NTS0103

Dual supply translating transceiver; open drain; auto direction sensing

Rev. 2 — 10 November 2011

Product data sheet

1. General description

The NTS0103 is a 3-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 3-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ($V_{CC(A)}$ and $V_{CC(B)}$). $V_{CC(A)}$ can be supplied at any voltage between 1.65 V and 3.6 V and $V_{CC(B)}$ can be supplied at any voltage between 2.3 V and 5.5 V, making the device suitable for translating between any of the voltage nodes (1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins An and OE are referenced to $V_{CC(A)}$ and pins Bn are referenced to $V_{CC(B)}$. A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

2. Features and benefits

- Wide supply voltage range:
 - ♦ V_{CC(A)}: 1.65 V to 3.6 V and V_{CC(B)}: 2.3 V to 5.5 V
- Maximum data rates:
 - ◆ Push-pull: 50 Mbps
- I_{OFF} circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
 - ♦ HBM JESD22-A114E Class 2 exceeds 2500 V for A port
 - ◆ HBM JESD22-A114E Class 3B exceeds 8000 V for B port
 - ◆ MM JESD22-A115-A exceeds 200 V
 - CDM JESD22-C101E exceeds 1500 V
 - ◆ IEC61000-4-2 contact discharge exceeds 8000 V for B port
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

3. Applications

- I²C/SMBus
- UART
- GPIO



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4. Ordering information

Table 1. Ordering information

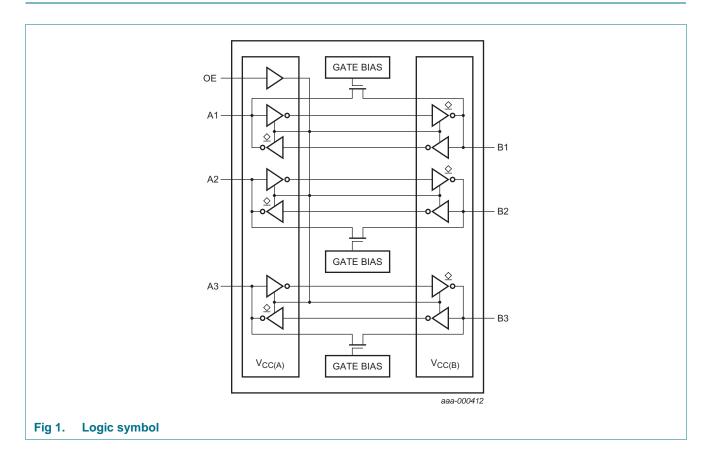
Type number	Package	Package							
	Temperature range	Name	Description	Version					
NTS0103GU10	–40 °C to +125 °C	XQFN10	plastic, extremely thin quad flat package; no leads; 10 terminals; body $1.40 \times 1.80 \times 0.50$ mm	SOT1160-1					

5. Marking

Table 2. Marking

Type number	Marking code
NTS0103GU10	s3

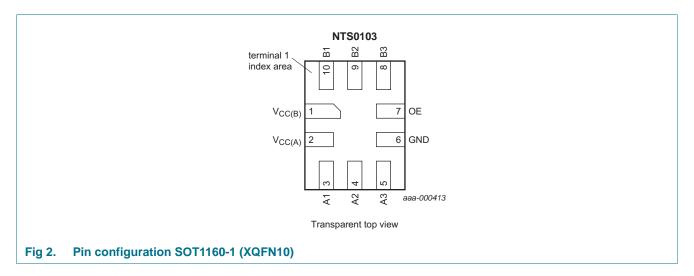
6. Functional diagram



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7. Pinning information

7.1 Pinning



7.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
V _{CC(B)}	1	supply voltage B
V _{CC(A)}	2	supply voltage A
A1, A2, A3	3, 4, 5	data input or output (referenced to $V_{\text{CC}(A)}$)
GND	6	ground (0 V)
OE	7	output enable input (active HIGH; referenced to $V_{\text{CC}(A)}$)
B3, B2, B1	8, 9, 10	data input or output (referenced to V _{CC(B)})

8. Functional description

Table 4. Function table[1]

