

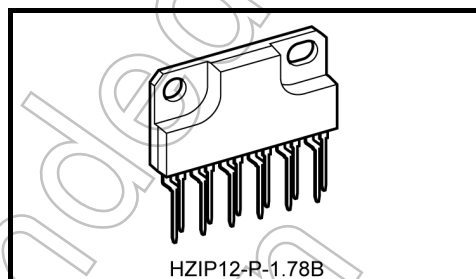
TA8429H, TA8429HQ

Full-bridge Driver (H-Switch) for DC Motor (Driver for Switching between Forward and Reverse Rotation)

The TA8429H/HQ is a full-bridge driver IC for brush motor rotation control. Four operating modes are selectable from forward, reverse, stop and brake.

The TA8429H/HQ is best suited to drive medium-sized DC and bipolar stepping motors.

Since the motor drive section and control section have separate power supply pins, the TA8429H/HQ also allows servo control.



Weight : 4.04 g (typ.)

Features

- Output current of up to 3.0 A (AVE.) and 4.5 A (PEAK)
- Four different modes (forward rotation, reverse rotation, stop, and brake) are supported.
A counter-electromotive force absorber diode is also incorporated.
- Stand-by mode available: $I_{ST} \leq 100 \mu A$
- Built-in thermal shutdown and short circuit protection circuits
- HZIP power package sealed
- Wide range of operating voltage: $V_{CC} = 7$ to $27 V$
 $V_S = 0$ to $27 V$
*Please consider the internal loss (V_{sat}) to operate the IC though minimum V_S is defined zero.

Terminals of TA8429 written below are sensitive to electrostatic discharge. When handling this product, ensure that the environment is protected against electrostatic discharge by using an earth strap, a conductive mat and an ionizer. Ensure also that the ambient temperature and relative humidity are maintained at reasonable levels.

Terminals which are sensitive to electrostatic discharge: No. 1, 2, and 12.

The IC should be installed correctly. Otherwise, the IC or peripheral parts and devices may be degraded or permanently damaged.

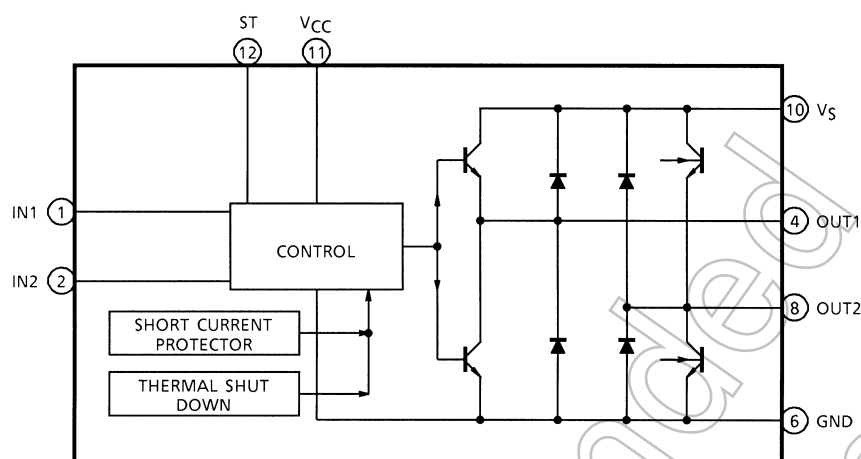
The TA8429HQ is a Sn-plated product. (The Pb-containing materials with a high melting point that are exempted from RoHS directives are used inside the IC.)

