

# Low-Power 3.3V-Supply Full-Duplex RS-485 Driver/Receiver

Check for Samples: SN65HVD37

### **FEATURES**

- Low-Current Standby Mode: <1 µA Typical</li>
- Operational Quiescent Current < 1 mA</li>
- High Receiver Hysteresis for Noise Immunity (60 mV Typical)
- 1/8 Unit-Load (Up to 256 Nodes on the Bus)
- Bus-pin ESD Protection Exceeds 15 kV HBM
- Driver Output Transition Times Optimized for Signaling Rate up to 20 Mbps
- Glitch-Free Power-Up and Power-Down Protection for Hot-Plugging Applications
- 5V-Tolerant Logic Inputs
- Bus Idle, Open, and Short-Circuit Failsafe
- · Driver Current Limiting and Thermal Shutdown
- Fully Meets All TIA-485-A Specifications

## **APPLICATIONS**

- Telecommunications Equipment
- Industrial Automation
- Process Automation
- Building Automation
- Point-of-Sale (POS) Terminals
- Improved Replacement for ADM3076, ADM3491, LTC2852, MAX3491 and SP3491

#### DESCRIPTION

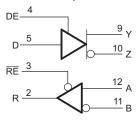
The SN65HVD37 combines a robust differential driver and a receiver with high noise immunity for demanding industrial applications. The driver differential outputs and the receiver differential inputs are separate pins, to form a bus port for full-duplex (four-wire) communications. The driver and receiver can be independently enabled, and feature a wide common-mode voltage range, making this device suitable for multi-point applications over long cable runs. The SN65HVD37 is characterized over the temperature range of -40°C to 85 °C.

### **D PACKAGE (TOP VIEW)**

NC	1	14	V <sub>cc</sub>
R	2	13	$\square$ $V_{CC}$
RE	3	12	A
DE	4	11	В
D	5	10	Z
GND	6	9	Y
GND	7	8	NC

NC - No internal connection

#### LOGIC DIAGRAM (POSITIVE LOGIC)



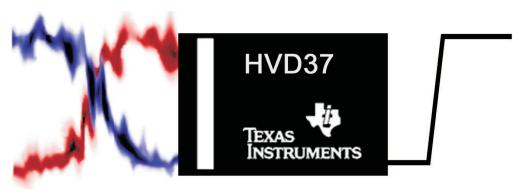


Figure 1. 60 mV Receiver Hysteresis for Noise Immunity



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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

# **ABSOLUTE MAXIMUM RATINGS**(1)

		VALUE/UNITS	
$V_{CC}$	Supply voltage		–0.5 V to 7 V
	Voltage range at A, B	, Y, Z pins	–13 V to 13 V
	Input voltage range a	–0.3 V to 5.7 V	
	Voltage range, transie	–25 V to 25 V	
	Receiver output curre	-24 mA to 24 mA	
TJ	Junction temperature		170°C
	Continuous total power	er dissipation	(see Thermal Table)
	IEC 60749-26 ESD	(Human Body Model), bus terminals and GND	±16 kV
	JEDEC Standard 22	Test Method A114 (Human Body Model), all pins	±5 kV
	JEDEC Standard 22	Test Method C101 (Charged Device Model), all pins	±1.5 kV
	JEDEC Standard 22	Test Method A115 (Machine Model), all pins	±150 V

<sup>(1)</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### THERMAL INFORMATION

		SN65HVD37	
	THERMAL METRIC <sup>(1)</sup>	D	UNITS
		14 PINS	
$\theta_{JA}$	Junction-to-ambient thermal resistance	79.3	
$\theta_{JCtop}$	Junction-to-case (top) thermal resistance	44.8	
$\theta_{JB}$	Junction-to-board thermal resistance	33.5	°C/W
ΨЈТ	Junction-to-top characterization parameter	13.3	
$\Psi_{JB}$	Junction-to-board characterization parameter	33.3	

