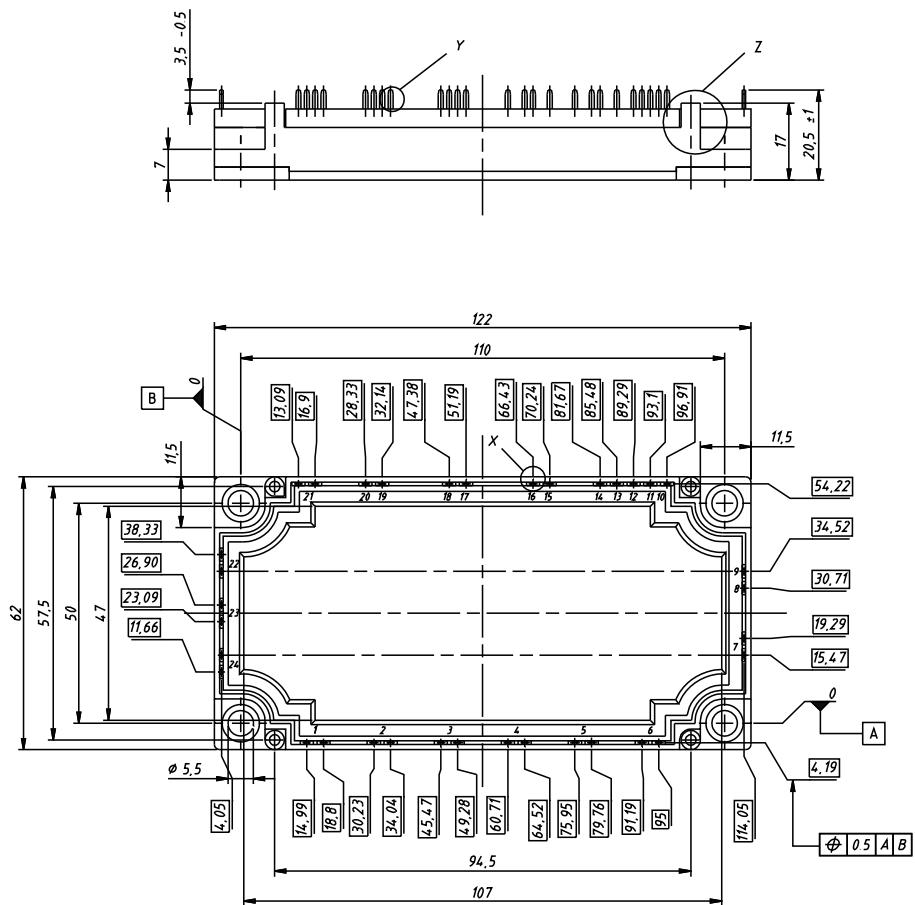
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$ $B_{25/50}$	$T = 25^\circ\text{C}$	4.75	5.0 3375	5.25 k $\Omega$ K

## Module

Symbol	Conditions	Maximum Ratings		
$T_{VJ}$	operating	-40...+125	°C	
$T_{JM}$		+150	°C	
$T_{stg}$		-40...+125	°C	
$V_{ISOL}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~	
$M_d$	Mounting torque (M5)	3 - 6	Nm	

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$		5	m $\Omega$	
$d_s$	Creepage distance on surface	6	mm	
$d_A$	Strike distance in air	6	mm	
$R_{thCH}$	with heatsink compound	0.01	K/W	
Weight		300	g	

Dimensions in mm (1 mm = 0.0394")



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