Dynamic NFC/RFID tag IC with 16-Kbit EEPROM,
energy harvesting, I ${ }^{2} \mathrm{C}$ bus and ISO 15693 RF interface

Datasheet - production data


## Features

- Belonging to ST25 family, which includes all NFC/RF ID tag and reader products from ST


## $I^{2} C$ interface

- Two-wire $\mathrm{I}^{2} \mathrm{C}$ serial interface supports 400 kHz protocol
- Single supply voltage: 1.8 V to 5.5 V
- Byte and Page Write (up to 4 bytes)
- Random and Sequential read modes
- Self-timed programming cycle
- Automatic address incrementing
- Enhanced ESD/latch-up protection
- $I^{2} \mathrm{C}$ timeout


## Contactless interface

- ISO 15693 and ISO 18000-3 mode 1 compatible
- $13.56 \mathrm{MHz} \pm 7 \mathrm{k} \mathrm{Hz}$ carrier frequency
- To tag: $10 \%$ or $100 \%$ ASK modulation using 1/4 (26 Kbit/s) or 1/256 (1.6 Kbit/s) pulse position coding
- From tag: load modulation using Manchester coding with 423 kHz and 484 kHz subcarriers in low ( $6.6 \mathrm{kbit} / \mathrm{s}$ ) or high ( $26 \mathrm{kbit} / \mathrm{s}$ ) data rate mode. Supports the $53 \mathrm{kbit} / \mathrm{s}$ data rate with Fast commands
- Internal tuning capacitance: 27.5 pF
- 64-bit unique identifier (UID)
- Read Block \& Write (32-bit blocks)


## Digital output pin

- User configurable pin: RF write in progress or RF busy mode


## Energy harvesting

- Analog pin for energy harvesting
- 4 sink current configurable ranges


## Temperature range:

- from $-40^{\circ} \mathrm{C}$ up to $85^{\circ} \mathrm{C}$


## Memory

- 16-Kbit EEPROM organized into:
- 2048 bytes in $\mathrm{I}^{2} \mathrm{C}$ mode
- 512 blocks of 32 bits in RF mode
- Write time
- $\mathrm{I}^{2} \mathrm{C}: 5 \mathrm{~ms}$ (max.)
- RF: 5.75 ms including the internal Verify time
- Write cycling enduramce:
- 1 million write cycles at $25^{\circ} \mathrm{C}$
- 150 k write cycles at $85^{\circ} \mathrm{C}$
- More than 40-year data retention
- Multiple password protection in RF mode
- Single password protection in $\mathrm{I}^{2} \mathrm{C}$ mode


## Package:

- ECOPACK2 ${ }^{\circledR}$ (RoHS compliant and Halogenfree)


## Contents

1 Description ..... 13
2 Signal descriptions ..... 15
2.1 Serial clock (SCL) ..... 15
2.2 Serial data (SDA) ..... 15
2.3 RF Write in progress / RF Busy (RF WIP/BUSY) ..... 15
2.4 Energy harvesting analog output (Vout) ..... 15
2.5 Antenna coil (AC0, AC1) ..... 15
2.5.1 Device reset in RF mode ..... 15
2.6 $\mathrm{V}_{\mathrm{SS}}$ ground ..... 16
2.7 Supply voltage ( $\mathrm{V}_{\mathrm{CC}}$ ) ..... 16
2.7.1 Operating supply voltage $\mathrm{V}_{\mathrm{CC}}$ ..... 16
2.7.2 Power-up conditions ..... 16
2.7.3 Device reset in $I^{2} \mathrm{C}$ mode ..... 16
2.7.4 Power-down conditions ..... 16
3 User memory organization ..... 19
4 System memory area ..... 24
4.1 M24LR16E-R block security in RF mode ..... 24
4.1.1 Example of the M24LR16E-R security protection in RF mode ..... 26
4.2 M24LR16E-R block security in $I^{2} \mathrm{C}$ mode (I2C_Write_Lock bit area) ..... 27
4.3 Configuration byte and Control register ..... 27
4.3.1 RF WIP/BUSY pin configuration ..... 27
4.3.2 Energy harvesting configuration ..... 28
4.3.3 FIELD_ON indicator bit ..... 29
4.3.4 Configuration byte access in $\mathrm{I}^{2} \mathrm{C}$ and RF modes ..... 30
4.3.5 Control register access in $\mathrm{I}^{2} \mathrm{C}$ or RF mode ..... 30
4.4 ISO 15693 system parameters ..... 30
$5 \quad I^{2} \mathrm{C}$ device operation ..... 32
5.1 Start condition ..... 32
5.2 Stop condition ..... 32
5.3 Acknowledge bit (ACK) ..... 32
5.4 Data input ..... 32
$5.5 \mathrm{I}^{2} \mathrm{C}$ timeout ..... 32
5.5.1 $\quad I^{2} \mathrm{C}$ timeout on Start condition ..... 33
5.5.2 $I^{2} \mathrm{C}$ timeout on clock period ..... 33
5.6 Memory addressing ..... 33
5.7 Write operations ..... 35
5.8 Byte write ..... 35
5.9 Page write ..... 35
5.10 Minimizing system delays by polling on ACK ..... 37
5.11 Read operations ..... 39
5.12 Random Address Read ..... 39
5.13 Current Address Read ..... 39
5.14 Sequential Read ..... 39
5.15 Acknowledge in Read mode ..... 39
5.16 M24LR16E-R I ${ }^{2}$ C password security ..... 40
5.16.1 $\quad I^{2} \mathrm{C}$ present password command description ..... 40
5.16.2 $\quad I^{2} \mathrm{C}$ write password command description ..... 41
6 M24LR16E-R memory initial state ..... 42
7 RF device operation ..... 43
7.1 RF communication and energy harvesting ..... 43
7.2 Commands ..... 44
7.3 Initial dialog for vicinity cards ..... 45
7.3.1 Power transfer ..... 45
7.3.2 Frequency ..... 45
7.3.3 Operating field ..... 45
8 Communication signal from VCD to M24LR16E-R ..... 46
9 Data rate and data coding ..... 48
9.1 Data coding mode: 1 out of 256 ..... 48
9.2 Data coding mode: 1 out of 4 ..... 49
9.3 VCD to M24LR16E-R frames ..... 51
$5 \%$
9.4 Start of frame (SOF) ..... 51
10 Communication signal from M24LR16E-R to VCD ..... 53
10.1 Load modulation ..... 53
10.2 Subcarrier ..... 53
10.3 Data rates ..... 53
11 Bit representation and coding ..... 54
11.1 Bit coding using one subcarrier ..... 54
11.1.1 High data rate ..... 54
11.1.2 Low data rate ..... 55
11.2 Bit coding using two subcarriers ..... 56
11.2.1 High data rate ..... 56
11.2.2 Low data rate ..... 56
12 M24LR16E-R to VCD frames ..... 57
12.1 SOF when using one subcarrier ..... 57
12.1.1 High data rate ..... 57
12.1.2 Low data rate ..... 57
12.2 SOF when using two subcarriers ..... 58
12.2.1 High data rate ..... 58
12.2.2 Low data rate ..... 58
12.3 EOF when using one subcarrier ..... 59
12.3.1 High data rate ..... 59
12.3.2 Low data rate ..... 59
12.4 EOF when using two subcarriers ..... 60
12.4.1 High data rate ..... 60
12.4.2 Low data rate ..... 60
13 Unique identifier (UID) ..... 61
14 Application family identifier (AFI) ..... 62
15 Data storage format identifier (DSFID) ..... 63
15.1 CRC ..... 63
16 M24LR16E-R protocol description ..... 64
17 M24LR16E-R states ..... 66
17.1 Power-off state ..... 66
17.2 Ready state ..... 66
17.3 Quiet state ..... 66
17.4 Selected state ..... 66
18 Modes ..... 68
18.1 Addressed mode ..... 68
18.2 Non-addressed mode (general request) ..... 68
18.3 Select mode ..... 68
19 Request format ..... 69
19.1 Request flags ..... 69
20 Response format ..... 71
20.1 Response flags ..... 71
20.2 Response error code ..... 72
21 Anticollision ..... 73
21.1 Request parameters ..... 73
22 Request processing by the M24LR16E-R ..... 75
23 Explanation of the possible cases ..... 76
24 Inventory Initiated command ..... 78
25 Timing definition ..... 79
25.1 t1: M24LR16E-R response delay ..... 79
25.2 t2: VCD new request delay ..... 79
$25.3 \quad t_{3}$ : VCD new request delay when no response is received from the M24LR16E-R ..... 79
26 Command codes ..... 80
26.1 Inventory ..... 81
26.2 Stay Quiet ..... 83
$5 \%$
26.3 Read Single Block ..... 84
26.4 Write Single Block ..... 85
26.5 Read Multiple Block ..... 89
26.6 Select ..... 90
26.7 Reset to Ready ..... 92
26.8 Write AFI ..... 93
26.9 Lock AFI ..... 94
26.10 Write DSFID ..... 96
26.11 Lock DSFID ..... 97
26.12 Get System Info ..... 99
26.13 Get Multiple Block Security Status ..... 101
26.14 Write-sector Password ..... 102
26.15 Lock-sector ..... 104
26.16 Present-sector Password ..... 105
26.17 Fast Read Single Block ..... 108
26.18 Fast Inventory Initiated ..... 109
26.19 Fast Initiate ..... 111
26.20 Fast Read Multiple Block ..... 112
26.21 Inventory Initiated ..... 113
26.22 Initiate ..... 115
26.23 ReadCfg ..... 116
26.24 WriteEHCfg ..... 117
26.25 WriteDOCfg ..... 118
26.26 SetRstEHEn ..... 120
26.27 CheckEHEn ..... 121
27 Maximum rating ..... 123
$28 \quad I^{2} C$ DC and AC parameters ..... 124
29 Write cycle definition ..... 128
30 RF electrical parameters ..... 129
31 Package information ..... 135
31.1 SO8N package information ..... 135
31.2 UFDFN8 package information ..... 137
31.3 TSSOP8 package information ..... 139
32 Ordering information ..... 140
Appendix A Anticollision algorithm (informative) ..... 142
A. 1 Algorithm for pulsed slots ..... 142
Appendix B CRC (informative) ..... 143
B. 1 CRC error detection method ..... 143
B. 2 CRC calculation example ..... 143
Appendix C Application family identifier (AFI) (informative) ..... 145
Revision history ..... 146

## List of tables

Table 1. Signal names ..... 14
Table 2. Device select code ..... 18
Table 3. Address most significant byte ..... 18
Table 4. Address least significant byte ..... 18
Table 5. Sector details ..... 21
Table 6. Sector security status byte area ..... 24
Table 7. Sector security status byte organization ..... 24
Table 8. Read / Write protection bit setting. ..... 24
Table 9. Password control bits ..... 25
Table 10. Password system area ..... 25
Table 11. M24LR16E-R sector security protection after power-up ..... 26
Table 12. M24LR16E-R sector security protection after a valid presentation of password 1 ..... 26
Table 13. I2C_Write_Lock bit ..... 27
Table 14. Configuration byte. ..... 28
Table 15. Control register ..... 29
Table 16. EH_enable bit value after power-up ..... 29
Table 17. System parameter sector ..... 31
Table 18. Operating modes ..... 34
Table 19. 10\% modulation parameters ..... 47
Table 20. Response data rates. ..... 53
Table 21. UID format ..... 61
Table 22. CRC transmission rules ..... 63
Table 23. VCD request frame format ..... 64
Table 24. M24LR16E-R Response frame format ..... 64
Table 25. M24LR16E-R response depending on Request_flags ..... 67
Table 26. General request format ..... 69
Table 27. Definition of request flags 1 to 4 ..... 69
Table 28. Request flags 5 to 8 when Bit $3=0$ ..... 70
Table 29. Request flags 5 to 8 when Bit $3=1$ ..... 70
Table 30. General response format ..... 71
Table 31. Definitions of response flags 1 to 8. ..... 71
Table 32. Response error code definition ..... 72
Table 33. Inventory request format ..... 73
Table 34. Example of the addition of 0-bits to an 11-bit mask value ..... 73
Table 35. Timing values ..... 79
Table 36. Command codes. ..... 80
Table 37. Inventory request format. ..... 81
Table 38. Inventory response format ..... 81
Table 39. Stay Quiet request format. ..... 83
Table 40. Read Single Block request format ..... 84
Table 41. Read Single Block response format when Error_flag is NOT set ..... 84
Table 42. Sector security status ..... 84
Table 43. Read Single Block response format when Error_flag is set ..... 84
Table 44. Write Single Block request format ..... 85
Table 45. Write Single Block response format when Error_flag is NOT set ..... 85
Table 46. Write Single Block response format when Error_flag is set ..... 86
Table 47. Read Multiple Block request format ..... 89
Table 48. Read Multiple Block response format when Error_flag is NOT set. ..... 89
Table 49. Sector security status ..... 89
Table 50. Read Multiple Block response format when Error flag is set ..... 90
Table 51. Select request format ..... 90
Table 52. Select Block response format when Error_flag is NOT set ..... 91
Table 53. Select response format when Error_flag is set ..... 91
Table 54. Reset to Ready request format ..... 92
Table 55. Reset to Ready response format when Error_flag is NOT set ..... 92
Table 56. Reset to ready response format when Error_flag is set ..... 92
Table 57. Write AFI request format. ..... 93
Table 58. Write AFI response format when Error_flag is NOT set ..... 93
Table 59. Write AFI response format when Error_flag is set ..... 93
Table 60. Lock AFI request format ..... 94
Table 61. Lock AFI response format when Error_flag is NOT set ..... 94
Table 62. Lock AFI response format when Error_flag is set ..... 95
Table 63. Write DSFID request format ..... 96
Table 64. Write DSFID response format when Error_flag is NOT set ..... 96
Table 65. Write DSFID response format when Error_flag is set ..... 96
Table 66. Lock DSFID request format ..... 97
Table 67. Lock DSFID response format when Error flag is NOT set ..... 97
Table 68. Lock DSFID response format when Error_flag is set ..... 98
Table 69. Get System Info request format ..... 99
Table 70. Get System Info response format when Protocol_extension_flag = 0 and Error_flag is NOT set ..... 99
Table 71. Get System Info response format when Protocol_extension_flag = 1 and Error_flag is NOT set ..... 99
Table 72. Get System Info response format when Error_flag is set ..... 100
Table 73. Get Multiple Block Security Status request format ..... 101
Table 74. Get Multiple Block Security Status response format when Error_flag is NOT set ..... 101
Table 75. Sector security status ..... 101
Table 76. Get Multiple Block Security Status response format when Error_flag is set ..... 102
Table 77. Write-sector Password request format ..... 102
Table 78. Write-sector Password response format when Error_flag is NOT set ..... 103
Table 79. Write-sector Password response format when Error_flag is set ..... 103
Table 80. Lock-sector request format ..... 104
Table 81. Sector security status ..... 104
Table 82. Lock-sector response format when Error_flag is NOT set ..... 104
Table 83. Lock-sector response format when Error_flag is set. ..... 105
Table 84. Present-sector Password request format ..... 106
Table 85. Present-sector Password response format when Error_flag is NOT set ..... 106
Table 86. Present-sector Password response format when Error_flag is set. ..... 106
Table 87. Fast Read Single Block request format ..... 108
Table 88. Fast Read Single Block response format when Error_flag is NOT set ..... 108
Table 89. Sector security status ..... 108
Table 90. Fast Read Single Block response format when Error_flag is set ..... 108
Table 91. Fast Inventory Initiated request format ..... 109
Table 92. Fast Inventory Initiated response format ..... 110
Table 93. Fast Initiate request format ..... 111
Table 94. Fast Initiate response format ..... 111
Table 95. Fast Read Multiple Block request format ..... 112
Table 96. Fast Read Multiple Block response format when Error_flag is NOT set ..... 112
Table 97. Sector security status if Option_flag is set ..... 112
Table 98. Fast Read Multiple Block response format when Error_flag is set ..... 113
Table 99. Inventory Initiated request format ..... 114
Table 100. Inventory Initiated response format ..... 114
Table 101. Initiate request format ..... 115
Table 102. Initiate Initiated response format. ..... 115
Table 103. ReadCfg request format ..... 116
Table 104. ReadCfg response format when Error_flag is NOT set ..... 116
Table 105. ReadCfg response format when Error_flag is set. ..... 116
Table 106. WriteEHCfg request format. ..... 117
Table 107. WriteEHCfg response format when Error_flag is NOT set ..... 117
Table 108. WriteEHCfg response format when Error_flag is set ..... 117
Table 109. WriteDOCfg request format ..... 118
Table 110. WriteDOCfg response format when Error_flag is NOT set ..... 119
Table 111. WriteDOCfg response format when Error_flag is set ..... 119
Table 112. SetRstEHEn request format ..... 120
Table 113. SetRstEHEn response format when Error_flag is NOT set ..... 120
Table 114. SetRstEHEn response format when Error_flag is set ..... 120
Table 115. CheckEHEn request format ..... 121
Table 116. CheckEHEn response format when Error_flag is NOT set . ..... 121
Table 117. CheckEHEn response format when Error_flag is set ..... 122
Table 118. Absolute maximum ratings ..... 123
Table 119. $I^{2} \mathrm{C}$ operating conditions ..... 124
Table 120. AC test measurement conditions ..... 124
Table 121. Input parameters ..... 124
Table 122. $I^{2} \mathrm{C}$ DC characteristics ..... 125
Table 123. $I^{2} C$ AC characteristics ..... 126
Table 124. Write cycle definition ..... 128
Table 125. RF characteristics ..... 129
Table 126. Operating conditions ..... 130
Table 127. Energy harvesting ..... 131
Table 128. SO8N - 8-lead plastic small outline, 150 mils body width, package mechanical data ..... 135
Table 129. UFDFN8-8-lead, $2 \times 3 \mathrm{~mm}, 0.5 \mathrm{~mm}$ pitch ultra thin profile fine pitch dual flat package mechanical data ..... 138
Table 130. TSSOP8 - 8-lead thin shrink small outline, $3 \times 6.4 \mathrm{~mm}, 0.65 \mathrm{~mm}$ pitch, package mechanical data ..... 139
Table 131. Ordering information scheme for packaged devices ..... 140
Table 132. Ordering and marking information ..... 141
Table 133. CRC definition ..... 143
Table 134. AFI coding. ..... 145
Table 135. Document revision history ..... 146

## List of figures

Figure 1. Logic diagram ..... 13
Figure 2. 8-pin package connections ..... 14
Figure 3. $\quad I^{2} C$ Fast mode ( $f_{C}=400 \mathrm{kHz}$ ): maximum $R_{\text {bus }}$ value versus bus parasitic capacitance ( $\mathrm{C}_{\text {bus }}$ ) ..... 17
Figure 4. $\quad \mathrm{I}^{2} \mathrm{C}$ bus protocol ..... 17
Figure 5. Circuit diagram ..... 19
Figure 6. Memory sector organization ..... 20
Figure 7. $I^{2} \mathrm{C}$ timeout on Start condition ..... 33
Figure 8. Write mode sequences with I2C_Write_Lock bit = 1 (data write inhibited). ..... 34
Figure 9. Write mode sequences with I2C_Write_Lock bit = 0 (data write enabled) ..... 36
Figure 10. Write cycle polling flowchart using ACK ..... 37
Figure 11. Read mode sequences ..... 38
Figure 12. $\mathrm{I}^{2} \mathrm{C}$ present password command ..... 40
Figure 13. $I^{2} \mathrm{C}$ write password command ..... 41
Figure 14. 100\% modulation waveform ..... 46
Figure 15. 10\% modulation waveform ..... 47
Figure 16. 1 out of 256 coding mode ..... 48
Figure 17. Detail of a time period ..... 49
Figure 18. 1 out of 4 coding mode ..... 50
Figure 19. 1 out of 4 coding example ..... 50
Figure 20. SOF to select 1 out of 256 data coding mode ..... 51
Figure 21. SOF to select 1 out of 4 data coding mode ..... 51
Figure 22. EOF for either data coding mode ..... 52
Figure 23. Logic 0, high data rate ..... 54
Figure 24. Logic 0, high data rate, fast commands ..... 54
Figure 25. Logic 1, high data rate ..... 54
Figure 26. Logic 1, high data rate, fast commands ..... 54
Figure 27. Logic 0, low data rate ..... 55
Figure 28. Logic 0, low data rate, fast commands ..... 55
Figure 29. Logic 1, low data rate ..... 55
Figure 30. Logic 1, low data rate, fast commands ..... 55
Figure 31. Logic 0, high data rate ..... 56
Figure 32. Logic 1, high data rate ..... 56
Figure 33. Logic 0, low data rate ..... 56
Figure 34. Logic 1, low data rate ..... 56
Figure 35. Start of frame, high data rate, one subcarrier ..... 57
Figure 36. Start of frame, high data rate, one subcarrier, fast commands ..... 57
Figure 37. Start of frame, low data rate, one subcarrier ..... 57
Figure 38. Start of frame, low data rate, one subcarrier, fast commands ..... 58
Figure 39. Start of frame, high data rate, two subcarriers ..... 58
Figure 40. Start of frame, low data rate, two subcarriers ..... 58
Figure 41. End of frame, high data rate, one subcarrier ..... 59
Figure 42. End of frame, high data rate, one subcarrier, fast commands ..... 59
Figure 43. End of frame, low data rate, one subcarrier ..... 59
Figure 44. End of frame, low data rate, one subcarrier, Fast commands ..... 59
Figure 45. End of frame, high data rate, two subcarriers ..... 60
Figure 46. End of frame, low data rate, two subcarriers ..... 60
Figure 47. M24LR16E-R decision tree for AFI ..... 62
Figure 48. M24LR16E-R protocol timing ..... 65
Figure 49. M24LR16E-R state transition diagram ..... 67
Figure 50. Principle of comparison between the mask, the slot number and the UID ..... 74
Figure 51. Description of a possible anticollision sequence ..... 77
Figure 52. M24LR16 RF-Busy management following Inventory command ..... 82
Figure 53. Stay Quiet frame exchange between VCD and M24LR16E-R ..... 83
Figure 54. Read Single Block frame exchange between VCD and M24LR16E-R ..... 85
Figure 55. Write Single Block frame exchange between VCD and M24LR16E-R ..... 86
Figure 56. M24LR16 RF-Busy management following Write command ..... 87
Figure 57. M24LR16 RF-Wip management following Write command ..... 88
Figure 58. Read Multiple Block frame exchange between VCD and M24LR16E-R ..... 90
Figure 59. Select frame exchange between VCD and M24LR16E-R ..... 91
Figure 60. Reset to Ready frame exchange between VCD and M24LR16E-R ..... 92
Figure 61. Write AFI frame exchange between VCD and M24LR16E-R ..... 94
Figure 62. Lock AFI frame exchange between VCD and M24LR16E-R ..... 95
Figure 63. Write DSFID frame exchange between VCD and M24LR16E-R ..... 97
Figure 64. Lock DSFID frame exchange between VCD and M24LR16E-R ..... 98
Figure 65. Get System Info frame exchange between VCD and M24LR16E-R ..... 100
Figure 66. Get Multiple Block Security Status frame exchange between VCD and M24LR16E-R ..... 102
Figure 67. Write-sector Password frame exchange between VCD and M24LR16E-R ..... 103
Figure 68. Lock-sector frame exchange between VCD and M24LR16E-R ..... 105
Figure 69. Present-sector Password frame exchange between VCD and M24LR16E-R ..... 107
Figure 70. Fast Read Single Block frame exchange between VCD and M24LR16E-R. ..... 109
Figure 71. Fast Initiate frame exchange between VCD and M24LR16E-R ..... 111
Figure 72. Fast Read Multiple Block frame exchange between VCD and M24LR16E-R ..... 113
Figure 73. Initiate frame exchange between VCD and M24LR16E-R ..... 115
Figure 74. ReadCfg frame exchange between VCD and M24LR16E-R ..... 116
Figure 75. ..... 116
Figure 76. WriteEHCfg frame exchange between VCD and M24LR16E-R ..... 118
Figure 77. WriteDOCfg frame exchange between VCD and M24LR16E-R ..... 119
Figure 78. SetRstEHEn frame exchange between VCD and M24LR16E-R ..... 121
Figure 79. CheckEHEn frame exchange between VCD and M24LR16E-R ..... 122
Figure 80. AC test measurement I/O waveform ..... 124
Figure 81. $\mathrm{I}^{2} \mathrm{C}$ AC waveforms ..... 127
Figure 82. ASK modulated signal ..... 131
Figure 83. Vout min vs. Isink ..... 132
Figure 84. Range 11 domain ..... 132
Figure 85. Range 10 domain ..... 133
Figure 86. Range 01 domain ..... 133
Figure 87. Range 00 domain ..... 134
Figure 88. SO8N-8-lead plastic small outline, 150 mils body width, package outline ..... 135
Figure 89. SO8N - 8-lead plastic small outline, 150 mils body width, package recommended footprint ..... 136
Figure 90. UFDFN8-8-lead, $2 \times 3 \mathrm{~mm}, 0.5 \mathrm{~mm}$ pitch ultra thin profile fine pitch dual flat package outline ..... 137
Figure 91. TSSOP8 - 8-lead thin shrink small outline, $3 \times 6.4 \mathrm{~mm}, 0.65 \mathrm{~mm}$ pitch, package outline ..... 139

## 1 Description

The M24LR16E-R device is a Dynamic NFC/RFID tag IC with dual-interface, electrically erasable programmable memory (EEPROM). It features an $I^{2} \mathrm{C}$ interface and can be operated from a $\mathrm{V}_{\mathrm{CC}}$ power supply. It is also a contactless memory powered by the received carrier electromagnetic wave. The M24LR16E-R is organized as $2048 \times 8$ bits in the $I^{2} C$ mode and as $512 \times 32$ bits in the ISO 15693 and ISO 18000-3 mode 1 RF mode.

