# E6B2-C

CSM\_E6B2-C\_DS\_E\_6\_1

# **General-purpose Encoder with External Diameter of 40 mm**

- Incremental model
- External diameter of 40 mm.
- Resolution of up to 2,000 ppr.





Be sure to read Safety Precautions on

For the most recent information on models that have been certified for safety standards, refer to your OMRON website.

# **Ordering Information**

#### Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configura- tion	Resolution (pulses/rotation)	Model	
5 to 24 VDC	NPN open-collector output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6B2-CWZ6C (resolution) 0.5M Example: E6B2-CWZ6C 10P/R 0.5M	
		720, 800, 1,000, 1,024		
		1,200, 1,500, 1,800, 2,000		
12 to 24 VDC	PNP open-collector output	100, 200, 360, 500, 600	<b>E6B2-CWZ5B (resolution) 0.5M</b> Example: E6B2-CWZ5B 100P/R 0.5M	
		1,000		
		2,000		
5 to 12 VDC	Voltage output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6B2-CWZ3E (resolution) 0.5M Example: E6B2-CWZ3E 10P/R 0.5M	
		1,000		
		1,200, 1,500, 1,800, 2,000		
5 VDC	Line-driver output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600		
		1,000, 1,024	<b>E6B2-CWZ1X (resolution) 0.5M Example:</b> E6B2-CWZ1X 10P/R 0.5M	
		1,200, 1,500, 1,800, 2,000	LAGINGIO. LOBE GVVETA TOTATO ON	

#### Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks	
	E69-C06B	Provided with the product.	
Couplings	E69-C68B	Different end diameter	
Couplings	E69-C610B	Different end diameter	
	E69-C06M	Metal construction	
Flanges	E69-FBA		
rianges	E69-FBA02	E69-2 Servo Mounting Bracket provided.	
Servo Mounting Bracket <b>E69-2</b>			

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Note: 1. Refer to Rotary Encoders Accessories on your OMRON website for details.

2. Refer to Precautions For Correct Use of Rotary Encoders on your OMRON website when using the Rotary Encoders together with a Coupling.

# **Ratings and Specifications**

Item	Model	E6B2-CWZ6C	E6B2-CWZ5B	E6B2-CWZ3E	E6B2-CWZ1X		
Power supply voltage		5 VDC –5% to 24 VDC +15%, ripple (p-p): 5% max.	12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.	5 VDC –5% to 12 VDC +10%, ripple (p-p): 5% max.	5 VDC ±5%, ripple (p-p): 5% max.		
Current consumption *1		80 mA max.	100 mA max.		160 mA max.		
Resolution (pulses/rotation)		10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000	100, 200, 360, 500, 600, 1,000, 2,000	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 1,000, 1,200, 1,500, 1,800, 2,000	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000		
Output phases		Phases A, B, and Z	Phases A, $\overline{A}$ , B, $\overline{B}$ , Z, and $\overline{Z}$				
Phase difference between outputs		$90^{\circ}\pm45^{\circ}$ between A and B (1/4 T $\pm$ 1/8 T)					
Output configuration		NPN open-collector output	PNP open-collector output	Voltage output (NPN output)	Line driver output *2		
Output capacity		Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA)	Applied voltage: 30 VDC max. Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA)	Output resistance: $2 \text{ k}\Omega$ Sink current: $20 \text{ mA max}$ . Residual voltage: $0.4 \text{ V max}$ . (at sink current of $20 \text{ mA}$ )	AM26LS31 equivalent Output current High level: Io = -20 mA Low level: Is = 20 mA Output voltage: Vo = 2.5 V min. Vs = 0.5 V max.		
Maximum response frequency *3		100 kHz	50 kHz	100 kHz			
Rise and fall times of output		1 $\mu$ s max. (Control output voltage: 5 V, Load resistance: 1 $k\Omega$ , Cable length: 2 m max.)	1 μs max. (Cable length: 2 m max., Sink current: 10 mA)		0.1 μs max. (Cable length: 2 m max., lo = -20 mA, ls = 20 mA)		
Starting torque		0.98 mN⋅m max.					
Moment	t of inertia	$\times 10^{-6}$ kg·m <sup>2</sup> max.; $3 \times 10^{-7}$ kg·m <sup>2</sup> max. at 600 P/R max.					
Shaft	Radial	30 N					
load- ing	Thrust	20 N					
Maximum permissible speed		6,000 r/min					
Protection circuits		Power supply reverse polarity protection, Load short-circuit protection					
Ambien tempera	t ature range	Operating: –10 to 70°C (with no icing), Storage: –25 to 85°C (with no icing)					
Ambient humidity range		Operating/Storage: 35% to 85% (with no condensation)					
Insulation resistance		20 $M\Omega$ min. (at 500 VDC) between current-carrying parts and case					
Dielectr	ic strength	500 VAC, 50/60 Hz for 1 min between current-carrying parts and case					
Vibration resistance		Destruction: 10 to 500 Hz, 150 m/s <sup>2</sup> or 2-mm double amplitude for 11 min 3 times each in X, Y, and Z directions					
Shock r	esistance	Destruction: 1,000m/s <sup>2</sup> 3 times each in X, Y, and Z directions					
Degree of protection		IEC 60529 IP50					
Connection method		Pre-wired Models (Standard cable length: 500 mm)					
Materials		Case: ABS, Main unit: Aluminum, Shaft: SUS420J2					
Weight (packed state)		Approx. 100 g					
Access	ories	ries Coupling, Hexagonal wrench, Instruction manual					
			wimataly 0.2 ma when the newer is				

