

SiGe:C Low Noise Amplifier MMIC for GPS, GLONASS, Galileo and Compass

Rev. 3 — 18 January 2017

Product data sheet

1. Product profile

1.1 General description

The BGU7004 is, also known as the GPS1103M, an AEC-Q100 qualified Low Noise Amplifier (LNA) for GNSS receiver applications in a plastic leadless 6-pin, extremely small SOT886 package. The BGU7004 requires only one external matching inductor and one external decoupling capacitor.

The BGU7004 adapts itself to the changing environment resulting from co-habitation of different radio systems in modern cellular handsets. It has been designed for low power consumption and optimal performance when jamming signals from co-existing cellular transmitters are present. At low jamming power levels it delivers 16.5 dB gain at a noise figure of 0.85 dB. During high jamming power levels, resulting for example from a cellular transmit burst, it temporarily increases its bias current to improve sensitivity.

1.2 Features and benefits

- AEC-Q100 qualified (see Section 9.1)
- Covers full GNSS L1 band, from 1559 MHz to 1610 MHz
- Noise figure (NF) = 0.85 dB and gain (G_p) = 16.5 dB
- High input 1 dB compression point P_i (1dB) of −11 dBm
- High out of band IP3_i of 9 dBm
- Supply voltage 1.5 V to 2.85 V
- Power-down mode current consumption < 1 μA
- Optimized performance at low supply current of 4.5 mA
- Integrated matching for the output
- Requires only one input matching inductor and one supply decoupling capacitor
- Input and output DC decoupled
- ESD protection on all pins (HBM > 2 kV)
- Integrated temperature stabilized bias for easy design
- Small 6-pin leadless package 1 mm × 1.45 mm × 0.5 mm
- 110 GHz transit frequency SiGe:C technology

1.3 Applications

■ LNA for GPS, GLONASS, Galileo and Compass (BeiDou) in automotive applications like Toll Collection and Emergency Call.



SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

■ LNA for GPS, GLONASS, Galileo and Compass (BeiDou) in smart phones, feature phones, tablet PCs, Personal Navigation Devices, Digital Still Cameras, Digital Video Cameras, RF Front End modules, complete GPS chipset modules and theft protection (laptop, ATM).

1.4 Quick reference data

Table 1. Quick reference data

f = 1559 MHz to 1610 MHz; V_{CC} = 1.8 V; P_i < -40 dBm; T_{amb} = 25 °C; input matched to 50 Ω using a 5.6 nH inductor; unless otherwise specified.

Symbo I	Parameter	Conditions		Min	Тур	Max	Unit
V _{CC}	supply voltage	RF input AC coupled		1.5	-	2.85	V
I _{CC}	supply current	V _{ENABLE} ≥ 0.8 V					
		P _i < -40 dBm		3.2	4.5	5.7	mΑ
		$P_i = -20 \text{ dBm}$		8.1	11.6	14.4	mΑ
Gp	power gain	P _i < -40 dBm, no jammer		14	16.5	19	dB
		P _i = -20 dBm, no jammer		15	17.5	20	dB
NF	noise figure	P _i < -40 dBm, no jammer	<u>[1]</u>	-	0.85	1.2	dB
		P _i < -40 dBm, no jammer	[2]	-	0.9	1.3	dB
		P _i = -20 dBm, no jammer		-	1.2	1.6	dB
P _{i(1dB)}	input power at 1 dB	f = 1559 MHz to 1610 MHz					
	gain compression	V _{CC} = 1.5 V		-15	-12	-	dBm
		V _{CC} = 1.8 V		-14	-11	-	dBm
		V _{CC} = 2.85 V		-11	-8	-	dBm
IP3 _i	input third-order intercept point	f = 1.575 GHz					
		V _{CC} = 1.5 V	[3]	5	8	-	dBm
		V _{CC} = 1.8 V	[3]	5	9	-	dBm
		V _{CC} = 2.85 V	[3]	5	12	-	dBm

- [1] PCB losses are substracted.
- [2] Including PCB losses.
- [3] $f_1 = 1713 \text{ MHz}$; $f_2 = 1851 \text{ MHz}$; $P_1 = P_2 = -30 \text{ dBm}$.