The M24LR16E-R also features an energy harvesting analog output, as well as a userconfigurable digital output pin toggling during either RF write in progress or RF busy mode.

Figure 1. Logic diagram

$I^{2} \mathrm{C}$ uses a two-wire serial interface, comprising a bidirectional data line and a clock line. The devices carry a built-in 4-bit device type identifier code (1010) in accordance with the $\mathrm{I}^{2} \mathrm{C}$ bus definition.

The device behaves as a slave in the $I^{2} C$ protocol, with all memory operations synchronized by the serial clock. Read and Write operations are initiated by a Start condition, generated by the bus master. The Start condition is followed by a device select code and Read/Write bit ( $\mathrm{R} \overline{\mathrm{W}}$ ) (as described in Table 2), terminated by an acknowledge bit.
When writing data to the memory, the device inserts an acknowledge bit during the $9^{\text {th }}$ bit time, following the bus master's 8 -bit transmission. When data is read by the bus master, the bus master acknowledges the receipt of the data byte in the same way. Data transfers are terminated by a Stop condition after an Ack for Write, and after a NoAck for Read.

In the ISO15693/ISO18000-3 mode 1 RF mode, the M24LR16E-R is accessed via the 13.56 MHz carrier electromagnetic wave on which incoming data are demodulated from the received signal amplitude modulation (ASK: amplitude shift keying). When connected to an antenna, the operating power is derived from the RF energy and no external power supply is required. The received ASK wave is $10 \%$ or $100 \%$ modulated with a data rate of $1.6 \mathrm{Kbit} / \mathrm{s}$ using the $1 / 256$ pulse coding mode or a data rate of $26 \mathrm{Kbit} / \mathrm{s}$ using the $1 / 4$ pulse coding mode.

Outgoing data are generated by the M24LR16E-R load variation using Manchester coding with one or two subcarrier frequencies at 423 kHz and 484 kHz . Data are transferred from the M24LR16E-R at $6.6 \mathrm{Kbit} / \mathrm{s}$ in low data rate mode and $26 \mathrm{Kbit} / \mathrm{s}$ high data rate mode. The

M24LR16E-R supports the $53 \mathrm{Kbit} /$ s fast mode in high data rate mode using one subcarrier frequency at 423 kHz .

The M24LR16E-R follows the ISO 15693 and ISO 18000-3 mode 1 recommendation for radio-frequency power and signal interface.

The M24LR16E-R provides an Energy harvesting mode on the analog output pin Vout. When the Energy harvesting mode is activated, the M24LR16E-R can output the excess energy coming from the RF field on the Vout analog pin. In case the RF field strength is insufficient or when Energy harvesting mode is disabled, the analog output pin Vout goes into high-Z state and Energy harvesting mode is automatically stopped.

The M24LR16E-R features a user configurable digital out pin RF WIP/BUSY that can be used to drive a micro controller interrupt input pin (available only when the M24LR16E-R is correctly powered on the Vcc pin).

When configured in the RF write in progress mode (RF WIP mode), the RF WIP/BUSY pin is driven low for the entire duration of the RF internal write operation. When configured in the RF busy mode (RF BUSY mode), the RF WIP/BUSY pin is driven low for the entire duration of the RF command progress.
The RF WIP/BUSY pin is an open drain output and must be connected to a pull-up resistor.
Table 1. Signal names

| Signal name | Function | Direction |
| :--- | :--- | :--- |
| Vout | Energy harvesting Output | Analog output |
| SDA | Serial Data | I/O |
| SCL | Serial Clock | Input |
| AC0, AC1 | Antenna coils | I/O |
| V $C C$ | Supply voltage | - |
| RF WIP/BUSY | Digital signal | Digital output |
| V $_{\text {SS }}$ | Ground | - |

Figure 2. 8-pin package connections


1. See Section 31 for package dimensions, and how to identify pin-1.

## 2 Signal descriptions

### 2.1 Serial clock (SCL)

This input signal is used to strobe all data in and out of the device. In applications where this signal is used by slave devices to synchronize the bus to a slower clock, the bus master must have an open drain output, and a pull-up resistor must be connected from Serial Clock (SCL) to $\mathrm{V}_{\mathrm{CC}}$. (Figure 3 indicates how the value of the pull-up resistor can be calculated). In most applications, though, this method of synchronization is not employed, and so the pullup resistor is not necessary, provided that the bus master has a push-pull (rather than open drain) output.

### 2.2 Serial data (SDA)

This bidirectional signal is used to transfer data in or out of the device. It is an open drain output that may be wire-OR'ed with other open drain or open collector signals on the bus. A pull up resistor must be connected from Serial Data (SDA) to $\mathrm{V}_{\mathrm{Cc}}$. (Figure 3 indicates how the value of the pull-up resistor can be calculated).

### 2.3 RF Write in progress / RF Busy (RF WIP/BUSY)

This configurable output signal is used either to indicate that the M24LR16E-R is executing an internal write cycle from the RF channel or that an RF command is in progress. RF WIP and signals are available only when the M24LR16E-R is powered by the Vcc pin. It is an open drain output and a pull up resistor must be connected from RF WIP/BUSY to $\mathrm{V}_{\mathrm{Cc}}$.

### 2.4 Energy harvesting analog output (Vout)

This analog output pin is used to deliver the analog voltage Vout available when the Energy harvesting mode is enabled and the RF field strength is sufficient. When the Energy harvesting mode is disabled or the RF field strength is not sufficient, the energy harvesting analog voltage output Vout is in High-Z state.

### 2.5 Antenna coil (AC0, AC1)

These inputs are used to connect the device to an external coil exclusively. It is advised not to connect any other DC or AC path to AC0 or AC1.
When correctly tuned, the coil is used to power and access the device using the ISO 15693 and ISO 18000-3 mode 1 protocols.

### 2.5.1 Device reset in RF mode

To ensure a proper reset of the RF circuitry, the RF field must be turned off (100\% modulation) for a minimum $t_{R F}$ OFF period of time.

### 2.6 VSS ground <br> $\mathrm{V}_{\mathrm{SS}}$ is the reference for the $\mathrm{V}_{\mathrm{CC}}$ supply voltage and Vout analog output voltage.

## $2.7 \quad$ Supply voltage ( $\mathrm{V}_{\mathrm{cc}}$ )

This pin can be connected to an external DC supply voltage.
Note: $\quad$ An internal voltage regulator allows the external voltage applied on $V_{C C}$ to supply the M24LR16E-R, while preventing the internal power supply (rectified RF waveforms) to output a DC voltage on the $V_{C C}$ pin.

### 2.7.1 Operating supply voltage $\mathbf{V}_{\mathrm{CC}}$

Prior to selecting the memory and issuing instructions to it, a valid and stable $\mathrm{V}_{\mathrm{Cc}}$ voltage within the specified $\left[\mathrm{V}_{\mathrm{CC}}(\mathrm{min}), \mathrm{V}_{\mathrm{CC}}(\max )\right]$ range must be applied (see Table 119). To maintain a stable DC supply voltage, it is recommended to decouple the $\mathrm{V}_{\mathrm{Cc}}$ line with a suitable capacitor (usually of the order of 10 nF ) close to the $\mathrm{V}_{\mathrm{CC}} / \mathrm{V}_{\mathrm{SS}}$ package pins.
This voltage must remain stable and valid until the end of the transmission of the instruction and, for a Write instruction, until the completion of the internal $I^{2} \mathrm{C}$ write cycle ( $\mathrm{t}_{\mathrm{w}}$ ).

### 2.7.2 Power-up conditions

When the power supply is turned on, $\mathrm{V}_{\mathrm{CC}}$ rises from $\mathrm{V}_{\mathrm{SS}}$ to $\mathrm{V}_{\mathrm{CC}}$. The $\mathrm{V}_{\mathrm{CC}}$ rise time must not vary faster than $1 \mathrm{~V} / \mu \mathrm{s}$.

### 2.7.3 Device reset in $I^{2} \mathrm{C}$ mode

In order to prevent inadvertent write operations during power-up, a power-on reset (POR) circuit is included. At power-up (continuous rise of $\mathrm{V}_{\mathrm{CC}}$ ), the device does not respond to any ${ }^{2} \mathrm{C}$ instruction until $\mathrm{V}_{\mathrm{CC}}$ has reached the power-on reset threshold voltage (this threshold is lower than the minimum $\mathrm{V}_{\mathrm{cc}}$ operating voltage defined in Table 119). When $\mathrm{V}_{\mathrm{Cc}}$ passes over the POR threshold, the device is reset and enters the Standby power mode. However, the device must not be accessed until $\mathrm{V}_{\mathrm{CC}}$ has reached a valid and stable $\mathrm{V}_{\mathrm{CC}}$ voltage within the specified $\left[\mathrm{V}_{\mathrm{CC}}(\mathrm{min}), \mathrm{V}_{\mathrm{CC}}(\mathrm{max})\right]$ range.

In a similar way, during power-down (continuous decrease in $\mathrm{V}_{\mathrm{CC}}$ ), as soon as $\mathrm{V}_{\mathrm{CC}}$ drops below the power-on reset threshold voltage, the device stops responding to any instruction sent to it.

### 2.7.4 Power-down conditions

During power-down (continuous decay of $\mathrm{V}_{\mathrm{CC}}$ ), the device must be in Standby power mode (mode reached after decoding a Stop condition, assuming that there is no internal write cycle in progress).

Figure 3. $I^{2} \mathrm{C}$ Fast mode ( $\mathrm{f}_{\mathrm{C}}=400 \mathrm{kHz}$ ): maximum $R_{\text {bus }}$ value versus bus parasitic capacitance ( $\mathrm{C}_{\text {bus }}$ )


Figure 4. $\mathrm{I}^{2} \mathrm{C}$ bus protocol


Table 2. Device select code

| - | Device type identifier ${ }^{(1)}$ |  |  |  | Chip Enable address |  |  | RW |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
| Device select code | 1 | 0 | 1 | 0 | E2 ${ }^{(2)}$ | 1 | 1 | RW |

1. The most significant bit, b7, is sent first.
2. E2 is not connected to any external pin. It is however used to address the M24LR16E-R as described in Section 3 and Section 4.

Table 3. Address most significant byte

| b15 | b14 | b13 | b12 | b11 | b10 | b9 | b8 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Table 4. Address least significant byte

| b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

## 3 User memory organization

The M24LR16E-R is divided into 16 sectors of 32 blocks of 32 bits, as shown in Table 5. Figure 6 shows the memory sector organization. Each sector can be individually readand/or write-protected using a specific password command. Read and write operations are possible if the addressed data are not in a protected sector.

The M24LR16E-R also has a 64-bit block that is used to store the 64-bit unique identifier (UID). The UID is compliant with the ISO 15963 description, and its value is used during the anticollision sequence (Inventory). This block is not accessible by the user and its value is written by ST on the production line.

The M24LR16E-R includes an AFI register that stores the application family identifier, and a DSFID register that stores the data storage family identifier used in the anticollision algorithm.
The M24LR16E-R has four 32-bit blocks that store an $I^{2}$ C password plus three RF password codes.

Figure 5. Circuit diagram


Figure 6. Memory sector organization

| Sector | Area | Sector security status |
| :---: | :---: | :---: |
| $\begin{aligned} & 0 \\ & 1 \\ & 2 \\ & 3 \end{aligned}$ | 1 Kbit EEPROM sector | 5 bits |
|  | 1 Kbit EEPROM sector | 5 bits |
|  | 1 Kbit EEPROM sector | 5 bits |
|  | 1 Kbit EEPROM sector | 5 bits |
| $\begin{aligned} & 12 \\ & 13 \\ & 14 \\ & 15 \end{aligned}$ | 1 Kbit EEPROM sector | 5 bits |
|  | 1 Kbit EEPROM sector | 5 bits |
|  | 1 Kbit EEPROM sector | 5 bits |
|  | 1 Kbit EEPROM sector | 5 bits |
|  | $1^{2} \mathrm{C}$ password | System |
|  | RF password 1 | System |
|  | RF password 2 | System |
|  | RF password 3 | System |
|  | 8-bit DSFID |  |
|  | 8-bit AFI | System |
|  | 64-bit UID | System |
|  | 8-bit configuration | System |
|  | 16-bit ${ }^{2} \mathrm{C}$ Write Lock_bit | System |
|  | 80-bit SSS | System |
| MST974IV1 |  |  |

## Sector details

The M24LR16E-R user memory is divided into 16 sectors. Each sector contains 1024 bits. The protection scheme is described in Section 4: System memory area.
In RF mode, a sector provides 32 blocks of 32 bits. Each read and write access is done by block. Read and write block accesses are controlled by a Sector Security Status byte that defines the access rights to the 32 blocks contained in the sector. If the sector is not protected, a Write command updates the complete 32 bits of the selected block.
In $I^{2} \mathrm{C}$ mode, a sector provides 128 bytes that can be individually accessed in Read and Write modes. When protected by the corresponding I2C_Write_Lock bit, the entire sector is write-protected. To access the user memory, the device select code used for any $\mathrm{I}^{2} \mathrm{C}$ command must have the E2 Chip Enable address at 0.

Table 5. Sector details

| Sector number | RF block address | $I^{2} \mathrm{C}$ byte address | Bits [31:24] | Bits [23:16] | Bits [15:8] | Bits [7:0] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | user | user | user | user |
|  | 1 | 4 | user | user | user | user |
|  | 2 | 8 | user | user | user | user |
|  | 3 | 12 | user | user | user | user |
|  | 4 | 16 | user | user | user | user |
|  | 5 | 20 | user | user | user | user |
|  | 6 | 24 | user | user | user | user |
|  | 7 | 28 | user | user | user | user |
|  | 8 | 32 | user | user | user | user |
|  | 9 | 36 | user | user | user | user |
|  | 10 | 40 | user | user | user | user |
|  | 11 | 44 | user | user | user | user |
|  | 12 | 48 | user | user | user | user |
|  | 13 | 52 | user | user | user | user |
|  | 14 | 56 | user | user | user | user |
|  | 15 | 60 | user | user | user | user |
|  | 16 | 64 | user | user | user | user |
|  | 17 | 68 | user | user | user | user |
|  | 18 | 72 | user | user | user | user |
|  | 19 | 76 | user | user | user | user |
|  | 20 | 80 | user | user | user | user |
|  | 21 | 84 | user | user | user | user |
|  | 22 | 88 | user | user | user | user |
|  | 23 | 92 | user | user | user | user |
|  | 24 | 96 | user | user | user | user |
|  | 25 | 100 | user | user | user | user |
|  | 26 | 104 | user | user | user | user |
|  | 27 | 108 | user | user | user | user |
|  | 28 | 112 | user | user | user | user |
|  | 29 | 116 | user | user | user | user |
|  | 30 | 120 | user | user | user | user |
|  | 31 | 124 | user | user | user | user |

Table 5. Sector details (continued)

| Sector number | RF block address | $\mathrm{I}^{2} \mathrm{C}$ byte address | Bits [31:24] | Bits [23:16] | Bits [15:8] | Bits [7:0] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 32 | 128 | user | user | user | user |
|  | 33 | 132 | user | user | user | user |
|  | 34 | 136 | user | user | user | user |
|  | 35 | 140 | user | user | user | user |
|  | 36 | 144 | user | user | user | user |
|  | 37 | 148 | user | user | user | user |
|  | 38 | 152 | user | user | user | user |
|  | 39 | 156 | user | user | user | user |
|  | $\ldots$ | $\ldots$ | $\ldots$ | $\ldots$ | $\ldots$ | $\ldots$ |
| ... | ... | ... | ... | ... | ... | $\ldots$ |

Table 5. Sector details (continued)

| Sector number | RF block address | $1^{2} \mathrm{C}$ byte address | Bits [31:24] | Bits [23:16] | Bits [15:8] | Bits [7:0] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 15 | 480 | 1920 | user | user | user | user |
|  | 481 | 1924 | user | user | user | user |
|  | 482 | 1928 | user | user | user | user |
|  | 483 | 1932 | user | user | user | user |
|  | 484 | 1936 | user | user | user | user |
|  | 485 | 1940 | user | user | user | user |
|  | 486 | 1944 | user | user | user | user |
|  | 487 | 1948 | user | user | user | user |
|  | 488 | 1952 | user | user | user | user |
|  | 489 | 1956 | user | user | user | user |
|  | 490 | 1960 | user | user | user | user |
|  | 491 | 1964 | user | user | user | user |
|  | 492 | 1968 | user | user | user | user |
|  | 493 | 1972 | user | user | user | user |
|  | 494 | 1976 | user | user | user | user |
|  | 495 | 1980 | user | user | user | user |
|  | 496 | 1984 | user | user | user | user |
|  | 497 | 1988 | user | user | user | user |
|  | 498 | 1992 | user | user | user | user |
|  | 499 | 1996 | user | user | user | user |
|  | 500 | 2000 | user | user | user | user |
|  | 501 | 2004 | user | user | user | user |
|  | 502 | 2008 | user | user | user | user |
|  | 503 | 2012 | user | user | user | user |
|  | 504 | 2016 | user | user | user | user |
|  | 505 | 2020 | user | user | user | user |
|  | 506 | 2024 | user | user | user | user |
|  | 507 | 2028 | user | user | user | user |
|  | 508 | 2032 | user | user | user | user |
|  | 509 | 2036 | user | user | user | user |
|  | 510 | 2040 | user | user | user | user |
|  | 511 | 2044 | user | user | user | user |

## 4 System memory area

### 4.1 M24LR16E-R block security in RF mode

The M24LR16E-R provides a special protection mechanism based on passwords. In RF mode, each memory sector of the M24LR16E-R can be individually protected by one out of three available passwords, and each sector can also have Read/Write access conditions set.

Each memory sector of the M24LR16E-R is assigned with a Sector security status byte including a Sector Lock bit, two Password Control bits and two Read/Write protection bits, as shown in Table 7.

Table 6 describes the organization of the Sector security status byte, which can be read using the Read Single Block and Read Multiple Block commands with the Option_flag set to 1 .

On delivery, the default value of the SSS bytes is set to 00 h .
Table 6. Sector security status byte area

| $\mathbf{I}^{2} \mathrm{C}$ byte address |  | Bits [31:24] | Bits [23:16] | Bits [15:8] | Bits [7:0] |
| :---: | :---: | :---: | :---: | :---: | :---: |
| E2 $=1$ | 0 | SSS 3 | SSS 2 | SSS 1 | SSS 0 |
| E2 $=1$ | 4 | SSS 7 | SSS 6 | SSS 5 | SSS 4 |
| E2 = 1 | 8 | SSS 11 | SSS 10 | SSS 9 | SSS 8 |
| E2 = 1 | 12 | SSS 15 | SSS 14 | SSS 13 | SSS 12 |

Table 7. Sector security status byte organization

| $\mathrm{b}_{7}$ | $\mathrm{~b}_{6}$ | $\mathrm{~b}_{5}$ | $\mathrm{~b}_{4}$ | $\mathrm{~b}_{3}$ | $\mathrm{~b}_{2}$ | $\mathrm{~b}_{1}$ | $\mathrm{~b}_{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | Password control bits | Read $/$ Write <br> protection bits | Sector <br> Lock |  |  |

When the Sector Lock bit is set to 1, for instance by issuing a Lock-sector command, the two Read/Write protection bits $\left(b_{1}, b_{2}\right)$ are used to set the Read/Write access of the sector as described in Table 8.

Table 8. Read / Write protection bit setting

| Sector <br> Lock | $\mathbf{b}_{\mathbf{2}}, \mathbf{b}_{\mathbf{1}}$ | Sector access <br> when password presented |  | Sector access <br> when password not presented |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | xx | Read | Write | Read | Write |
| 1 | 00 | Read | Write | Read | No Write |
| 1 | 01 | Read | Write | Read | Write |
| 1 | 10 | Read | Write | No Read | No Write |
| 1 | 11 | Read | No Write | No Read | No Write |

The next two bits of the Sector security status byte $\left(\mathrm{b}_{3}, \mathrm{~b}_{4}\right)$ are the password control bits. The value of these two bits is used to link a password to the sector, as defined in Table 9.

Table 9. Password control bits

| $\mathbf{b}_{\mathbf{4}}, \mathbf{b}_{\mathbf{3}}$ | Password |
| :---: | :---: |
| 00 | The sector is not protected by a password. |
| 01 | The sector is protected by password 1. |
| 10 | The sector is protected by password 2. |
| 11 | The sector is protected by password 3. |

The M24LR16E-R password protection is organized around a dedicated set of commands, plus a system area of three password blocks where the password values are stored. This system area is described in Table 10.

Table 10. Password system area

| Add | Password |
| :---: | :---: |
| 1 | Password 1 |
| 2 | Password 2 |
| 3 | Password 3 |

The dedicated commands for protection in RF mode are:

- Write-sector password:

The Write-sector password command is used to write a 32-bit block into the password system area. This command must be used to update password values. After the write cycle, the new password value is automatically activated. It is possible to modify a password value after issuing a valid Present-sector password command. On delivery, the three default password values are set to 00000000 h and are activated.

- Lock-sector:

The Lock-sector command is used to set the sector security status byte of the selected sector. Bits $b_{4}$ to $b_{1}$ of the sector security status byte are affected by the Lock-sector command. The sector lock bit, $\mathrm{b}_{0}$, is set to 1 automatically. After issuing a Lock-sector command, the protection settings of the selected sector are activated. The protection of a locked block cannot be changed in RF mode. A Lock-sector command sent to a locked sector returns an error code.

- Present-sector password:

The Present-sector password command is used to present one of the three passwords to the M24LR16E-R in order to modify the access rights of all the memory sectors linked to that password (Table 8) including the password itself. If the presented password is correct, the access rights remain activated until the tag is powered off or until a new Present-sector password command is issued. If the presented password value is not correct, all the access rights of all the memory sectors are deactivated.

- Sector security status byte area access conditions in I2C mode:

In $I^{2} \mathrm{C}$ mode, read access to the sector security status byte area is always allowed. Write access depends on the correct presentation of the $\mathrm{I}^{2} \mathrm{C}$ password (see Section 5.16.1: I2C present password command description).
To access the Sector security status byte area, the device select code used for any $I^{2} \mathrm{C}$ command must have the E2 Chip Enable address at 1.
An $I^{2} \mathrm{C}$ write access to a sector security status byte re-initializes the RF access condition to the given memory sector.

### 4.1.1 Example of the M24LR16E-R security protection in RF mode

Table 11 and Table 12 show the sector security protections before and after a valid Presentsector password command. Table 11 shows the sector access rights of an M24LR16E-R after power-up. After a valid Present-sector password command with password 1, the memory sector access is changed as shown in Table 12.

Table 11. M24LR16E-R sector security protection after power-up

| Sector address | Sector features |  |  | Sector security status byte |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\mathrm{b}_{7} \mathrm{~b}_{6} \mathrm{~b}_{5}$ | $\mathrm{b}_{4}$ | $\mathrm{b}_{3}$ | $\mathrm{b}_{2}$ | $\mathrm{b}_{1}$ | $\mathrm{b}_{0}$ |
| 0 | Protection: standard | Read | No Write | xxx | 0 | 0 | 0 | 0 | 1 |
| 1 | Protection: pswd 1 | Read | No Write | xxx | 0 | 1 | 0 | 0 | 1 |
| 2 | Protection: pswd 1 | Read | Write | xxx | 0 | 1 | 0 | 1 | 1 |
| 3 | Protection: pswd 1 | No Read | No Write | xxx | 0 | 1 | 1 | 0 | 1 |
| 4 | Protection: pswd 1 | No Read | No Write | xxx | 0 | 1 | 1 | 1 | 1 |

Table 12. M24LR16E-R sector security protection after a valid presentation of password 1

| Sector address | Sector features |  |  | Sector security status byte |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | $\mathrm{b}_{7} \mathrm{~b}_{6} \mathrm{~b}_{5}$ | $\mathrm{b}_{4}$ | $\mathrm{b}_{3}$ | $b_{2}$ |  | $\mathrm{b}_{0}$ |
| 0 | Protection: standard | Read | No Write | xxx | 0 | 0 | 0 | 0 | 1 |
| 1 | Protection: pswd 1 | Read | Write | xxx | 0 | 1 | 0 | 0 | 1 |
| 2 | Protection: pswd 1 | Read | Write | xxx | 0 | 1 | 0 | 1 | 1 |
| 3 | Protection: pswd 1 | Read | Write | xxx | 0 | 1 | 1 | 0 | 1 |
| 4 | Protection: pswd 1 | Read | No Write | xxx | 0 | 1 | 1 | 1 | 1 |

### 4.2 M24LR16E-R block security in I²C mode (I2C_Write_Lock bit area)

In the $I^{2} \mathrm{C}$ mode only, it is possible to protect individual sectors against Write operations. This feature is controlled by the I2C_Write_Lock bits stored in the 2 bytes of the I2C_Write_Lock bit area. I2C_Write_Lock bit area starts from location 2048 (see Table 13). To access the I2C_Write_Lock bit area, the device select code used for any I ${ }^{2} \mathrm{C}$ command must have the E2 Chip Enable address at 1.
Using these 16 bits, it is possible to write-protect all the 16 sectors of the M24LR16E-R memory. Each bit controls the $1^{2} \mathrm{C}$ write access to a specific sector as shown in Table 13. It is always possible to unprotect a sector in the $I^{2} \mathrm{C}$ mode. When an I2C_Write_Lock bit is reset to 0 , the corresponding sector is unprotected. When the bit is set to 1 , the corresponding sector is write-protected.
$\ln I^{2} \mathrm{C}$ mode, read access to the I2C_Write_Lock bit area is always allowed. Write access depends on the correct presentation of the ${ }^{2} \mathrm{C}$ password.
On delivery, the default value of the eight bytes of the I2C_Write_Lock bit area is reset to 00h.