Supply voltage		Input	Input/output	
V _{CC(A)} V _{CC(B)}		OE	An	Bn
1.65 V to V _{CC(B)}	2.3 V to 5.5 V	L	Z	Z
1.65 V to V _{CC(B)}	2.3 V to 5.5 V	Н	input or output	output or input
GND[2]	GND[2]	Χ	Z	Z

 $^{[1] \}quad \ \ H = HIGH \ voltage \ level; \ L = LOW \ voltage \ level; \ X = don't \ care; \ Z = high-impedance \ OFF-state.$

^[2] When either $V_{\text{CC(A)}}$ or $V_{\text{CC(B)}}$ is at GND level, the device goes into power-down mode.

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9. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
$V_{CC(B)}$	supply voltage B		-0.5	+6.5	V
V_{I}	input voltage	A port and OE input	<u>[1][2]</u> –0.5	+6.5	V
		B port	[1][2] -0.5	+6.5	V
Vo	output voltage	Active mode	[1][2]		
		A or B port	-0.5	V _{CCO} + 0.5	V
		Power-down or 3-state mode	<u>[1]</u>		
		A port	-0.5	+4.6	V
		B port	-0.5	+6.5	V
I _{IK}	input clamping current	V _I < 0 V	-50	-	mA
I _{OK}	output clamping current	V _O < 0 V	-50	-	mA
Io	output current	$V_O = 0 V \text{ to } V_{CCO}$	<u>[2]</u> -	±50	mA
I _{CC}	supply current	I _{CC(A)} or I _{CC(B)}	-	100	mA
I _{GND}	ground current		-100	-	mA
T _{stg}	storage temperature		-65	+150	°C
P _{tot}	total power dissipation	$T_{amb} = -40 ^{\circ}\text{C} \text{ to } +125 ^{\circ}\text{C}$	<u>[3]</u> _	250	mW

^[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

10. Recommended operating conditions

Table 6. Recommended operating conditions[1][2]

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		1.65	3.6	V
V _{CC(B)}	supply voltage B		2.3	5.5	V
T _{amb}	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	A or B port; push-pull driving			
		$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	-	10	ns/V
		OE input			
		$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	-	10	ns/V

^[1] The A and B sides of an unused I/O pair must be held in the same state, both at V_{CCI} or both at GND.

^[2] V_{CCO} is the supply voltage associated with the output.

^[3] For XQFN10 package: above 128 °C the value of Ptot derates linearly with 11.5 mW/K.

^[2] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$.

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11. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.

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Symbol	Parameter	Conditions	Min	Тур	Max	Unit
II	input leakage current	OE input; V_I = 0 V to 3.6 V; $V_{CC(A)}$ = 1.65 V to 3.6 V; $V_{CC(B)}$ = 2.3 V to 5.5 V	-	-	±1	μА
I _{OZ}	OFF-state output current	A or B port; V_O = 0 V or V_{CCO} ; $V_{CC(A)}$ = 1.65 V to 3.6 V; $V_{CC(B)}$ = 2.3 V to 5.5 V	<u>[1]</u> -	-	±1	μА
I _{OFF}	power-off leakage current	A port; V_1 or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V	-	-	±1	μА
		B port; V_1 or $V_O = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V	-	-	±1	μА
C _I	input capacitance	OE input; $V_{CC(A)} = 3.3 \text{ V}$; $V_{CC(B)} = 3.3 \text{ V}$	-	2	-	pF
$C_{I/O}$	input/output	A port	-	4	-	pF
	capacitance	B port	-	7	-	pF
		A or B port; $V_{CC(A)} = 3.3 \text{ V}$; $V_{CC(B)} = 3.3 \text{ V}$	-	9	-	pF

^[1] V_{CCO} is the supply voltage associated with the output.

Table 8. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.