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

#### RECOMMENDED OPERATING CONDITIONS

			MIN	NOM	MAX	UNIT
$V_{CC}$	Supply voltage <sup>(1)</sup>		3	3.3	3.6	V
$V_{I}$	Input voltage at a	any bus terminal (separately or common mode) (2)	-7		12	V
$V_{IH}$	High-level input	voltage (Driver, driver enable, and receiver enable inputs)	2		VCC	V
$V_{IL}$	Low-level input v	oltage (Driver, driver enable, and receiver enable inputs)	0		0.8	V
$V_{\text{ID}}$	Differential input	voltage	-12		12	V
	Output current	Driver			60	A
IO		Receiver	-8		8	mA
$R_L$	High-level input voltage (Driver, driver enable, and receiver enable inputs)  Low-level input voltage (Driver, driver enable, and receiver enable inputs)  Differential input voltage  Output current  Driver Receiver  Differential load resistance  Differential load capacitance  Signaling rate  HVD37  Operating free-air temperature (See application section for thermal information)  2 VCG  0 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0				Ω	
$C_L$	Differential load	capacitance		50		pF
	Signaling rate	HVD37			20	Mbps
T <sub>A</sub>	Operating free-a	ir temperature (See application section for thermal information)	-40		85	°C
$T_{J}$	Junction Temper	ature	-40		150	°C

<sup>(1)</sup> Both pins 13 and 14 should be connected to the supply voltage; both pins 6 and 7 should be connected to ground.

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<sup>2)</sup> The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.



# **ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST COND	MIN	TYP	MAX	UNIT	
		See Figure 1, $R_L$ = 60 $\Omega$ , $V_{CC}$ 375 $\Omega$ on each output to –7 V	1.5	1.9		٧	
$ V_{OD} $	Driver differential output voltage magnitude	$R_L = 54 \Omega (RS-485)$			2		V
	magnitude	$R_L = 100 \Omega \text{ (RS-422)},$ See Figure 3 $T_J \ge 25^{\circ}\text{C}, V_{CC} \ge 3.3 \text{ V}$		2	2.2		>
$\Delta  V_{OD} $	Change in magnitude of driver differential output voltage	$R_L = 54 \Omega, C_L = 50 pF$		-0.1	0	0.1	V
V <sub>OC(SS)</sub>	Steady-state common-mode output voltage			1.5	V <sub>CC</sub> /2	2.5	٧
$\Delta V_{OC}$	Change in differential driver output common-mode voltage	Center of two 27- $\Omega$ load resistors, $C_L = 50 \text{ pF}$	SAA FIGURA 3				٧
V <sub>OC(PP)</sub>	Peak-to-peak driver common-mode output voltage			400		mV	
$C_{ID}$	Differential input capacitance	A, B			3		pF
$C_{OD}$	Differential output capacitance	Y, Z			14		pF
V <sub>IT+</sub>	Positive-going receiver differential input voltage threshold		See (1)	-60	-20	mV	
V <sub>IT-</sub>	Negative-going receiver differential input voltage threshold		-200	-120	See (1)	mV	
$V_{HYS}$	Receiver differential input voltage threshold hysteresis ( $V_{IT+} - V_{IT-}$ )		30	60		mV	
$V_{OH}$	Receiver high-level output voltage	$I_{OH} = -8 \text{ mA}$	I <sub>OH</sub> = -8 mA				<b>V</b>
$V_{OL}$	Receiver low-level output voltage	$I_{OL} = 8 \text{ mA}$			0.2	0.4	٧
I	Driver input, driver enable, and receiver enable input current			-2		2	μΑ
l <sub>OZ</sub>	Receiver output high-impedance current	$V_O = 0 \text{ V or } V_{CC}, \overline{RE} \text{ at } V_{CC}$		-1		1	μΑ
Ios	Driver short-circuit output current			-250		250	mA
-	Due input current (dischlad driver)	V <sub>CC</sub> = 3 to 3.6 V or	V <sub>I</sub> = 12 V		75	125	
	Bus input current (disabled driver)	$V_{CC} = 0 \text{ V}$ , DE at 0 V	$V_I = -7 V$	-100	-40		μA
		Driver and Receiver enabled	DE = V <sub>CC</sub> , RE = GND		720	850	μΑ
	Supply current stoody state as load	Driver enabled, receiver disabled	$DE = V_{CC}$ , $RE = V_{CC}$			400	μΑ
I <sub>CC</sub>	Supply current, steady-state, no load (quiescent)	Driver disabled, receiver enabled	DE = GND, RE = GND			800	μΑ
		Driver and receiver disabled (standby) $DE = GND, D = open, RE = V_{CC}$			0.2	1	μΑ
	Supply current (dynamic)	See "TYPICAL CHARAC	TERISTICS" section				