Table 13. I2C_Write_Lock bit

| $\mathbf{I}^{2}$ C byte address |  | Bits [15:8] | Bits [7:0] |
| :---: | :---: | :---: | :---: |
| $\mathrm{E} 2=1$ | 2048 | sectors 15-8 | sectors 7-0 |

### 4.3 Configuration byte and Control register

The M24LR16E-R offers an 8-bit non-volatile Configuration byte located at ${ }^{2} \mathrm{C}$ location 2320 of the system area used to store the RF WIP/BUSY pin and the energy harvesting configuration (see Table 14).

The M24LR16E-R also offers an 8 -bit volatile Control register located at ${ }^{2} \mathrm{C}$ location 2336 of the system area used to store the energy harvesting enable bit as well as a FIELD_ON bit indicator (see Table 15).

### 4.3.1 RF WIP/BUSY pin configuration

The M24LR16E-R features a configurable open drain output RF WIP/BUSY pin used to provide RF activity information to an external device.
The RF WIP/BUSY pin functionality depends on the value of bit 3 of the Configuration byte.

## - RF busy mode

When bit 3 of the Configuration byte is set to 0 , the RF WIP/BUSY pin is configured in RF busy mode.

The purpose of this mode is to indicate to the $I^{2} \mathrm{C}$ bus master whether the M24LR16E-R is busy in RF mode or not.
In this mode, the RF WIP/BUSY pin is tied to 0 from the RF command Start Of Frame (SOF) until the end of the command execution.

If a bad RF command is received, the RF WIP/BUSY pin is tied to 0 from the RF command SOF until the reception of the RF command CRC. Otherwise, the RF WIP/BUSY pin is in high-Z state.

When tied to 0 , the RF WIP/BUSY signal returns to High-Z state if the RF field is cut-off.
During execution of $I^{2} \mathrm{C}$ commands, the RF WIP/BUSY pin remains in high-Z state.

## - RF Write in progress

When bit 3 of the Configuration byte is set to 1 , the RF WIP/BUSY pin is configured in RF Write in progress mode.

The purpose of this mode is to indicate to the $\mathrm{I}^{2} \mathrm{C}$ bus master that some data have been changed in RF mode.

In this mode, the RF WIP/BUSY pin is tied to 0 for the duration of an internal write operation (i.e. between the end of a valid RF write command and the beginning of the RF answer).

During execution of $\mathrm{I}^{2} \mathrm{C}$ write operations, the RF WIP/BUSY pin remains in high-Z state.

### 4.3.2 Energy harvesting configuration

The M24LR16E-R features an Energy harvesting mode on the Vout analog output.
The general purpose of the Energy harvesting mode is to deliver a part of the nonnecessary RF power received by the M24LR16E-R on the AC0-AC1 RF input in order to supply an external device. The current consumption on the analog voltage output Vout is limited to ensure that the M24LR16E-R is correctly supplied during the powering of the external device.

When the Energy harvesting mode is enabled and the power delivered on the AC0-AC1 RF input exceeds the minimum required $P_{A C 0-A C 1 ~ m i n ~}$, the $M 24 L R 16 E-R$ is able to deliver a limited and unregulated voltage on the Vout pin, assuming the current consumption on the Vout does not exceed the $I_{\text {sink_max }}$ maximum value.
If one of the condition above is not met, the analog voltage output pin Vout is set in High-Z state.

For robust applications using the Energy harvesting mode, four current fan-out levels can be chosen.

- Vout sink current configuration

The sink current level is chosen by programming EH_cfg1 and EH_cfg0 into the Configuration byte (see Table 14).

The minimum power level required on AC0-AC1 RF input $P_{A C 0-A C 1 \_m i n}$, the delivered voltage Vout, as well as the maximum current consumption $I_{\text {sink max }}$ on the Vout pin corresponding to the <EH_cfg1,EH_cfg0> bit values are described in Table 127.

Table 14. Configuration byte

| $I^{2}$ C byte address | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | BIT 1 | BIT 0 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $E 2=1$ | 2320 | $X^{(1)}$ | $X^{(1)}$ | $X^{(1)}$ | $X^{(1)}$ | RF WIP/BUSY | EH_mode | EH_cfg1 | EH_cfg0 |

1. Bit 7 to Bit 4 are don't care bits.

## - Energy harvesting enable control

Delivery of Energy harvesting analog output voltage on the Vout pin depends on the value of the EH_enable bit of the volatile Control register (see Table 15).

Table 15. Control register

| $I^{2} \mathbf{C}$ byte address | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| E2 = 1 | 2336 | T_Prog $^{(1)}$ | $0^{(1)}$ | $0^{(1)}$ | $0^{(1)}$ | $0^{(1)}$ | $0^{(1)}$ | FIELD_ON $^{(1)}$ | EH_enable |

1. Bit 7 to Bit 1 are read-only bits.

- When set to 1, the EH_enable bit enables the Energy harvesting mode, meaning that the Vout analog output signal is delivered when the $\mathrm{P}_{\mathrm{ACO}-\mathrm{AC} 1 \text { min }}$ and $\mathrm{I}_{\text {sink max }}$ conditions corresponding to the chosen sink current configuration bit are met (see Table 127).
- When set to 0, the EH_enable bit disable the Energy harvesting mode and the analog output Vout remains in set in High-Z state.
- The T_Prog flag indicates a correct duration of the $I^{2} \mathrm{C}$ write time (tw). This bit is reset to 0 after POR and at the beginning of each writing cycle; it is set to 1 only after a correct completion of the writing cycle.
- Energy harvesting default mode control

At power-up, in $I^{2} \mathrm{C}$ or RF mode, the EH_enable bit is updated according to the value of the EH_mode bit stored in the non-volatile Configuration byte (see Table 16). In other words, the EH_mode bit is used to configure whether the Energy harvesting mode is enabled or not by default.

Table 16. EH_enable bit value after power-up

| EH_mode value | EH_enable after power-up | Energy harvesting <br> after power-up |
| :---: | :---: | :---: |
| 0 | 1 | enabled |
| 1 | 0 | disabled |

### 4.3.3 FIELD_ON indicator bit

The FIELD_ON bit indicator located as Bit 1 of the Control register is a read-only bit used to indicate when the RF power level delivered to the M24LR16E-R is sufficient to execute RF commands.

- When FIELD_ON $=0$, the M24LR16E-R is not able to execute any RF commands.
- When FIELD_ON =1, the M24LR16E-R is able to execute any RF commands.

Note: $\quad$ During read access to the Control register in RF mode, the FIELD_ON bit is always read at 1 .

### 4.3.4 Configuration byte access in $I^{2} \mathrm{C}$ and RF modes

In $I^{2} \mathrm{C}$ mode, read and write accesses to the non-volatile Configuration byte are always allowed. To access the Configuration byte, the device select code used for any $\mathrm{I}^{2} \mathrm{C}$ command must have the E2 Chip enable address at 1.

The dedicated commands to access the Configuration byte in RF mode are:

- Read configuration byte command (ReadCfg):

The ReadCfg command is used to read the eight bits of the Configuration byte.

- Write energy harvesting configuration command (WriteEHCfg):

The WriteEHCfg command is used to write the EH_mode, EH_cfg1 and EH_cfg0 bits into the Configuration byte.

- Write RF WIP/BUSY pin configuration command (WriteDOCfg):

The WriteDOCfg command is used to write the RF WIP/BUSY bit into the Configuration byte.

After any write access to the Configuration byte, the new configuration is automatically applied.

### 4.3.5 Control register access in $\mathrm{I}^{2} \mathrm{C}$ or RF mode

In $I^{2} \mathrm{C}$ mode, read and write accesses to the volatile Control register are always allowed. To access the Control register, the device select code used for any $I^{2} \mathrm{C}$ command must have the E2 Chip enable address at 1.

The dedicated commands to access the Control register in RF mode are:

- Check energy harvesting enable bit command (CheckEHEn):

The CheckEHEn command is used to read the eight bits of the Control register. When it is run, the FIELD_ON bit is always read at 1.

- Set/reset energy harvesting enable bit command (SetRstEHEn):

The SetRstEHEn command is used to set or reset the value of the EH_enable bit into the Control register.

### 4.4 ISO 15693 system parameters

The M24LR16E-R provides the system area required by the ISO 15693 RF protocol, as shown in Table 17.

The first 32 -bit block starting from $I^{2} \mathrm{C}$ address 2304 stores the $\mathrm{I}^{2} \mathrm{C}$ password. This password is used to activate/deactivate the write protection of the protected sector in $\mathrm{I}^{2} \mathrm{C}$ mode. At power-on, all user memory sectors protected by the I2C_Write_Lock bits can be read but cannot be modified. To remove the write protection, it is necessary to use the $\mathrm{I}^{2} \mathrm{C}$ present password described in Figure 12. When the password is correctly presented - that is, when all the presented bits correspond to the stored ones - it is also possible to modify the $I^{2} \mathrm{C}$ password using the I2C write password command described in Figure 13.

The next three 32-bit blocks store the three RF passwords. These passwords are neither read- nor write- accessible in the $I^{2} \mathrm{C}$ mode.

The next byte stores the Configuration byte, at $I^{2} \mathrm{C}$ location 2320. This Control register is used to store the three energy harvesting configuration bits and the RF WIP/BUSY configuration bit.

The next two bytes are used to store the AFI, at $I^{2} \mathrm{C}$ location 2322, and the DSFID, at $\mathrm{I}^{2} \mathrm{C}$ location 2323. These two values are used during the RF inventory sequence. They are read-only in the $\mathrm{I}^{2} \mathrm{C}$ mode.
The next eight bytes, starting from location 2324, store the 64-bit UID programmed by ST on the production line. Bytes at $I^{2} \mathrm{C}$ locations 2332 to 2335 store the IC Ref and the Mem_Size data used by the RF Get_System_Info command. The UID, Mem_Size and IC ref values are read-only data.

Table 17. System parameter sector

| $1^{2} \mathrm{C}$ byte address |  | Bits [31:24] | Bits [23:16] | Bits [15:8] | Bits [7:0] |
| :---: | :---: | :---: | :---: | :---: | :---: |
| E2 = 1 | 2304 | $\mathrm{I}^{2} \mathrm{C}$ password ${ }^{(1)}$ |  |  |  |
| $\mathrm{E} 2=1$ | 2308 | RF password $1{ }^{(1)}$ |  |  |  |
| $\mathrm{E} 2=1$ | 2312 | RF password $2{ }^{(1)}$ |  |  |  |
| $\mathrm{E} 2=1$ | 2316 | RF password $3{ }^{(1)}$ |  |  |  |
| $E 2=1$ | 2320 | DSFID (FFh) | AFI (00h) | $\begin{aligned} & \text { ST reserved } \\ & \text { (Exh }^{(2)} \end{aligned}$ | Configuration byte (F4h) |
| $\mathrm{E} 2=1$ | 2324 | UID | UID | UID | UID |
| $\mathrm{E} 2=1$ | 2328 | UID (EOh) | UID (02h) | UID | UID |
| $E 2=1$ | 2332 | $\begin{aligned} & \text { Mem_Size } \\ & \text { (03 01FFh) } \end{aligned}$ |  |  | IC Ref (4Eh) |
| $E 2=1$ | 2336 | - | - | - | Prog. completion and Energy harvesting status ${ }^{(3)}$ |

1. Delivery state: $I^{2} \mathrm{C}$ password $=00000000 \mathrm{~h}, \mathrm{RF}$ password $=00000000 \mathrm{~h}$, Configuration byte $=\mathrm{F} 4 \mathrm{~h}$.
2. The product revision is the Most significant nibble of the byte located at address $0 \times 911$ (2321 d) in the system area (Device select code E2 =1). From DS rev9, the product revision value is $0 x E$. The Least significant nibble is ST reserved.
3. Address system 2336 ( $920 \mathrm{~h}, \mathrm{E} 2=1$ ) is the control register.

Bit 7 is T_Prog (refer to Table 15: Control register). When accessed in RF, this bit is not significant and set to 0.
Bits 2-6 are RFU and set to 0 .
Bit 1 is FIELD_ON (refer to Table 15: Control register).
Bit 0 is EH_enable (refer to Table 15: Control register).

## $5 \quad I^{2} C$ device operation

The device supports the $I^{2} \mathrm{C}$ protocol. This is summarized in Figure 4. Any device that sends data to the bus is defined as a transmitter, and any device that reads data is defined as a receiver. The device that controls the data transfer is known as the bus master, and the other as the slave device. A data transfer can only be initiated by the bus master, which also provides the serial clock for synchronization. The M24LR16E-R device is a slave in all communications.

### 5.1 Start condition

Start is identified by a falling edge of serial data (SDA) while the serial clock (SCL) is stable in the high state. A Start condition must precede any data transfer command. The device continuously monitors (except during a write cycle) the SDA and the SCL for a Start condition, and does not respond unless one is given.

### 5.2 Stop condition

Stop is identified by a rising edge of serial data (SDA) while the serial clock (SCL) is stable and driven high. A Stop condition terminates communication between the device and the bus master. A Read command that is followed by NoAck can be followed by a Stop condition to force the device into the Standby mode. A Stop condition at the end of a Write command triggers the internal write cycle.

### 5.3 Acknowledge bit (ACK)

The acknowledge bit is used to indicate a successful byte transfer. The bus transmitter, whether it be bus master or slave device, releases the serial data (SDA) after sending eight bits of data. During the $9^{\text {th }}$ clock pulse period, the receiver pulls the SDA low to acknowledge the receipt of the eight data bits.

### 5.4 Data input

During data input, the device samples serial data (SDA) on the rising edge of the serial clock (SCL). For correct device operation, the SDA must be stable during the rising edge of the SCL, and the SDA signal must change only when the SCL is driven low.

## $5.5 \quad I^{2} \mathrm{C}$ timeout

During the execution of an $I^{2} \mathrm{C}$ operation, RF communications are not possible.
To prevent RF communication freezing due to inadvertent unterminated instructions sent to the $I^{2} C$ bus, the M24LR16E-R features a timeout mechanism that automatically resets the $1^{2} \mathrm{C}$ logic block.

### 5.5.1 $\quad I^{2} \mathrm{C}$ timeout on Start condition

$I^{2} \mathrm{C}$ communication with the M24LR16E-R starts with a valid Start condition, followed by a device select code.

If the delay between the Start condition and the following rising edge of the Serial Clock (SCL) that samples the most significant of the Device Select exceeds the tstart out time (see Table 123), the $\mathrm{I}^{2} \mathrm{C}$ logic block is reset and further incoming data transfer is ignored until the next valid Start condition.

Figure 7. ${ }^{2} \mathrm{C}$ timeout on Start condition


### 5.5.2 $\quad I^{2} \mathrm{C}$ timeout on clock period

During data transfer on the $\mathrm{I}^{2} \mathrm{C}$ bus, the serial clock high pulse width High ( $\mathrm{t}_{\mathrm{CHCL}}$ ) or serial clock pulse width Low ( $\mathrm{t}_{\mathrm{CLCH}}$ ) exceeds the maximum value specified in Table 123, the $\mathrm{I}^{2} \mathrm{C}$ logic block is reset and any further incoming data transfer is ignored until the next valid Start condition.

### 5.6 Memory addressing

To start communication between the bus master and the slave device, the bus master must initiate a Start condition. Following this, the bus master sends the device select code, shown in Table 2 (on Serial Data (SDA), most significant bit first).

The device select code consists of a 4-bit device type identifier and a 3-bit Chip Enable "Address" (E2,1,1). To address the memory array, the 4-bit device type identifier is 1010b. Refer to Table 2.

The eighth bit is the Read $/ \overline{W r i t e}$ bit $(R \bar{W})$. It is set to 1 for Read and to 0 for Write operations.
If a match occurs on the device select code, the corresponding device gives an acknowledgment on serial data (SDA) during the ninth bit time. If the device does not match the device select code, it deselects itself from the bus, and goes into Standby mode.

Table 18. Operating modes

| Mode | $\mathrm{R} \overline{\mathrm{W}}$ bit | Bytes | Initial sequence |
| :--- | :---: | :---: | :--- |
| Current address read | 1 | 1 | Start, device select, $\mathrm{R} \overline{\mathrm{W}}=1$ |
| Random address read | 0 | 1 | Start, device select, $\mathrm{R} \overline{\mathrm{W}}=0$, address |
|  | 1 |  | reStart, device select, $\mathrm{R} \overline{\mathrm{W}}=1$ |
| Sequential read | 1 | $\geq 1$ | Similar to current or random address read |
| Byte write | 0 | 1 | Start, device select, $\mathrm{R} \overline{\mathrm{W}}=0$ |
| Page write | 0 | $\leq 4$ bytes | Start, device select, $\mathrm{R} \overline{\mathrm{W}}=0$ |

Figure 8. Write mode sequences with I2C_Write_Lock bit = 1 (data write inhibited)


### 5.7 Write operations

Following a Start condition, the bus master sends a device select code with the Read/Write bit (RW) reset to 0 . The device acknowledges this, as shown in Figure 8, and waits for two address bytes. The device responds to each address byte with an acknowledge bit, and then waits for the data byte.
Writing to the memory may be inhibited if the I2C_Write_Lock bit = 1. A Write instruction issued with the I2C_Write_Lock bit = 1 and with no I2C_Password presented does not modify the memory contents, and the accompanying data bytes are not acknowledged, as shown in Figure 8.

Each data byte in the memory has a 16-bit (two byte wide) address. The most significant byte (Table 3) is sent first, followed by the least significant byte (Table 4). Bits b15 to b0 form the address of the byte in memory.

When the bus master generates a Stop condition immediately after the Ack bit (in the tenthbit time slot), either at the end of a byte write or a page write, the internal write cycle is triggered. A Stop condition at any other time slot does not trigger the internal write cycle.
After the Stop condition, the delay $\mathrm{t}_{\mathrm{W}}$, and the successful completion of a Write operation, the device's internal address counter is incremented automatically, to point to the next byte address after the last one that was modified.

During the internal write cycle, the serial data (SDA) signal is disabled internally, and the device does not respond to any requests.

### 5.8 Byte write

After the device select code and the address bytes, the bus master sends one data byte. If the addressed location is write-protected by the I2C_Write_Lock bit (= 1), the device replies with NoAck, and the location is not modified. If the addressed location is not write-protected, the device replies with Ack. The bus master terminates the transfer by generating a Stop condition, as shown in Figure 9.

### 5.9 Page write

The Page write mode allows up to four bytes to be written in a single write cycle, provided that they are all located in the same "row" in the memory: that is, the most significant memory address bits (b12-b2) are the same. If more bytes are sent than fit up to the end of the row, a condition known as "roll-over" occurs. This should be avoided, as data starts to become overwritten in an implementation-dependent way.

The bus master sends from one to four bytes of data, each of which is acknowledged by the device if the I2C_Write_Lock bit = 0 or the I2C_Password was correctly presented. If the I2C_Write_Lock_bit = 1 and the I2C_password are not presented, the contents of the addressed memory location are not modified, and each data byte is followed by a NoAck. After each byte is transferred, the internal byte address counter (inside the page) is incremented. The transfer is terminated by the bus master generating a Stop condition.

Figure 9. Write mode sequences with I2C_Write_Lock bit = 0 (data write enabled)


Figure 10. Write cycle polling flowchart using ACK


### 5.10 Minimizing system delays by polling on ACK

During the internal write cycle, the device disconnects itself from the bus, and writes a copy of the data from its internal latches to the memory cells. The maximum $I^{2} \mathrm{C}$ write time ( $\mathrm{t}_{\mathrm{w}}$ ) is shown in Table 123, but the typical time is shorter. To make use of this, a polling sequence can be used by the bus master.

The sequence, as shown in Figure 10, is:

1. Initial condition: a write cycle is in progress.
2. Step 1: the bus master issues a Start condition followed by a device select code (the first byte of the new instruction).
3. Step 2: if the device is busy with the internal write cycle, no Ack is returned and the bus master goes back to Step 1. If the device has terminated the internal write cycle, it responds with an Ack, indicating that the device is ready to receive the second part of the instruction (the first byte of this instruction having been sent during Step 1).

Figure 11. Read mode sequences


[^0]
### 5.11 Read operations

Read operations are performed independently of the state of the I2C_Write_Lock bit.
After the successful completion of a read operation, the device's internal address counter is incremented by one, to point to the next byte address.

### 5.12 Random Address Read

A dummy write is first performed to load the address into this address counter (as shown in Figure 11) but without sending a Stop condition. Then, the bus master sends another Start condition, and repeats the device select code, with the Read/Write bit ( $R \bar{W}$ ) set to 1. The device acknowledges this, and outputs the contents of the addressed byte. The bus master must not acknowledge the byte, and terminates the transfer with a Stop condition.

### 5.13 Current Address Read

For the Current Address Read operation, following a Start condition, the bus master only sends a device select code with the Read/Write bit (RW) set to 1 . The device acknowledges this, and outputs the byte addressed by the internal address counter. The counter is then incremented. The bus master terminates the transfer with a Stop condition, as shown in Figure 11, without acknowledging the byte.

### 5.14 Sequential Read

This operation can be used after a Current Address Read or a Random Address Read. The bus master does acknowledge the data byte output, and sends additional clock pulses so that the device continues to output the next byte in sequence. To terminate the stream of bytes, the bus master must not acknowledge the last byte, and must generate a Stop condition, as shown in Figure 11.

The output data come from consecutive addresses, with the internal address counter automatically incremented after each byte output. After the last memory address, the address counter "rolls-over", and the device continues to output data from memory address 00h.

### 5.15 Acknowledge in Read mode

For all Read commands, the device waits, after each byte read, for an acknowledgment during the ninth bit time. If the bus master does not drive Serial Data (SDA) low during this time, the device terminates the data transfer and switches to its Standby mode.

### 5.16 M24LR16E-R $I^{2} C$ password security

The M24LR16E-R controls $\mathrm{I}^{2} \mathrm{C}$ sector write access using the 32 -bit-long $\mathrm{I}^{2} \mathrm{C}$ password and the 64-bit I2C_Write_Lock bit area. The I ${ }^{2} \mathrm{C}$ password value is managed using two $I^{2} \mathrm{C}$ commands: $I^{2} \mathrm{C}$ present password and $I^{2} \mathrm{C}$ write password.

### 5.16.1 $\quad \mathrm{I}^{2} \mathrm{C}$ present password command description

The $I^{2} C$ present password command is used in $I^{2} C$ mode to present the password to the M24LR16E-R in order to modify the write access rights of all the memory sectors protected by the I2C_Write_Lock bits, including the password itself. If the presented password is correct, the access rights remain activated until the M24LR16E-R is powered off or until a new $I^{2} \mathrm{C}$ present password command is issued.
Following a Start condition, the bus master sends a device select code with the Read/ $\overline{\text { Write }}$ bit ( $\mathrm{R} \overline{\mathrm{W}}$ ) reset to 0 and the Chip Enable bit E2 at 1 . The device acknowledges this, as shown in Figure 12, and waits for two $\mathrm{I}^{2} \mathrm{C}$ password address bytes 09h and 00h. The device responds to each address byte with an acknowledge bit, and then waits for the four password data bytes, the validation code, 09h, and a resend of the four password data bytes. The most significant byte of the password is sent first, followed by the least significant bytes.

It is necessary to send the 32-bit password twice to prevent any data corruption during the sequence. If the two 32-bit passwords sent are not exactly the same, the M24LR16E-R does not start the internal comparison.
When the bus master generates a Stop condition immediately after the Ack bit (during the tenth bit time slot), an internal delay equivalent to the write cycle time is triggered. A Stop condition at any other time does not trigger the internal delay. During that delay, the M24LR16E-R compares the 32 received data bits with the 32 bits of the stored $I^{2} \mathrm{C}$ password. If the values match, the write access rights to all protected sectors are modified after the internal delay. If the values do not match, the protected sectors remains protected.
During the internal delay, the serial data (SDA) signal is disabled internally, and the device does not respond to any requests.