V _{CC(A)}	V _{CC(B)}	V _{CC(B)}							
	2.5 V		3.3 V	3.3 V					
	I _{CC(A)}	I _{CC(B)}	I _{CC(A)}	I _{CC(B)}	I _{CC(A)}	I _{CC(B)}			
1.8 V	0.1	0.5	0.1	1.5	0.1	4.6	μΑ		
2.5 V	0.1	0.1	0.1	0.8	0.1	3.8	μΑ		
3.3 V	-	-	0.1	0.1	0.1	2.8	μΑ		

Table 9. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	–40 °C to	+85 °C	-40 °C to +125 °C		Unit
			Min	Max	Min	Max	
V_{IH}	HIGH-level	A port					
	$V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	V _{CCI} - 0.2	-	V _{CCI} - 0.2	-	V	
		33(7.1)	V _{CCI} - 0.4	-	V _{CCI} – 0.4	-	V
		B port					
		$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	V _{CCI} - 0.4	-	V _{CCI} - 0.4	-	V
		OE input					
		$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	0.65V _{CC(A)}	-	0.65V _{CC(A)}	-	V

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Table 9. Static characteristics ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		-40 °C 1	to +85 °C	–40 °C to	Unit	
				Min	Max	Min	Max	
V _{IL}	LOW-level	A or B port			'			
	input voltage	$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$		-	0.15	-	0.15	V
		OE input						
		$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$		-	0.35V _{CC(A)}	-	0.35V _{CC(A)}	V
V _{OH}	HIGH-level	A or B port; $I_O = -20 \mu A$						
	output voltage	$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	[2]	0.67V _{CCO}	-	0.67V _{CCO}	-	V
V _{OL}	LOW-level	A or B port; $I_0 = 1 \text{ mA}$	[2]					
	output voltage	$V_I \le 0.15 \text{ V};$ $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$		-	0.4	-	0.4	V
lı	input leakage current	OE input; $V_I = 0 \text{ V to } 3.6 \text{ V};$ $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$		-	±2	-	±12	μΑ
loz	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$; $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V}$; $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$	[2]	-	±2	-	±12	μΑ
l _{OFF}	power-off leakage	A port; V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V		-	<u>±2</u>	-	±12	μΑ
	current	B port; V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V		-	±2	-	±12	μΑ
lcc	supply current	$V_I = 0 \text{ V or } V_{CCI}$; $I_O = 0 \text{ A}$	[1]					
		I _{CC(A)}						
		$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$		-	2.4	-	15	μΑ
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	2.2	-	15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$		-	-1	-	-8	μΑ
		$I_{CC(B)}$						
		$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$		-	12	-	30	μΑ
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	-1	-	- 5	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$		-	1	-	6	μΑ
		$I_{CC(A)} + I_{CC(B)}$						
		$V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}$		-	14.4	-	45	μΑ

^[1] V_{CCI} is the supply voltage associated with the input.

^[2] V_{CCO} is the supply voltage associated with the output.

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12. Dynamic characteristics

Table 10. Dynamic characteristics for temperature range –40 °C to +85 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 5; for wave forms see Figure 3 and Figure 4.