<sup>(1)</sup> Under any specific conditions,  $V_{\text{IT+}}$  is assured to be at least  $V_{\text{HYS}}$  higher than  $V_{\text{IT-}}$ .



# **SWITCHING CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS			TYP	MAX	UNIT
DRIVER							
t <sub>r</sub> , t <sub>f</sub>	Driver differential output rise/fall time		3	6	14		
t <sub>PHL</sub> , t <sub>PLH</sub>	Driver propagation delay	$R_L = 54 \Omega$ , $C_L = 50 pF$ , Se	$R_L = 54 \Omega$ , $C_L = 50 pF$ , See Figure 4		10	20	ns
t <sub>SK(P)</sub>	Driver pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub>				1		
t <sub>PHZ</sub> , t <sub>PLZ</sub>	Driver disable time	See Figure 5 and Figure 6		20	50	ns	
	Driver enable time	Receiver enabled Receiver disabled See Figure 5 and Figure 6			8	25	ns
t <sub>PZH</sub> , t <sub>PZL</sub>	Driver enable time				2.6	8	μs
RECEIVER							
t <sub>r</sub> , t <sub>f</sub>	Receiver output rise/fall time			2	5	9	ns
t <sub>PHL</sub> , t <sub>PLH</sub>	Receiver propagation delay time	C 15 pF See Figure 7		40	50	75	ns
t <sub>SK(P)</sub>	Receiver pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>	- C <sub>L</sub> = 15 pF, See Figure 7			2	5	ns
t <sub>PLZ</sub> , t <sub>PHZ</sub>	Receiver disable time				15	25	ns
torum torum		Driver enabled, See Figure 8			35	50	ns
$t_{PZL(2)},\ t_{PZH(2)}$	Receiver enable time	Driver disabled, See Figure 8			3	8	μs

# **DRIVER FUNCTION TABLE**

INPUT	ENABLE	OUTPUTS		
D	DE	Y	Z	
Н	Н	Н	L	Actively drive bus High
L	Н	L	Н	Actively drive bus Low
X	L	Z	Z	Driver disabled
Х	OPEN	Z	Z	Driver disabled by default
OPEN	Н	Н	L	Actively drive bus High by default