2. Pinning information

Table 2. Pinning

Pin	Description	Simplified outline	Graphic symbol
1	GND		
2	GND	6 5 4	4 5
3	RF_IN		3—6
4	V _{CC}		
5	ENABLE		2 1 sym129
6	RF_OUT	1 2 3 Transparent top view	3,25

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

3. Ordering information

Table 3. Ordering information

Type number	Package							
	Name	Description	Version					
BGU7004	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 \times 1.45 \times 0.5 mm	SOT886					

4. Marking

Table 4. Marking codes

Type number	Marking code
BGU7004	UY

5. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions		Min	Max	Unit
V _{CC}	supply voltage	RF input AC coupled		-0.5	3.1	V
V _{ENABLE}	voltage on pin ENABLE	$V_{CC} \ge 2.5 \text{ V}$		-0.5	3.1	V
		V _{CC} < 2.5 V	[2]	-0.5	$V_{CC} + 0.6$	V
V_{RF_IN}	voltage on pin RF_IN	DC				
		$V_{CC} \ge 3.0 \text{ V}$	[3]	-0.5	3.6	V
		V _{CC} < 3.0 V	[2][3]	-0.5	$V_{CC} + 0.6$	V
V_{RF_OUT}	voltage on pin RF_OUT	DC				
		V _{CC} ≥ 1.8 V	[3]	-0.5	3.6	V
		V _{CC} < 1.8 V	[2][3]	-0.5	V _{CC} + 1.8	V
Pi	input power			-	0	dBm
P _{tot}	total power dissipation	T _{sp} ≤ 130 °C	<u>[1]</u>		55	mW
T _{stg}	storage temperature			-65	150	°C
Tj	junction temperature			-	150	°C

^[1] T_{sp} is the temperature at the soldering point of the emitter lead.

6. Thermal characteristics

Table 6. Thermal characteristics

Symbol	Parameter	Conditions	Тур	Unit
R _{th(j-sp)}	thermal resistance from junction to solder point		225	K/W

^[2] Due to internal ESD diode protection, the applied voltage should not exceed the specified maximum in order to avoid excess current.

^[3] The RF input and RF output are AC coupled through internal DC blocking capacitors.

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

7. Characteristics

Table 7. Characteristics

f = 1559 MHz to 1610 MHz; $V_{CC} = 1.8$ V; $V_{ENABLE} \ge 0.8$ V; $P_i < -40$ dBm; $T_{amb} = 25$ °C; input matched to 50 Ω using a 5.6 nH inductor; unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V _{CC}	supply voltage	RF input AC coupled	1.5	-	2.85	V
I _{CC}	supply current	V _{ENABLE} ≥ 0.8 V				
		$P_i < -40 \text{ dBm}$	3.2	4.5	5.7	mA
		$P_i = -20 \text{ dBm}$	8.1	11.6	14.4	mA
		V _{ENABLE} ≤ 0.3 V	-	-	1	μΑ
T _{amb}	ambient temperature		-40	+25	+125	°C
G _p	power gain	T _{amb} = 25 °C				
		P _i < −40 dBm, no jammer	14	16.5	19	dB
		P _i = −20 dBm, no jammer	15	17.5	20	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	15	17.5	20	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	15	17.5	20	dB
		$-40 ^{\circ}\text{C} \le T_{amb} \le +125 ^{\circ}\text{C}$				
		P _i < −40 dBm, no jammer	13	-	20	dB
		P _i = −20 dBm, no jammer	14	-	21	dB
	$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	14	-	21	dB	
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	14	-	21	dB
RLin	input return loss	$P_i < -40 \text{ dBm}$	5	8	-	dB
		$P_i = -20 \text{ dBm}$	6	10	-	dB
RL _{out}	output return loss	$P_i < -40 \text{ dBm}$	10	20	-	dB
		$P_i = -20 \text{ dBm}$	10	14	-	dB
ISL	isolation		20	23	-	dB
NF	noise figure	T _{amb} = 25 °C				
		P _i < -40 dBm, no jammer [1	<u>l</u> -	0.85	1.2	dB
		P _i < -40 dBm, no jammer	<u>l</u> -	0.9	1.3	dB
		P _i = −20 dBm, no jammer	-	1.2	1.6	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	-	1.1	1.5	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	-	1.3	1.7	dB
		$-40 ^{\circ}\text{C} \le T_{amb} \le +125 ^{\circ}\text{C}$				
		P _i < -40 dBm, no jammer	-	-	1.8	dB
		P _i = −20 dBm, no jammer	-	-	2.0	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 850 \text{ MHz}$	-	-	1.9	dB
		$P_{jam} = -20 \text{ dBm}; f_{jam} = 1850 \text{ MHz}$	-	-	2.1	dB