Symbol	Parameter	Conditions				Vc	C(B)			Unit
				2.5 V	Ŀ 0.2 V		± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	
V _{CC(A)} =	1.8 V ± 0.15 V		'		I					
t _{PHL}	HIGH to LOW propagation delay	A to B		-	4.6	-	4.7	-	5.8	ns
t _{PLH}	LOW to HIGH propagation delay	A to B		-	6.8	-	6.8	-	7.0	ns
t _{PHL}	HIGH to LOW propagation delay	B to A		-	4.4	-	4.5	-	4.7	ns
t _{PLH}	LOW to HIGH propagation delay	B to A		-	5.3	-	4.5	-	0.5	ns
t _{en}	enable time	OE to A; B		-	200	-	200	-	200	ns
t _{dis}	disable time	OE to A; no external load	[2]	-	35	-	35	-	35	ns
		OE to B; no external load	[2]	-	35	-	35	-	35	ns
		OE to A		-	230	-	230	-	230	ns
		OE to B		-	200	-	200	-	200	ns
t _{TLH}	LOW to HIGH	A port		3.2	9.5	2.3	9.3	1.8	7.6	ns
	output transition time	B port		3.3	10.8	2.7	9.1	2.7	7.6	ns
^t THL	HIGH to LOW	A port		2.0	5.9	1.9	6.0	1.7	13.3	ns
	output transition time	B port		2.9	7.6	2.8	7.5	2.8	10.0	ns
t _{sk(o)}	output skew time	between channels	[3]	-	0.7	-	0.7	-	0.7	ns
t _W	pulse width	data inputs		20	-	20	-	20	-	ns
f _{data}	data rate			-	50	-	50	-	50	Mbp
$V_{CC(A)} = 1$	2.5 V ± 0.2 V									
t _{PHL}	HIGH to LOW propagation delay	A to B		-	3.2	-	3.3	-	3.4	ns
t _{PLH}	LOW to HIGH propagation delay	A to B		-	3.5	-	4.1	-	4.4	ns
t _{PHL}	HIGH to LOW propagation delay	B to A		-	3.0	-	3.6	-	4.3	ns
t _{PLH}	LOW to HIGH propagation delay	B to A		-	2.5	-	1.6	-	0.7	ns
en	enable time	OE to A; B		-	200	-	200	-	200	ns
dis	disable time	OE to A; no external load	[2]	-	35	-	35	-	35	ns
		OE to B; no external load	[2]	-	35	-	35	-	35	ns
		OE to A		-	200	-	200	-	200	ns
		OE to B		-	200	-	200	-	200	ns
TLH	LOW to HIGH	A port		2.8	7.4	2.6	6.6	1.8	6.2	ns
	output transition time	B port		3.2	8.3	2.9	7.9	2.4	6.8	ns

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Table 10. Dynamic characteristics for temperature range –40 °C to +85 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 5; for wave forms see Figure 3 and Figure 4.

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Symbol	Parameter	Conditions				Vc	C(B)			Unit
				2.5 V	± 0.2 V	3.3 V :	± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	
t _{THL}	HIGH to LOW	A port		1.9	5.7	1.9	5.5	1.8	5.3	ns
	output transition time	B port		2.2	7.8	2.4	6.7	2.6	6.6	ns
t _{sk(o)}	output skew time	between channels	[3]	-	0.7	-	0.7	-	0.7	ns
t_{W}	pulse width	data inputs		20	-	20	-	20	-	ns
f _{data}	data rate			-	50	-	50	-	50	Mbps
$V_{CC(A)} =$	$3.3~V\pm0.3~V$									
t _{PHL}	HIGH to LOW propagation delay	A to B		-	-	-	2.4	-	3.1	ns
t _{PLH}	LOW to HIGH propagation delay	A to B		-	-	-	4.2	-	4.4	ns
t _{PHL}	HIGH to LOW propagation delay	B to A		-	-	-	2.5	-	3.3	ns
t _{PLH}	LOW to HIGH propagation delay	B to A		-	-	-	2.5	-	2.6	ns
t _{en}	enable time	OE to A; B		-	-	-	200	-	200	ns
t _{dis}	disable time	OE to A; no external load	[2]	-	-	-	35	-	35	ns
		OE to B; no external load	[2]	-	-	-	35	-	35	ns
		OE to A		-	-	-	260	-	260	ns
		OE to B		-	-	-	200	-	200	ns
t _{TLH}	LOW to HIGH	A port		-	-	2.3	5.6	1.9	5.9	ns
	output transition time	B port		-	-	2.5	6.4	2.1	7.4	ns
t_{THL}	HIGH to LOW	A port		-	-	2.0	5.4	1.9	5.0	ns
	output transition time	B port		-	-	2.3	7.4	2.4	7.6	ns
t _{sk(o)}	output skew time	between channels	[3]	-	-	-	0.7	-	0.7	ns
t _W	pulse width	data inputs		-	-	20	-	20	-	ns
f _{data}	data rate			-	-	-	50	-	50	Mbps

^[1] t_{en} is the same as t_{PZL} and t_{PZH} . t_{dis} is the same as t_{PLZ} and t_{PHZ} .

^[2] Delay between OE going LOW and when the outputs are actually disabled.

^[3] Skew between any two outputs of the same package switching in the same direction.