Figure 12. $\mathrm{I}^{2} \mathrm{C}$ present password command


### 5.16.2 $\quad I^{2} \mathrm{C}$ write password command description

The $I^{2} \mathrm{C}$ write password command is used to write a 32 -bit block into the M24LR16E-R I ${ }^{2} \mathrm{C}$ password system area. This command is used in $I^{2} \mathrm{C}$ mode to update the $I^{2} \mathrm{C}$ password value. It cannot be used to update any of the RF passwords. After the write cycle, the new $I^{2} \mathrm{C}$ password value is automatically activated. The $I^{2} \mathrm{C}$ password value can only be modified after issuing a valid $\mathrm{I}^{2} \mathrm{C}$ present password command.
On delivery, the $I^{2} \mathrm{C}$ default password value is set to 00000000 h and is activated.
Following a Start condition, the bus master sends a device select code with the Read/ $\overline{W r i t e}$ bit $(R \bar{W})$ reset to 0 and the Chip Enable bit E2 at 1. The device acknowledges this, as shown in Figure 13, and waits for the two $I^{2} \mathrm{C}$ password address bytes, 09 h and 00 h . The device responds to each address byte with an acknowledge bit, and then waits for the four password data bytes, the validation code, 07 h , and a resend of the four password data bytes. The most significant byte of the password is sent first, followed by the least significant bytes.
It is necessary to send twice the 32-bit password to prevent any data corruption during the write sequence. If the two 32 -bit passwords sent are not exactly the same, the M24LR16E$R$ does not modify the $I^{2} \mathrm{C}$ password value.
When the bus master generates a Stop condition immediately after the Ack bit (during the tenth bit time slot), the internal write cycle is triggered. A Stop condition at any other time does not trigger the internal write cycle.
During the internal write cycle, the serial data (SDA) signal is disabled internally, and the device does not respond to any requests.

Figure 13. $I^{2} \mathrm{C}$ write password command


## 6 M24LR16E-R memory initial state

The device is delivered with all bits in the user memory array set to 1 (each byte contains FFh).

The DSFID is programmed to FFh and the AFI is programmed to 00h.
Configuration byte set to F4h:

- Bit 7 to bit 4: all set to 1
- Bit 3: set to 0 (RF BUSY mode on RF WIP/BUSY pin)
- Bit 2: set to 1 (Energy harvesting not activated by default)
- Bit 1 and bit 0: set to 0


## 7 RF device operation

The M24LR16E-R is divided into 16 sectors of 32 blocks of 32 bits, as shown in Table 5. Each sector can be individually read- and/or write-protected using a specific lock or password command.

Read and Write operations are possible if the addressed block is not protected. During a Write, the 32 bits of the block are replaced by the new 32-bit value.

The M24LR16E-R also has a 64-bit block that is used to store the 64-bit unique identifier (UID). The UID is compliant with the ISO 15963 description, and its value is used during the anticollision sequence (Inventory). This block is not accessible by the user and its value is written by ST on the production line.

The M24LR16E-R also includes an AFI register in which the application family identifier is stored, and a DSFID register in which the data storage family identifier used in the anticollision algorithm is stored.

The M24LR16E-R has three 32-bit blocks in which the password codes are stored and a 8bit Configuration byte in which the Energy harvesting mode and RF WIP/BUSY pin configuration is stored.

### 7.1 RF communication and energy harvesting

Because current consumption can affect the AC signal delivered by the antenna, RF communications with M24LR16E-R are not guaranteed during voltage delivery on the energy harvesting analog output Vout.

RF communication can disturb and possibly stop Energy Harvesting mode.

### 7.2 Commands

The M24LR16E-R supports the following commands:

- Inventory, used to perform the anticollision sequence.
- Stay quiet, used to put the M24LR16E-R in quiet mode, where it does not respond to any inventory command.
- $\quad$ Select, used to select the M24LR16E-R. After this command, the M24LR16E-R processes all Read/Write commands with Select_flag set.
- Reset to ready, used to put the M24LR16E-R in the ready state.
- Read block, used to output the 32 bits of the selected block and its locking status.
- Write block, used to write the 32-bit value in the selected block, provided that it is not locked.
- Read multiple blocks, used to read the selected blocks and send back their value.
- Write AFI, used to write the 8-bit value in the AFI register.
- Lock AFI, used to lock the AFI register.
- Write DSFID, used to write the 8-bit value in the DSFID register.
- Lock DSFID, used to lock the DSFID register.
- Get system info, used to provide the system information value
- Get multiple block security status, used to send the security status of the selected block.
- Initiate, used to trigger the tag response to the Inventory initiated sequence.
- Inventory initiated, used to perform the anticollision sequence triggered by the Initiate command.
- Write-sector password, used to write the 32 bits of the selected password.
- Lock-sector, used to write the sector security status bits of the selected sector.
- Present-sector password, enables the user to present a password to unprotect the user blocks linked to this password.
- Fast initiate, used to trigger the tag response to the Inventory initiated sequence.
- Fast inventory initiated, used to perform the anticollision sequence triggered by the Initiate command.
- Fast read single block, used to output the 32 bits of the selected block and its locking status.
- Fast read multiple blocks, used to read the selected blocks and send back their value.
- ReadCfg, used to read the 8-bit Configuration byte and send back its value.
- WriteEHCfg, used to write the energy harvesting configuration bits into the Configuration byte.
- WriteDOCfg, used to write the RF WIP/BUSY pin configuration bit into the Configuration byte.
- SetRstEHEn, used to set or reset the EH_enable bit into the volatile Control register.
- CheckEHEn, used to send back the value of the volatile Control register.


### 7.3 Initial dialog for vicinity cards

The dialog between the vicinity coupling device or VCD (commonly the "RF reader") and the vicinity integrated circuit card or VICC (M24LR16E-R) takes place as follows:

- activation of the M24LR16E-R by the RF operating field of the VCD,
- transmission of a command by the VCD,
- transmission of a response by the M24LR16E-R.

These operations use the RF power transfer and communication signal interface described below (see Power transfer, Frequency and Operating field). This technique is called RTF (Reader talk first).

### 7.3.1 Power transfer

Power is transferred to the M24LR16E-R by radio frequency at 13.56 MHz via coupling antennas in the M24LR16E-R and the VCD. The RF operating field of the VCD is transformed on the M24LR16E-R antenna to an AC voltage which is rectified, filtered and internally regulated.

During communications, the amplitude modulation (ASK) on this received signal is demodulated by the ASK demodulator.

### 7.3.2 Frequency

The ISO 15693 standard defines the carrier frequency $\left(f_{C}\right)$ of the operating field as $13.56 \mathrm{MHz} \pm 7 \mathrm{kHz}$.

### 7.3.3 Operating field

The M24LR16E-R operates continuously between the minimum and maximum values of the electromagnetic field H defined in Table 125. The VCD has to generate a field within these limits.

## 8 Communication signal from VCD to M24LR16E-R

Communications between the VCD and the M24LR16E-R takes place using the modulation principle of ASK (Amplitude shift keying). Two modulation indexes are used, 10\% and $100 \%$. The M24LR16E-R decodes both. The VCD determines which index is used.

The modulation index is defined as $[a-b] /[a+b]$, where $a$ is the peak signal amplitude, and $b$ the minimum signal amplitude of the carrier frequency.

Depending on the choice made by the VCD, a "pause" is created as described in Figure 14 and Figure 15.
The M24LR16E-R is operational for the $100 \%$ modulation index or for any degree of modulation index between $10 \%$ and $30 \%$ (see Table 125).

Figure 14. 100\% modulation waveform


The clock recovery shall be operational after $\mathrm{t}_{4}$ max.

Table 19. 10\% modulation parameters

| Symbol | Parameter definition | Value |
| :---: | :---: | :---: |
| hr | $0.1 \times(\mathrm{a}-\mathrm{b})$ | $\max$ |
| hf | $0.1 \times(\mathrm{a}-\mathrm{b})$ | $\max$ |

Figure 15. 10\% modulation waveform


The VICC shall be operational for any value of modulation index between $10 \%$ and $30 \%$.

## $9 \quad$ Data rate and data coding

The data coding implemented in the M24LR16E-R uses pulse position modulation. Both data coding modes that are described in the ISO15693 are supported by the M24LR16E-R. The selection is made by the VCD and indicated to the M24LR16E-R within the start of frame (SOF).

### 9.1 Data coding mode: 1 out of 256

The value of one single byte is represented by the position of one pause. The position of the pause on 1 of 256 successive time periods of $18.88 \mu \mathrm{~s}\left(256 / f_{C}\right)$ determines the value of the byte. In this case, the transmission of one byte takes 4.833 ms and the resulting data rate is 1.65 Kbits/s ( $f_{C} / 8192$ ).

Figure 16 illustrates this pulse position modulation technique. In this figure, data E1h (225 decimal) is sent by the VCD to the M24LR16E-R.

The pause occurs during the second half of the position of the time period that determines the value, as shown in Figure 17.

A pause during the first period transmits the data value 00h. A pause during the last period transmits the data value FFh (255 decimal).

Figure 16.1 out of $\mathbf{2 5 6}$ coding mode


Figure 17. Detail of a time period


### 9.2 Data coding mode: 1 out of 4

The value of two bits is represented by the position of one pause. The position of the pause on 1 of 4 successive time periods of $18.88 \mu \mathrm{~s}\left(256 / f_{C}\right)$ determines the value of the two bits. Four successive pairs of bits form a byte, where the least significant pair of bits is transmitted first.

In this case, the transmission of one byte takes $302.08 \mu$ s and the resulting data rate is 26.48 Kbits/s ( $f_{C} / 512$ ). Figure 18 illustrates the 1 out of 4 pulse position technique and coding. Figure 19 shows the transmission of E1h (225d - 11100001 b) by the VCD.

Figure 18. 1 out of 4 coding mode


Figure 19.1 out of 4 coding example


### 9.3 VCD to M24LR16E-R frames

Frames are delimited by a start of frame (SOF) and an end of frame (EOF). They are implemented using code violation. Unused options are reserved for future use.

The M24LR16E-R is ready to receive a new command frame from the VCD $311.5 \mu \mathrm{~s}$ after sending a response frame to the VCD.
The M24LR16E-R takes a power-up time of 0.1 ms after being activated by the powering field. After this delay, the M24LR16E-R is ready to receive a command frame from the VCD.

### 9.4 Start of frame (SOF)

The SOF defines the data coding mode the VCD is to use for the following command frame. The SOF sequence described in Figure 20 selects the 1 out of 256 data coding mode. The SOF sequence described in Figure 21 selects the 1 out of 4 data coding mode. The EOF sequence for either coding mode is described in Figure 22.

Figure 20. SOF to select 1 out of 256 data coding mode


Figure 21. SOF to select 1 out of 4 data coding mode


Figure 22. EOF for either data coding mode


## 10 Communication signal from M24LR16E-R to VCD

The M24LR16E-R has several modes defined for some parameters, owing to which it can operate in various noise environments and meet various application requirements.

### 10.1 Load modulation

The M24LR16E-R is capable of communication to the VCD via an inductive coupling area whereby the carrier is loaded to generate a subcarrier with frequency $f_{S}$. The subcarrier is generated by switching a load in the M24LR16E-R.

The load-modulated amplitude received on the VCD antenna must be of at least 10 mV when measured as described in the test methods defined in International Standard ISO10373-7.

### 10.2 Subcarrier

The M24LR16E-R supports the one-subcarrier and two-subcarrier response formats. These formats are selected by the VCD using the first bit in the protocol header. When one subcarrier is used, the frequency $f_{S 1}$ of the subcarrier load modulation is $423.75 \mathrm{kHz}\left(f_{C} / 32\right)$. When two subcarriers are used, the frequency $f_{S 1}$ is $423.75 \mathrm{kHz}\left(f_{C} / 32\right)$, and frequency $f_{S 2}$ is $484.28 \mathrm{kHz}\left(f_{C} / 28\right)$. When using the two-subcarrier mode, the M24LR16E-R generates a continuous phase relationship between $f_{S 1}$ and $f_{S 2}$.

### 10.3 Data rates

The M24LR16E-R can respond using the low or the high data rate format. The selection of the data rate is made by the VCD using the second bit in the protocol header. For fast commands, the selected data rate is multiplied by two. Table 20 shows the different data rates produced by the M24LR16E-R using the different response format combinations.

Table 20. Response data rates

| Data rate |  | One subcarrier | Two subcarriers |
| :---: | :--- | :---: | :---: |
| Low | Standard commands | $6.62 \mathrm{Kbit} / \mathrm{s}\left(f_{\mathrm{c}} / 2048\right)$ | $6.67 \mathrm{Kbit} / \mathrm{s}\left(f_{\mathrm{c}} / 2032\right)$ |
|  | Fast commands | $13.24 \mathrm{Kbit} / \mathrm{s}\left(f_{\mathrm{c}} / 1024\right)$ | not applicable |
| High | Standard commands | $26.48 \mathrm{Kbit} / \mathrm{s}\left(f_{\mathrm{c}} / 512\right)$ | $26.69 \mathrm{Kbit} / \mathrm{s}\left(f_{\mathrm{c}} / 508\right)$ |
|  | Fast commands | $52.97 \mathrm{Kbit} / \mathrm{s}\left(f_{\mathrm{c}} / 256\right)$ | not applicable |

## 11 Bit representation and coding

Data bits are encoded using Manchester coding, according to the following schemes. For the low data rate, same subcarrier frequency or frequencies is/are used. In this case, the number of pulses is multiplied by 4 and all times increase by this factor. For the Fast commands using one subcarrier, all pulse numbers and times are divided by 2.

### 11.1 Bit coding using one subcarrier

### 11.1.1 High data rate

A logic 0 starts with eight pulses at $423.75 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 32\right)$ followed by an unmodulated time of $18.88 \mu \mathrm{~s}$, as shown in Figure 23.

Figure 23. Logic 0, high data rate


For the fast commands, a logic 0 starts with four pulses at $423.75 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 32\right)$ followed by an unmodulated time of $9.44 \mu \mathrm{~s}$, as shown in Figure 24.

Figure 24. Logic 0, high data rate, fast commands


A logic 1 starts with an unmodulated time of $18.88 \mu$ sollowed by eight pulses at 423.75 kHz ( $\mathrm{f}_{\mathrm{C}} / 32$ ), as shown in Figure 25.

Figure 25. Logic 1, high data rate


For the Fast commands, a logic 1 starts with an unmodulated time of $9.44 \mu \mathrm{~s}$ followed by four pulses of $423.75 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 32\right)$, as shown in Figure 26.

Figure 26. Logic 1, high data rate, fast commands


### 11.1.2 Low data rate

A logic 0 starts with 32 pulses at $423.75 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 32\right)$ followed by an unmodulated time of $75.52 \mu \mathrm{~s}$, as shown in Figure 27.

Figure 27. Logic 0, low data rate


For the Fast commands, a logic 0 starts with 16 pulses at $423.75 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 32\right)$ followed by an unmodulated time of $37.76 \mu \mathrm{~s}$, as shown in Figure 28.

Figure 28. Logic 0, low data rate, fast commands


A logic 1 starts with an unmodulated time of $75.52 \mu \mathrm{~s}$ followed by 32 pulses at 423.75 kHz ( $\mathrm{f}_{\mathrm{C}} / 32$ ), as shown in Figure 29.

Figure 29. Logic 1, low data rate


For the Fast commands, a logic 1 starts with an unmodulated time of $37.76 \mu$ s followed by 16 pulses at 423.75 kHz ( $\mathrm{f}_{\mathrm{C}} / 32$ ), as shown in Figure 30.

Figure 30. Logic 1, low data rate, fast commands


### 11.2 Bit coding using two subcarriers

### 11.2.1 High data rate

A logic 0 starts with eight pulses at $423.75 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 32\right)$ followed by nine pulses at 484.28 kHz ( $\mathrm{f}_{\mathrm{C}} / 28$ ), as shown in Figure 31. Bit coding using two subcarriers is not supported for the Fast commands.

Figure 31. Logic 0, high data rate


A logic 1 starts with nine pulses at $484.28 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 28\right)$ followed by eight pulses at 423.75 kHz ( $\mathrm{f}_{\mathrm{C}} / 32$ ), as shown in Figure 32. Bit coding using two subcarriers is not supported for the Fast commands.

Figure 32. Logic 1, high data rate


### 11.2.2 Low data rate

A logic 0 starts with 32 pulses at 423.75 kHz ( $\mathrm{f}_{\mathrm{C}} / 32$ ) followed by 36 pulses at 484.28 kHz ( $\mathrm{f}_{\mathrm{C}} / 28$ ), as shown in Figure 33. Bit coding using two subcarriers is not supported for the Fast commands.

Figure 33. Logic 0, low data rate


A logic 1 starts with 36 pulses at $484.28 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 28\right)$ followed by 32 pulses at 423.75 kHz ( $\mathrm{f}_{\mathrm{C}} / 32$ ) as shown in Figure 34. Bit coding using two subcarriers is not supported for the Fast commands.

Figure 34. Logic 1, low data rate


## 12 M24LR16E-R to VCD frames

Frames are delimited by an SOF and an EOF. They are implemented using code violation. Unused options are reserved for future use. For the low data rate, the same subcarrier frequency or frequencies is/are used. In this case, the number of pulses is multiplied by 4. For the Fast commands using one subcarrier, all pulse numbers and times are divided by 2.

### 12.1 SOF when using one subcarrier

### 12.1.1 High data rate

The SOF includes an unmodulated time of $56.64 \mu \mathrm{~s}$, followed by 24 pulses at 423.75 kHz ( $\mathrm{f}_{\mathrm{C}} / 32$ ), and a logic 1 that consists of an unmodulated time of $18.88 \mu \mathrm{~s}$ followed by eight pulses at 423.75 kHz, as shown in Figure 35.

Figure 35. Start of frame, high data rate, one subcarrier


For the Fast commands, the SOF comprises an unmodulated time of $28.32 \mu \mathrm{~s}$, followed by 12 pulses at $423.75 \mathrm{kHz}\left(\mathrm{f}_{\mathrm{C}} / 32\right)$, and a logic 1 that consists of an unmodulated time of $9.44 \mu \mathrm{~s}$ followed by four pulses at 423.75 kHz , as shown in Figure 36.

Figure 36. Start of frame, high data rate, one subcarrier, fast commands


### 12.1.2 Low data rate

The SOF comprises an unmodulated time of $226.56 \mu \mathrm{~s}$, followed by 96 pulses at 423.75 $\mathrm{kHz}\left(f_{C} / 32\right)$, and a logic 1 that consists of an unmodulated time of $75.52 \mu \mathrm{~s}$ followed by 32 pulses at 423.75 kHz, as shown in Figure 37.

Figure 37. Start of frame, low data rate, one subcarrier


For the Fast commands, the SOF comprises an unmodulated time of $113.28 \mu \mathrm{~s}$, followed by 48 pulses at $423.75 \mathrm{kHz}\left(f_{C} / 32\right)$, and a logic 1 that includes an unmodulated time of 37.76 $\mu$ s followed by 16 pulses at 423.75 kHz, as shown in Figure 38.

Figure 38. Start of frame, low data rate, one subcarrier, fast commands


### 12.2 SOF when using two subcarriers

### 12.2.1 High data rate

The SOF comprises 27 pulses at $484.28 \mathrm{kHz}\left(f_{C} / 28\right)$, followed by 24 pulses at 423.75 kHz ( $f_{C} / 32$ ), and a logic 1 that includes nine pulses at 484.28 kHz followed by eight pulses at 423.75 kHz, as shown in Figure 39.

Bit coding using two subcarriers is not supported for the Fast commands.
Figure 39. Start of frame, high data rate, two subcarriers


### 12.2.2 Low data rate

The SOF comprises 108 pulses at $484.28 \mathrm{kHz}\left(f_{C} / 28\right)$, followed by 96 pulses at 423.75 kHz ( $f_{C} / 32$ ), and a logic 1 that includes 36 pulses at 484.28 kHz followed by 32 pulses at 423.75 kHz, as shown in Figure 40.

Bit coding using two subcarriers is not supported for the Fast commands.
Figure 40. Start of frame, low data rate, two subcarriers


### 12.3 EOF when using one subcarrier

### 12.3.1 High data rate

The EOF comprises a logic 0 that includes eight pulses at 423.75 kHz and an unmodulated time of $18.88 \mu \mathrm{~s}$, followed by 24 pulses at $423.75 \mathrm{kHz}\left(f_{C} / 32\right)$, and by an unmodulated time of $56.64 \mu \mathrm{~s}$, as shown in Figure 41.

Figure 41. End of frame, high data rate, one subcarrier


For the Fast commands, the EOF comprises a logic 0 that includes four pulses at 423.75 kHz and an unmodulated time of $9.44 \mu \mathrm{~s}$, followed by 12 pulses at 423.75 kHz $\left(f_{C} / 32\right)$ and an unmodulated time of $37.76 \mu \mathrm{~s}$, as shown in Figure 42.

Figure 42. End of frame, high data rate, one subcarrier, fast commands


### 12.3.2 Low data rate

The EOF comprises a logic 0 that includes 32 pulses at 423.75 kHz and an unmodulated time of $75.52 \mu \mathrm{~s}$, followed by 96 pulses at $423.75 \mathrm{kHz}\left(f_{C} / 32\right)$ and an unmodulated time of $226.56 \mu \mathrm{~s}$, as shown in Figure 43.

Figure 43. End of frame, low data rate, one subcarrier


For the Fast commands, the EOF comprises a logic 0 that includes 16 pulses at 423.75 kHz and an unmodulated time of $37.76 \mu \mathrm{~s}$, followed by 48 pulses at $423.75 \mathrm{kHz}\left(f_{C} / 32\right)$ and an unmodulated time of $113.28 \mu \mathrm{~s}$, as shown in Figure 44.

Figure 44. End of frame, low data rate, one subcarrier, Fast commands


### 12.4 EOF when using two subcarriers

### 12.4.1 High data rate

The EOF comprises a logic 0 that includes eight pulses at 423.75 kHz and nine pulses at 484.28 kHz , followed by 24 pulses at $423.75 \mathrm{kHz}\left(f_{C} / 32\right)$ and 27 pulses at 484.28 kHz ( $f_{C} / 28$ ), as shown in Figure 45.

Bit coding using two subcarriers is not supported for the Fast commands.
Figure 45. End of frame, high data rate, two subcarriers


### 12.4.2 Low data rate

The EOF comprises a logic 0 that includes 32 pulses at 423.75 kHz and 36 pulses at 484.28 kHz , followed by 96 pulses at $423.75 \mathrm{kHz}\left(f_{C} / 32\right)$ and 108 pulses at 484.28 kHz ( $f_{C} / 28$ ), as shown in Figure 46.
Bit coding using two subcarriers is not supported for the Fast commands.
Figure 46. End of frame, low data rate, two subcarriers


## 13 Unique identifier (UID)

The M24LR16E-R is uniquely identified by a 64-bit unique identifier (UID). This UID complies with ISO/IEC 15963 and ISO/IEC 7816-6. The UID is a read-only code and comprises:

- eight MSBs with a value of EOh,
- the IC manufacturer code "ST 02h" on 8 bits (ISO/IEC 7816-6/AM1),
- a unique serial number on 48 bits.

Table 21. UID format

| MSB |  |  |  | LSB |  |
| :--- | ---: | :--- | :--- | :--- | :--- |
| 63 | 56 | 55 | 48 | 47 | 0 |
|  | $0 \times E 0$ |  | $0 \times 02$ |  | Unique serial number |

With the UID, each M24LR16E-R can be addressed uniquely and individually during the anticollision loop and for one-to-one exchanges between a VCD and an M24LR16E-R.

## 14 Application family identifier (AFI)

The AFI (application family identifier) represents the type of application targeted by the VCD and is used to identify, among all the M24LR16E-Rs present, only the M24LR16E-Rs that meet the required application criteria.

Figure 47. M24LR16E-R decision tree for AFI


The AFI is programmed by the M24LR16E-R issuer (or purchaser) in the AFI register. Once programmed and locked, it can no longer be modified.

The most significant nibble of the AFI is used to code one specific or all application families.
The least significant nibble of the AFI is used to code one specific or all application subfamilies. Subfamily codes different from 0 are proprietary.
(See ISO 15693-3 documentation.)

## 15 Data storage format identifier (DSFID)

The data storage format identifier indicates how the data is structured in the M24LR16E-R memory. The logical organization of data can be known instantly using the DSFID. It can be programmed and locked using the Write DSFID and Lock DSFID commands.

### 15.1 CRC

The CRC used in the M24LR16E-R is calculated as per the definition in ISO/IEC 13239. The initial register contents are all ones: "FFFF".

The two-byte CRC is appended to each request and response, within each frame, before the EOF. The CRC is calculated on all the bytes after the SOF up to the CRC field.
Upon reception of a request from the VCD, the M24LR16E-R verifies that the CRC value is valid. If it is invalid, the M24LR16E-R discards the frame and does not answer to the VCD.

Upon reception of a response from the M24LR16E-R, it is recommended that the VCD verifies whether the CRC value is valid. If it is invalid, actions to be performed are left to the discretion of the VCD designer.
The CRC is transmitted least significant byte first. Each byte is transmitted least significant bit first.

Table 22. CRC transmission rules

| LSByte <br> LSBit MSBit | MSByte <br> LSBit MSBit |
| :---: | :---: |
| CRC 16 (8 bits) | CRC 16 (8 bits) |

## 16 M24LR16E-R protocol description

The transmission protocol (or simply "the protocol") defines the mechanism used to exchange instructions and data between the VCD and the M24LR16E-R in both directions. It is based on the concept of "VCD talks first".

This means that an M24LR16E-R does not start transmitting unless it has received and properly decoded an instruction sent by the VCD. The protocol is based on an exchange of:

- a request from the VCD to the M24LR16E-R,
- a response from the M24LR16E-R to the VCD.

Each request and each response are contained in a frame. The frame delimiters (SOF, EOF) are described in Section 12.