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

Table 7. Characteristics ... continued

f = 1559 MHz to 1610 MHz; V_{CC} = 1.8 V; $V_{ENABLE} \ge 0.8$ V; P_i < -40 dBm; T_{amb} = 25 °C; input matched to 50 Ω using a 5.6 nH inductor; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
P _{i(1dB)} input power at 1 dB		f = 1559 MHz to 1610 MHz					
	gain compression	V _{CC} = 1.5 V		-15	-12	-	dBm
		V _{CC} = 1.8 V		-14	-11	-	dBm
		V _{CC} = 2.85 V		-11	-8	-	dBm
		f = 806 MHz to 928 MHz					
		V _{CC} = 1.5 V	[3]	-15	-12	-	dBm
		V _{CC} = 1.8 V	[3]	-14	-11	-	dBm
		V _{CC} = 2.85 V	[3]	-14	-11	-	dBm
		f = 1612 MHz to 1909 MHz					
		V _{CC} = 1.5 V	[3]	-13	-10	-	dBm
		V _{CC} = 1.8 V	[3]	-12	-9	-	dBm
		V _{CC} = 2.85 V	[3]	-10	-7	-	dBm
IP3 _i	input third-order intercept point	f = 1.575 GHz					
		V _{CC} = 1.5 V	[4]	5	8	-	dBm
		V _{CC} = 1.8 V	[4]	5	9	-	dBm
		V _{CC} = 2.85 V	[4]	5	12	-	dBm
t _{on}	turn-on time		[5]	-	-	2	μS
t _{off}	turn-off time		[5]	-	-	1	μS
K	Rollett stability factor			1	-	-	

- [1] PCB losses are subtracted.
- [2] Including PCB losses.
- [3] Out of band
- [4] $f_1 = 1713 \text{ MHz}$; $f_2 = 1851 \text{ MHz}$; $P_1 = P_2 = -30 \text{ dBm}$.
- [5] Within 10 % of the final gain.

Table 8. ENABLE (pin 5)

 $-40 \,{}^{\circ}C \le T_{amb} \le +125 \,{}^{\circ}C; \ 1.5 \ V \le V_{CC} \le 2.85 \ V$

V _{ENABLE} (V)	State
≤ 0.3	OFF
≥ 0.8	ON

SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

8. Application information

8.1 GNSS LNA

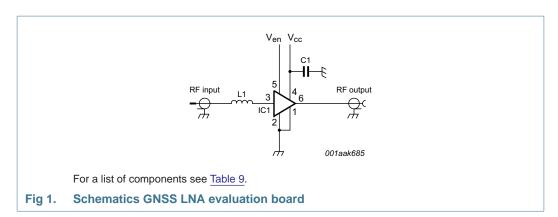
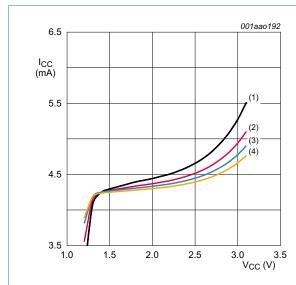


Table 9. List of components

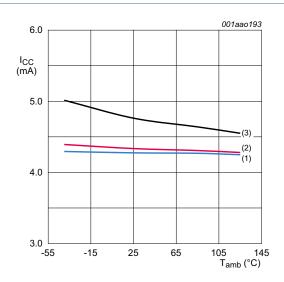
For schematics see Figure 1.

Component	Description	Value	Supplier	Remarks
C1	decoupling capacitor	1 nF	various	
IC1	BGU7004	-	NXP	
L1	high quality matching inductor	5.6 nH	Murata LQW15A	



- $P_i = -45 \text{ dBm}.$
- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

Fig 2. Supply current as a function of supply voltage; typical values

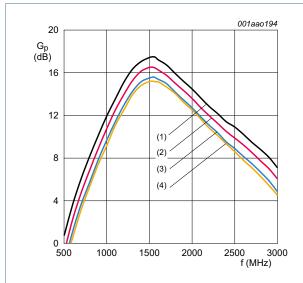


- $P_i = -45 \text{ dBm}.$
- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

Fig 3. Supply current as a function of ambient temperature; typical values

BGU7004

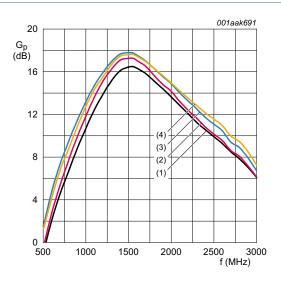
SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass



$$V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$$

- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

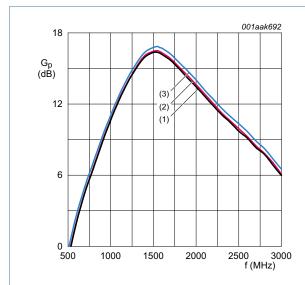
Fig 4. Power gain as a function of frequency; typical values



$$V_{CC}$$
 = 1.8 V; T_{amb} = 25 °C.