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Table 11. Dynamic characteristics for temperature range –40 °C to +125 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 5</u>; for wave forms see <u>Figure 3</u> and <u>Figure 4</u>.

Symbol	Parameter	Conditions		V _{CC(B)}						Unit
				$2.5~V\pm0.2~V$		$3.3 \text{ V} \pm 0.3 \text{ V}$		5.0 V ± 0.5 V		
				Min	Max	Min	Max	Min	Max	
V _{CC(A)} =	1.8 V ± 0.15 V		·						'	
t _{PHL}	HIGH to LOW propagation delay	A to B		-	5.8	-	5.9	-	7.3	ns
t _{PLH}	LOW to HIGH propagation delay	A to B		-	8.5	-	8.5	-	8.8	ns
PHL	HIGH to LOW propagation delay	B to A		-	5.5	-	5.7	-	5.9	ns
[‡] PLH	LOW to HIGH propagation delay	B to A		-	6.7	-	5.7	-	0.7	ns
t _{en}	enable time	OE to A; B		-	200	-	200	-	200	ns
dis	disable time	OE to A; no external load	[2]	-	45	-	45	-	45	ns
		OE to B; no external load	[2]	-	45	-	45	-	45	ns
		OE to A		-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	ns
t _{TLH}	LOW to HIGH	A port		3.2	11.9	2.3	11.7	1.8	9.5	ns
	output transition time	B port		3.3	13.5	2.7	11.4	2.7	9.5	ns
***=	HIGH to LOW	A port		2.0	7.4	1.9	7.5	1.7	16.7	ns
output transition time		B port		2.9	9.5	2.8	9.4	2.8	12.5	ns
t _{sk(o)}	output skew time	between channels	[3]	-	8.0	-	8.0	-	0.8	ns
tw	pulse width	data inputs		20	-	20	-	20	-	ns
data	data rate			-	50	-	50	-	50	Mbp
$V_{CC(A)} =$	2.5 V ± 0.2 V									
t _{PHL}	HIGH to LOW propagation delay	A to B		-	4.0	-	4.2	-	4.3	ns
t _{PLH}	LOW to HIGH propagation delay	A to B		-	4.4	-	5.2	-	5.5	ns
t _{PHL}	HIGH to LOW propagation delay	B to A		-	3.8	-	4.5	-	5.4	ns
PLH	LOW to HIGH propagation delay	B to A		-	3.2	-	2.0	-	0.9	ns
en	enable time	OE to A; B		-	200	-	200	-	200	ns
dis	disable time	OE to A; no external load	[2]	-	45	-	45	-	45	ns
		OE to B; no external load	[2]	-	45	-	45	-	45	ns
		OE to A		-	220	-	220	-	220	ns
		OE to B		-	220	-	220	-	220	ns
t _{TLH}	LOW to HIGH	A port		2.8	9.3	2.6	8.3	1.8	7.8	ns
	output transition time	B port		3.2	10.4	2.9	9.7	2.4	8.3	ns

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Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C[1] ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 5</u>; for wave forms see <u>Figure 3</u> and <u>Figure 4</u>.