Each request consists of:

- a request SOF (see Figure 20 and Figure 21),
- flags,
- a command code,
- parameters depending on the command,
- application data,
- a 2-byte CRC,
- a request EOF (see Figure 22).

Each response consists of:

- an answer SOF (see Figure 35 to Figure 40),
- flags,
- parameters depending on the command,
- application data,
- a 2-byte CRC,
- an answer EOF (see Figure 41 to Figure 46).

The protocol is bit-oriented. The number of bits transmitted in a frame is a multiple of eight (8), that is an integer number of bytes.

A single-byte field is transmitted least significant bit (LSBit) first. A multiple-byte field is transmitted least significant byte (LSByte) first and each byte is transmitted least significant bit (LSBit) first.

The setting of the flags indicates the presence of the optional fields. When the flag is set (to one), the field is present. When the flag is reset (to zero), the field is absent.

Table 23. VCD request frame format

| Request SOF | Request_flags | Command <br> code | Parameters | Data | 2-byte CRC | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Table 24. M24LR16E-R Response frame format

| Response <br> SOF | Response_flags | Parameters | Data | 2-byte CRC | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |

Figure 48. M24LR16E-R protocol timing

| VCD | Request frame (Table 23) |  | $\begin{aligned} & \text { Request } \\ & \text { frame } \\ & \text { (Table 23) } \end{aligned}$ |  |
| :---: | :---: | :---: | :---: | :---: |
| M24LR16E-R |  | Response frame (Table 23) |  | Response frame (Table 23) |
| timing |  |  |  |  |

## 17 M24LR16E-R states

An M24LR16E-R can be in one of four states:

- Power-off
- Ready
- Quiet
- Selected

Transitions between these states are specified in Figure 49 and Table 25.

### 17.1 Power-off state

The M24LR16E-R is in the Power-off state when it does not receive enough energy from the VCD.

### 17.2 Ready state

The M24LR16E-R is in the Ready state when it receives enough energy from the VCD. When in the Ready state, the M24LR16E-R answers any request where the Select_flag is not set.

### 17.3 Quiet state

When in the Quiet state, the M24LR16E-R answers any request except for Inventory requests with the Address_flag set.

### 17.4 Selected state

 In the Selected state, the M24LR16E-R answers any request in all modes (see Section 18):- Request in Select mode with the Select_flag set
- Request in Addressed mode if the UID matches
- Request in Non-Addressed mode as it is the mode for general requests

Table 25. M24LR16E-R response depending on Request_flags

| Flags | Address_flag |  | Select_flag |  |
| :--- | :---: | :---: | :---: | :---: |
|  | 1 <br> Addressed | 0 <br> Non addressed | 1 <br> Selected | 0 <br> Non selected |
| M24LR16E-R in Ready or <br> Selected state (Devices in Quiet <br> state do not answer) | - | X | - | X |
| M24LR16E-R in Selected state | - | X | X | - |
| M24LR16E-R in Ready, Quiet or <br> Selected state (the device which <br> matches the UID) | X | - | - | X |
| Error (03h) | X | - | X | - |

Figure 49. M24LR16E-R state transition diagram


1. The M24LR16E-R returns to the Power Off state if the tag is out of the RF field for at least $t_{R F}$ _OfF. Please refer to application note AN4125 for more information.
2. The intention of the state transition method is that only one M24LR16E-R should be in the Selected state at a time.

## 18 Modes

The term "mode" refers to the mechanism used in a request to specify the set of M24LR16E-Rs that answers the request.

### 18.1 Addressed mode

When the Address_flag is set to 1 (Addressed mode), the request contains the Unique ID (UID) of the addressed M24LR16E-R.

Any M24LR16E-R that receives a request with the Address_flag set to 1 compares the received Unique ID to its own. If it matches, then the M24LR16E-R executes the request (if possible) and returns a response to the VCD as specified in the command description.
If the UID does not match, then it remains silent.

### 18.2 Non-addressed mode (general request)

When the Address_flag is cleared to 0 (Non-Addressed mode), the request does not contain a Unique ID. Any M 24 LR16E-R receiving a request with the Address_flag cleared to 0 executes it and returns a response to the VCD as specified in the command description.

### 18.3 Select mode

When the Select_flag is set to 1 (Select mode), the request does not contain an M24LR16ER Unique ID. The M24LR16E-R in the Selected state that receives a request with the Select_flag set to 1 executes it and returns a response to the VCD as specified in the command description.
Only M24LR16E-Rs in the Selected state answer a request where the Select_flag set to 1 .
The system design ensures in theory that only one M24LR16E-R can be in the Select state at a time.

## 19 Request format

The request consists of:

- an SOF,
- flags,
- a command code,
- parameters and data,
- a CRC,
- an EOF.

Table 26. General request format

| S |  |  |  |  | E |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| O | Request_flags | Command code | Parameters | Data | CRC | O |
| F |  |  |  | F |  |  |

### 19.1 Request flags

In a request, the "flags" field specifies the actions to be performed by the M24LR16E-R and whether corresponding fields are present or not.

The flags field consists of eight bits. Bit 3 (Inventory_flag) of the request flag defines the contents of the four MSBs (bits 5 to 8 ). When bit 3 is reset ( 0 ), bits 5 to 8 define the M24LR16E-R selection criteria. When bit 3 is set (1), bits 5 to 8 define the M24LR16E-R Inventory parameters.

Table 27. Definition of request flags 1 to 4

| Bit No | Flag | Level | Description |
| :--- | :--- | :---: | :--- |
| Bit 1 | Subcarrier_flag ${ }^{(1)}$ |  | 0 |
|  |  | 1 | A single subcarrier frequency is used by the <br> M24LR16E-R |
| Bit 2 | Data_rate_flag $^{(2)}$ | 0 | Low data rate is used |
|  |  | 1 | High data rate is used |
| Bit 3 | Inventory_flag | 0 | The meaning of flags 5 to 8 is described in Table 28 |
|  | Protocol_extension_flag ${ }^{(3)}$ | 0 | No Protocol format extension |
|  |  | 1 | Protocol format extension |

1. Subcarrier_flag refers to the M24LR16E-R-to-VCD communication.
2. Data_rate_flag refers to the M24LR16E-R-to-VCD communication.
3. Protocol_extension flag must be set to 1 for commands: Read Single Block, Read Multiple Block, Fast Read Mūltiple Block, Write Single Block, Get Multiple Block Security Status. Command Get System Info supports two options: a standard response format when Protocol_extension_flag is set to 0, and a rich response when protocol extension is set to 1.

Table 28. Request flags 5 to 8 when Bit $3=0$

| Bit No | Flag | Level | Description |
| :---: | :---: | :---: | :--- |
| Bit 5 | Select flag ${ }^{(1)}$ | 0 | Request is executed by any M24LR16E-R according to the setting <br> of Address_flag |
|  |  | 1 | Request is executed only by the M24LR16E-R in Selected state |
| Bit 6 | Address flag ${ }^{(1)}$ | 0 | Request is not addressed. UID field is not present. The request is <br> executed by all M24LR16E-Rs. |
|  |  | Request is addressed. UID field is present. The request is <br> executed only by the M24LR16E-R whose UID matches the UID <br> specified in the request. |  |
| Bit 7 | Option flag | 0 | Option not activated. |
|  |  | 1 | Option activated. |
| Bit 8 | RFU | 0 | - |

1. If the Select_flag is set to 1 , the Address_flag is set to 0 and the UID field is not present in the request.

Table 29. Request flags 5 to 8 when Bit $3=1$

| Bit No | Flag | Level | Description |
| :---: | :---: | :---: | :--- |
| Bit 5 | AFI flag | 0 | AFI field is not present |
|  |  | 1 | AFl field is present |
| Bit 6 | Nb_slots flag | 0 | 16 slots |
|  |  | 1 | 1 slot |
| Bit 7 | Option flag | 0 | - |
| Bit 8 | RFU | 0 | - |

## 20 Response format

The response consists of:

- an SOF,
- flags,
- parameters and data,
- a CRC,
- an EOF.

Table 30. General response format

| S | Response_flags | Parameters | Data | CRC | E |
| :--- | :--- | :--- | :--- | :--- | :--- |
| O |  |  |  |  |  |
| F |  |  |  |  |  |

### 20.1 Response flags

In a response, the flags indicate how actions have been performed by the M24LR16E-R and whether corresponding fields are present or not. The response flags consist of eight bits.

Table 31. Definitions of response flags 1 to 8

| Bit No | Flag | Level | Description |
| :--- | :--- | :---: | :--- |
| Bit 1 | Error_flag | 0 | No error |
|  |  | 1 | Error detected. Error code is in the "Error" field. |
| Bit 2 | RFU | 0 | - |
| Bit 3 | RFU | 0 | - |
| Bit 4 | Extension flag | 0 | No extension |
| Bit 5 | RFU | 0 | - |
| Bit 6 | RFU | 0 | - |
| Bit 7 | RFU | 0 | - |
| Bit 8 | RFU | 0 | - |

### 20.2 Response error code

If the Error_flag is set by the M24LR16E-R in the response, the Error code field is present and provides information about the error that occurred.

Error codes not specified in Table 32 are reserved for future use.
Table 32. Response error code definition

| Error code |  |
| :---: | :--- |
| 03 h | The option is not supported. |
| 0 Fh | Error with no information given. |
| 10 h | The specified block is not available. |
| 11 h | The specified block is already locked and thus cannot be locked again. |
| 12 h | The specified block is locked and its contents cannot be changed. |
| 13 h | The specified block was not successfully programmed. |
| 14 h | The specified block was not successfully locked. |
| 15 h | The specified block is read-protected. |

## 21 Anticollision

The purpose of the anticollision sequence is to inventory the M24LR16E-Rs present in the VCD field using their unique ID (UID).

The VCD is the master of communications with one or several M24LR16E-Rs. It initiates M24LR16E-R communication by issuing the Inventory request.

The M24LR16E-R sends its response in the determined slot or does not respond.

### 21.1 Request parameters

When issuing the Inventory Command, the VCD:

- sets the Nb_slots_flag as desired,
- adds the mask length and the mask value after the command field.
- The mask length is the number of significant bits of the mask value.
- The mask value is contained in an integer number of bytes. The mask length indicates the number of significant bits. LSB is transmitted first.
- If the mask length is not a multiple of 8 (bits), as many 0 -bits as required are added to the mask value MSB so that the mask value is contained in an integer number of bytes.
- The next field starts at the next byte boundary.

Table 33. Inventory request format
MSB

| SOF | Request_ <br> flags | Command | Optional <br> AFI | Mask <br> length | Mask value | CRC | EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 8 bits | 8 bits | 0 to 8 bytes | 16 bits | - |

In the example provided in Table 34 and Figure 50, the mask length is 11 bits. Five 0-bits are added to the mask value MSB. The 11-bit mask and the current slot number are compared to the UID.

Table 34. Example of the addition of 0 -bits to an 11-bit mask value

| $\mathbf{( \mathbf { b } _ { \mathbf { 1 5 } } ) \text { MSB }}$ | LSB $\left(\mathbf{b}_{\mathbf{0}}\right)$ |
| :---: | :---: |
| 00000 | 10011001111 |
| 0-bits added | 11-bit mask value |

Figure 50. Principle of comparison between the mask, the slot number and the UID

| Mask value received in the Inventory command |  | MSB LSB <br> 00000 0100 <br> 1100 1111 | 16 bits |
| :---: | :---: | :---: | :---: |
| The Mask value less the padding $0 s$ is loaded into the Tag comparator |  |  | 11 bits |
| The Slot counter is calculated Nb_slots_flags $=0$ ( 16 slots), Slot Counter is 4 bits |  | $\begin{gathered} \text { MSBLSB } \\ \mathrm{xxxx} \end{gathered}$ | 4 bits |
| The Slot counter is concatened to the Mask value$\mathrm{Nb} \text { _slots_flags }=0$ |  |  | 15 bits |
|  | b63 UID |  |  |
| The concatenated result is compared with the least significant bits of the Tag UID. |  |  | 64 bits |
|  |  |  | Al06682 |

The AFI field is present if the AFI_flag is set.
The pulse is generated according to the definition of the EOF in ISO/IEC 15693-2.
The first slot starts immediately after the request EOF is received. To switch to the next slot, the VCD sends an EOF.

The following rules and restrictions apply:

- If no M24LR16E-R answer is detected, the VCD may switch to the next slot by sending an EOF.
- If one or more M24LR16E-R answers are detected, the VCD waits until the complete frame has been received before sending an EOF for switching to the next slot.


## 22 Request processing by the M24LR16E-R

Upon reception of a valid request, the M24LR16E-R performs the following algorithm:

- $\quad \mathrm{NbS}$ is the total number of slots (1 or 16)
- $\quad \mathrm{SN}$ is the current slot number ( 0 to 15 )
- LSB (value, $n$ ) function returns the $n$ Less Significant Bits of value
- MSB (value, $n$ ) function returns the n Most Significant Bits of value
- " $\&$ " is the concatenation operator
- Slot_Frame is either an SOF or an EOF

```
SN = 0
if (Nb_slots_flag)
    then NbS = 1
            SN_length = 0
            endif
    else NbS = 16
            SN_length = 4
            endif
label1:
if LSB(UID, SN_length + Mask_length) =
    LSB (SN, SN_length) &LSB (Mask,Mask_length)
    then answer to inventory request
                endif
wait (Slot_Frame)
if Slot_Frame = SOF
    then Stop Anticollision
            decode/process request
            exit
            endif
if Slot_Frame = EOF
    if SN < NbS-1
        then SN = SN + 1
            goto label1
            exit
            endif
    endif
```


## 23 Explanation of the possible cases

Figure 51 summarizes the main possible cases that can occur during an anticollision sequence when the number of slots is 16 .

The sequence of steps is as follows:

- The VCD sends an Inventory request, in a frame terminated by an EOF. The number of slots is 16.
- M24LR16E-R_1 transmits its response in Slot 0. It is the only one to do so, therefore no collision occurs and its UID is received and registered by the VCD.
- The VCD sends an EOF in order to switch to the next slot.
- In Slot 1, two M24LR16E-Rs, M24LR16E-R_2 and M24LR16E-R_3 transmit a response, thus generating a collision. The VCD records the event and registers that a collision was detected in Slot 1.
- The VCD sends an EOF in order to switch to the next slot.
- In Slot 2, no M24LR16E-R transmits a response. Therefore the VCD does not detect any M24LR16E-R SOF and switches to the next slot by sending an EOF.
- In Slot 3, another collision occurs due to responses from M24LR16E-R_4 and M24LR16E-R_5.
- The VCD sends a request (for instance a Read Block) to M24LR16E-R_1 whose UID has already been correctly received.
- All M24LR16E-Rs detect an SOF and exit the anticollision sequence. They process this request and since the request is addressed to M24LR16E-R_1, only M24LR16E-R_1 transmits a response.
- All M24LR16E-Rs are ready to receive another request. If it is an Inventory command, the slot numbering sequence restarts from 0 .

Note: $\quad$ The decision to interrupt the anticollision sequence is made by the VCD. It could have continued to send EOFs until Slot 16 and only then sent the request to M24LR16E-R_1.

Figure 51. Description of a possible anticollision sequence


## 24 Inventory Initiated command

The M24LR16E-R provides a special feature to improve the inventory time response of moving tags using the Initiate_flag value. This flag, controlled by the Initiate command, allows tags to answer to Inventory Initiated commands.

For applications in which multiple tags are moving in front of a reader, it is possible to miss tags using the standard inventory command. The reason is that the inventory sequence has to be performed on a global tree search. For example, a tag with a particular UID value may have to wait the run of a long tree search before being inventoried. If the delay is too long, the tag may be out of the field before it has been detected.

Using the Initiate command, the inventory sequence is optimized. When multiple tags are moving in front of a reader, the ones which are within the reader field are initiated by the Initiate command. In this case, a small batch of tags answers to the Inventory Initiated command, which optimizes the time necessary to identify all the tags. When finished, the reader has to issue a new Initiate command in order to initiate a new small batch of tags which are new inside the reader field.

It is also possible to reduce the inventory sequence time using the Fast Initiate and Fast Inventory Initiated commands. These commands allow the M24LR16E-Rs to increase their response data rate by a factor of 2 , up to $53 \mathrm{Kbit} / \mathrm{s}$.

## 25 Timing definition

## $25.1 \quad \mathrm{t}_{1}$ : M24LR16E-R response delay

Upon detection of the rising edge of the EOF received from the VCD, the M24LR16E-R waits for a time $t_{1 \text { nom }}$ before transmitting its response to a VCD request or switching to the next slot during an inventory process. Values of $t_{1}$ are given in Table 35. The EOF is defined in Figure 22.

## $25.2 \quad t_{2}$ : VCD new request delay

$t_{2}$ is the time after which the VCD may send an EOF to switch to the next slot when one or more M24LR16E-R responses have been received during an Inventory command. It starts from the reception of the EOF from the M24LR16E-Rs.

The EOF sent by the VCD may be either $10 \%$ or $100 \%$ modulated regardless of the modulation index used for transmitting the VCD request to the M24LR16E-R.
$t_{2}$ is also the time after which the VCD may send a new request to the M24LR16E-R, as described in Figure 48.

Values of $\mathrm{t}_{2}$ are given in Table 35.

## $25.3 \quad t_{3}$ : VCD new request delay when no response is received from the M24LR16E-R

$t_{3}$ is the time after which the VCD may send an EOF to switch to the next slot when no M24LR16E-R response has been received.

The EOF sent by the VCD may be either $10 \%$ or $100 \%$ modulated regardless of the modulation index used for transmitting the VCD request to the M24LR16E-R.

From the time the VCD has generated the rising edge of an EOF:

- If this EOF is $100 \%$ modulated, the VCD waits for a time at least equal to $t_{3 \min }$ before sending a new EOF.
- If this EOF is $10 \%$ modulated, the VCD waits for a time at least equal to the sum of $t_{3 \text { min }}+$ the M24LR16E-R nominal response time (which depends on the M24LR16E-R data rate and subcarrier modulation mode) before sending a new EOF.

Table 35. Timing values ${ }^{(1)}$

|  | Minimum (min) values | Nominal (nom) values | Maximum (max) values |
| :---: | :---: | :---: | :---: |
| $\mathrm{t}_{1}$ | $318.6 \mu \mathrm{~s}$ | $320.9 \mu \mathrm{~s}$ | $323.3 \mu \mathrm{~s}$ |
| $\mathrm{t}_{2}$ | $309.2 \mu \mathrm{~s}$ | No $\mathrm{t}_{\text {nom }}$ | No $_{\text {max }}$ |
| $\mathrm{t}_{3}$ | $\mathrm{t}_{\text {max }^{\text {max }}}{ }^{(2)}+\mathrm{t}_{\text {SOF }^{(3)}}$ | No $_{\text {nom }}$ | No $_{\text {max }}$ |

1. The tolerance of specific timings is $\pm 32 / \mathrm{fC}$.
2. $\mathrm{t}_{1 \text { max }}$ does not apply for write-alike requests. Timing conditions for write-alike requests are defined in the command description.
3. $\mathrm{t}_{\text {SOF }}$ is the time taken by the M24LR16E-R to transmit an SOF to the VCD. $\mathrm{t}_{\text {SOF }}$ depends on the current data rate: High data rate or Low data rate.

## 26 Command codes

The M24LR16E-R supports the commands described in this section. Their codes are given in Table 36.

Table 36. Command codes

| Command code <br> standard | Function |
| :---: | :--- |
| 01 h | Inventory |
| 02 h | Stay Quiet |
| 20 h | Read Single Block |
| 21 h | Write Single Block |
| 23 h | Read Multiple Block |
| 25 h | Select |
| 26 h | Reset to Ready |
| 27 h | Write AFI |
| 28 h | Lock AFI |
| 29 h | Write DSFID |
| 2 hh | Lock DSFID |
| 2 Bh | Get System Info |


| Command code <br> custom | Function |
| :---: | :--- |
| 2 Ch | Get Multiple Block Security <br> Status |
| B1h | Write-sector Password |
| B2h | Lock-sector |
| B3h | Present-sector Password |
| C0h | Fast Read Single Block |
| C1h | Fast Inventory Initiated |
| C2h | Fast Initiate |
| C3h | Fast Read Multiple Block |
| D1h | Inventory Initiated |
| D2h | Initiate |
| A0h | ReadCfg |
| A1h | WriteEHCfg |
| A2h | SetRstEHEn |
| A3h | CheckEHEn |
| A4h | WriteDOCfg |

### 26.1 Inventory

When receiving the Inventory request, the M24LR16E-R runs the anticollision sequence. The Inventory_flag is set to 1 . The meaning of flags 5 to 8 is shown in Table 29.

The request contains:

- the flags,
- the Inventory command code (see Table 36),
- the AFI if the AFI flag is set,
- the mask length,
- the mask value,
- the CRC.

The M24LR16E-R does not generate any answer in case of error.
Table 37. Inventory request format

| Request <br> SOF | Request_flag <br> $\mathbf{s}$ | Inventory | Optional <br> AFI | Mask <br> length | Mask <br> value | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 01 h | 8 bits | 8 bits | $0-64$ bits | 16 bits | - |

The response contains:

- the flags,
- the Unique ID.

Table 38. Inventory response format

| Response <br> SOF | Response_ <br> flags | DSFID | UID | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 64 bits | 16 bits | - |

During an Inventory process, if the VCD does not receive an RF M24LR16E-R response, it waits for a time $t_{3}$ before sending an EOF to switch to the next slot. $t_{3}$ starts from the rising edge of the request EOF sent by the VCD.

- If the VCD sends a $100 \%$ modulated EOF, the minimum value of $t_{3}$ is:
$\mathrm{t}_{3} \mathrm{~min}=4384 / \mathrm{f}_{\mathrm{C}}(323.3 \mu \mathrm{~s})+\mathrm{t}_{\text {SOF }}$
- If the VCD sends a $10 \%$ modulated EOF, the minimum value of $t_{3}$ is:

$$
\mathrm{t}_{3} \min =4384 / \mathrm{f}_{\mathrm{C}}(323.3 \mu \mathrm{~s})+\mathrm{t}_{\mathrm{NRT}}
$$

where:

- $\quad t_{\text {SOF }}$ is the time required by the M24LR16E-R to transmit an SOF to the VCD,
- $\quad t_{N R T}$ is the nominal response time of the M24LR16E-R.
$\mathrm{t}_{\text {NRT }}$ and $\mathrm{t}_{\text {SOF }}$ are dependent on the M24LR16E-R-to-VCD data rate and subcarrier modulation mode.

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF starting the inventory command to the end of the M24LR16E-R response. If the M24LR16ER does not receive the corresponding slot marker, the RF WIP/BUSY pin remains at 0 until the next RF power-off.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

Figure 52. M24LR16 RF-Busy management following Inventory command

1) M24LR16 replies in slot n. RF_Busy is released after M24LR16 response.


RF_Busy
2) Slot n never occurs. RF_Busy is only released by Power-off.


RF_Busy
3) VCD sends a Valid command before slot n. RF_Busy is released after M24LR16 response.

Slot 1


RF_Busy
4) VCD sends a Bad command before slot n. RF_Busy is released after VCD command.

Slot 1


RF_Busy


### 26.2 Stay Quiet

Command code $=0 \times 02$
On receiving the Stay Quiet command, the M24LR16E-R enters the Quiet State if no error occurs, and does NOT send back a response. There is NO response to the Stay Quiet command even if an error occurs.

When in the Quiet state

- the M24LR16E-R does not process any request if the Inventory_flag is set,
- the M24LR16E-R processes any Addressed request.

The M24LR16E-R exits the Quiet State when:

- it is reset (power off),
- receiving a Select request. It then goes to the Selected state,
- receiving a Reset to Ready request. It then goes to the Ready state.

Table 39. Stay Quiet request format

| Request <br> SOF | Request flags | Stay Quiet | UID | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 02 h | 64 bits | 16 bits | - |

The Stay Quiet command must always be executed in Addressed mode (Select_flag is reset to 0 and Address_flag is set to 1 ).

Figure 53. Stay Quiet frame exchange between VCD and M24LR16E-R
$\square$

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 during the Stay Quiet command.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.3 Read Single Block

On receiving the Read Single Block command, the M24LR16E-R reads the requested block and sends back its 32 -bit value in the response. The Protocol_extension_flag should be set to 1 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 0 , the M24LR16E-R answers with an error code. The Option_flag is supported.

Table 40. Read Single Block request format

| Request <br> SOF | Request_ <br> flags | Read Single <br> Block | UID ${ }^{(1)}$ | Block <br> number | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 20 h | 64 bits | 16 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flags
- UID (optional)
- Block number

Table 41. Read Single Block response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | Sector <br> security <br> status <br> $(1)$ | Data | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 32 bits | 16 bits | - |

1. Gray means that the field is optional.

Response parameters:

- $\quad$ Sector security status if Option_flag is set (see Table 42)
- Four bytes of block data

Table 42. Sector security status

| $b_{7} \quad b_{6} \quad b_{5}$ | $b_{4} \quad b_{3}$ | $b_{2}$ | $b_{1}$ | $b_{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Reserved for future <br> use. All at 0. | Password <br> control bits | Read / Write <br> protection bits | 0 : Current sector not locked <br> $1:$ Current sector locked |  |

Table 43. Read Single Block response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set
- $\quad$ 10h: the specified block is not available
- 15 h : the specified block is read-protected

Figure 54. Read Single Block frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Read Single Block command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.4 Write Single Block

On receiving the Write Single Block command, the M24LR16E-R writes the data contained in the request to the requested block and reports whether the write operation was successful in the response. The Protocol_extension_flag should be set to 1 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 0, the M24LR16E-R answers with an error code. The Option_flag is supported.

