

Large Current External FET Controller Type Switching Regulators



Single-output Step-up, Negative Voltage, Step-down Switching Regulators (Controller type)

BD9300F/BD9300FV

● Description

The BD9300F/FV 1-channel DC/DC Step-up, step-down, and inverting converter controller.

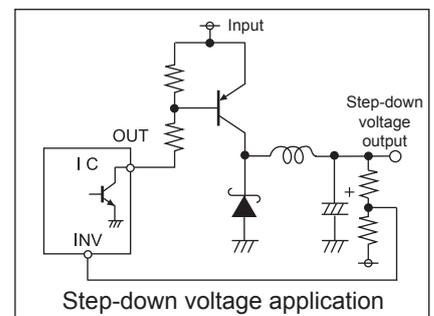
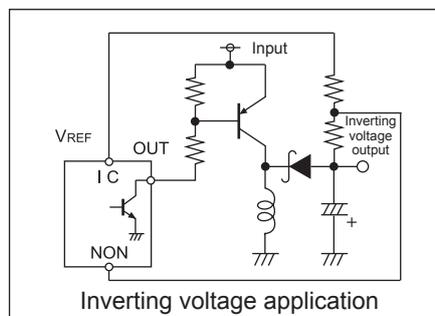
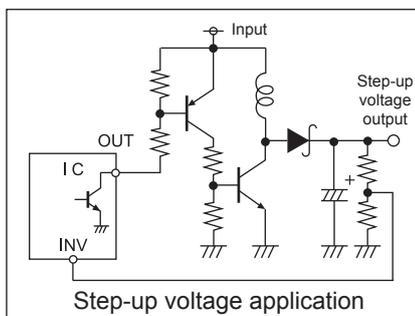
This IC has a wide input voltage range of 3.6 to 35 V, providing for a variety of applications. The pin assignment is similar to that of the BA9700, facilitating a space-saving application.

● Features

- 1) 1-channel PWM control DC/DC converter controller
- 2) High voltage input of 3.6 to 35 V
- 3) Reference voltage accuracy of $\pm 1\%$
- 4) Oscillation frequency variable in the range of 20 to 800 kHz
- 5) Built-in UVLO (Under Voltage Lock Out) circuit and SCP (Short Circuit Prevention) circuit
- 6) Current in standby mode: 0 μA (typ.)
- 7) Switching external synchronization available (Slave operation)
- 8) SSOP-B14 Package (for BD9300FV) or SOP14 Package (for BD9300F)

● Applications

- TV, power supply for liquid crystal display TV, and backlight
- DSC, DVD, printer, DVD/DVD recorder, and other consumer products



● Absolute maximum ratings(Ta=25°C)

Item	Symbol	Rating	Unit
Power supply voltage	Vcc	36	V
Power dissipation	Pd	400 *	mW
Operating temperature	Topr	-40 to +85	°C
Storage temperature	Tstg	-55 to +125	°C
Output current	Io	100 **	mA
Output voltage	Vo	36	V
Maximum junction temperature	Tjmax	125	°C

* Reduce by 4 mW/°C over 25°C, when mounted on a glass epoxy PCB of 70mmX70mmX1.6mm)

** Should not exceed Pd-value.

● Recommended operating range (Ta=25°C)

Item	Symbol	Limits			Unit
		Min	Typ	Max	
Power supply voltage	Vcc	3.6	12	35	V
Output sink current	Io	-	-	30	mA
Output voltage	Vo	-	-	35	V
Timing capacitance	CT	33	-	1000	pF
Timing resistance	RT	5	-	100	kΩ
Oscillation frequency	Fosc	20	-	800	kHz

● Electrical characteristics (Unless otherwise specified, Ta=25°C, Vcc=12V, CT=200pF, RT=20kΩ)

Item	Symbol	Limits			Unit	Conditions
		Min	Typ	Max		
[Reference voltage block]						
Reference voltage	VREF	2.475	2.500	2.525	V	IREF=1mA
Input stability	VDLI	-	1.5	20	mV	Vcc=3.6 to 35V IREF=1mA
Load stability	VULD	-	0.5	20	mV	IREF=0 ~ 1mA
1/2 reference voltage	1/2VREF	1.212	1.25	1.288	V	
[Triangular wave oscillator block]						
Oscillation frequency	FOSC	165	220	275	kHz	
Charge mode threshold voltage	VOSC+	-	1.95	-	V	
Discharge mode threshold voltage	VOSC-	-	1.45	-	V	
Frequency variation	FDVO	-	1	-	%	Vcc=3.6 to 35V
[Protection circuit block]						
Threshold voltage	VIT	1.5	1.8	2.1	V	
Charge current	Iscp	-	7	11	μA	
[Rest period adjustment circuit block]						
Upper limit threshold voltage	VtH	2.05	-	-	V	Duty Cycle=0%
Lower limit threshold voltage	VtL	-	-	1.35	V	Duty Cycle=100%
Input bias current	Ibd	-	0.1	1	μA	DTC=1.5V
Latch mode charge current	Idtc	200	500	-	μA	DTC=0V
[Under voltage lock out block]						
Threshold voltage	VUT	-	2.8	-	V	

○ Not designed to be radiation-resistant.

● Electrical characteristics (Unless otherwise specified, $T_a=25^\circ\text{C}$, $V_{cc}=12\text{V}$, $C_T=200\text{pF}$, $R_T=20\text{k}\Omega$)

Item	Symbol	Limits			Unit	Conditions
		Min	Typ	Max		
[Error amplifier block]						
Input bias current	I_{IB}	–	0.1	1	μA	
Open loop gain	A_V	–	85	–	dB	Null AMP
Maximum output voltage	V_{OH}	2.3	2.5	–	V	
Minimum output voltage	V_{OL}	–	0.7	0.9	V	
Output sink current	I_{OI}	0.1	1	–	mA	$V_{FB}=1.25\text{V}$
Output source current	I_{OO}	40	70	–	μA	$V_{FB}=1.25\text{V}$
[Output block]						
Saturation voltage	V_{SAT}	–	1.0	1.4	V	$I_o=30\text{mA}$
Leak current	I_{LEAK}	–	–	10	μA	$OUT=35\text{V}$
[Control block]						
CTL ON voltage	V_{ON}	2	–	–	V	
CTL OFF voltage	V_{OFF}	–	–	0.7	V	
CTL sink current	I_{CTL}	–	57	90	μA	$V_{CTL}=5\text{V}$
[Whole device]						
Standby current	I_{STB}	–	0	10	μA	$V_{CTL}=0\text{V}$
Average supply current	I_{CC}	–	1.2	2.4	mA	$R_T=V_{REF}$

○ Not designed to be radiation-resistant.