- (1) $P_i = -45 \text{ dBm}$
- (2) $P_i = -30 \text{ dBm}$
- (3) $P_i = -20 \text{ dBm}$
- (4) $P_i = -15 \text{ dBm}$

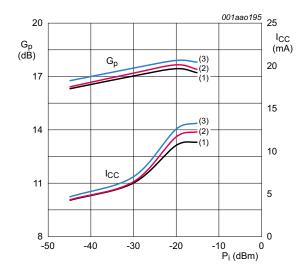
Fig 5. Power gain as a function of frequency; typical values



 $P_i = -45 \text{ dBm}$; $T_{amb} = 25 \text{ }^{\circ}\text{C}$.

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

Fig 6. Power gain as a function of frequency; typical values



$$T_{amb} = 25 \, ^{\circ}C; f = 1575 \, MHz.$$

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

Fig 7. Power gain and supply current as function of input power; typical values

SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

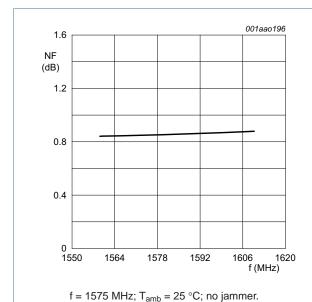
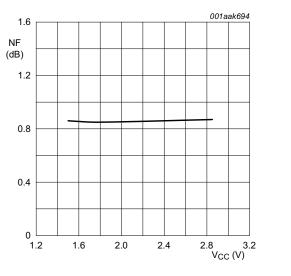
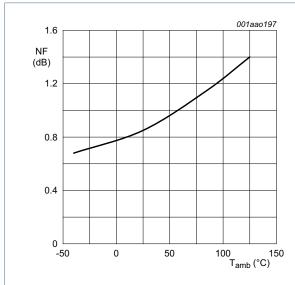


Fig 8. Noise figure as a function of supply voltage; typical values

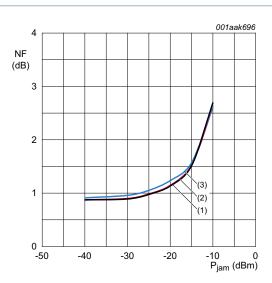


f = 1575 MHz; $T_{amb} = 25 \,^{\circ}\text{C}$; no jammer.

Fig 9. Noise figure as a function of supply voltage; typical values



f = 1575 MHz; V_{CC} = 1.8 V; no jammer.



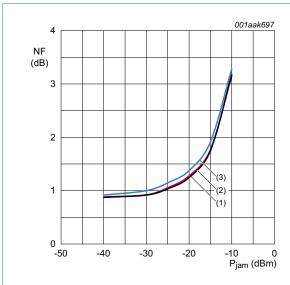
 f_{jam} = 850 MHz; T_{amb} = 25 °C; f = 1575 MHz.

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

Fig 11. Noise figure as a function of jamming power; typical values

Fig 10. Noise figure as a function of ambient temperature; typical values

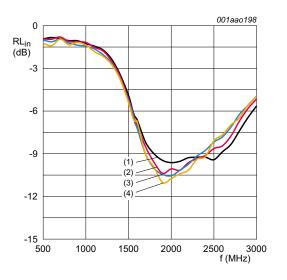
SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass



 f_{jam} = 1850 MHz; T_{amb} = 25 °C; f = 1575 MHz.

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

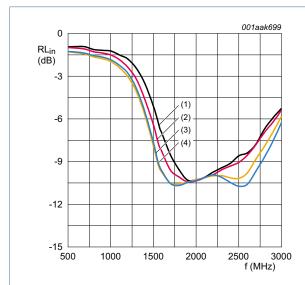
Fig 12. Noise figure as a function of jamming power; typical values



 $V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$

- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

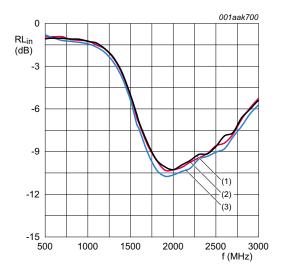
Fig 13. Input return loss as a function of frequency; typical values