During the RF write cycle $W_{t}$, there should be no modulation (neither 100\% nor 10\%), otherwise, the M24LR16E-R may not program correctly the data into the memory. The $\mathrm{W}_{\mathrm{t}}$ time is equal to $t_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$.

Table 44. Write Single Block request format

| Request <br> SOF | Request_ <br> flags | Write <br> Single <br> Block | UID ${ }^{(1)}$ | Block <br> number | Data | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 21 h | 64 bits | 16 bits | 32 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flags
- UID (optional)
- Block number
- Data

Table 45. Write Single Block response format when Error_flag is NOT set

| Response SOF | Response_flags | CRC16 | Response EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter. The response is send back after the writing cycle.

Table 46. Write Single Block response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 0Fh: error with no information given
- 10 h : the specified block is not available
- $\quad 12 \mathrm{~h}$ : the specified block is locked and its contents cannot be changed
- 13h: the specified block was not successfully programmed

Figure 55. Write Single Block frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Write Single Block command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the duration of the internal write cycle (from the end of a valid write single block command to the beginning of the M24LR16E-R response).

Figure 56. M24LR16 RF-Busy management following Write command

1) M24LR16 replies. RF_Busy is released after M24LR16 response.


RF_Busy $\qquad$
2) M24LR16 replies when option flag is set. RF_Busy is released after M24LR16 response.


RF_Busy $\qquad$
3) VCD sends a forbidden Write (sector lock, password-protected). RF_Busy is released after M24LR16 command.


RF_Busy $\qquad$

When configuring in the RF Write in progress mode, the RF WIP/BUSY pin is tied to 0 during the Write \& verify sequence, as shown in Figure 57.

Figure 57. M24LR16 RF-Wip management following Write command

1) M24LR16 replies. RF_Wip is released after M24LR16 response.


RF_Wip
2) M24LR16 replies when option flag is set. RF_Wip is released after M24LR16 response.


RF_Wip

3) VCD sends a forbidden Write (sector lock, password-protected). RF_Wip is released after M24LR16 command.


RF_Wip

### 26.5 Read Multiple Block

When receiving the Read Multiple Block command, the M24LR16E-R reads the selected blocks and sends back their value in multiples of 32 bits in the response. The blocks are numbered from 00 h to 1 FFh in the request and the value is minus one $(-1)$ in the field. For example, if the "Number of blocks" field contains the value 06h, seven blocks are read. The maximum number of blocks is fixed at 32 assuming that they are all located in the same sector. If the number of blocks overlaps sectors, the M24LR16E-R returns an error code.

The Protocol_extension_flag should be set to 1 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 0 , the M24LR16E-R answers with an error code. The Option_flag is supported.

Table 47. Read Multiple Block request format

| Request <br> SOF | Request__ <br> flags | Read <br> Multiple <br> Block | UID(1) | First <br> block <br> number | Number <br> of blocks | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 23 h | 64 bits | 16 bits | 8 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flags
- UID (optional)
- First block number
- Number of blocks

Table 48. Read Multiple Block response format when Error_flag is NOT set

| Response <br> SOF | Response_ <br> flags | Sector <br> security <br> status | Data | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits $^{(2)}$ | 32 bits $^{(2)}$ | 16 bits | - |

1. Gray means that the field is optional.
2. Repeated as needed.

Response parameters:

- Sector security status if Option_flag is set (see Table 49)
- N blocks of data

Table 49. Sector security status

| $b_{7} \quad b_{6} \quad b_{5}$ | $b_{4} \quad b_{3}$ | $b_{2} \quad b_{1}$ | $b_{0}$ |
| :---: | :---: | :---: | :---: | :--- | :--- |
| Reserved for future <br> use. All at 0. | Password <br> control bits | Read / Write <br> protection bits | 0 : Current sector not locked <br> $1:$ Current sector locked |

Table 50. Read Multiple Block response format when Error_flag is set

| Response SOF | Response_flags | Error code | CRC16 | Response EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 0Fh: error with no information given
- 10h: the specified block is not available
- 15 h : the specified block is read-protected

Figure 58. Read Multiple Block frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Read Multiple Block command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.6 Select

When receiving the Select command:

- If the UID is equal to its own UID, the M24LR16E-R enters or stays in the Selected state and sends a response.
- If the UID does not match its own, the selected M24LR16E-R returns to the Ready state and does not send a response.

The M24LR16E-R answers an error code only if the UID is equal to its own UID. If not, no response is generated. If an error occurs, the M24LR16E-R remains in its current state.

Table 51. Select request format

| Request <br> SOF | Request_ <br> flags | Select | UID | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 25 h | 64 bits | 16 bits | - |

Request parameter:

- UID

Table 52. Select Block response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter

Table 53. Select response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 03h: the option is not supported

Figure 59. Select frame exchange between VCD and M24LR16E-R
$\square$

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Select command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.7 Reset to Ready

On receiving a Reset to Ready command, the M24LR16E-R returns to the Ready state if no error occurs. In the Addressed mode, the M24LR16E-R answers an error code only if the UID is equal to its own UID. If not, no response is generated.

Table 54. Reset to Ready request format

| Request <br> SOF | Request_ <br> flags | Reset to <br> Ready | UID(1) | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 26 h | 64 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameter:

- UID (optional)

Table 55. Reset to Ready response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter

Table 56. Reset to ready response format when Error_flag is set

| Response <br> SOF | Response_flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 03h: the option is not supported

Figure 60. Reset to Ready frame exchange between VCD and M24LR16E-R
$\square$

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Reset to ready command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.8 Write AFI

On receiving the Write AFI request, the M24LR16E-R programs the 8-bit AFI value to its memory. The Option_flag is supported.
During the RF write cycle $W_{t}$, there should be no modulation (neither 100\% nor 10\%), otherwise, the M24LR16E-R may not write correctly the AFI value into the memory. The $\mathrm{W}_{\mathrm{t}}$ time is equal to $\mathrm{t}_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$.

Table 57. Write AFI request format

| Request <br> SOF | Request <br> flags | Write <br> AFI | UID(1) | AFI | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 27 h | 64 bits | 8 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameter:

- Request flags
- UID (optional)
- AFI

Table 58. Write AFI response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter

Table 59. Write AFI response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set
- 12h: the specified block is locked and its contents cannot be changed
- 13h: the specified block was not successfully programmed

Figure 61. Write AFI frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Write AFI command to the end of the M24LR16E-R response.
When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the duration of the internal write cycle (from the end of a valid Write AFI command to the beginning of the M24LR16E-R response).

### 26.9 Lock AFI

On receiving the Lock AFI request, the M24LR16E-R locks the AFI value permanently. The Option_flag is supported.
During the RF write cycle $W_{t}$, there should be no modulation (neither $100 \%$ nor $10 \%$ ), otherwise, the M24LR16E-R may not Lock correctly the AFI value in memory. The $\mathrm{W}_{\mathrm{t}}$ time is equal to $\mathrm{t}_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$.

Table 60. Lock AFI request format

| Request <br> SOF | Request_ <br> flags | Lock <br> AFI | UID $^{(1)}$ | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 28 h | 64 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameter:

- Request Flags
- UID (optional)

Table 61. Lock AFI response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter

Table 62. Lock AFI response format when Error_flag is set

| Response <br> SOF | Response_flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set
- $\quad 11 \mathrm{~h}$ : the specified block is already locked and thus cannot be locked again
- 14h: the specified block was not successfully locked

Figure 62. Lock AFI frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Lock AFI command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the entire duration of the internal write cycle (from the end of valid Lock AFI command to the beginning of the M24LR16E-R response).

### 26.10 Write DSFID

On receiving the Write DSFID request, the M24LR16E-R programs the 8-bit DSFID value to its memory. The Option_flag is supported.

During the RF write cycle $W_{t}$, there should be no modulation (neither 100\% nor 10\%), otherwise, the M24LR16E-R may not write correctly the DSFID value in memory. The $\mathrm{W}_{\mathrm{t}}$ time is equal to $\mathrm{t}_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$.

Table 63. Write DSFID request format

| Request <br> SOF | Request <br> flags | Write <br> DSFID | UID(1) | DSFID | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 29 h | 64 bits | 8 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameter:

- Request flags
- UID (optional)
- DSFID

Table 64. Write DSFID response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter

Table 65. Write DSFID response format when Error_flag is set

| Response <br> SOF | Response_flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set
- $\quad 12 \mathrm{~h}$ : the specified block is locked and its contents cannot be changed
- 13h: the specified block was not successfully programmed

Figure 63. Write DSFID frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Write DSFID command to the end of the M24LR16E-R response.
When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the duration of the internal write cycle (from the end of a valid Write DSFID command to beginning of the M24LR16E-R response).

### 26.11 Lock DSFID

On receiving the Lock DSFID request, the M24LR16E-R locks the DSFID value permanently. The Option_flag is supported.
During the RF write cycle $W_{t}$, there should be no modulation (neither 100\% nor 10\%), otherwise, the M24LR16E-R may not lock correctly the DSFID value in memory. The $W_{t}$ time is equal to $\mathrm{t}_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$.

Table 66. Lock DSFID request format

| Request <br> SOF | Request_ <br> flags | Lock <br> DSFID | UID(1) | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 2 Ah | 64 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameter:

- Request flags
- UID (optional)

Table 67. Lock DSFID response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter.

Table 68. Lock DSFID response format when Error_flag is set

| Response <br> SOF | Response_flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- $\quad 11 \mathrm{~h}$ : the specified block is already locked and thus cannot be locked again
- 14h: the specified block was not successfully locked

Figure 64. Lock DSFID frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Lock DSFID command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the duration of the internal write cycle (from the end of a valid Lock DSFID command to the beginning of the M24LR16E-R response).

### 26.12 Get System Info

When receiving the Get System Info command, the M24LR16E-R sends back its information data in the response. The Option_flag is not supported. The Get System Info can be issued in both Addressed and Non Addressed modes.

The Protocol_extension_flag can be set to 0 or 1. Table 70 and Table 72 show M24LR16ER response to the Get System Info command depending on the value of the Protocol_extension_flag.

Table 69. Get System Info request format

| Request <br> SOF | Request <br> flags | Get System <br> Info | UID(1) | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 2 Bh | 64 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameter:

- Request flags
- UID (optional)

Table 70. Get System Info response format when Protocol_extension_flag = 0 and Error_flag is NOT set

| Response <br> SOF | Response <br> flags | Information <br> flags | UID | DSFID | AFI | IC ref. | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | $00 h$ | $0 B h$ | 64 bits | 8 bits | 8 bits | $4 E h$ | 16 bits | - |

## Response parameters:

- Information flags set to 0Ch. DSFID, AFI and IC reference fields are present.
- UID code on 64 bits
- DSFID value
- AFI value
- M24LR16E-R IC reference: the 8 bits are significant.

Table 71. Get System Info response format when Protocol_extension_flag = 1 and Error_flag is NOT set

| Response <br> SOF | Response <br> _flags | Information <br> flags | UID | DSFID | AFI | Memory <br> size | IC <br> ref. | CRC <br> $\mathbf{1 6}$ | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 00 h | 0 Fh | 64 <br> bits | 8 bits | 8 bits | 0301 FF | 4 Eh | 16 <br> bits | - |

Response parameters:

- Information flags set to 0Fh. DSFID, AFI, Memory Size and IC reference fields are present.
- UID code on 64 bits
- DSFID value
- AFI value
- Memory size. The M24LR16E-R provides 512 blocks (01FFh) of 4 byte (03h)
- IC reference: the 8 bits are significant.

Table 72. Get System Info response format when Error_flag is set

| Response <br> SOF | Response_flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 01 h | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 03h: Option not supported

Figure 65. Get System Info frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Get System Info command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.13 Get Multiple Block Security Status

When receiving the Get Multiple Block Security Status command, the M24LR16E-R sends back the sector security status. The blocks are numbered from 00 h to 01FFh in the request and the value is minus one ( -1 ) in the field. For example, a value of ' 06 ' in the "Number of blocks" field requests to return the security status of seven blocks.
The Protocol_extension_flag should be set to 1 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 0 , the M24LR16E-R answers with an error code.

During the M24LR16E-R response, if the internal block address counter reaches 01FFh, it rolls over to 0000h and the Sector Security Status bytes for that location are sent back to the reader.

Table 73. Get Multiple Block Security Status request format

| Request <br> SOF | Request <br> flags | Multiple <br> Block <br> Security <br> Status | UID(1) | First <br> block <br> number | Number <br> of blocks | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | $2 C h$ | 64 bits | 16 bits | 16 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameter:

- Request flags
- UID (optional)
- First block number
- Number of blocks

Table 74. Get Multiple Block Security Status response format when Error_flag is NOT set

| Response <br> SOF | Response_ <br> flags | Sector security <br> status | Response <br> EOF |  |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits $^{(1)}$ | 16 bits | - |

1. Repeated as needed.

Response parameters:

- $\quad$ Sector security status (see Table 75)

Table 75. Sector security status

| $b_{7}$ | $b_{6} \quad b_{5}$ | $b_{4} \quad b_{3}$ | $b_{2}$ | $b_{1}$ | $b_{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Reserved for future use. All <br> at 0. | Password control <br> bits | Read / Write <br> protection bits | 0: Current sector not locked <br> 1: Current sector locked |  |  |

Table 76. Get Multiple Block Security Status response format when Error_flag is set

| Response <br> SOF | Response <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

## Response parameter:

- Error code as Error_flag is set:
- 03h: the option is not supported
- 10 h : the specified block is not available

Figure 66. Get Multiple Block Security Status frame exchange between VCD and M24LR16E-R

| VCDM24LR16E-R | SOF | Get Multiple Block Security Status | EOF |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | <-t $t_{1}$-> | SOF | Get Multiple Block Security Status | EOF |

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Get Multiple Block Security Status command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.14 Write-sector Password

On receiving the Write-sector Password command, the M24LR16E-R uses the data contained in the request to write the password and reports whether the operation was successful in the response. The Option_flag is supported.
During the RF write cycle time, $W_{t}$, there must be no modulation at all (neither $100 \%$ nor $10 \%$ ), otherwise, the M24LR16E-R may not correctly program the data into the memory.
The $W_{t}$ time is equal to $t_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$. After a successful write, the new value of the selected password is automatically activated. It is not required to present the new password value until M24LR16E-R power-down.

Table 77. Write-sector Password request format

| Request <br> SOF | Request <br> flags | Write- <br> sector <br> password | IC Mfg <br> Code | UID(1) | Password <br> number | Data | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | B1h | 02 h | 64 bits | 8 bits | 32 bits | 16 bits | - |

[^1]Request parameter:

- Request flags
- UID (optional)
- Password number (01h = Pswd1, 02h = Pswd2, 03h = Pswd3, other = Error $)$
- Data

Table 78. Write-sector Password response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- no parameter.

Table 79. Write-sector Password response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 10h: the password number is incorrect
- 12h: the session was not opened before the password update
- 13h: the specified block was not successfully programmed
- 0Fh: the presented password is incorrect

Figure 67. Write-sector Password frame exchange between VCD and M24LR16E-R

| VCD ${ }_{\text {M }}$ M24LR16E-R | SOF | Writesector Password request | EOF |  |  |  | Write sequence when error |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | SOF | Write-sector Password response | EOF |  |  |
| M24LR16E-R |  |  |  | --- | Wt ------------> | SOF | Writesector Password response | EOF |

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Write-sector Password command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the duration of the internal write cycle (from the end of a valid Write sector password command to the beginning of the M24LR16E-R response).

### 26.15 Lock-sector

On receiving the Lock-sector command, the M24LR16E-R sets the access rights and permanently locks the selected sector. The Option_flag is supported.
A sector is selected by giving the address of one of its blocks in the Lock-sector request (Sector number field). For example, addresses 0 to 31 are used to select sector 0 and addresses 32 to 63 are used to select sector 1 . Care must be taken when issuing the Locksector command as all the blocks belonging to the same sector are automatically locked by a single command.
The Protocol_extension_flag should be set to 1 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 0 , the M24LR16E-R answers with an error code.

During the RF write cycle $W_{t}$, there should be no modulation (neither 100\% nor 10\%), otherwise, the M24LR16E-R may not correctly lock the memory block. The $\mathrm{W}_{\mathrm{t}}$ time is equal to $\mathrm{t}_{1 \mathrm{nom}}+18 \times 302 \mu \mathrm{~s}$.

Table 80. Lock-sector request format

| Request <br> SOF | Request <br> flags | Lock- <br> sector | IC <br> Mfg <br> code | UID(1) | Sector <br> number | Sector <br> security <br> status | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | B2h | 02 h | 64 bits | 16 bits | 8 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flags
- (optional) UID
- Sector number
- $\quad$ Sector security status (refer to Table 81)

Table 81. Sector security status

| $b_{7}$ | $b_{6}$ | $b_{5}$ | $b_{4}$ | $b_{3}$ | $b_{2}$ | $b_{1}$ | $b_{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | password control bits | Read / Write protection <br> bits | 1 |  |  |

Table 82. Lock-sector response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter

Table 83. Lock-sector response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- $\quad$ 10h: the specified block is not available
- $\quad 11 \mathrm{~h}$ : the specified block is already locked and thus cannot be locked again
- $\quad 14 \mathrm{~h}$ : the specified block was not successfully locked

Figure 68. Lock-sector frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Lock-sector command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the duration of the internal write cycle (from the end of a valid Lock sector command to the beginning of the M24LR16E-R response).

### 26.16 Present-sector Password

On receiving the Present-sector Password command, the M24LR16E-R compares the requested password with the data contained in the request and reports whether the operation has been successful in the response. The Option_flag is supported.

During the comparison cycle equal to $W_{t}$, there should be no modulation (neither 100\% nor $10 \%$ ), otherwise, the M24LR16E-R the Password value may not be correctly compared. The $W_{t}$ time is equal to $t_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$.
After a successful command, the access to all the memory blocks linked to the password is changed as described in Section 4.1: M24LR16E-R block security in RF mode.

Table 84. Present-sector Password request format

| Request <br> SOF | Request <br> flags | Present- <br> sector <br> Password | IC <br> Mfg <br> code | UID(1) | Password <br> number | Password | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | B3h | 02 h | 64 bits | 8 bits | 32 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameter:

- Request flags
- UID (optional)
- Password Number (0x01 = Pswd1, 0x02 = Pswd2, 0x03 = Pswd3, other = Error)
- Password

Table 85. Present-sector Password response format when Error_flag is NOT set

| Response <br> SOF | Response_flags | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter. The response is send back after the write cycle.

Table 86. Present-sector Password response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 10h: the password number is incorrect
- OFh: the present password is incorrect

Figure 69. Present-sector Password frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Present Sector Password command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY remains in high-Z state.

### 26.17 Fast Read Single Block

On receiving the Fast Read Single Block command, the M24LR16E-R reads the requested block and sends back its 32-bit value in the response. The Option_flag is supported. The data rate of the response is multiplied by 2.
The Protocol_extension_flag should be set to 1 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 0, the M24LR16E-R answers with an error code.

The subcarrier_flag should be set to 0 , otherwise the M24LR16E-R answers with an error code.

Table 87. Fast Read Single Block request format

| Request <br> SOF | Request_ <br> flags | Fast Read <br> Single <br> Block | IC Mfg <br> code | UID(1) | Block <br> number | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | C0h | 02 h | 64 bits | 16 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flags
- UID (optional)
- Block number

Table 88. Fast Read Single Block response format when Error_flag is NOT set
$\begin{array}{|c|c|c|c|c|c|}\hline \begin{array}{c}\text { Response } \\ \text { SOF }\end{array} & \begin{array}{c}\text { Response } \\ \text { flags }\end{array} & \begin{array}{c}\text { Sector } \\ \text { security } \\ \text { status }\end{array}{ }^{(1)}\end{array} \quad$ Data $\quad$ CRC16 $\left.\begin{array}{c}\text { Response } \\ \text { EOF }\end{array}\right]$

1. Gray means that the field is optional.

Response parameters:

- $\quad$ Sector security status if Option_flag is set (see Table 89)
- Four bytes of block data

Table 89. Sector security status

| $\mathrm{b}_{7} \quad \mathrm{~b}_{6} \quad \mathrm{~b}_{5}$ | $\mathrm{b}_{4} \quad \mathrm{~b}_{3}$ | $\mathrm{b}_{2} \quad \mathrm{~b}_{1}$ | $\mathrm{b}_{0}$ |
| :---: | :---: | :---: | :---: |
| Reserved for future used. All at 0 . | Password control bits | Read / Write protection bits | 0: Current sector not locked <br> 1: Current sector locked |

Table 90. Fast Read Single Block response format when Error_flag is set

| Response <br> SOF | Response_flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 10h: the specified block is not available
- 15 h : the specified block is read protected

Figure 70. Fast Read Single Block frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Fast Read Single block command to the end of the M24LR16E-R response.
When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.18 Fast Inventory Initiated

Before receiving the Fast Inventory Initiated command, the M24LR16E-R must have received an Initiate or a Fast Initiate command in order to set the Initiate_ flag. If not, the M24LR16E-R does not answer to the Fast Inventory Initiated command.

The subcarrier_flag should be set to 0 , otherwise the M24LR16E-R answers with an error code.

On receiving the Fast Inventory Initiated request, the M24LR16E-R runs the anticollision sequence. The Inventory_flag must be set to 1 . The meaning of flags 5 to 8 is shown in Table 29. The data rate of the response is multiplied by 2.
The request contains:

- the flags,
- the Inventory command code,
- the AFI if the AFI flag is set,
- the mask length,
- the mask value,
- the CRC.

The M24LR16E-R does not generate any answer in case of error.
Table 91. Fast Inventory Initiated request format

| Request <br> SOF | Request <br> flags | Fast <br> Inventory <br> Initiated | IC Mfg <br> code | Optional <br> AFI | Mask <br> Iength | Mask value | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | C1h | 02 h | 8 bits | 8 bits | $0-64$ bits | 16 bits | - |

The Response contains:

- the flags,
- the Unique ID.

Table 92. Fast Inventory Initiated response format

| Response <br> SOF | Response <br> flags | DSFID | UID | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 64 bits | 16 bits | - |

During an Inventory process, if the VCD does not receive an RF M24LR16E-R response, it waits for a time $t_{3}$ before sending an EOF to switch to the next slot. $t_{3}$ starts from the rising edge of the request EOF sent by the VCD.

- If the VCD sends a $100 \%$ modulated EOF, the minimum value of $t_{3}$ is:
$\mathrm{t}_{3} \min =4384 / \mathrm{f}_{\mathrm{C}}(323.3 \mu \mathrm{~s})+\mathrm{t}_{\text {SOF }}$
- If the VCD sends a $10 \%$ modulated EOF, the minimum value of $\mathrm{t}_{3}$ is: $\mathrm{t}_{3} \min =4384 / \mathrm{f}_{\mathrm{C}}(323.3 \mu \mathrm{~s})+\mathrm{t}_{\text {NRT }}$
where:
- $\mathrm{t}_{\text {SOF }}$ is the time required by the M24LR16E-R to transmit an SOF to the VCD
- $\quad t_{\text {NRT }}$ is the nominal response time of the M24LR16E-R
$t_{\text {NRT }}$ and $\mathrm{t}_{\text {SOF }}$ are dependent on the M24LR16E-R-to-VCD data rate and subcarrier modulation mode.

When configured in the RF busy mode, the RF WIP/BUSY pin is driven to 0 from the SOF starting the inventory command to the end of the M24LR16E-R response.If the M24LR16ER does not receive the corresponding slot marker, the RF WIP/BUSY pin remains at 0 till the next RF power-off.
When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.19 Fast Initiate

On receiving the Fast Initiate command, the M24LR16E-R sets the internal Initiate_flag and sends back a response only if it is in the Ready state. The command has to be issued in the Non Addressed mode only (Select_flag is reset to 0 and Address_flag is reset to 0 ). If an error occurs, the M24LR16E-R does not generate any answer. The Initiate_flag is reset after a power-off of the M24LR16E-R. The data rate of the response is multiplied by 2.

The subcarrier_flag should be set to 0 , otherwise the M24LR16E-R answers with an error code.

The request contains:

- No data

Table 93. Fast Initiate request format

| Request <br> SOF | Request_flags | Fast <br> Initiate | IC Mfg <br> Code | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | C2h | 02 h | 16 bits | - |

The response contains:

- the flags,
- the Unique ID.

Table 94. Fast Initiate response format

| Response <br> SOF | Response <br> flags | DSFID | UID | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 64 bits | 16 bits | - |

Figure 71. Fast Initiate frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Fast Initiate command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.20 Fast Read Multiple Block

On receiving the Fast Read Multiple Block command, the M24LR16E-R reads the selected blocks and sends back their value in multiples of 32 bits in the response. The blocks are numbered from 00h to 1 FFh in the request and the value is minus one $(-1)$ in the field. For example, if the "Number of blocks" field contains the value 06h, seven blocks are read. The maximum number of blocks is fixed to 32 assuming that they are all located in the same sector. If the number of blocks overlaps sectors, the M24LR16E-R returns an error code.