● Measurement circuit diagram

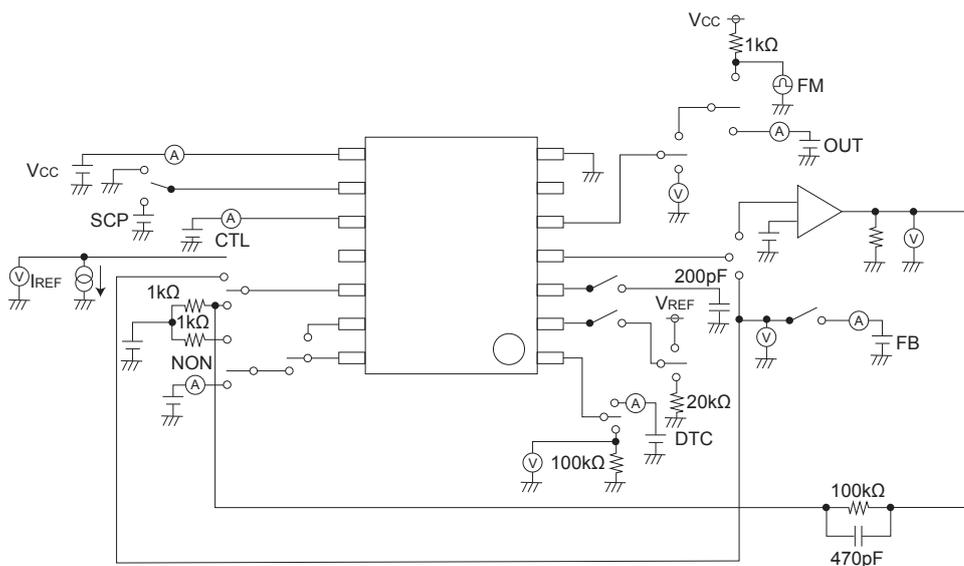


Fig. 1 Typical measurement circuit

● Reference characteristics data (Unless otherwise specified, Ta=25°C)

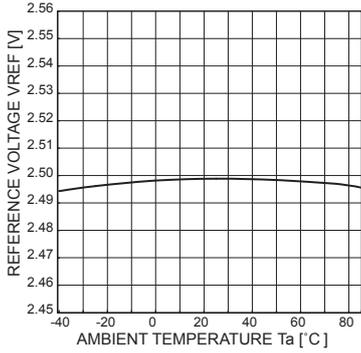


Fig.2 Reference voltage vs. Ambient temperature

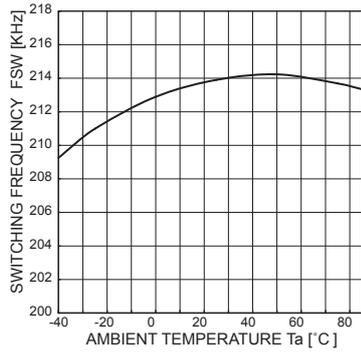


Fig.3 Switching frequency vs. Ambient temperature

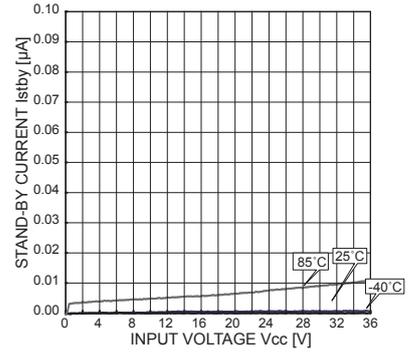


Fig.4 Standby current

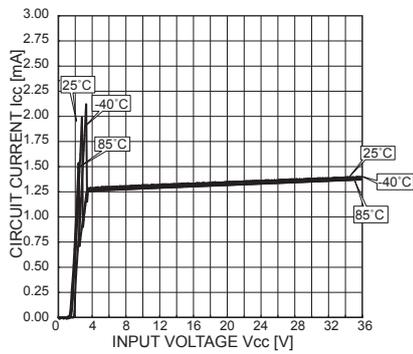


Fig.5 Circuit current

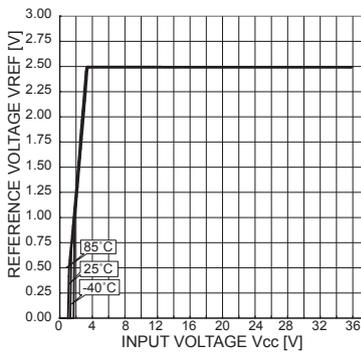


Fig.6 Reference voltage

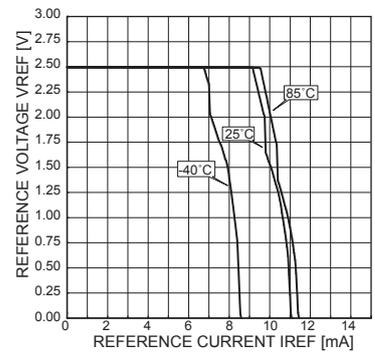


Fig.7 Reference voltage vs. Output current

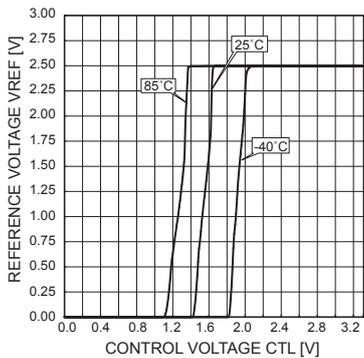


Fig.8 Control threshold voltage

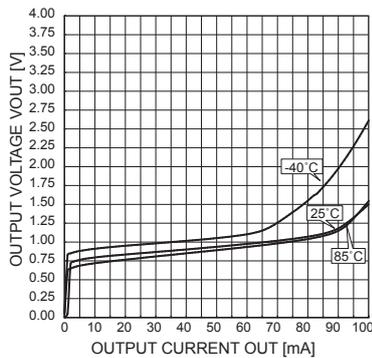


Fig.9 Output current capacitance

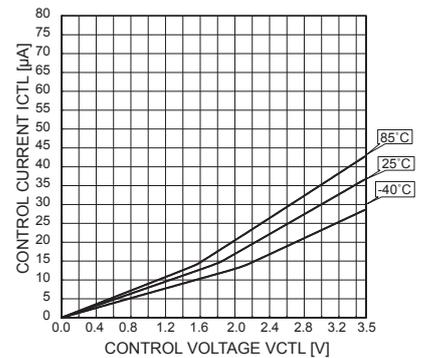
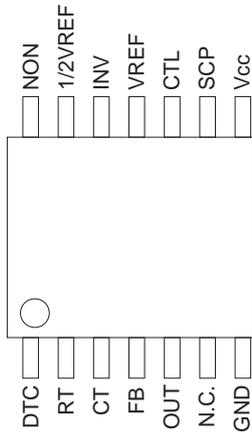


