Incremental 25-mm-dia. Rotary Encoder

E6A2-C

Compact Encoder with External Diameter of 25 mm

- Incremental model
- External diameter of 25 mm.
- Resolution of up to 500 ppr.



For the most recent information on models that have been certified for safety standards, refer to your OMRON website.



Ordering Information

Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Output phases	Resolution (pulses/rotation)	Model
5 to 12 VDC	Voltage output	Phases A, B, and Z	100, 200, 360	E6A2-CWZ3E (resolution) 0.5M
	vollage output		500	Example: E6A2-CWZ3E 100P/R 0.5M
	Open-collector output (NPN output)		100, 200, 360	E6A2-CWZ3C (resolution) 0.5M
			500	Example: E6A2-CWZ3C 100P/R 0.5M
12 to 24 VDC			100, 200, 360	E6A2-CWZ5C (resolution) 0.5M
			500	Example: E6A2-CWZ5C 100P/R 0.5M
5 to 12 VDC	Voltago output	Phases A and B	100, 200, 360	E6A2-CW3E (resolution) 0.5M
	Voltage output		500	Example: E6A2-CW3E 100P/R 0.5M
	Open-collector output (NPN output)		100, 200, 360	E6A2-CW3C (resolution) 0.5M
			500	Example: E6A2-CW3C 100P/R 0.5M
12 to 24 VDC			100, 200, 360	E6A2-CW5C (resolution) 0.5M
			500	Example: E6A2-CW5C 100P/R 0.5M
5 to 12 VDC	Voltage output		10, (20) *, 60, 100, 200, 300, 360	E6A2-CS3E (resolution) 0.5M Example: E6A2-CS3E 10P/R 0.5M
			500	Example: E6A2-CS3E T0P/R 0.5M
	Open-collector output	Phase A	10, 20, 60, 100, 200, 300, 360	E6A2-CS3C (resolution) 0.5M
			500	Example: E6A2-CS3C 10P/R 0.5M
12 to 24 VDC	(NPN output)		10, 20, 60, 100, 200, 300, 360	E6A2-CS5C (resolution) 0.5M
			500	Example: E6A2-CS5C 10P/R 0.5M

* Only a 2-m cable is available for the 20P/R Model.

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks		
Coupling	E69-C04B	Provided with the product.		
Servo Mounting Bracket	E69-1	Provided with the E6A2-CWZ.		

Refer to Accessories for details.

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Ratings and Specifications

Item	Model	E6A2- CWZ3E	E6A2- CWZ3C	E6A2- CWZ5C	E6A2-CW3E	E6A2-CW3C	E6A2-CW5C	E6A2-CS3E	E6A2-CS3C	E6A2-CS5C	
Power su voltage	pply				5 VDC –5% to 12 V +10%, ripple (p-p): 5% max. (p-p): 5% max.		5 VDC -5% to 12 V +10%, ripple (p-p): 5% max. 12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.				
Current consump	tion*1	50 mA max. 30 mA max.		30 mA max.	20 mA max.		30 mA max.	20 mA max.			
Resolutio rotation)	on (pulses/	100, 200, 360	, 500		1				10, 20, 60, 100, 200, 300, 360, 500		
Output pl	nases	Phases A, B, a	and Z		Phases A and B			Phase A			
Output co	onfiguration	Voltage out- put NPN open-collector output		Voltage out- put	NPN open-collector output		Voltage out- put	NPN open-collector output			
Cutput capacity Output capacity Output capacity Cutput capacity Max. (Output		Residual volt- age: 0.4 V max. (Output cur- rent: 20 mA	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)		Output resistance: $2 \ k\Omega$ Output current: 20 mA max. Residual voltage: 0.4 V max. (Output current: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)		Output resistance: $2 \ k\Omega$ Output cur- rent: 20 mA max. Residual voltage: 0.4 V max. (Output cur- rent: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)		
Maximum frequency	response y*2	30 kHz									
Phase dif between o		Phase differer	Phase difference between phases A and B: $90^{\circ}\pm45^{\circ}$								
Output du	uty factor	{					50±25%				
Rise and fall times of output		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)		
Starting to	orque	1 mN·m max.									
Moment o	of inertia	$1 \times 10^{-7} \text{ kg} \cdot \text{m}^2$	max.								
Shaft	Radial	10 N									
loading	Thrust	50 N									
Maximum permissit		5,000 r/min									
Ambient t range	emperature	Operating: -10	Operating: -10 to 55°C (with no icing), Storage: -25 to 80°C (with no icing)								
Ambient I range	humidity	Operating/storage: 35% to 85% (with no condensation)									
Insulatior	n resistance	20 M Ω min. (at 500 VDC) between current-carrying parts and case									
Dielectric	strength	500 VAC, 50/60 Hz for 1 min between current-carrying parts and case									
Vibration	resistance	Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions									
Shock res	sistance	Destruction: 5	00m/s ² 3 times	each in X, Y, an	d Z directions						
Degree of protection	f n*3	IEC 60529 IP50									
Connectio	on method	Pre-wired Models (Standard cable length: 500 mm)									
Material		Case: Aluminum alloy, Main unit: Aluminum, Shaft: SUS420J2, Mounting Bracket: Galvanized iron									
Weight (packed s	state)	Approx. 35 g									
Accessor	ies	Coupling, Servo Mounting Bracket (provided with the E6A2-CWZ), Hexagonal wrench, Instruction manual									
1 An inrus	sh ourront of a		A will flow for a	pprovimately 0	3 ms when the p	ower is turned	ON				

*1. An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.*2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

Maximum electrical response speed (rpm) = <u>Maximum response frequency</u> × 60 Resolution

This means that the E6A2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. *3. No protection is provided against water or oil.

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I/O Circuit Diagrams



Safety Precautions

Refer to Warranty and Limitations of Liability.

<u> WARNING</u>

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

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(Unit: mm)

Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

Encoder





Accessories (Order Separately)

Coupling Servo Mounting Bracket E69-C04B E69-1 Refer to Accessories for details.

Read and understand this catalog.

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