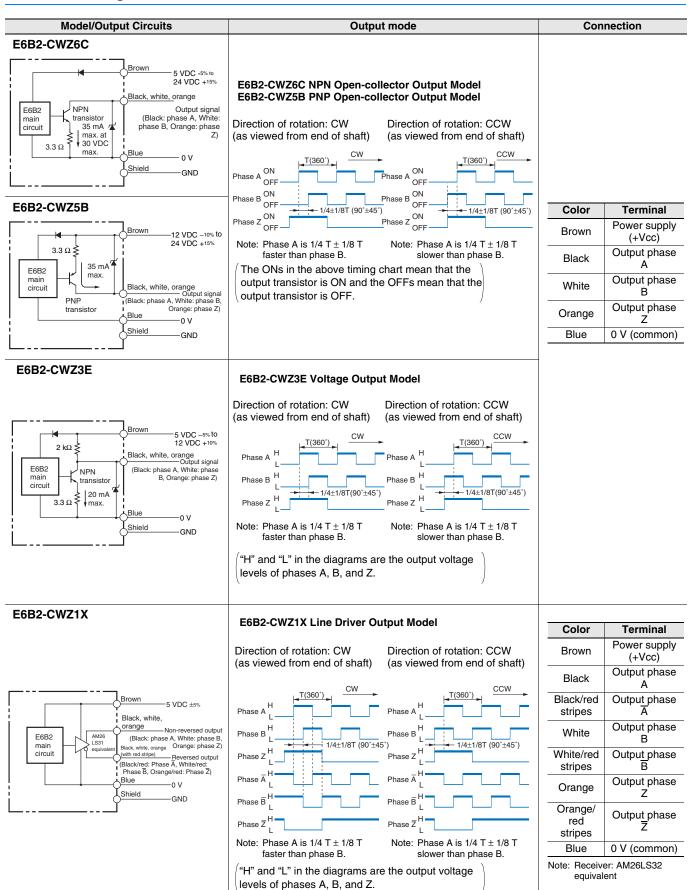
Maximum response frequency ×60 Maximum electrical response speed (rpm) = -Resolution

This means that the E6B2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

<sup>\*1.</sup> An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.
\*2. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable. The quality is equivalent to AM26LS31.

<sup>\*3.</sup> The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

### I/O Circuit Diagrams



Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case.

- 2. The phase A, phase B, and phase Z circuits are all identical. 3. Normally, connect GND to 0 V or to an external ground.

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### **Safety Precautions**

Be sure to read the precautions for all models in the website at: http://www.ia.omron.com/.

#### **⚠** WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



#### **Precautions for Safe Use**

Incorrect wiring may damage internal circuits.

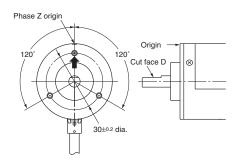
#### **Precautions for Correct Use**

Do not use the Encoder under ambient conditions that exceed the ratings.

#### Mounting

Origin Indication

It is easy to adjust the position of phase Z with the origin indication function. The following illustration shows the relationship between phase Z and the origin. Set cut face D to the phase Z origin as shown in the illustration.



 Do not extend the length of the cable to more than 2 m. If the cable must be more than 2 m, use a Model with a Line-driver Output (max. length: 100 m).

#### Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)

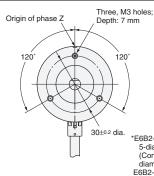
#### **Dimensions**

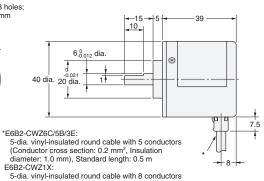
Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

#### **Encoder**

E6B2-C







(Conductor cross section: 0.2 mm², Insulation diameter: 1.0 mm), Standard length: 0.5 m

#### Accessories (Order Separately)

Couplings Flanges E69-C06B E69-FBA

E69-C68B E69-FBA02

E69-C610B E69-C06M

Refer to Rotary Encoders Accessories on your OMRON website for details.

**Servo Mounting Bracket** 

E69-2

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E6B2-CWZ1X 1000P/R 0.5M E6B2-CWZ1X 1000P/R 2M E6B2-CWZ1X 600P/R 2M E6B2-CWZ5B 500P/R 0.5M