The Protocol_extension_flag should be set to 1 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 0 , the M24LR16E-R answers with an error code.
The Option_flag is supported. The data rate of the response is multiplied by 2.
The subcarrier_flag should be set to 0 , otherwise the M24LR16E-R answers with an error code.

Table 95. Fast Read Multiple Block request format

| Request <br> SOF | Request__ <br> flags | Fast <br> Read <br> Multiple <br> Block | IC Mfg <br> code | UID(1) | First <br> block <br> number | Number <br> of <br> blocks | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | C3h | 02 h | 64 bits | 16 bits | 8 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flag
- UID (Optional)
- First block number
- Number of blocks

Table 96. Fast Read Multiple Block response format when Error_flag is NOT set

| Response <br> SOF | Response_ <br> flags | Sector <br> security <br> status $^{(1)}$ | Data | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits $^{(2)}$ | 32 bits $^{(2)}$ | 16 bits | - |

1. Gray means that the field is optional.
2. Repeated as needed.

Response parameters:

- $\quad$ Sector security status if Option_flag is set (see Table 97)
- $\quad \mathrm{N}$ block of data

Table 97. Sector security status if Option_flag is set

| $b_{7} \quad b_{6} \quad b_{5}$ | $b_{4} \quad b_{3}$ | $b_{2} \quad b_{1}$ | $b_{0}$ |
| :---: | :---: | :---: | :---: | :---: | :--- |
| Reserved for future use. <br> All at 0. | Password <br> control bits | Read / Write <br> protection bits | 0: Current sector not locked <br> 1: Current sector locked |

Table 98. Fast Read Multiple Block response format when Error_flag is set

| Response SOF | Response_flags | Error code | CRC16 | Response EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 03h: the option is not supported
- 10h: block address not available
- 15 h : block read-protected

Figure 72. Fast Read Multiple Block frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Fast Read Multiple Block command to the end of the M24LR16E-R response.
When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.21 Inventory Initiated

Before receiving the Inventory Initiated command, the M24LR16E-R must have received an Initiate or a Fast Initiate command in order to set the Initiate_flag. If not, the M24LR16E-R does not answer to the Inventory Initiated command.
On receiving the Inventory Initiated request, the M24LR16E-R runs the anticollision sequence. The Inventory_flag must be set to 1 . The meaning of flags 5 to 8 is given in Table 29.

The request contains:

- the flags,
- the Inventory Command code,
- the AFI if the AFI flag is set,
- the mask length,
- the mask value,
- the CRC.

The M24LR16E-R does not generate any answer in case of error.

Table 99. Inventory Initiated request format

| Request <br> SOF | Request <br> flags | Inventory <br> Initiated | IC <br> Mfg <br> Code | Optional <br> AFI | Mask <br> length | Mask value | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | D1h | 02 h | 8 bits | 8 bits | $0-64$ bits | 16 bits | - |

The response contains:

- the flags,
- the Unique ID.

Table 100. Inventory Initiated response format

| Response <br> SOF | Response <br> _flags | DSFID | UID | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 64 bits | 16 bits | - |

During an Inventory process, if the VCD does not receive an RF M24LR16E-R response, it waits for a time $t_{3}$ before sending an EOF to switch to the next slot. $t_{3}$ starts from the rising edge of the request EOF sent by the VCD.

- If the VCD sends a $100 \%$ modulated EOF, the minimum value of $t_{3}$ is:
$\mathrm{t}_{3} \mathrm{~min}=4384 / \mathrm{f}_{\mathrm{C}}(323.3 \mu \mathrm{~s})+\mathrm{t}_{\text {SOF }}$
- If the VCD sends a $10 \%$ modulated EOF, the minimum value of $t_{3}$ is: $\mathrm{t}_{3} \min =4384 / \mathrm{f}_{\mathrm{C}}(323.3 \mu \mathrm{~s})+\mathrm{t}_{\mathrm{NRT}}$
where:
- $\quad t_{\text {SOF }}$ is the time required by the M24LR16E-R to transmit an SOF to the VCD
- $\quad t_{\text {NRT }}$ is the nominal response time of the M24LR16E-R
$t_{\text {NRT }}$ and $t_{\text {SOF }}$ are dependent on the M24LR16E-R-to-VCD data rate and subcarrier modulation mode.

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF starting the inventory command to the end of the M24LR16E-R response. If the M24LR16ER does not receive the corresponding slot marker, the RF WIP/BUSY pin remains at 0 till the next RF power-off.
When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.22 Initiate

On receiving the Initiate command, the M24LR16E-R sets the internal Initiate_flag and sends back a response only if it is in the ready state. The command has to be issued in the Non Addressed mode only (Select_flag is reset to 0 and Address_flag is reset to 0 ). If an error occurs, the M24LR16E-R does not generate any answer. The Initiate_flag is reset after a power-off of the M24LR16E-R.

The request contains:

- No data

Table 101. Initiate request format

| Request <br> SOF | Request_flags | Initiate | IC Mfg <br> code | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | D2h | 02 h | 16 bits | - |

The response contains:

- the flags,
- the Unique ID.

Table 102. Initiate Initiated response format

| Response <br> SOF | Response <br> _flags | DSFID | UID | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 64 bits | 16 bits | - |

Figure 73. Initiate frame exchange between VCD and M24LR16E-R
$\square$

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the Initiate command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.23 ReadCfg

On receiving the ReadCfg command, the M24LR16E-R reads the Configuration byte and sends back its 8 -bit value in the response.

The Protocol_extension_flag should be set to 0 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 1, the M24LR16E-R answers with an error code. The Option_flag is not supported. The Inventory_flag must be set to 0 .

Table 103. ReadCfg request format

| Request <br> SOF | Request_ <br> flags | ReadCfg | IC Mfg code | UID $^{(1)}$ | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | A0h | 02 h | 64 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- UID (optional)

Table 104. ReadCfg response format when Error_flag is NOT set

| Response SOF | Response_flags | Data | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameters:

- One byte of data: Configuration byte

Table 105. ReadCfg response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set
- 03h: the option is not supported
- OFh: error with no information given

Figure 74. ReadCfg frame exchange between VCD and M24LR16E-R
Figure 75.


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the ReadCfg command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.24 WriteEHCfg

On receiving the WriteEHCfg command, the M24LR16E-R writes the data contained in the request to the Configuration byte and reports whether the write operation was successful in the response. The Protocol_extension_flag should be set to 0 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 1, the M24LR16E-R answers with an error code.

The Option_flag is supported, the Inventory_flag is not supported.
During the RF write cycle $W_{t}$, there should be no modulation (neither 100\% nor 10\%), otherwise, the M24LR16E-R may not program correctly the data into the Configuration byte. The $W_{t}$ time is equal to $t_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$.

Table 106. WriteEHCfg request format

| Request <br> SOF | Request_ <br> flags | WriteEHCfg | IC Mfg <br> code | UID(1) | Data | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | A1h | 02 h | 64 bits | 8 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flags
- UID (optional)
- Data: during WriteEHCfg command, bit 3 of the data is ignored (see Table 14).

Table 107. WriteEHCfg response format when Error_flag is NOT set

| Response SOF | Response_flags | CRC16 | Response EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter. The response is send back after the writing cycle.

Table 108. WriteEHCfg response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 13h: the specified block was not successfully programmed

Figure 76. WriteEHCfg frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the WriteEHCfg command to the end of the M24LR16E-R response.
When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the entire duration of the internal write cycle (from the end of a valid WriteEHCfg command to the beginning of the M24LR16E-R response).

### 26.25 WriteDOCfg

On receiving the WriteDOCfg command, the M24LR16E-R writes the data contained in the request to the Configuration byte and reports whether the write operation was successful in the response. The Protocol_extension_flag should be set to 0 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 1, the M24LR16E-R answers with an error code.

The Option_flag is supported, the Inventory_flag is not supported.
During the RF write cycle $W_{t}$, there should be no modulation (neither 100\% nor 10\%), otherwise, the M24LR16E-R may not program correctly the data into the Configuration byte. The $W_{t}$ time is equal to $t_{1 \text { nom }}+18 \times 302 \mu \mathrm{~s}$.

Table 109. WriteDOCfg request format

| Request <br> SOF | Request_ <br> flags | WriteDOCfg | IC Mfg <br> code | UID(1) | Data | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | A4h | 02 h | 64 bits | 8 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flag
- UID (optional)
- Data: during a WriteDOCfg command, bits 2 to 0 of the data are ignored (see Table 14).

Table 110. WriteDOCfg response format when Error_flag is NOT set

| Response SOF | Response_flags | CRC16 | Response EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter. The response is sent back after the writing cycle.

Table 111. WriteDOCfg response format when Error_flag is set

| Response <br> SOF | Response <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- $\quad 13 \mathrm{~h}$ : the specified block was not successfully programmed

Figure 77. WriteDOCfg frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the WriteEHCfg command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin is tied to 0 for the entire duration of the internal write cycle (from the end of a valid WriteDOCfg command to the beginning of the M24LR16E-R response).

### 26.26 SetRstEHEn

On receiving the SetRstEHEn command, the M24LR16E-R sets or resets the EH_enable bit in the volatile Control register. The Protocol_extension_flag should be set to 0 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 1, the M24LR16E-R answers with an error code. The Option_flag and the Inventory_flag are not supported.

Table 112. SetRstEHEn request format

| Request <br> SOF | Request_ <br> flags | SetRstEHEn | IC Mfg <br> code | UID(1) | Data | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | A2h | 02 h | 64 bits | 8 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- Request flags
- UID (optional)
- Data: during a SetRstEHEn command, bits 7 to 1 are ignored. Bit 0 is the EH_enable bit.

Table 113. SetRstEHEn response format when Error_flag is NOT set

| Response SOF | Response_flags | CRC16 | Response EOF |
| :---: | :---: | :---: | :---: |
| - | 8 bits | 16 bits | - |

Response parameter:

- No parameter. The response is sent back after $t_{1}$.

Table 114. SetRstEHEn response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set:
- 03h: the option is not supported

Figure 78. SetRstEHEn frame exchange between VCD and M24LR16E-R

VCD

| SOF | SetRstEHEn <br> request | EOF |
| :---: | :---: | :---: |

M24LR16E-R


WriteEHCfg sequence when error

When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the SetRstEHEn command to the end of the M24LR16E-R response.
When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

### 26.27 CheckEHEn

On receiving the CheckEHEn command, the M24LR16E-R reads the Control register and sends back its 8 -bit value in the response.

The Protocol_extension_flag should be set to 0 for the M24LR16E-R to operate correctly. If the Protocol_extension_flag is at 1, the M24LR16E-R answers with an error code. The Option_flag is not supported. The Inventory_flag must be set to 0 .

Table 115. CheckEHEn request format

| Request <br> SOF | Request_ <br> flags | CheckEHEn | IC Mfg code | UID $^{(1)}$ | CRC16 | Request <br> EOF |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | A3h | 02 h | 64 bits | 16 bits | - |

1. Gray means that the field is optional.

Request parameters:

- UID (optional)

Table 116. CheckEHEn response format when Error_flag is NOT set

| Response SOF | Response_flags | Data | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

## Response parameters:

- One byte of data: volatile Control register (see Table 15)

Table 117. CheckEHEn response format when Error_flag is set

| Response <br> SOF | Response_ <br> flags | Error code | CRC16 | Response <br> EOF |
| :---: | :---: | :---: | :---: | :---: |
| - | 8 bits | 8 bits | 16 bits | - |

Response parameter:

- Error code as Error_flag is set
- 03h: the option is not supported

Figure 79. CheckEHEn frame exchange between VCD and M24LR16E-R


When configured in the RF busy mode, the RF WIP/BUSY pin is tied to 0 from the SOF that starts the CheckEHEn command to the end of the M24LR16E-R response.

When configured in the RF write in progress mode, the RF WIP/BUSY pin remains in high-Z state.

## 27 Maximum rating

Stressing the device above the rating listed in Table 118 may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect the device reliability. Refer also to the STMicroelectronics SURE Program and other relevant quality documents.

Table 118. Absolute maximum ratings

| Symbol | Parameter |  | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{T}_{\text {A }}$ | Ambient operating temperature |  | -40 | 85 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {STG }}$, $h_{\text {STG }}$, t $_{\text {STG }}$ | Storage conditions | Sawn wafer on UV tape | 15 | 25 | ${ }^{\circ} \mathrm{C}$ |
|  |  |  | - | $9^{(1)}$ | months |
|  |  |  | kept in its original packing form |  |  |
| $\mathrm{T}_{\text {STG }}$ | Storage temperature | UFDFPN8 (MLP8), SO8, TSSOP8 | -65 | 150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {LEAD }}$ | Lead temperature during soldering | UFDFPN8 (MLP8), SO8, TSSOP8 | see note ${ }^{(2)}$ |  | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{V}_{10}$ | $\mathrm{I}_{2} \mathrm{C}$ input or output range |  | -0.50 | 6.5 | V |
| $\mathrm{V}_{\mathrm{CC}}$ | $\mathrm{I}_{2} \mathrm{C}$ supply voltage |  | -0.50 | 6.5 | V |
| IOL_MAX | DC output current on pin SDA or RF WIP/BUSY (when equal to 0) |  | - | 5 | mA |
| $\mathrm{ICC}^{(3)}$ | RF supply current AC0 - AC1 |  | - | 50 | mA |
| $\mathrm{V}_{\text {MAX_1 }}{ }^{(3)}$ | RF input voltage amplitude peak to peak between AC0 and AC1, GND pad left floating | VAC0-VAC1 | - | 27 | V |
| $\mathrm{V}_{\text {MAX_2 }}{ }^{(3)}$ | AC voltage between ACO and GND, or AC1 and GND | VACO-GND, or VAC1-GND | -1 | 11 | V |
| $V_{\text {ESD }}$ | Electrostatic discharge voltage (human body model) ${ }^{(4)}$ | AC0, AC1 | - | 1000 | V |
|  |  | Other pads | - | 3500 |  |
|  | Electrostatic discharge voltage (Machine model) |  | - | 400 |  |
|  | Electrostatic discharge voltage on antenna ${ }^{(5)}$ | AC0, AC1 | - | 4000 |  |

1. Counted from ST shipment date.
2. Compliant with JEDEC Std J-STD-020C (for small body, Sn-Pb or Pb assembly), the ST ECOPACK ${ }^{\circledR}$ 7191395 specification, and the European directive on Restrictions on Hazardous Substances (RoHS) 2002/95/EU.
3. Based on characterization, not tested in production.
4. AEC-Q100-002 (compliant with JEDEC Std JESD22-A114A, C1 $=100 \mathrm{pF}, \mathrm{R} 1=1500 \Omega \mathrm{R} 2=500 \Omega$ )
5. Compliant with IEC 61000-4-3 method. (M24LRxxE packaged in S08N is mounted on ST's reference antenna ANT1- M24LRxxE)

## 28 <br> $I^{2} C D C$ and $A C$ parameters

This section summarizes the operating and measurement conditions, and the DC and AC characteristics of the device in $I^{2} \mathrm{C}$ mode. The parameters in the DC and AC characteristic tables that follow are derived from tests performed under the measurement conditions summarized in the relevant tables. Designers should check that the operating conditions in their circuit match the measurement conditions when relying on the quoted parameters.

Table 119. $I^{2} \mathrm{C}$ operating conditions

| Symbol | Parameter | Min. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ | Supply voltage | 1.8 | 5.5 | V |
| $\mathrm{~T}_{\mathrm{A}}$ | Ambient operating temperature | -40 | 85 | ${ }^{\circ} \mathrm{C}$ |

Table 120. AC test measurement conditions

| Symbol | Parameter | Min. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{C}_{\mathrm{L}}$ | Load capacitance | 100 |  | pF |
| - | Input rise and fall times | - | 50 | ns |
| - | Input levels | $0.2 \mathrm{~V}_{\mathrm{CC}}$ to $0.8 \mathrm{~V}_{\mathrm{CC}}$ | V |  |
| - | Input and output timing reference levels | $0.3 \mathrm{~V}_{\mathrm{CC}}$ to $0.7 \mathrm{~V}_{\mathrm{CC}}$ | V |  |

Figure 80. AC test measurement I/O waveform

| Input Levels | Input and Output Timing Reference Levels |
| :---: | :---: |
|  |  |
|  | Al00825B |

Table 121. Input parameters

| Symbol | Parameter | Min. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{C}_{\mathrm{IN}}$ | Input capacitance (SDA) | - | 8 | pF |
| $\mathrm{C}_{\mathbb{I}}$ | Input capacitance (other pins) | - | 6 | pF |
| $\mathrm{t}_{\mathrm{NS}}{ }^{(1)}$ | Pulse width ignored (Input filter on SCL and SDA) | - | 80 | ns |

1. Characterized only.

Table 122. $1^{2}$ C DC characteristics

| Symbol | Parameter | Test condition | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{\mathrm{LI}}$ | Input leakage current (SCL, SDA) | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{SS}} \text { or } \mathrm{V}_{\mathrm{CC}}$ <br> device in Standby mode | - | $\pm 2$ | $\mu \mathrm{A}$ |
| ILO_Vout | Vout output leakage current | external voltage applied on Vout: Vss or Vcc | - | $\pm 5$ | $\mu \mathrm{A}$ |
| ILO | Output leakage current | SDA in Hi-Z, external voltage applied on SDA: Vss or Vcc | - | $\pm 2$ | $\mu \mathrm{A}$ |
| $I_{\text {cc }}$ | Supply current (Read) ${ }^{(1)}$ | $\begin{gathered} \mathrm{V}_{\mathrm{cC}}=1.8 \mathrm{~V}, \mathrm{f}_{\mathrm{c}}=100 \mathrm{kHz} \\ \text { (rise/fall time }<50 \mathrm{~ns} \text { ) } \end{gathered}$ | - | 50 | $\mu \mathrm{A}$ |
|  |  | $\begin{gathered} \mathrm{V}_{\mathrm{CC}}=1.8 \mathrm{~V}, \mathrm{f}_{\mathrm{c}}=400 \mathrm{kHz} \\ \text { (rise/fall time }<50 \mathrm{~ns} \text { ) } \end{gathered}$ | - | 100 |  |
|  |  | $\begin{gathered} \mathrm{V}_{\mathrm{CC}}=2.5 \mathrm{~V}, \mathrm{f}_{\mathrm{c}}=400 \mathrm{kHz} \\ \text { (rise/fall time }<50 \mathrm{~ns} \text { ) } \end{gathered}$ | - | 200 |  |
|  |  | $\begin{gathered} \mathrm{V}_{\mathrm{CC}}=5.5 \mathrm{~V}, \mathrm{f}_{\mathrm{c}}=400 \mathrm{kHz} \\ \text { (rise/fall time }<50 \mathrm{~ns} \text { ) } \end{gathered}$ | - | 400 |  |
| ICco | Supply current (Write) ${ }^{(1)}$ | $V_{C C}=1.8-5.5 \mathrm{~V}$ |  | 220 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\mathrm{CC} 1}$ | Standby supply current | $\begin{gathered} \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{SS}} \text { or } \mathrm{V}_{\mathrm{CC}} \\ \mathrm{~V}_{\mathrm{CC}}=1.8 \mathrm{~V} \end{gathered}$ | - | 30 | $\mu \mathrm{A}$ |
|  |  | $\begin{gathered} \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{SS}} \text { or } \mathrm{V}_{\mathrm{CC}} \\ \mathrm{~V}_{\mathrm{CC}}=2.5 \mathrm{~V} \end{gathered}$ | - | 30 |  |
|  |  | $\begin{gathered} \mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{SS}} \text { or } \mathrm{V}_{\mathrm{CC}} \\ \mathrm{~V}_{\mathrm{CC}}=5.5 \mathrm{~V} \end{gathered}$ | - | 100 |  |
| $\mathrm{V}_{\text {IL }}$ | Input low voltage (SDA, SCL) | $\mathrm{V}_{C C}=1.8 \mathrm{~V}$ | -0.45 | $0.25 \mathrm{~V}_{\mathrm{CC}}$ | V |
|  |  | $\mathrm{V}_{\mathrm{CC}}=2.5 \mathrm{~V}$ | -0.45 | $0.25 \mathrm{~V}_{\mathrm{CC}}$ |  |
|  |  | $\mathrm{V}_{\mathrm{CC}}=5.5 \mathrm{~V}$ | -0.45 | $0.3 \mathrm{~V}_{\mathrm{CC}}$ |  |
| $\mathrm{V}_{\mathrm{IH}}$ | Input high voltage (SDA, SCL) | $\mathrm{V}_{C C}=1.8 \mathrm{~V}$ | $0.75 \mathrm{~V}_{\text {cC }}$ | $\mathrm{V}_{\mathrm{CC}}+1$ | V |
|  |  | $\mathrm{V}_{\mathrm{CC}}=2.5 \mathrm{~V}$ | $0.75 \mathrm{~V}_{\text {CC }}$ | $\mathrm{V}_{\mathrm{CC}}+1$ |  |
|  |  | $\mathrm{V}_{\mathrm{CC}}=5.5 \mathrm{~V}$ | $0.7 \mathrm{~V}_{\mathrm{CC}}$ | $\mathrm{V}_{\mathrm{CC}}+1$ |  |
| $\mathrm{V}_{\mathrm{OL}}$ | Output low voltage | $\begin{gathered} \mathrm{I}_{\mathrm{OL}}=2.1 \mathrm{~mA}, \mathrm{~V}_{\mathrm{CC}}=1.8 \mathrm{~V} \text { or } \\ \mathrm{I}_{\mathrm{OL}}=3 \mathrm{~mA}, \mathrm{~V}_{\mathrm{CC}}=5.5 \mathrm{~V} \end{gathered}$ | - | 0.4 | V |

1. SCL, SDA connected to Ground or $\mathrm{V}_{\mathrm{CC}}$. SDA connected to $\mathrm{V}_{\mathrm{CC}}$ through a pull-up resistor.

Table 123. $I^{2} \mathrm{C}$ AC characteristics

| Test conditions specified in Table 119 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol | Alt. | Parameter | Min. | Max. | Unit |
| $\mathrm{f}_{\mathrm{C}}$ | $\mathrm{f}_{\mathrm{SCL}}$ | Clock frequency | 25 | 400 | kHz |
| $\mathrm{t}_{\mathrm{CHCL}}$ | $\mathrm{t}_{\mathrm{HIGH}}$ | Clock pulse width high | 0.6 | $20000^{(1)}$ | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\mathrm{CLCH}}$ | tow | Clock pulse width low | 1.3 | $20000^{(2)}$ | $\mu \mathrm{s}$ |
| tstart_out | - | $1^{2} \mathrm{C}$ timeout on Start condition | 40 | - | ms |
| $\mathrm{t}_{\mathrm{XH} 1 \mathrm{XH2}}{ }^{(3)}$ | $t_{R}$ | Input signal rise time | 20 | 300 | ns |
| $\mathrm{t}_{\mathrm{XL1} 1 \times 2}{ }^{(3)}$ | $\mathrm{t}_{\mathrm{F}}$ | Input signal fall time | 20 | 300 | ns |
| $\mathrm{t}_{\mathrm{DL1} 1 \mathrm{LL} 2}$ | $\mathrm{t}_{\mathrm{F}}$ | SDA (out) fall time | 20 | 100 | ns |
| $t_{\text {DXCX }}$ | $\mathrm{t}_{\text {SU:DAT }}$ | Data in set up time | 100 | - | ns |
| $\mathrm{t}_{\text {CLD }}$ | $\mathrm{t}_{\mathrm{HD}: \text { DAT }}$ | Data in hold time | 0 | - | ns |
| $\mathrm{t}_{\text {CLQX }}$ | $t_{\text {DH }}$ | Data out hold time | 100 | - | ns |
| $\mathrm{t}_{\mathrm{CLQV}}{ }^{(4)(5)}$ | ${ }^{\text {ta }}$ | Clock low to next data valid (access time) | 100 | 900 | ns |
| $\mathrm{t}_{\text {CHDX }}{ }^{(6)}$ | $\mathrm{t}_{\text {SU:STA }}$ | Start condition set up time | 600 | - | ns |
| $t_{\text {DLCL }}$ | $\mathrm{t}_{\text {HD: STA }}$ | Start condition hold time | 0.6 | $35000^{(7)}$ | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\mathrm{CHDH}}$ | $\mathrm{t}_{\text {Su:STO }}$ | Stop condition set up time | 600 | - | ns |
| ${ }^{\text {D }}$ HDL | $t_{\text {BUF }}$ | Time between Stop condition and next Start condition | 1300 | - | ns |
| $t_{\text {w }}$ | - | $1^{2} \mathrm{C}$ write time | - | 5 | ms |

1. $\mathrm{t}_{\mathrm{CHCL}}$ timeout.
2. $\mathrm{t}_{\mathrm{CLCH}}$ timeout.
3. Values recommended by the $I^{2} \mathrm{C}$-bus Fast-Mode specification.
4. To avoid spurious Start and Stop conditions, a minimum delay is placed between SCL=1 and the falling or rising edge of SDA.
5. $\mathrm{t}_{\mathrm{CLQV}}$ is the time (from the falling edge of SCL ) required by the SDA bus line to reach $0.8 \mathrm{~V}_{\mathrm{CC}}$ in a compatible way with the $I^{2} C$ specification (which specifies $\mathrm{t}_{\text {SU:DAT }}(\mathrm{min})=100 \mathrm{~ns}$ ), assuming that the $R_{\text {bus }}$ $\times \mathrm{C}_{\text {bus }}$ time constant is less than 500 ns (as specified in Figure 3).
6. For a reStart condition, or following a write cycle.
7. $t_{\text {DLCL }}$ timeout

Figure 81. $\mathrm{I}^{2} \mathrm{C} A C$ waveforms


## 29 Write cycle definition

Table 124. Write cycle definition ${ }^{(1)}$

| Symbol | Parameter | Test conditions | Min | Max | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Ncycle $^{(2)}$ | Write cycle <br> endurance${ }^{(3)}$ | $\mathrm{T}_{\mathrm{A}} \leq+25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CC}(\text { min })}<\mathrm{V}_{\mathrm{CC}}<\mathrm{V}_{\mathrm{CC}(\max )}$ | - | 1.000 .000 | Write cycle |
|  | $\mathrm{T}_{\mathrm{A}} \leq+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CC}(\text { min })}<\mathrm{V}_{\mathrm{CC}}<\mathrm{V}_{\mathrm{CC}(\max )}$ | - | 150.000 |  |  |

1. A write cycle means the writing of 1 byte, 2 bytes, 3 bytes or 4 bytes ( 1 page) simultaneously.
2. Ncycle is the total number of write/erase cycles for one memory cell or the overall number of write/erase cycles decoded by the whole memory.
3. Write cycle endurance is defined by characterization and qualification.