Symbol	Parameter	Conditions		V _{CC(B)}						Unit
				$2.5 \text{ V} \pm 0.2 \text{ V}$		$3.3 \text{ V} \pm 0.3 \text{ V}$		5.0 V ± 0.5 V		
				Min	Max	Min	Max	Min	Max	
t _{THL}	HIGH to LOW	A port	'	1.9	7.2	1.9	6.9	1.8	6.7	ns
	output transition time	B port		2.2	9.8	2.4	8.4	2.6	8.3	ns
t _{sk(o)}	output skew time	between channels	[3]	-	8.0	-	8.0	-	0.8	ns
t_{W}	pulse width	data inputs		20	-	20	-	20	-	ns
f _{data}	data rate			-	50	-	50	-	50	Mbps
V _{CC(A)} =	3.3 V ± 0.3 V									
t _{PHL}	HIGH to LOW propagation delay	A to B		-	-	-	3.0	-	3.9	ns
t _{PLH}	LOW to HIGH propagation delay	A to B		-	-	-	5.3	-	5.5	ns
t _{PHL}	HIGH to LOW propagation delay	B to A		-	-	-	3.2	-	4.2	ns
t _{PLH}	LOW to HIGH propagation delay	B to A		-	-	-	3.2	-	3.3	ns
t _{en}	enable time	OE to A; B		-	-	-	200	-	200	ns
t _{dis}	disable time	OE to A; no external load	[2]	-	-	-	45	-	45	ns
		OE to B; no external load	[2]	-	-	-	45	-	45	ns
		OE to A		-	-	-	280	-	280	ns
		OE to B		-	-	-	220	-	220	ns
t _{TLH}	LOW to HIGH	A port		-	-	2.3	7.0	1.9	7.4	ns
	output transition time	B port		-	-	2.5	8.0	2.1	9.3	ns
t _{THL}	HIGH to LOW	A port		-	-	2.0	6.8	1.9	6.3	ns
	output transition time	B port		-	-	2.3	9.3	2.4	9.5	ns
t _{sk(o)}	output skew time	between channels	[3]	-	-	-	0.8	-	0.8	ns
t _W	pulse width	data inputs		-	-	20	-	20	-	ns
f _{data}	data rate			-	-	-	50	-	50	Mbps

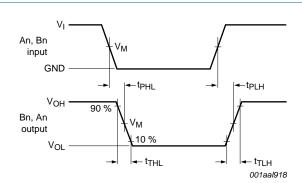
^[1] t_{en} is the same as t_{PZL} and t_{PZH} . t_{dis} is the same as t_{PLZ} and t_{PHZ} .

^[2] Delay between OE going LOW and when the outputs are actually disabled.

^[3] Skew between any two outputs of the same package switching in the same direction.

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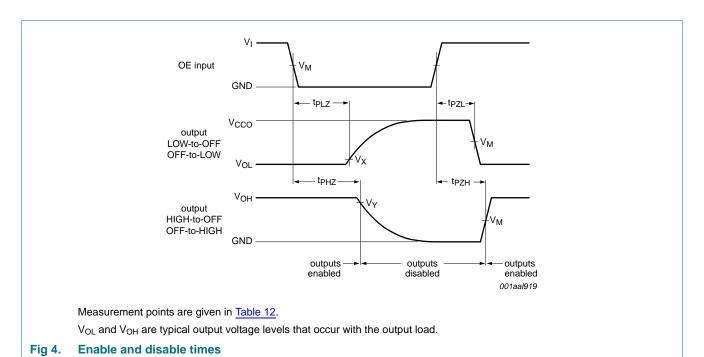
13. Waveforms



Measurement points are given in Table 12.

 V_{OL} and V_{OH} are typical output voltage levels that occur with the output load.

Fig 3. The data input (An, Bn) to data output (Bn, An) propagation delay times



Supply voltage	Input	Output			
V _{CCO}	V _M	V _M	V _X	V _Y	
$1.8~\textrm{V} \pm 0.15~\textrm{V}$	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.15 V	V _{OH} – 0.15 V	
2.5 V ± 0.2 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.15 V	V _{OH} – 0.15 V	
3.3 V ± 0.3 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.3 V	V _{OH} – 0.3 V	
5.0 V ± 0.5 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.3 V	V _{OH} – 0.3 V	

^[1] V_{CCI} is the supply voltage associated with the input.

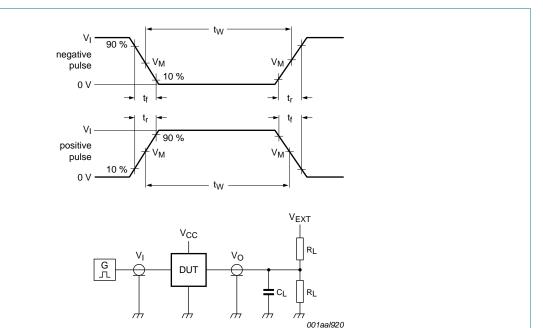
Measurement points[1][2]

[2] V_{CCO} is the supply voltage associated with the output.

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Table 12.