 $V_{CC} = 1.8 \text{ V}; T_{amb} = 25 ^{\circ}\text{C}.$

- (1) $P_i = -45 \text{ dBm}$
- (2) $P_i = -30 \text{ dBm}$
- (3) $P_i = -20 \text{ dBm}$
- (4) $P_i = -15 \text{ dBm}$

Fig 14. Input return loss as a function of frequency; typical values

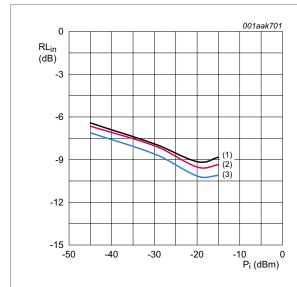


 $P_i = -45 \text{ dBm}$; $T_{amb} = 25 \,^{\circ}\text{C}$.

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

Fig 15. Input return loss as a function of frequency; typical values

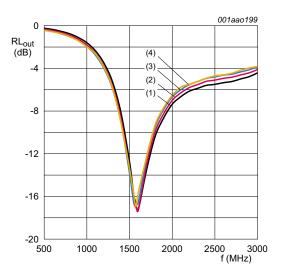
SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass



$$T_{amb} = 25 \, ^{\circ}\text{C}; f = 1575 \, \text{MHz}.$$

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

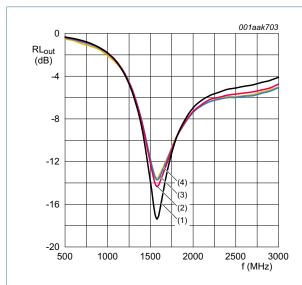
Fig 16. Input return loss as a function of input power; typical values



$$V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$$

- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

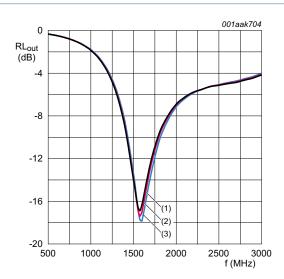
Fig 17. Output return loss as a function of frequency; typical values



 V_{CC} = 1.8 V; T_{amb} = 25 °C.

- (1) $P_i = -45 \text{ dBm}$
- (2) $P_i = -30 \text{ dBm}$
- (3) $P_i = -20 \text{ dBm}$
- (4) $P_i = -15 \text{ dBm}$

Fig 18. Output return loss as a function of frequency; typical values

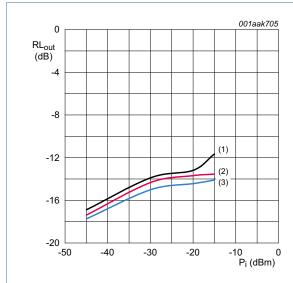


 $P_i = -45 \text{ dBm}$; $T_{amb} = 25 \text{ }^{\circ}\text{C}$.

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

Fig 19. Output return loss as a function of frequency; typical values

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass



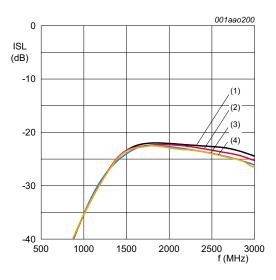
$$T_{amb} = 25 \, ^{\circ}\text{C}; f = 1575 \, \text{MHz}.$$

(1)
$$V_{CC} = 1.5 \text{ V}$$

(2)
$$V_{CC} = 1.8 \text{ V}$$

(3)
$$V_{CC} = 2.85 \text{ V}$$

Fig 20. Output return loss as a function of input power; typical values



$$V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$$

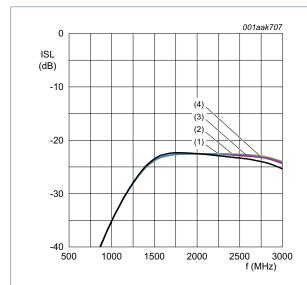
(1)
$$T_{amb} = -40 \, ^{\circ}C$$

(2)
$$T_{amb} = +25 \, ^{\circ}C$$

(3)
$$T_{amb} = +85 \, ^{\circ}C$$

(4)
$$T_{amb} = +125 \, ^{\circ}C$$

Fig 21. Isolation as a function of frequency; typical values



$$V_{CC}$$
 = 1.8 V; T_{amb} = 25 °C.