Fig.10 Control sink current

● Pin assignment



● Block diagram

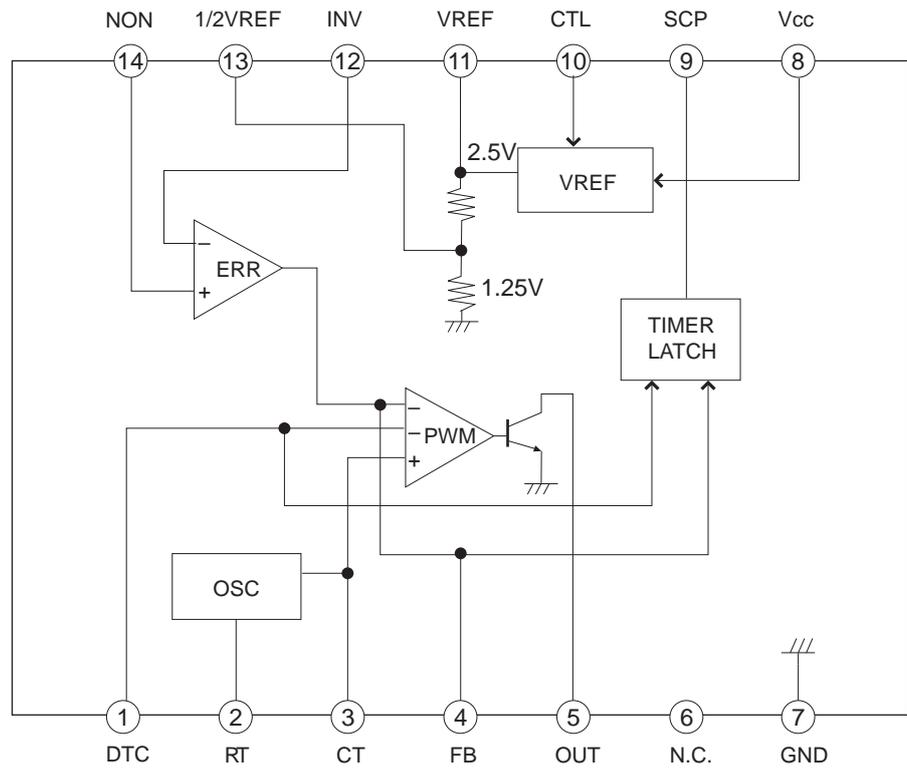


Fig. 11 Pin assignment / Block diagram

● Pin assignment and function

Pin No.	Pin name	Function
1	DTC	Rest period setting voltage input
2	RT	External timing resistance
3	CT	External timing capacitance
4	FB	Error amplifier output
5	OUT	PWM output (open collector)
6	N.C.	–
7	GND	Ground
8	Vcc	Power supply
9	SCP	External timer latch setting capacitance (Ground if not used)
10	CTL	Control input
11	VREF	Reference voltage output
12	INV	Inverting input for error amplifier
13	1/2VREF	1/2 reference voltage output
14	NON	Non-inverting input for error amplifier