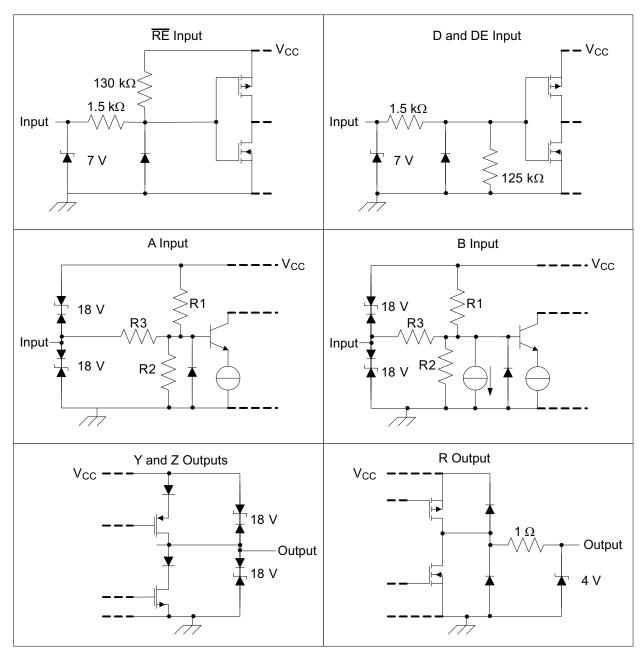
# **RECEIVER FUNCTION TABLE**

DIFFERENTIAL INPUT	ENABLE	OUTPUT	
$V_{ID} = V_A - V_B$	RE	R	
$V_{IT+} < V_{ID}$	L	Н	Receive valid bus High
$V_{IT-} < V_{ID} < V_{IT+}$	L	?	Indeterminate bus state
$V_{ID} < V_{IT-}$	L	L	Receive valid bus Low
X	Н	Z	Receiver disabled
X	OPEN	Z	Receiver disabled by default
Open-circuit bus	L	Н	Fail-safe high output
Short-circuit bus	L	Н	Fail-safe high output
Idle (terminated) bus	L	Н	Fail-safe high output

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# **EQUIVALENT INPUT AND OUTPUT SCHEMATIC DIAGRAMS**



	R1/R2	R3
SN65HVD37	18 kΩ	190 kΩ



#### PARAMETER MEASUREMENT INFORMATION

Input generator rate is 100 kbps, 50% duty cycle, rise and fall times less than 6 nsec, output impedance 50  $\Omega$ 

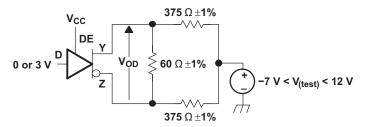


Figure 2. Measurement of Driver Differential Output Voltage With Common-mode Load

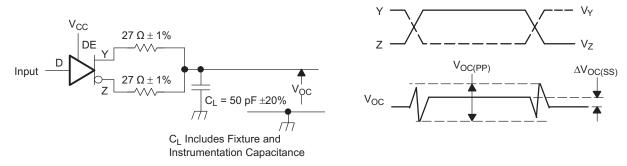


Figure 3. Measurement of Driver Differential and Common-mode Output with RS-485 Load

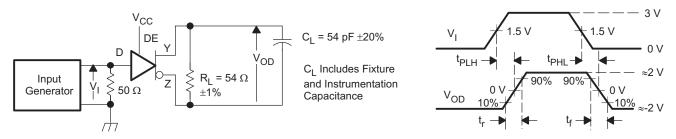
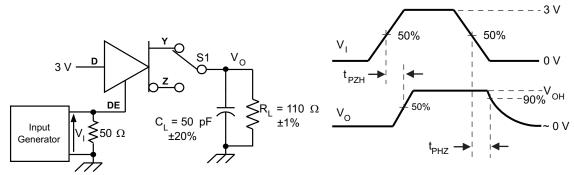


Figure 4. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays

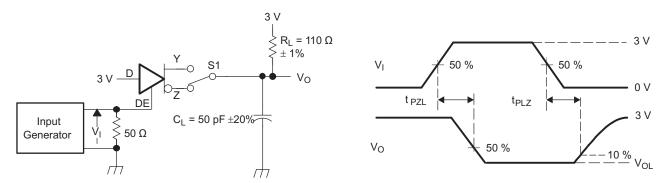


NOTE: D at 3 V to test non-inverting output, D at 0 V to test inverting output.  $C_i$  includes Fixture and Instrumentation Capacitance

Figure 5. Measurement of Driver Enable and Disable Times with Active High Output and Pull-down Load



# PARAMETER MEASUREMENT INFORMATION (continued)



NOTE: D at 0 V to test non-inverting output, D at 3 V to test inverting output.