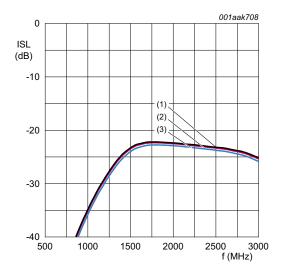
(1)
$$P_i = -45 \text{ dBm}$$

(2)
$$P_i = -30 \text{ dBm}$$

(3)
$$P_i = -20 \text{ dBm}$$

(4)
$$P_i = -15 \text{ dBm}$$

Fig 22. Isolation as a function of frequency; typical values



$$P_i = -45 \text{ dBm}$$
; $T_{amb} = 25 \,^{\circ}\text{C}$.

(1)
$$V_{CC} = 1.5 \text{ V}$$

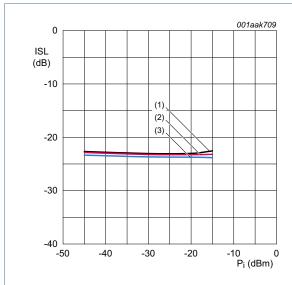
(2)
$$V_{CC} = 1.8 \text{ V}$$

(3)
$$V_{CC} = 2.85 \text{ V}$$

Fig 23. Isolation as a function of frequency; typical values

11 of 20

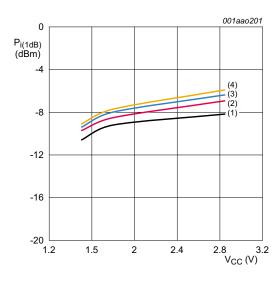
SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass



 $T_{amb} = 25 \,^{\circ}C$; f = 1575 MHz.

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

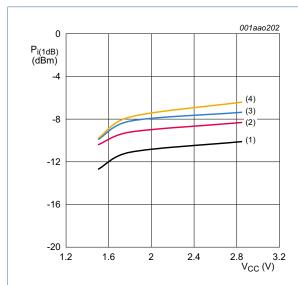
Fig 24. Isolation as a function of input power; typical values



f = 850 MHz.

- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

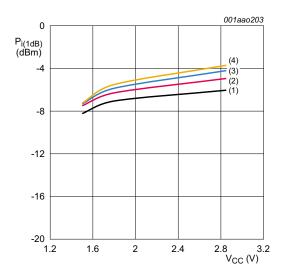
Fig 25. Input power at 1 dB gain compression as a function of supply voltage; typical values



f = 1850 MHz.

- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

Fig 26. Input power at 1 dB gain compression as a function of supply voltage; typical values

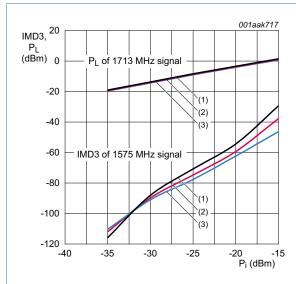


f = 1575 MHz.

- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

Fig 27. Input power at 1 dB gain compression as a function of supply voltage; typical values

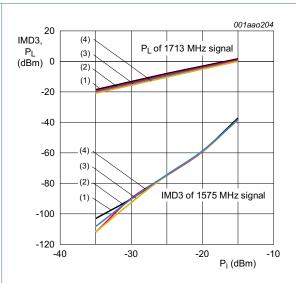
SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass



 $f = 1575 \text{ MHz}; \ f_1 = 1713 \text{ MHz}; \ f_2 = 1851 \text{ MHz}; \\ T_{amb} = 25 \ ^{\circ}\text{C}.$

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

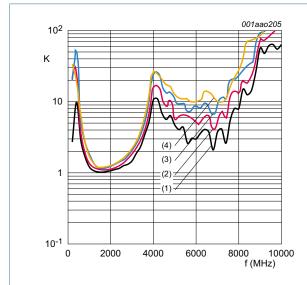
Fig 28. Third order intermodulation distortion and output power as function of input power; typical values



 $f = 1575 \; \text{MHz}; \; f_1 = 1713 \; \text{MHz}; \; f_2 = 1851 \; \text{MHz}; \\ V_{CC} = 1.8 \; \text{V}.$

- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

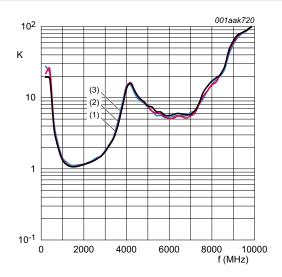
Fig 29. Third order intermodulation distortion and output power as function of input power; typical values



 $V_{CC} = 1.8 \text{ V}; P_i = -45 \text{ dBm}.$

- (1) $T_{amb} = -40 \, ^{\circ}C$
- (2) $T_{amb} = +25 \, ^{\circ}C$
- (3) $T_{amb} = +85 \, ^{\circ}C$
- (4) $T_{amb} = +125 \, ^{\circ}C$