● Timing chart

· Basic operation

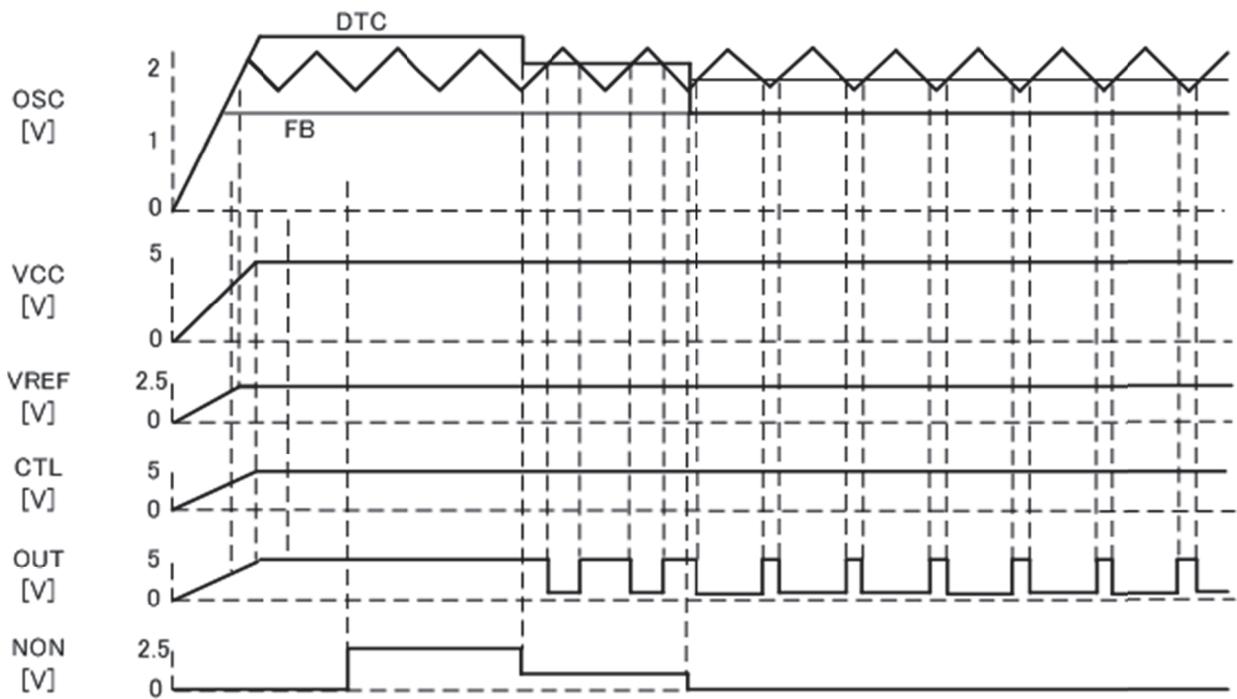


Fig. 13 Basic operation

· When the short circuit protection is activated

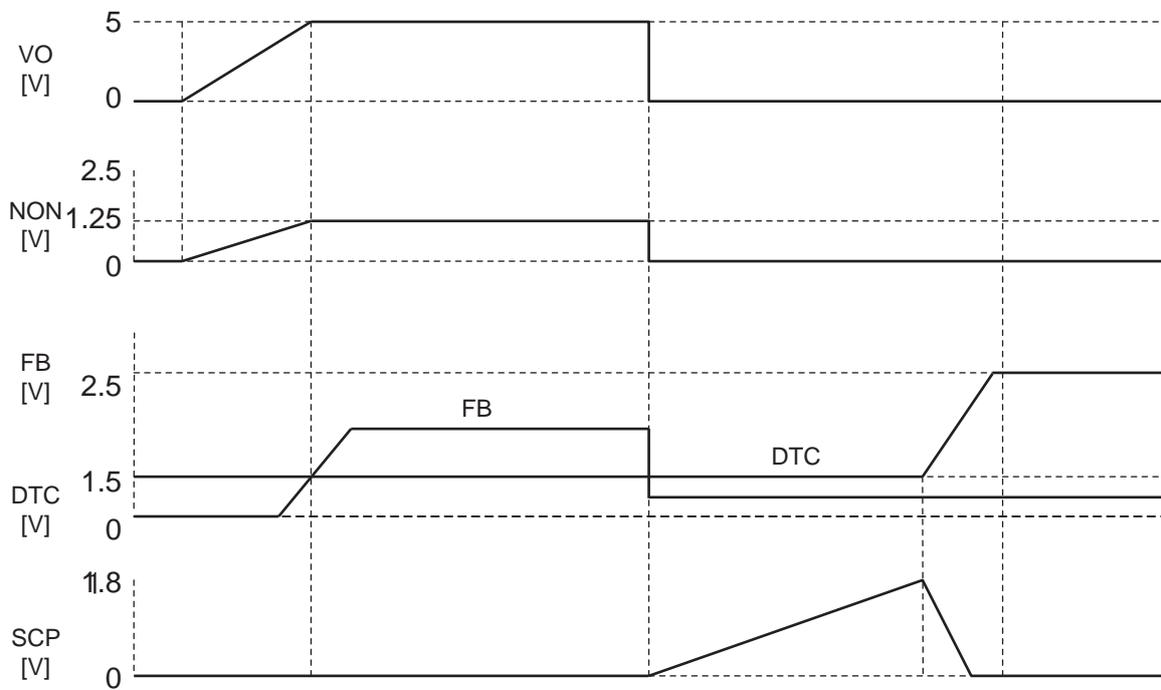


Fig. 14 Timing when the short circuit protection is activated

● External component setting procedure

(1) Design of feedback resistance constant

Set step-down, step-up, and inverting feedback resistance as shown below. Set resistance in the range of 1 kΩ to 330 kΩ. Setting the resistance to 1 kΩ or less will result in degraded power efficiency, while setting it to 330 kΩ or more will increase the offset voltage due to the input bias current of 0.1μA (TYP) of the error amplifier.

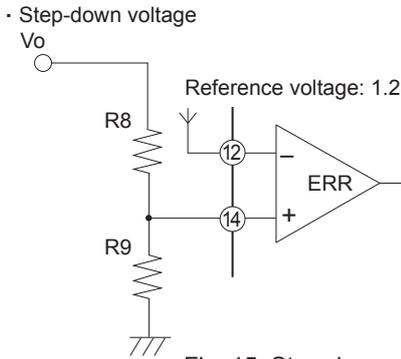


Fig. 15 Step-down voltage

$$V_o = \frac{R8+R9}{R9} \times 1.25 \text{ [V]}$$

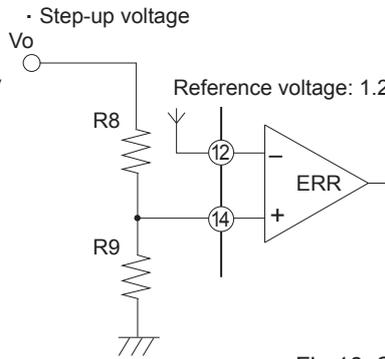


Fig.16 Step-up voltage

$$V_o = \frac{R8+R9}{R9} \times 1.25 \text{ [V]}$$

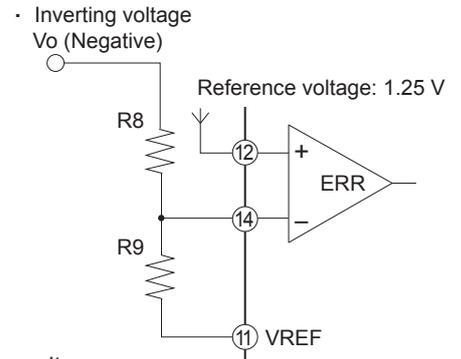


Fig. 17 Inverting voltage

$$V_o = 1.25 \left(1 - \frac{R8}{R9} \right) \text{ [V]}$$

(2) Setting of oscillation frequency

Connecting a resistor and capacitor to the RT pin (pin 2) and the CT pin (pin 3) will set the triangular wave oscillation frequency. The RT determines the charge/discharge current to the capacitor. Referring to Fig. 18, set RT resistor and the CT capacitor. Recommended setting ranges are 5 to 100 kΩ for the CT resistor, 33 to 1000 pF for the CT capacitor, and 20 kHz to 800 kHz for the oscillation frequency. Any setting outside of these ranges may turn OFF switching, thus impairing the operation guarantee.

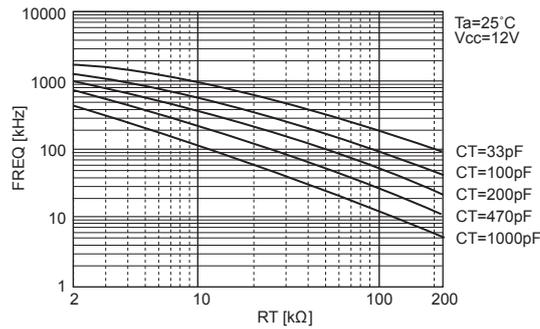


Fig. 18 RT/CT vs. Frequency

(3) Setting of DTC voltage

Applying the VDTC voltage to the DTC pin (pin 1) will fix the maximum duty ratio. This will serve to prevent the power transistor (FET) from being FULL ON. Fig. 19 shows the relationship between the DTC voltage and the maximum duty ratio. Referring to this Figure, set the DTC voltage. Next, generate the VDTC by dividing the VREF voltage with resistance and then input the VDTC in the DTC pin.

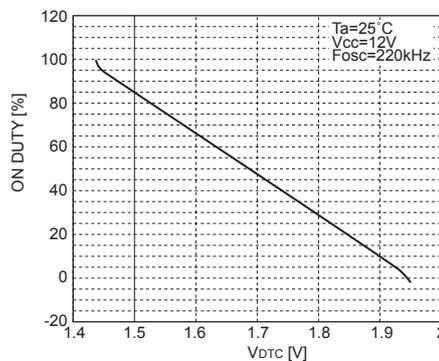


Fig. 19 DTC voltage vs. Maximum duty

Furthermore, the maximum duty ratio should be designed so as not to become a maximum duty for the normal use. The following section shows ranges for the normal use.

• Step-down voltage

$$ONDutyMAX = \frac{VOMAX}{VCCMIN}$$

• Step-up voltage

$$ONDutyMAX = \frac{VOMAX - VOMIN}{VOMAX}$$

• Inverting voltage

$$ONDutyMAX = \frac{VOMAX}{VOMAX - VCCMIN}$$

(4) Setting of soft start time

Adding a capacitor to the DTC resistance divider will enable the soft start function activation.

The soft start function will be required to prevent an excessive increase in the coil current and overshoot of the output voltage, while in startup operation. Fig. 20 shows the relationship between the capacitor and the soft start time. Referring to this Figure, set the capacitor. It is recommended to set the capacitance value in the range of 0.01 to 10 μF . Setting the capacitance value to 0.01 μF or less, may cause overshoot to the output voltage, while setting it to 10 μF or more may cause an inverse current in the internal parasitic diode when the power supply is grounded, thus resulting in damage to the internal element.