## 30 RF electrical parameters

This section summarizes the operating and measurement conditions, and the DC and AC characteristics of the device in RF mode.

The parameters in the DC and AC Characteristic tables that follow are derived from tests performed under the Measurement Conditions summarized in the relevant tables.
Designers should check that the operating conditions in their circuit match the measurement conditions when relying on the quoted parameters.

Table 125. RF characteristics ${ }^{(1)}$

| Symbol | Parameter | Condition | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{f}_{\mathrm{CC}}$ | External RF signal frequency | - | 13.553 | 13.56 | 13.567 | MHz |
| H_ISO | Operating field according to ISO | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 150 | - | 5000 | $\begin{aligned} & \mathrm{mA} / \\ & \mathrm{m} \end{aligned}$ |
| MI ${ }_{\text {CARRIER }}$ | $10 \%$ carrier modulation index ${ }^{(3)}$$\mathrm{MI}=(\mathrm{A}-\mathrm{B}) /(\mathrm{A}+\mathrm{B})$ | $\begin{gathered} 150 \mathrm{~mA} / \mathrm{m}>\mathrm{H} \text { _ISO }>1000 \\ \mathrm{~mA} / \mathrm{m} \end{gathered}$ | 15 | - | 30 | \% |
|  |  | H_ISO > $1000 \mathrm{~mA} / \mathrm{m}$ | 10 | - | 30 |  |
| $\mathrm{t}_{\text {RFR }}, \mathrm{t}_{\text {RFF }}$ | 10\% rise and fall time | - | 0.5 | - | 3.0 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {RFSBL }}$ | 10\% minimum pulse width for bit | - | 7.1 | - | 9.44 | $\mu \mathrm{s}$ |
| MICARRIER | 100\% carrier modulation index | $\mathrm{MI}=(\mathrm{A}-\mathrm{B}) /(\mathrm{A}+\mathrm{B})^{(4)}$ | 95 | - | 100 | \% |
| $\mathrm{t}_{\text {RFR }}, \mathrm{t}_{\text {RFF }}$ | 100\% rise and fall time | - | 0.5 | - | 3.5 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {RFSBL }}$ | 100\% minimum pulse width for bit | - | 7 | - | 9.44 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {MIN CD }}$ | Minimum time from carrier generation to first data | From H-field min | - | - | 1 | ms |
| $\mathrm{f}_{\text {SH }}$ | Subcarrier frequency high | $\mathrm{F}_{\mathrm{CC}} / 32$ | - | 423.75 | - | kHz |
| $\mathrm{f}_{\text {SL }}$ | Subcarrier frequency low | $\mathrm{F}_{\mathrm{CC}} / 28$ | - | 484.28 | - | kHz |
| $\mathrm{t}_{1}$ | Time for M24LR16E-R response | $4224 / \mathrm{F}_{\mathrm{S}}$ | 318.6 | 320.9 | 323.3 | $\mu \mathrm{s}$ |
| $\mathrm{t}_{2}$ | Time between commands | 4224/FS | 309 | 311.5 | 314 | $\mu \mathrm{s}$ |
| $\mathrm{W}_{\mathrm{t}}$ | RF write time (including internal Verify) | - | - | 5.75 | - | ms |
| ICC_RF | Operating current (Read) ${ }^{(5)}$ | VAC0-VAC1 (4 V peak to peak) |  | 20 | - | $\mu \mathrm{A}$ |
| $\mathrm{C}_{\text {TUN }}$ | Internal tuning capacitor in $\mathrm{SO}^{(6)}$ | $\mathrm{f}=13.56 \mathrm{MHz}$ | 24.8 | 27.5 | 30.2 | pF |
| $V_{\text {BACK }}$ | Backscattered level as defined by ISO test | ISO10373-7 | 10 | - | - | mV |
| $\mathrm{V}_{\text {MAX_1 }^{1}}{ }^{(3)}$ | RF input voltage amplitude between AC0 and AC1, GND pad left floating, VAC0-VAC1 peak to peak ${ }^{(7)}$ | - | - | - | 20 | V |
|  |  | - | - | - |  |  |
| $\mathrm{V}_{\text {MAX_2 }}{ }^{(3)}$ | AC voltage between AC0 and GND or between AC1 and GND | - | -1 | - | 8.5 | V |

Table 125. RF characteristics ${ }^{(1)(2)}$ (continued)

| Symbol | Parameter | Condition | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {MIN_1 }}{ }^{(3)}$ | RF input voltage amplitude between AC0 and AC1, GND pad left floating, VAC0-VAC1 peak to peak ${ }^{(7)}$ | Inventory and Read operations | - | 4 | 4.5 | V |
|  |  | Write operations | - | 4.5 | 5 | V |
| $\mathrm{V}_{\text {MIN_2 }}{ }^{(3)}$ | $A C$ voltage between $A C 0$ and GND or between AC1 and GND | Inventory and Read operations | - | 1.8 | 2 | V |
|  |  | Write operations | - | 2 | 2.2 | V |
| $\mathrm{t}_{\text {RF_OFF }}$ | RF OFF time | Chip reset | 2 | - | - | ms |

1. $\mathrm{T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$. Characterized only.
2. All timing characterizations were performed on a reference antenna with the following characteristics:

External size: $75 \mathrm{~mm} \times 48 \mathrm{~mm}$
Number of turns: 5
Width of conductor: 0.5 mm
Space between two conductors: 0.3 mm
Value of the tuning capacitor in SO8: 27.5 pF (M24LR16E-R)
Value of the coil: $5 \mu \mathrm{H}$
Tuning frequency: 13.56 MHz .
3. $15 \%$ (or more) carrier modulation index offers a better signal/noise ratio and therefore a wider operating range with a better noise immunity.
4. Temperature range $0^{\circ} \mathrm{C}$ to $90^{\circ} \mathrm{C}$
5. Characterized on bench.
6. Characterized only, at room temperature only, measured at VAC0-VAC1 $=1 \mathrm{~V}$ peak to peak.
7. Characterized only, at room temperature only.

Table 126. Operating conditions

| Symbol | Parameter | Min. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{T}_{\mathrm{A}}$ | Ambient operating temperature | -40 | 85 | ${ }^{\circ} \mathrm{C}$ |

Figure 82 shows an ASK modulated signal from the VCD to the M24LR16E-R. The test condition for the AC/DC parameters are:

- Close coupling condition with tester antenna (1 mm)
- M24LR16E-R performance measured at the tag antenna
- M24LR16E-R synchronous timing, transmit and receive

Figure 82. ASK modulated signal


Table 127 below summarizes respectively the minimum AC0-AC1 input power level $P_{A C 0}$ AC1_min required for the Energy harvesting mode, the corresponding maximum current consumption $I_{\text {sink_max }}$ and variation of the analog voltage Vout for the various Energy harvesting fan-out configurations defined by bits b0 and b1 of the Configuration byte.

Table 127. Energy harvesting ${ }^{(1)(2)}$

| Range | $\mathrm{H}_{\text {min }}{ }^{(3)}$ | $\mathrm{P}_{\text {min }}{ }^{(4)}$ | Vout@l=0 | Vout@l ${ }_{\text {sink_max }}$ | $I_{\text {sink_max }} @ P_{\text {min }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 3.5 A/m | 100 mW | $\begin{aligned} & 2.7 \mathrm{~V} \text { min } \\ & 4.5 \mathrm{~V} \text { max } \end{aligned}$ | 1.7 V | 6 mA |
| 01 | 2.4 A/m | 66 mW | $\begin{aligned} & 2.7 \mathrm{~V} \text { min } \\ & 4.5 \mathrm{~V} \text { max } \end{aligned}$ | 1.9 V | 3 mA |
| 10 | 1.6 A/m | 33 mW | $\begin{aligned} & 2.7 \mathrm{~V} \text { min } \\ & 4.5 \mathrm{~V} \text { max } \end{aligned}$ | 2.1 V | 1 mA |
| 11 | 1.0 A/m | 18 mW | $\begin{aligned} & 2.7 \mathrm{~V} \text { min } \\ & 4.5 \mathrm{~V} \text { max } \end{aligned}$ | 2.3 V | $300 \mu \mathrm{~A}$ |

1. Characterized only
2. Valid from $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
3. $H_{\text {min }}$ characterized according to ISO10373-7 test method
4. $P_{\min }$ calculated from DC measurements

Figure 83. Vout min vs. Isink


Figure 84. Range 11 domain


Figure 85. Range 10 domain


Figure 86. Range 01 domain


Figure 87. Range 00 domain


## 31 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK ${ }^{\circledR}$ packages, depending on their level of environmental compliance. ECOPACK ${ }^{\circledR}$ specifications, grade definitions and product status are available at: www.st.com. ECOPACK ${ }^{\circledR}$ is an ST trademark.

### 31.1 SO8N package information

Figure 88. SO8N - 8-lead plastic small outline, 150 mils body width, package outline


1. Drawing is not to scale.

Table 128. SO8N - 8-lead plastic small outline, 150 mils body width, package mechanical data

| Symbol | millimeters |  |  | inches ${ }^{(1)}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min. | Typ. | Max. | Min. | Typ. | Max. |
| A | - | - | 1.750 | - | - | 0.0689 |
| A1 | 0.100 | - | 0.250 | 0.0039 | - | 0.0098 |
| A2 | 1.250 | - | - | 0.0492 | - | - |
| b | 0.280 | - | 0.480 | 0.0110 | - | 0.0189 |
| c | 0.170 | - | 0.230 | 0.0067 | - | 0.0091 |
| D | 4.800 | 4.900 | 5.000 | 0.1890 | 0.1929 | 0.1969 |
| E | 5.800 | 6.000 | 6.200 | 0.2283 | 0.2362 | 0.2441 |
| E1 | 3.800 | 3.900 | 4.000 | 0.1496 | 0.1535 | 0.1575 |
| e | - | 1.270 | - | - | 0.0500 | - |
| h | 0.250 | - | 0.500 | 0.0098 | - | 0.0197 |
| k | $0^{\circ}$ | - | $8^{\circ}$ | $0^{\circ}$ | - | $8^{\circ}$ |
| L | 0.400 | - | 1.270 | 0.0157 | - | 0.0500 |

Table 128. SO8N - 8-lead plastic small outline, 150 mils body width, package mechanical data (continued)

| Symbol | millimeters |  |  | inches $^{(1)}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min. | Typ. | Max. | Min. | Typ. | Max. |
| L1 | - | 1.040 | - | - | 0.0409 | - |
| Ccc | - | - | 0.100 | - | - | 0.0039 |

1. Values in inches are converted from mm and rounded to four decimal digits.

Figure 89. SO8N - 8-lead plastic small outline, 150 mils body width, package recommended footprint


1. Dimensions are expressed in millimeters.

### 31.2 UFDFN8 package information

Figure 90. UFDFN8-8-lead, $2 \times 3 \mathrm{~mm}, 0.5 \mathrm{~mm}$ pitch ultra thin profile fine pitch dual flat package outline


1. Max. package warpage is 0.05 mm .
2. Exposed copper is not systematic and can appear partially or totally according to the cross section.
3. Drawing is not to scale.
4. The central pad (E2 by D2 in the above illustration) is internally pulled to VSS. It must not be connected to any other voltage or signal line on the PCB, for example during the soldering process.

Table 129. UFDFN8 - 8-lead, $2 \times 3 \mathrm{~mm}, 0.5 \mathrm{~mm}$ pitch ultra thin profile fine pitch dual flat package mechanical data

| Symbol | millimeters |  |  | inches $^{(1)}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min | Typ | Max | Min | Typ | Max |
| A | 0.450 | 0.550 | 0.600 | 0.0177 | 0.0217 | 0.0236 |
| A1 | 0.000 | 0.020 | 0.050 | 0.0000 | 0.0008 | 0.0020 |
| b $^{(2)}$ | 0.200 | 0.250 | 0.300 | 0.0079 | 0.0098 | 0.0118 |
| D | 1.900 | 2.000 | 2.100 | 0.0748 | 0.0787 | 0.0827 |
| D2 | 1.200 | - | 1.600 | 0.0472 | - | 0.0630 |
| E | 2.900 | 3.000 | 3.100 | 0.1142 | 0.1181 | 0.1220 |
| E2 | 1.200 | - | 1.600 | 0.0472 | - | 0.0630 |
| e | - | 0.500 | - |  | 0.0197 |  |
| K | 0.300 | - | - | 0.0118 | - | - |
| L | 0.300 | - | 0.500 | 0.0118 | - | 0.0197 |
| L1 | - | - | 0.150 | - | - | 0.0059 |
| L3 | 0.300 | - | - | 0.0118 | - | - |
| aaa | - | - | 0.150 | - | - | 0.0059 |
| bbb | - | - | 0.100 | - | - | 0.0039 |
| ccc | - | - | 0.100 | - | - | 0.0039 |
| ddd | - | - | 0.050 | - | - | 0.0020 |
| eee ${ }^{(3)}$ | - | - | 0.080 | - | - | 0.0031 |

1. Values in inches are converted from mm and rounded to 4 decimal digits.
2. Dimension b applies to plated terminal and is measured between 0.15 and 0.30 mm from the terminal tip.
3. Applied for exposed die paddle and terminals. Exclude embedding part of exposed die paddle from measuring.

### 31.3 TSSOP8 package information

Figure 91.TSSOP8 - 8-lead thin shrink small outline, $3 \times 6.4 \mathrm{~mm}, 0.65 \mathrm{~mm}$ pitch, package outline


1. Drawing is not to scale.

Table 130. TSSOP8 - 8-lead thin shrink small outline, $3 \times 6.4 \mathrm{~mm}, 0.65 \mathrm{~mm}$ pitch, package mechanical data

| Symbol | millimeters |  |  | inches $^{(1)}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min. | Typ. | Max. | Min. | Typ. | Max. |
| A | - | - | 1.200 | - | - | 0.0472 |
| A1 | 0.050 | - | 0.150 | 0.0020 | - | 0.0059 |
| A2 | 0.800 | 1.000 | 1.050 | 0.0315 | 0.0394 | 0.0413 |
| b | 0.190 | - | 0.300 | 0.0075 | - | 0.0118 |
| c | 0.090 | - | 0.200 | 0.0035 | - | 0.0079 |
| CP | - | - | 0.100 | - | - | 0.0039 |
| D | 2.900 | 3.000 | 3.100 | 0.1142 | 0.1181 | 0.1220 |
| e | - | 0.650 | - | - | 0.0256 | - |
| E | 6.200 | 6.400 | 6.600 | 0.2441 | 0.2520 | 0.2598 |
| E1 | 4.300 | 4.400 | 4.500 | 0.1693 | 0.1732 | 0.1772 |
| L | 0.450 | 0.600 | 0.750 | 0.0177 | 0.0236 | 0.0295 |
| L1 | - | 1.000 | - | - | 0.0394 | - |
| $\alpha$ | $0^{\circ}$ | - | $8^{\circ}$ | $0^{\circ}$ | - | $8^{\circ}$ |

1. Values in inches are converted from mm and rounded to four decimal digits.

## 32 Ordering information

Table 131. Ordering information scheme for packaged devices


T = Tape and reel packing

## Capacitance

$/ 2=27.5 \mathrm{pF}$

Note: $\quad$ Parts marked as ES or E are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST's Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

Table 132. Ordering and marking information

| Reference | Package | Ordering code | First line marking |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Actual revision <br> 0xE and below |  |
|  | TSSOP08 | M24LR16E-RDW6T/2 | $416 E U$ | 4DEUB |
|  | MLP | M24LR16E-RMC6T/2 | $416 E$ | 4DEB |
|  | SO8N | M24LR16E-RMN6T/2 | $24 L 16 E R$ | $24 L D E R B$ |
|  | Bare die | M24LR16E-RUW20/2 | N/A | N/A |

## Appendix A Anticollision algorithm (informative)

The following pseudocode describes how anticollision could be implemented on the VCD, using recursivity.

## A. 1 Algorithm for pulsed slots

```
function push (mask, address); pushes on private stack
function pop (mask, address); pops from private stack
function pulse_next_pause; generates a power pulse
function store(M24LR16E-R_UID); stores M24LR16E-R_UID
function poll_loop (sub_address_size as integer)
    pop (mask, address)
    mask = address & mask; generates new mask
                ; send the request
    mode = anticollision
    send_Request (Request_cmd, mode, mask length, mask value)
    for sub_address = 0 to (2^sub_address_size - 1)
        pulse_next_pause
        if no_collision_is_detected ; M24LR16E-R is inventoried
            then
                store (M24LR16E-R_UID)
            else ; remember a collision was detected
                    push(mask,address)
            endif
            next sub_address
    if stack_not_empty ; if some collisions have been detected and
            then ; not yet processed, the function calls itself
            poll_loop (sub_address_size); recursively to process the
last stored collision
            endif
end poll_loop
main_cycle:
    mask = null
    address = null
    push (mask, address)
    poll_loop(sub_address_size)
end_main_cycle
```


## Appendix B CRC (informative)

## B. $1 \quad$ CRC error detection method

The cyclic redundancy check (CRC) is calculated on all data contained in a message, from the start of the flags through to the end of Data. The CRC is used from VCD to M24LR16E$R$ and from M24LR16E-R to VCD.

Table 133. CRC definition

| CRC definition |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CRC type | Length | Polynomial | Direction | Preset | Residue |
| ISO/IEC 13239 | 16 bits | $X^{16}+X^{12}+X^{5}+1=8408 \mathrm{~h}$ | Backward | FFFFh | F0B8h |

To add extra protection against shifting errors, a further transformation on the calculated CRC is made. The one's complement of the calculated CRC is the value attached to the message for transmission.
To check received messages, the two CRC bytes are often also included in the recalculation, for ease of use. In this case, the expected value for the generated CRC is the residue F0B8h.

## B. $2 \quad$ CRC calculation example

This example in C language illustrates one method of calculating the CRC on a given set of bytes comprising a message.

## C-example to calculate or check the CRC16 according to ISO/IEC 13239

```
#define POLYNOMIAL0x8408// x^16 + x^12 + x^5 + 1
#define PRESET_VALUE0xFFFF
#define CHECK_VALUE0xF0B8
#define NUMBER_OF_BYTES4// Example: 4 data bytes
#define CALC_CRC1
#define CHECK_CRC0
void main()
{
    unsigned int current_crc_value;
    unsigned char array_of_databytes[NUMBER_OF_BYTES + 2] = {1, 2, 3,
4, 0x91, 0x39};
    int number_of_databytes = NUMBER_OF_BYTES;
    int calculate_or_check_crc;
    int i, j;
    calculate_or_check_crc = CALC_CRC;
// calculate_or_check_crc = CHECK_CRC;// This could be an other
example
    if (calculate_or_check_crc == CALC_CRC)
    {
```

```
            number_of_databytes = NUMBER_OF_BYTES;
    }
    else // check CRC
    {
        number_of_databytes = NUMBER_OF_BYTES + 2;
    }
    current_crc_value = PRESET_VALUE;
    for (i = 0; i < number_of_databytes; i++)
    {
        current_crc_value = current_crc_value ^ ((unsigned
int)array_of_databytes[i]);
    for (j = 0; j < 8; j++)
        {
            if (current_crc_value & 0x0001)
            {
                current_crc_value = (current_crc_value >> 1) ^
POLYNOMIAL;
            }
            else
            {
                        current_crc_value = (current_crc_value >> 1);
            }
        }
    }
    if (calculate_or_check_crc == CALC_CRC)
    {
        current_crc_value = ~current_crc_value;
        printf ("Generated CRC is 0x%04X\n", current_crc_value);
        // current_crc_value is now ready to be appended to the data
stream
            // (first LSByte, then MSByte)
    }
    else // check CRC
    {
            if (current_crc_value == CHECK_VALUE)
            {
                printf ("Checked CRC is ok (0x%04X)\n",
current_crc_value);
            }
            else
            {
            printf ("Checked CRC is NOT ok (0x%04X)\n",
current_crc_value);
            }
    }
}
```


## Appendix C Application family identifier (AFI) (informative)

The AFI (application family identifier) represents the type of application targeted by the VCD and is used to extract from all the M24LR16E-Rs present only the M24LR16E-R meeting the required application criteria.
It is programmed by the M24LR16E-R issuer (the purchaser of the M24LR16E-R). Once locked, it cannot be modified.

The most significant nibble of the AFI is used to code one specific or all application families, as defined in Table 134.

The least significant nibble of the AFI is used to code one specific or all application subfamilies. Subfamily codes different from 0 are proprietary.

Table 134. AFI coding ${ }^{(1)}$

| AFI most significant nibble | AFI <br> least significant nibble | Meaning <br> VICCs respond from | Examples / Note |
| :---: | :---: | :---: | :---: |
| '0' | '0' | All families and subfamilies | No applicative preselection |
| 'X' | '0 | All subfamilies of family $X$ | Wide applicative preselection |
| 'X | 'Y' | Only the Yth subfamily of family $X$ | - |
| '0' | 'Y' | Proprietary subfamily Y only | - |
| '1 | '0', 'Y' | Transport | Mass transit, bus, airline,... |
| '2 | "0', 'Y' | Financial | IEP, banking, retail,... |
| '3 | "0', 'Y' | Identification | Access control,... |
| '4 | '0', 'Y' | Telecommunication | Public telephony, GSM,... |
| '5' | '0', 'Y' | Medical | - |
| '6 | '0', 'Y' | Multimedia | Internet services.... |
| '7 | '0', 'Y' | Gaming | - |
| 8 | "0', 'Y' | Data Storage | Portable files,... |
| '9 | '0', 'Y' | Item management | - |
| 'A | '0', 'Y' | Express parcels | - |
| 'B | "0', 'Y' | Postal services | - |
| 'C | '0', 'Y' | Airline bags | - |
| 'D | '0', 'Y' | RFU | - |
| 'E | '0', 'Y' | RFU | - |
| 'F' | '0', 'Y' | RFU | - |

1. $X=$ '1' to ' $F$ ', $Y=$ '1' to ' $F$ '

## Revision history

Table 135. Document revision history

| Date | Revision | Changes |
| :---: | :---: | :--- |
| 24-Jun-2011 | 1 | Initial release. |
| 28-Jul-2011 | 2 | Updated Description, Table 118: Absolute maximum ratings, <br> Table 127: Energy harvesting. <br> Added figures 52, 56, 57, 83 to 87. |
| 29-Jul-2011 | 3 | Updated IC Ref data. |
| 29-Jul-2011 | 4 | Updated IC Ref data from 4Fh to 4Eh. |
| 09-Aug-2011 | 5 | Updated: <br> - Table 127: Energy harvesting <br> - Section 5.6: Memory addressing <br> - Figure 12: I2C present password command |
| - Figure 13: I2C write password command |  |  |$|$| Updated: |
| :--- |
| - Table 118: Absolute maximum ratings |
| - Table 122: I2C DC characteristics |
| - Table 125: RF characteristics |
| - Table 127: Energy harvesting |
| - Figure 82: ASK modulated signal |
| - Figure 83: Vout min vs. Isink |
| - Figure 84: Range 11 domain |
| - Figure 85: Range 10 domain |
| - Figure 86: Range 01 domain |
| - Figure 87: Range 00 domain |, | 09-Nov-2011 |
| :--- |
| 13-Jun-2013 |

Table 135. Document revision history (continued)

| Date | Revision | Changes |
| :---: | :---: | :--- |
| 13-May-2016 | 12 | Updated Features in cover page. <br> Added Section 29: Write cycle definition. |
| 13-Mar-2017 | 13 | Updated Features in cover page. |
| 01-Aug-2017 | 14 | Added note 4 on Figure 90: UFDFN8-8-lead, $2 \times 3 \mathrm{~mm}, 0.5 \mathrm{~mm}$ pitch <br> ultra thin profile fine pitch dual flat package outline <br> Updated Section 32: Ordering information |

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[^0]:    1. The seven most significant bits of the device select code of a random read (in the first and fourth bytes) must be identical.
[^1]:    1. Gray means that the field is optional.