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Test data is given in Table 13.

All input pulses are supplied by generators having the following characteristics: PRR \leq 10 MHz; Z_{O} = 50 Ω ; $dV/dt \geq$ 1.0 V/ns.

R_L = Load resistance.

 C_L = Load capacitance including jig and probe capacitance.

 V_{EXT} = External voltage for measuring switching times.

Fig 5. Test circuit for measuring switching times

Table 13. Test data

Supply voltage		Input		Load	V _{EXT}			
V _{CC(A)}	V _{CC(B)}	۷ _ا [1]	Δt/ΔV	CL	R _L [2]	t _{PLH} , t _{PHL}	t _{PZH} , t _{PHZ}	t _{PZL} , t _{PLZ} [3]
1.65 V to 3.6 V	2.3 V to 5.5 V	V_{CCI}	≤ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V _{CCO}

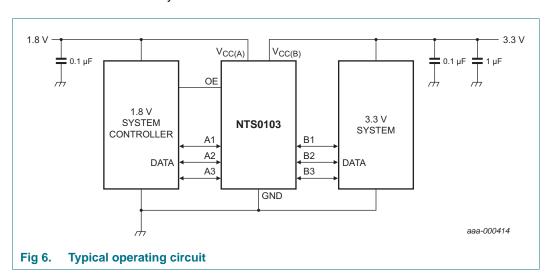
- [1] V_{CCI} is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements, $R_L = 1 \text{ M}\Omega$; for measuring enable and disable times, $R_L = 50 \text{ k}\Omega$.
- [3] V_{CCO} is the supply voltage associated with the output.

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14. Application information

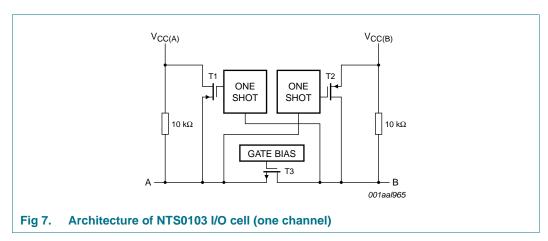
14.1 Applications

Voltage level-translation applications. The NTS0103 can be used in point-to-point applications to interface between devices or systems operating at different supply voltages. The device is primarily targeted at I²C or 1-wire which use open-drain drivers, it may also be used in applications where push-pull drivers are connected to the ports, however the NTB0103 may be more suitable.



14.2 Architecture

The architecture of the NTS0103 is shown in <u>Figure 7</u>. The device does not require an extra input signal to control the direction of data flow from A to B or B to A.



The NTS0103 is a "switch" type voltage translator, it employs two key circuits to enable voltage translation:

- 1. A pass-gate transistor (N-channel) that ties the ports together.
- 2. An output edge-rate accelerator that detects and accelerates rising edges on the I/O pins.

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The gate bias voltage of the pass gate transistor (T3) is set at approximately one threshold voltage above the V_{CC} level of the low-voltage side. During a LOW-to-HIGH transition the output one-shot accelerates the output transition by switching on the PMOS transistors (T1, T2) bypassing the 10 k Ω pull-up resistors and increasing current drive capability. The one-shot is activated once the input transition reaches approximately $V_{CCI}/2$; it is de-activated approximately 50 ns after the output reaches $V_{CCO}/2$. During the acceleration time the driver output resistance is between approximately 50 Ω and 70 Ω . To avoid signal contention and minimize dynamic I_{CC} , the user should wait for the one-shot circuit to turn-off before applying a signal in the opposite direction. Pull-up resistors are included in the device for DC current sourcing capability.

14.3 Input driver requirements

As the NTS0103 is a switch type translator, properties of the input driver directly effect the output signal. The external open-drain or push-pull driver applied to an I/O determines the static current sinking capability of the system; the max data rate, HIGH-to-LOW output transition time (t_{THL}) and propagation delay (t_{PHL}) are dependent upon the output impedance and edge-rate of the external driver. The limits provided for these parameters in the datasheet assume a driver with output impedance below 50 Ω is used.