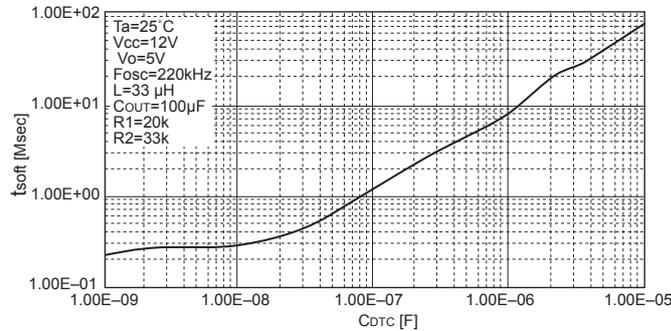


Fig. 20 Soft start capacitance vs. Delay time

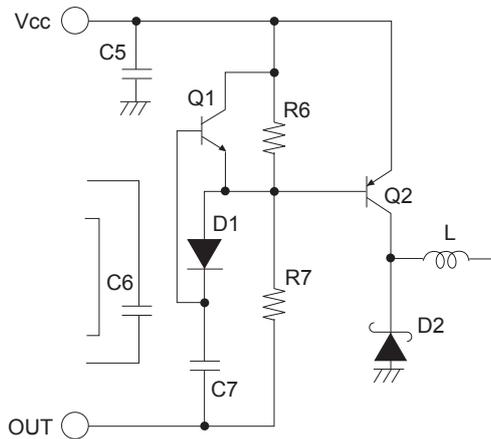


Fig. 21 ON/OFF peak circuit

Since the PNP Tr is generally slow in switching, in terms of the sat characteristics, the ON/OFF peak circuit is used as an acceleration circuit. The D1 and the C7 generate an ON peak current, while the Q1 and the C7 forms an OFF peak circuit. Set pull-up resistance to 510 Ω as a guide at VCC=12 V. It is recommended to set this resistance in the range of 100 k Ω to 10 k Ω . In order to make adjustment of the R6 and R7, however, pay attention of the points listed in table below.

NO.	Item	To reduce R6	To reduce R7
1	Efficiency	Degraded	Degraded
2	Tr Turn ON / Turn OFF	Faster Turn OFF	Faster Turn OFF
3	Switching frequency	Increasable	Increasable
4	Load current capacitance	Degraded	Degraded

Take 1000 pF as a guide for the C7 setting. If the ON/OFF peak currents are inadequate, increase the C7 capacitance value. It is recommended to set capacitance values in the range of 100 pF to 10000 pF. Setting the capacitance value to 10000 pF or more may increase the peak current and degrade the power efficiency.

(6) Phase compensation

Phase compensation setting procedure

The phase compensation setting procedure varies with the selection of output capacitors used for DC/DC converter application. In this connection, the following section describes the procedure by classifying into the two types. Furthermore, the application stability conditions are described in the Description section.

1. Application stability conditions
2. For output capacitors having high ESR, such as electrolytic capacitor
3. For output capacitors having low ESR, such as ceramic capacitor or OS-CON

1. Application stability conditions

The following section shows the stability conditions of negative feedback system.

- DSC, DVD, printer, DVD/DVD recorder, and other consumer products At a 1 (0-dB) gain, the phase delay is 150° or less (i.e., the phase margin is 30° or more).

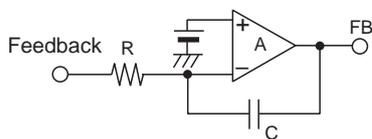
Furthermore, since the DC/DC converter application is sampled according to the switching frequency, GBW of the overall system should be set to 1/10 or less of the switching frequency. The following section summarizes the targeted characteristics of this application.

- DSC, DVD, printer, DVD/DVD recorder, and other consumer products At a 1 (0-dB) gain, the phase delay is 150° or less (i.e., the phase margin is 30° or more).
- DSC, DVD, printer, DVD/DVD recorder, and other consumer products The GBW (i.e., frequency at 0-dB gain) for this occasion is 1/10 or less of the switching frequency.

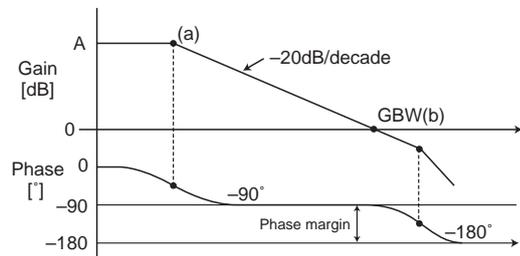
In other words, the responsiveness is determined with restrictions on the GBW. Consequently, in order to upgrade the responsiveness, higher switching frequency should be provided.

In order to ensure the stability through the phase compensation, a secondary phase delay (-180°) resulting from LC resonance should be canceled with a secondary phase lead (i.e., through inserting two phase leads). Furthermore, the GBW (i.e., frequency at 1-dB gain) is determined according to phase compensation capacitance to be provided for the error amplifier. Consequently, in order to reduce the GBW, increase the capacitance value.

(1) Typical (sun) integrator (Low pass filter)



(2) Open loop characteristics of (mon) integrator



(a) point $f_a = \frac{1}{2\pi R C A}$ [Hz]

(b) point $f_b = \text{GBW} = \frac{1}{2\pi R C}$ [Hz]

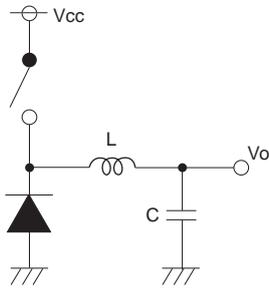
Fig. 22 Typical integrator characteristics

Since the error amplifier is provided with (sun) or (mon) phase compensation, the low pass filter is applied. In the case of the DC/DC converter application, the R becomes a parallel resistance of the feedback resistance.

2. For output capacitors having high ESR, such as aluminum electrolytic capacitor

For output capacitors having high ESR (i.e., several ohms), the phase compensation setting procedure becomes comparatively simple. Since the DC/DC converter application has a LC resonant circuit attached to the output, a -180° phase-delay occurs in that area. If ESR component is present there, however, a $+90^\circ$ phase-lead occurs to shift the phase delay to -90° . Since the phase delay is desired to set within 150° , this is a very effective method but has a demerit to increase the ripple component of the output voltage.

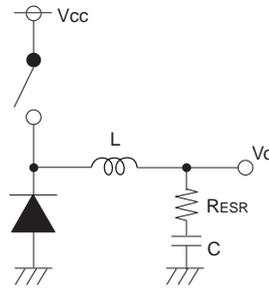
(3) LC resonant circuit



$$f_z = \frac{1}{2\pi\sqrt{LC}} \text{ [Hz]}$$

At this resonance point, a -180° phase-delay occurs.

(4) With ESR provided



$$f_z = \frac{1}{2\pi\sqrt{LC}} \text{ [Hz]} : \text{Resonance point}$$

$$f_{ESR} = \frac{1}{2\pi \text{RESR}C} \text{ [Hz]} : \text{Phase lead}$$

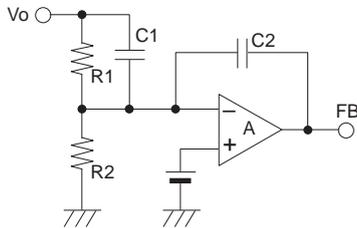
A -90° phase-delay occurs.