C<sub>1</sub> Includes Fixture and Instrumentation Capacitance

Figure 6. Measurement of Driver Enable and Disable Times with Active Low Output and Pull-up Load

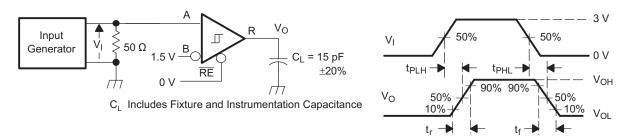


Figure 7. Measurement of Receiver Output Rise and Fall Times and Propagation Delays

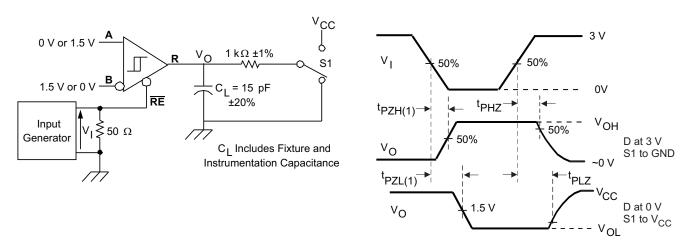
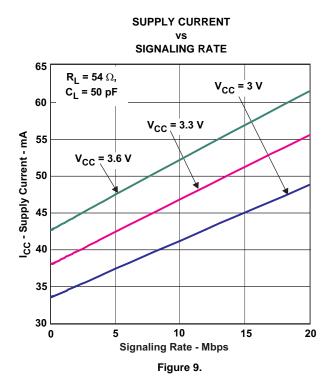
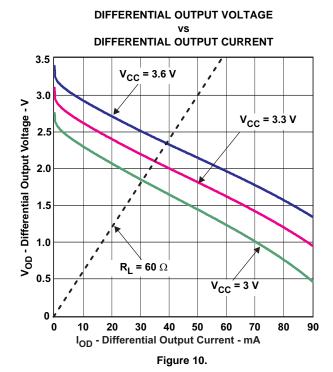


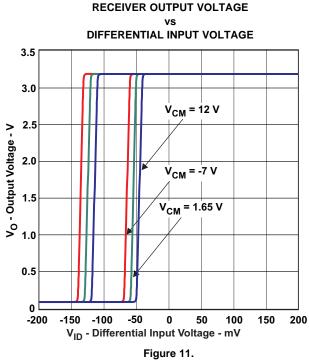
Figure 8. Measurement of Receiver Enable/Disable Times

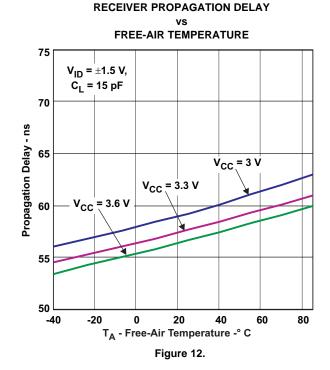


## **TYPICAL CHARACTERISTICS**





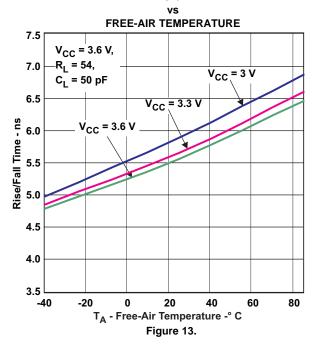






# TYPICAL CHARACTERISTICS (continued)

DRIVER RISE/FALL TIME



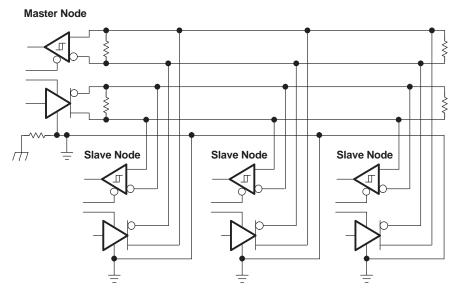


Figure 14. Example Full-Duplex Master/Slave Application Circuit



#### APPLICATION INFORMATION

#### RECEIVER FAILSAFE

The differential receiver is "failsafe" to invalid bus states caused by:

- open bus conditions such as a disconnected connector,
- · shorted bus conditions such as cable damage shorting the twisted-pair together,
- · or idle bus conditions that occur when no driver on the bus is actively driving.