14.4 Output load considerations

The maximum lumped capacitive load that can be driven is dependant upon the one-shot pulse duration. In cases with very heavy capacitive loading there is a risk that the output will not reach the positive rail within the one-shot pulse duration.

To avoid excessive capacitive loading and to ensure correct triggering of the one-shot it's recommended to use short trace lengths and low capacitance connectors on NTS0103 PCB layouts. To ensure low impedance termination and avoid output signal oscillations and one-shot re-triggering, the length of the PCB trace should be such that the round trip delay of any reflection is within the one-shot pulse duration (approximately 50 ns).

14.5 Power up

During operation $V_{CC(A)}$ must never be higher than $V_{CC(B)}$, however during power-up $V_{CC(A)} \ge V_{CC(B)}$ does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTS0103 includes circuitry that disables all output ports when either $V_{CC(A)}$ or $V_{CC(B)}$ is switched off.

14.6 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW

causes all I/Os to assume the high-impedance OFF-state. The disable time (t_{dis} with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time (t_{en}) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

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14.7 Pull-up or pull-down resistors on I/Os lines

Each A port I/O has an internal 10 k Ω pull-up resistor to $V_{CC(A)}$, and each B port I/O has an internal 10 k Ω pull-up resistor to $V_{CC(B)}$. If a smaller value of pull-up resistor is required, an external resistor must be added parallel to the internal 10 k Ω , this will effect the V_{OL} level. When OE goes LOW the internal pull-ups of the NTS0103 are disabled.

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15. Package outline

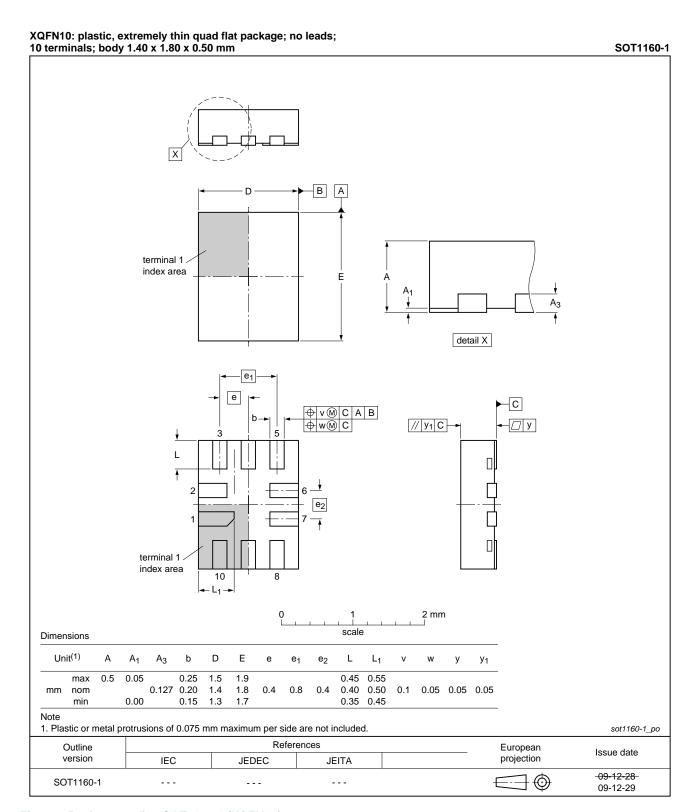


Fig 8. Package outline SOT1160-1 (XQFN10)

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16. Abbreviations

Table 14. Abbreviations

Acronym	Description
CDM	Charged Device Model
DUT	Device Under Test
ESD	ElectroStatic Discharge
GPIO	General Purpose Input Output
НВМ	Human Body Model
I ² C	Inter-Integrated Circuit
MM	Machine Model
SMBus	System Management Bus
UART	Universal Asynchronous Receiver Transmitter

17. Revision history

Table 15. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
NTS0103 v.2	20111110	Product data sheet	-	NTS0103 v.1
Modifications:	 Legal pages 	updated.		
NTS0103 v.1	20110921	Product data sheet	-	-

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18. Legal information

18.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
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Date of release: 10 November 2011 Document identifier: NTS0103

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