Fig 30. Rollett stability factor as a function of frequency; typical values



 $T_{amb} = 25 \, ^{\circ}C; \, P_i = -45 \, dBm.$

- (1) $V_{CC} = 1.5 \text{ V}$
- (2) $V_{CC} = 1.8 \text{ V}$
- (3) $V_{CC} = 2.85 \text{ V}$

Fig 31. Rollett stability factor as a function of frequency; typical values

BGU7004

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

8.2 GPS front-end

The GPS LNA is typically used in a GPS front-end. A GPS front-end application circuit and its characteristics is provided here.

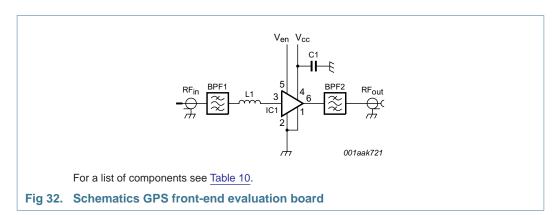


Table 10. List of components

For schematics see Figure 32.

Component	Description	Value	Supplier	Remarks
BPF1, BPF2	GPS SAW filter	-	Murata SAFEA1G57KE0F00	Alternatives from Epcos:
				• B9444
				Alternatives from Murata:
				SAFEA1G57KH0F00
				SAFEA1G57KB0F00
				Alternatives from Fujitsu:
				• FAR-F6KA-1G5754-L4AA
				• FAR-F6KA-1G5754-L4AJ
C1	decoupling capacitor	1 nF	Various	
IC1	BGU7004	-	NXP	
L1	high quality matching inductor	5.6 nH	Murata LQW15A	

SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

8.3 Characteristics GPS front-end

Table 11. Characteristics GPS front-end

f = 1575 MHz; $V_{CC} = 1.8$ V; $V_{ENABLE} \ge 0.8$ V; power at LNA input $P_i < -40$ dBm; $T_{amb} = 25$ °C; input and output matched to 50 Ω ; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
V _{CC}	supply voltage	RF input AC coupled		1.5	-	2.85	V
I _{CC}	supply current			-	4.5	-	mA
Gp	power gain	power at LNA input P _i < -40 dBm	[1]	-	14.5	-	dB
		power at LNA input P _i = −20 dBm	[1]	-	15.5	-	dB
RLin	input return loss	power at LNA input P _i < -40 dBm	[1]	-	8.5	-	dB
		power at LNA input P _i = -20 dBm	[1]	-	10.5	-	dB
RL _{out}	output return loss	power at LNA input P _i < -40 dBm	[1]	-	14.5	-	dB
		power at LNA input P _i = -20 dBm	[1]	-	12.5	-	dB
NF	noise figure	power at LNA input P _i < -40 dBm	[1]	-	1.8	-	dB
		power at LNA input P _i = -20 dBm	[1]	-	1.9	-	dB
P _{i(1dB)}	input power at 1 dB gain compression	f = 1575 MHz			-8.2		dBm
		f = 806 MHz to 928 MHz	[2]		31		dBm
		f = 1612 MHz to 1909 MHz	[2]		40		dBm
IP3 _i	input third-order intercept point		[3]		64		dBm
α	attenuation	f = 850 MHz	[4]	95	-	-	dBc
		f = 1850 MHz	[4]	90	-	-	dBc
t _{on}	turn-on time		[5]	-	-	2	μS
t _{off}	turn-off time		[5]	-	-	1	μS

^[1] Power at GPS front-end input = power at LNA input + attenuation BPF1.

9. Test information

9.1 Quality information

All qualification tests are performed according AEC-Q100 except for read point testing (final test of qualification sample). Which is done only at room temperature.

As part of the zero defect program, the following is part of the industrial test flow:

- Part Average Testing
- Maverick Lot Handling at assembly factory

^[2] Out of band.

^[3] $f_1 = 1713 \text{ MHz}$; $f_2 = 1851 \text{ MHz}$; $P_1 = P_2 = +10 \text{ dBm}$.

^[4] Relative to f = 1575 MHz.

^[5] Within 10 % of the final gain.