* Same for the phase compensation of inverting and step-up voltages

Fig. 23 DC/DC converter output application

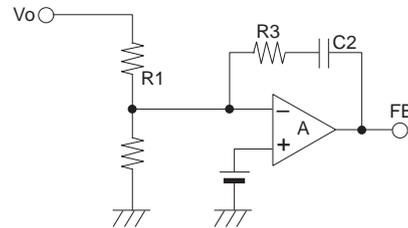
According to changes in phase characteristics due to the ESR, only one phase lead should be inserted. For this phase lead, select either of the methods shown below:

(5) Insert feedback resistance in the C.



$$\text{Phase lead: } f_z = \frac{1}{2\pi C_1 R_1} \text{ [Hz]}$$

(6) Insert the R3 in integrator.



$$\text{Phase lead: } f_z = \frac{1}{2\pi C_2 R_3} \text{ [Hz]}$$

Fig. 24 Typical phase compensation circuit

To cancel the LC resonance, phase lead frequency should be set close to the LC resonant frequency.

3. For output capacitors having low ESR, such as a ceramic capacitor or OS-CON

In order to use capacitors having low ESR (i.e., several tens of mW), two phase-leads should be inserted so that a -180° phase-delay, due to LC resonance, will be compensated. The following section shows a typical phase compensation procedure.

· Phase compensation with secondary phase lead

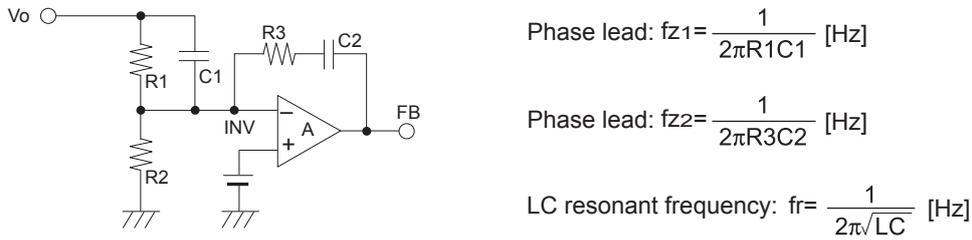


Fig. 25 Typical circuit after secondary compensation circuit

For the settings of phase lead frequency, insert both of the phase leads close to the LC resonant frequency.

Phase compensation on the BD9300F/FV

For BD9300F/FV, since the error amplifier input is inverted to the normal input, the phase compensation procedure is slightly different. (The BD9300F/FV returns feedback to the NON pin.)

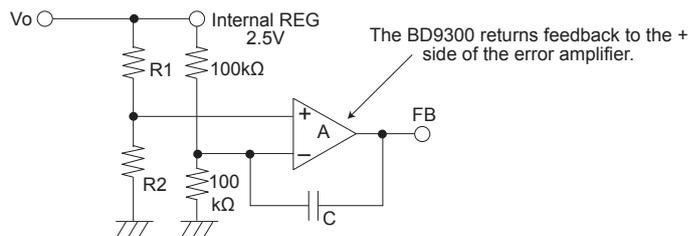


Fig. 26 Typical circuit after phase compensation on BD9300F/FV

The BD9300F/FV feeds back on the + side input and returns the phase compensation on the - side input. Consequently, resistance of the resistance divider being used to determine the reference voltage has influence on the frequency characteristics. (The BD9300F/FV has a 1/2 VREF pin to divide resistance by 100 kΩ.)

The following section shows the phase characteristics.

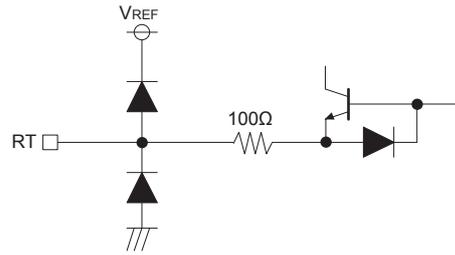
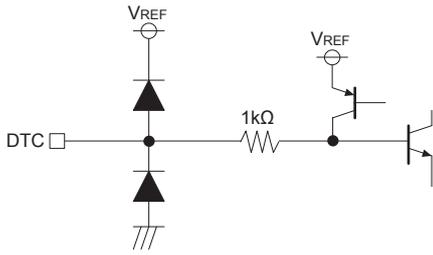
$$\text{Primary phase delay: } fp = \frac{1}{2\pi C \frac{100k\Omega}{2} (1+A)} \text{ [Hz], where A is approximately 80 dB.}$$

$$\text{Phase lead: } fz = \frac{1}{2\pi C \frac{100k\Omega}{2}} \text{ [Hz]}$$

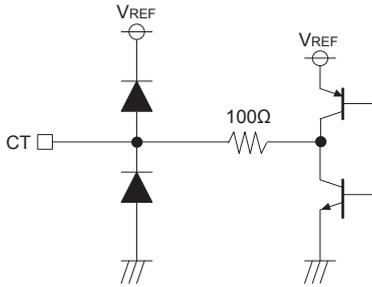
As a result, inserting a phase compensation capacitor will cause phase lead component. If any further phase lead is required, add a capacitor in parallel with the R1.