In any of these cases, the differential receiver outputs a failsafe logic High state, so that the output of the receiver is not indeterminate.

In the HVD37, receiver failsafe is accomplished by offsetting the receiver thresholds so that the "input indeterminate" range does not include zero volts differential. In order to comply with the RS-422 and RS-485 standards, the receiver output must output a High when the differential input  $V_{ID}$  is more positive than 200 mV, and must output a Low when the  $V_{ID}$  is more negative than -200 mV. The receiver parameters which determine the failsafe performance are  $V_{IT+}$  and  $V_{IT-}$  and  $V_{HYS-}$ . In the Electrical Characteristics table,  $V_{IT-}$  has a typical value of -120 mV and a minimum (most negative) value of -200 mV, so differential signals more negative than -200 mV will always cause a Low receiver output. Similarly, differential signals more positive than 200 mV will always cause a High receiver output, because the typical value of  $V_{IT+}$  is -60mV, and  $V_{IT+}$  is never more positive than -20 mV under any conditions of temperature, supply voltage, or common-mode offset.

When the differential input signal is close to zero, it will still be above the  $V_{IT+}$  threshold, and the receiver output will be High. Only when the differential input is more negative than  $V_{IT-}$  will the receiver output transition to a Low state. So, the noise immunity of the receiver inputs during a bus fault condition includes the receiver hysteresis value  $V_{HYS}$  (the separation between  $V_{IT+}$  and  $V_{IT-}$ ) as well as the value of  $V_{IT+}$ .

For the HVD37, the typical noise immunity is about 120 mV, which is the negative noise level needed to exceed the  $V_{IT}$  threshold ( $V_{IT}$  TYP = -120 mV). In the worst case, the failsafe noise immunity is never less than 50 mV, which is set by the maximum positive threshold ( $V_{IT}$  MAX = -20mV) plus the minimum hysteresis voltage ( $V_{HYS}$  MIN = 30 mV).

#### **HOT-PLUGGING**

These devices are designed to operate in "hot swap" or "hot pluggable" applications. Key features for hot-pluggable applications are power-up, power-down glitch free operation, default disabled input/output pins, and receiver failsafe. An internal Power-On Reset circuit keeps the driver outputs in a high-impedance state until the supply voltage has reached a level at which the device will reliably operate. This ensures that no spurious transitions (glitches) will occur on the bus pin outputs as the power supply turns on or turns off.

As shown in the device FUNCTION TABLE, the ENABLE inputs have the feature of default disable on both the driver enable and receiver enable. This ensures that the device will neither drive the bus nor report data on the R pin until the associated controller actively drives the enable pins.

#### LOW POWER STANDBY MODE

As is customary with RS-485 devices, the receiver output is directly enabled/disabled by  $\overline{\text{RE}}$ , and the driver outputs are directly enabled/disabled by DE.

When both the driver and receiver are disabled, (DE=LO and RE=HI) the receiver differential comparator stage enters a standby mode for reduced power.

When either the Driver or Receiver is enabled, the receiver differential comparator stage is enabled for fast response to signal changes.

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# **REVISION HISTORY**

Cł	nanges from Original (October 2011) to Revision A	Pag
•	Changed the device From: Product Preview To: Production	



# PACKAGE OPTION ADDENDUM

6-Feb-2020

#### **PACKAGING INFORMATION**

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Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
SN65HVD37D	ACTIVE	SOIC	D	14	50	Green (RoHS & no Sb/Br)	NIPDAU	Level-1-260C-UNLIM	-40 to 85	HVD37	Samples
SN65HVD37DR	ACTIVE	SOIC	D	14	2500	Green (RoHS & no Sb/Br)	NIPDAU	Level-1-260C-UNLIM	-40 to 85	HVD37	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead/Ball Finish Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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6-Feb-2020

# D (R-PDSO-G14)

# PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AB.



# D (R-PDSO-G14)

# PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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