SiGe:C LNA MMIC for GPS, GLONASS, Galileo and Compass

10. Package outline

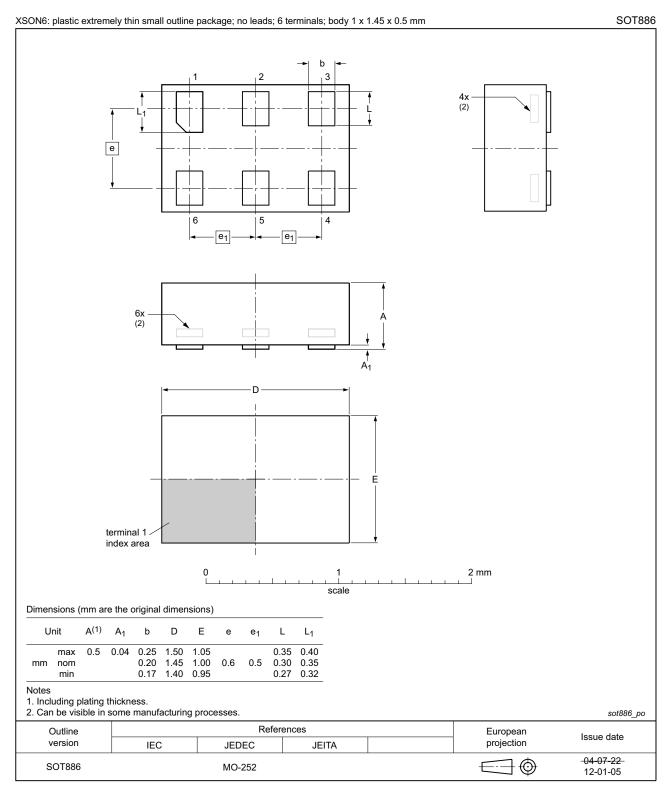


Fig 33. Package outline SOT886 (XSON6)

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

11. Handling information

CAUTION



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the ANSI/ESD S20.20, IEC/ST 61340-5, JESD625-A or equivalent standards.

12. Abbreviations

Table 12. Abbreviations

Acronym	Description
AEC	Automotive Electronics Council
ATM	Automated Teller Machine (cash dispenser)
BPF	Band-Pass Filter
ESD	ElectroStatic Discharge
GLONASS	GLObal NAvigation Satellite System
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
НВМ	Human Body Model
MMIC	Monolithic Microwave Integrated Circuit
PCB	Printed Circuit Board
SAW	Surface Acoustic Wave
SiGe:C	Silicon Germanium Carbon

13. Revision history

Table 13. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
BGU7004 v.3	20170118	Product data sheet	-	BGU7004 v.2	
Modifications:	Section 1: added GPS1103M according to our new naming convention				
BGU7004 v.2	20150220	Product data sheet	-	BGU7004 v.1	
Modifications:	 The title of this data sheet has been changed. Section 1.3 on page 1: Added GLONASS, Galileo and Compass (BeiDou) to the possible applications. Section 11 on page 17: ESD information has moved from Section 1.1 to this section. Section 14.3 on page 18: Adjusted the disclaimers with respect to "suitability to use in automotive applications" and "Translations". 				
BGU7004 v.1	20110705	Product data sheet	-	-	

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

14. Legal information

14.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

14.2 Definitions

Draft — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

Product specification — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

14.3 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the *Terms and conditions of commercial sale* of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use in automotive applications — This NXP

Semiconductors product has been qualified for use in automotive applications. Unless otherwise agreed in writing, the product is not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

Terms and conditions of commercial sale — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at http://www.nxp.com/profile/terms, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

No offer to sell or license — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

Export control — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Quick reference data — The Quick reference data is an extract of the product data given in the Limiting values and Characteristics sections of this document, and as such is not complete, exhaustive or legally binding.

Translations — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

14.4 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

15. Contact information

For more information, please visit: http://www.nxp.com

For sales office addresses, please send an email to: salesaddresses@nxp.com

SiGe: C LNA MMIC for GPS, GLONASS, Galileo and Compass

16. Contents

Product profile
General description
Features and benefits 1
Applications
Quick reference data 2
Pinning information 2
Ordering information 3
Marking 3
Limiting values
Thermal characteristics
Characteristics 4
Application information 6
GNSS LNA 6
GPS front-end
Characteristics GPS front-end 15
Test information
Quality information
Package outline
Handling information
Abbreviations
Revision history
Legal information
Data sheet status
Definitions
Disclaimers
Trademarks19
Contact information
Contents

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP Semiconductors N.V. 2017.

All rights reserved.

For more information, please visit: http://www.nxp.com For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 18 January 2017 Document identifier: BGU7004

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

NXP:

OM7804/BGU7004,598 OM7814/BGU7004/FE,598