● Equivalent circuit

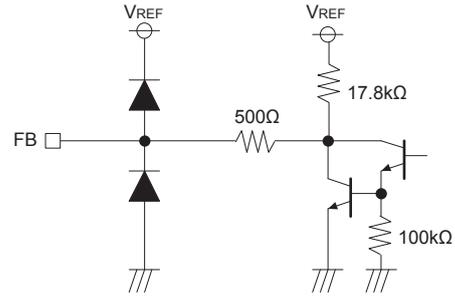
(1) DTC



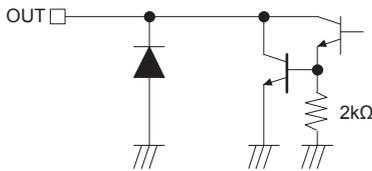
(3) CT



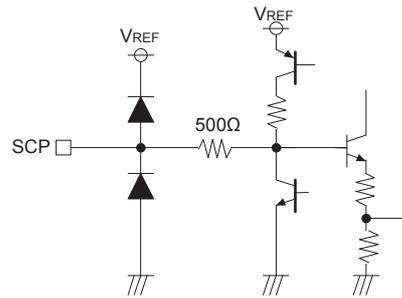
(4) FB



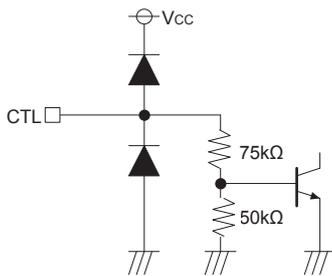
(5) OUT



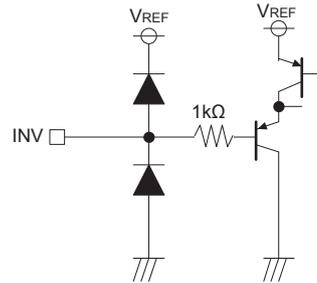
(9) SCP



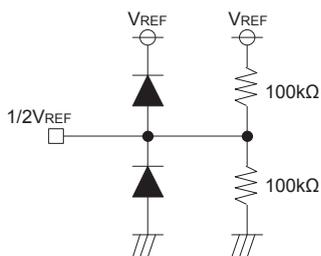
(10) CTL



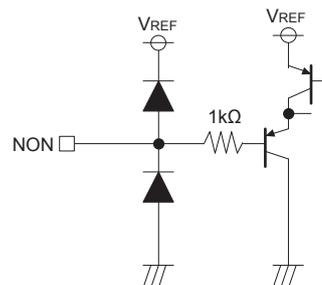
(12) INV



(13) 1/2VREF



(14) NON



● Cautions on use

1) Absolute maximum ratings

An excess in the absolute maximum ratings, such as supply voltage, temperature range of operating conditions, etc., can break down the devices, thus making impossible to identify breaking mode, such as a short circuit or an open circuit. If any over rated values will expect to exceed the absolute maximum ratings, consider adding circuit protection devices, such as fuses.

2) GND potential

Ground-GND potential should maintain at the minimum ground voltage level. Furthermore, no terminals should be lower than the GND potential voltage including an electric transients.

3) Thermal design

Use a thermal design that allows for a sufficient margin in light of the power dissipation (P_d) in actual operating conditions.

4) Inter-pin shorts and mounting errors

Use caution when positioning the IC for mounting on printed circuit boards. The IC may be damaged if there is any connection error or if positive and ground power supply terminals are reversed. The IC may also be damaged if pins are shorted together or are shorted to other circuit's power lines.

5) Operation in strong electromagnetic field

Use caution when using the IC in the presence of a strong electromagnetic field as doing so may cause the IC to malfunction.

6) Testing on application boards

When testing the IC on an application board, connecting a capacitor to a pin with low impedance subjects the IC to stress. Always discharge capacitors after each process or step. Always turn the IC's power supply off before connecting it to, or removing it from a jig or fixture, during the inspection process. Ground the IC during assembly steps as an antistatic measure. Use similar precaution when transporting and storing the IC.

7) IC pin input

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements to keep them isolated. PñN junctions are formed at the intersection of these P layers with the N layers of other elements, creating a parasitic diode or transistor. For example, the relation between each potential is as follows:

○ When $GND > Pin A$ and $GND > Pin B$, the PñN junction operates as a parasitic diode.

○ When $Pin B > GND > Pin A$, the PñN junction operates as a parasitic transistor^f.

Parasitic diodes can occur inevitably in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Accordingly, methods by which parasitic diodes operate, such as applying a voltage that is lower than the GND (P substrate) voltage to an input pin, should not be used.

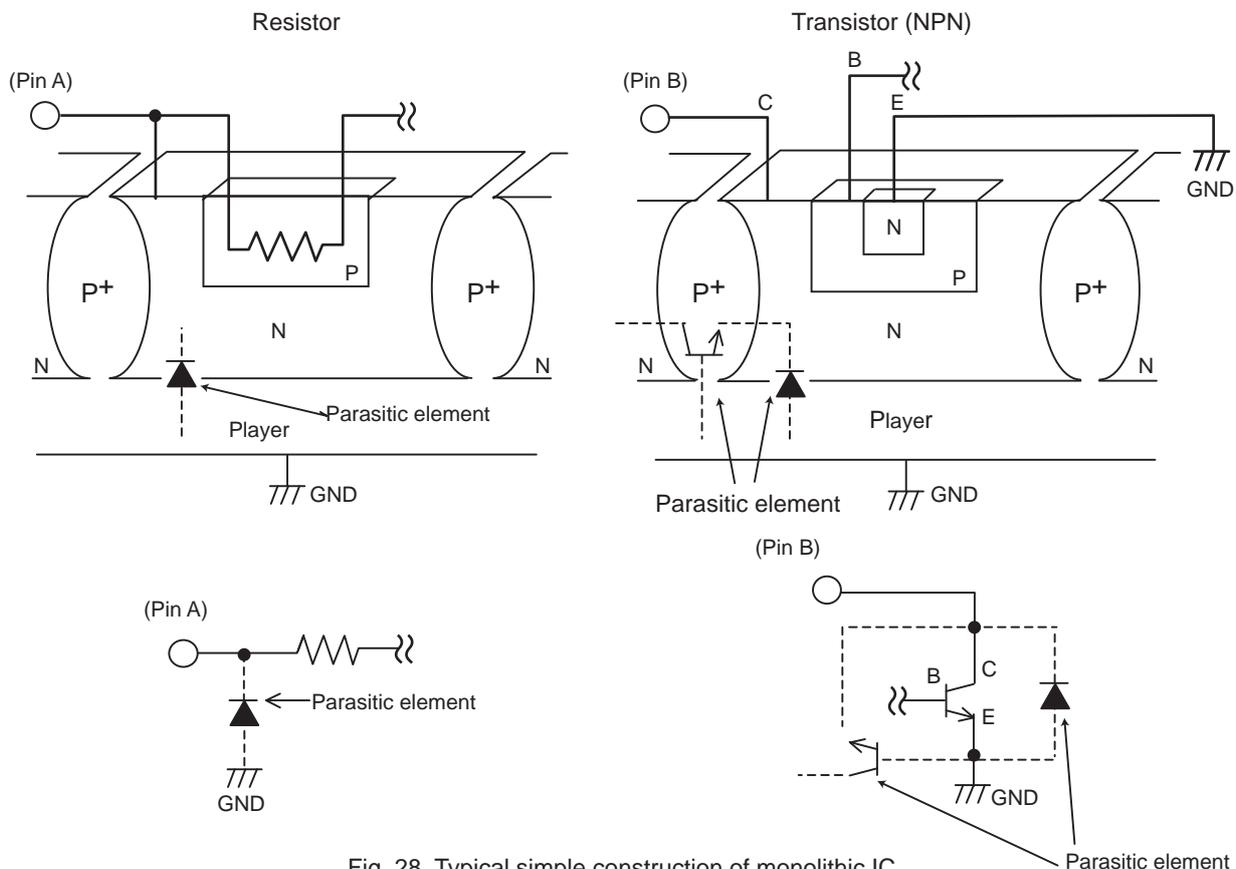


Fig. 28 Typical simple construction of monolithic IC

8) Ground wiring pattern

The power supply and ground lines must be as short and thick as possible to reduce line impedance. Fluctuating voltage on the power ground line may damage the device.

● Derating curve

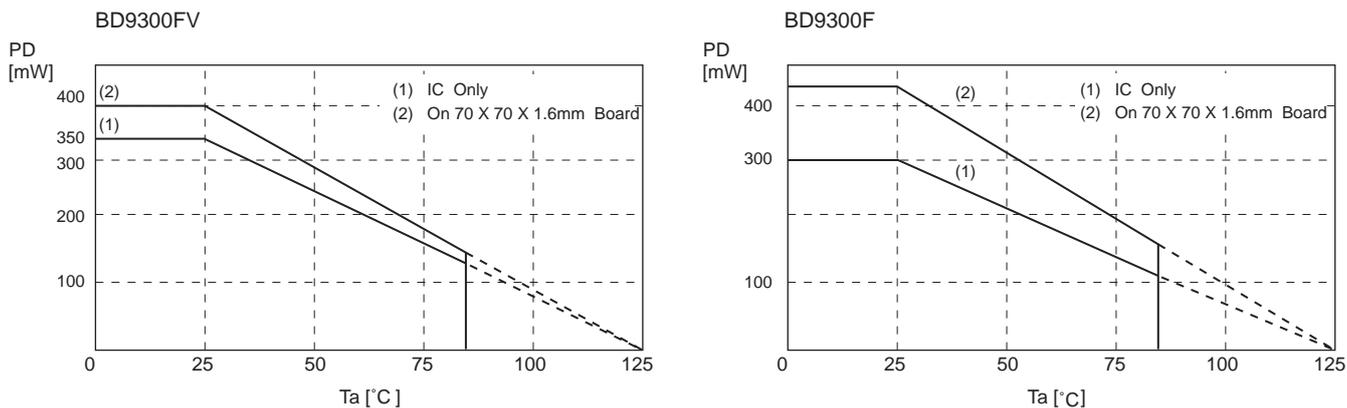
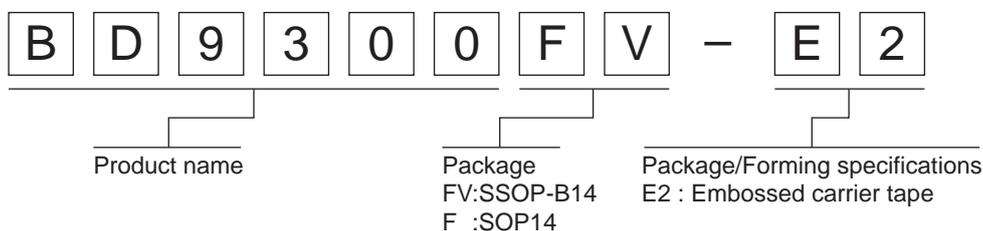


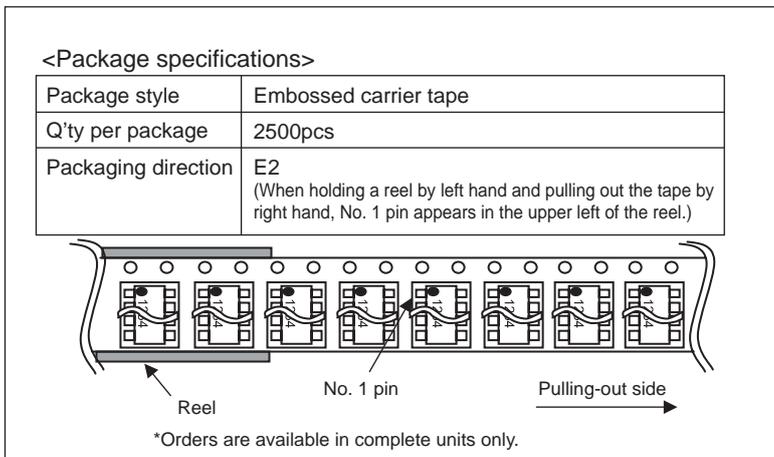
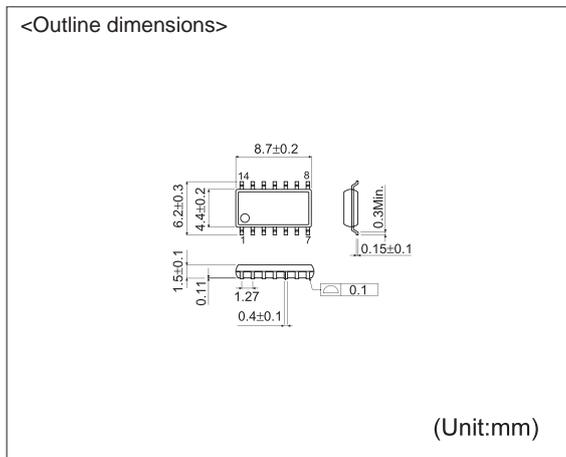
Fig. 29 Thermal derating characteristics

● Selection of order type

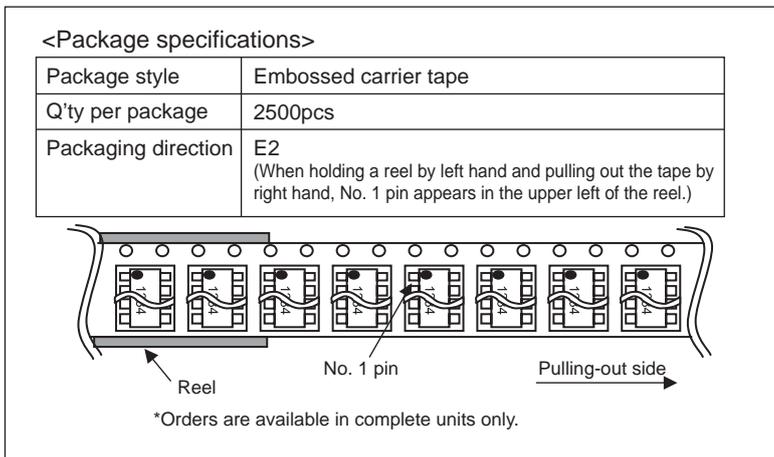
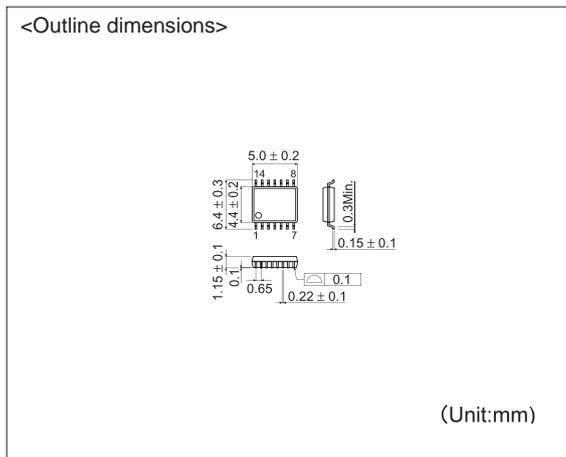


● Package specifications

SOP14



SSOP-B14



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JAPAN	USA	EU	CHINA
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 - Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
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 - Use of the Products in places subject to dew condensation
- The Products are not subject to radiation-proof design.
- Please verify and confirm characteristics of the final or mounted products in using the Products.
- In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
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- ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

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- When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
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 - [c] the Products are exposed to direct sunshine or condensation
 - [d] the Products are exposed to high Electrostatic
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