The following conditions apply to solderability:

*Solderability

1. Use of Sn-37Pb solder bath
 - *solder bath temperature = $230^{\circ}C$
 - *dipping time = 5 seconds
 - *number of times = once
 - *use of R-type flux
2. Use of Sn-3.0Ag-0.5Cu solder bath
 - *solder bath temperature = $245^{\circ}C$
 - *dipping time = 5 seconds
 - *the number of times = once
 - *use of R-type flux

Block Diagram

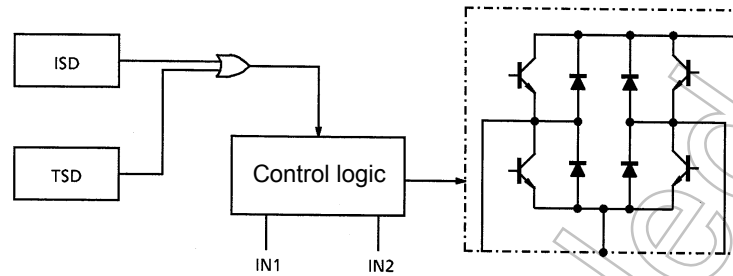


Pin Function

Pin No.	Symbol	Functional Description
1	IN1	These pins receive inputs for controlling the state of the outputs. The input sections incorporate a PNP-type voltage comparator.
2	IN2	
3	N.C	Non-connection
4	OUT1	This pin connects to a DC motor. It has a current carrying capacity of 3 A in both sink and source modes. A diode for absorbing counter-electromotive force in the motor is incorporated on both V_{CC} and ground sides.
5	N.C	Non-connection
6	GND	GND terminal
7	N.C	Non-connection
8	OUT2	This pin, along with pin 4, connects to a motor. It has the same function as pin 4. Its state is controlled with inputs to pins 1 and 2.
9	N.C	Non-connection
10	V_S	Supply voltage terminal for motor drive
11	V_{CC}	This is a supply voltage pin for the control section. It is completely separated from V_S .
12	ST	When this pin is open or connected to a ground, the current flowing through the motor is minimized (100 μ A).

How Multi-Protection Works

The TA8429H/HQ incorporates two protection functions: over-current (ISD) and overheat (TSD).



Note 1: These protection functions are only a means of temporarily avoiding some output short circuits or other abnormal conditions and are not guaranteed to prevent damage to the IC.

Note 2: If used under conditions where the absolute maximum ratings are exceeded, the IC may break down before the protection circuits start operating.

Overheat Protection (TSD)

• Basic operation

The input signal of the IC controls the output while the junction temperature (chip temperature) of the IC is equal to or lower than the TSD detection temperature. If the junction temperature becomes higher than the TSD detection temperature, the output enters a high-impedance state regardless of the level of the input signal.

• Explanation of the operation

The junction temperature is detected by monitoring the V_F of a diode on the chip. When the V_F becomes lower than the internal reference voltage, the control logic is directed to turn off the output transistor. While the V_F is higher than the reference voltage, the input signal at pins 1 and 2 controls the logic section.

Over-current Protection (ISD)

- **Basic operation**

When the output current (pin 4 or 8, that is, I_{sink} or I_{source}) is equal to or lower than the ISD detection current, the input signal controls the output. If the output current exceeds the detection current, it changes to a switching waveform shown in Figure 1.

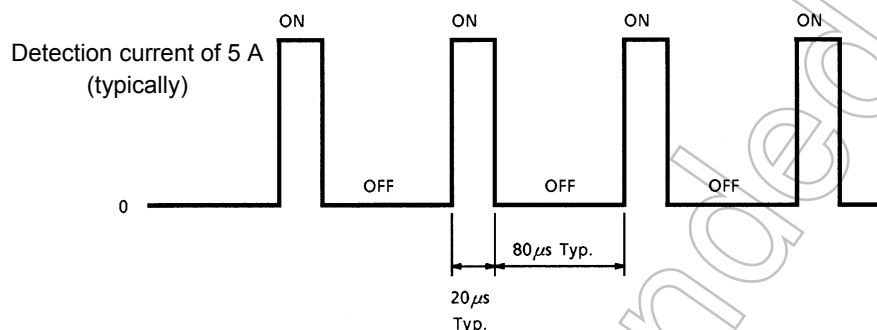


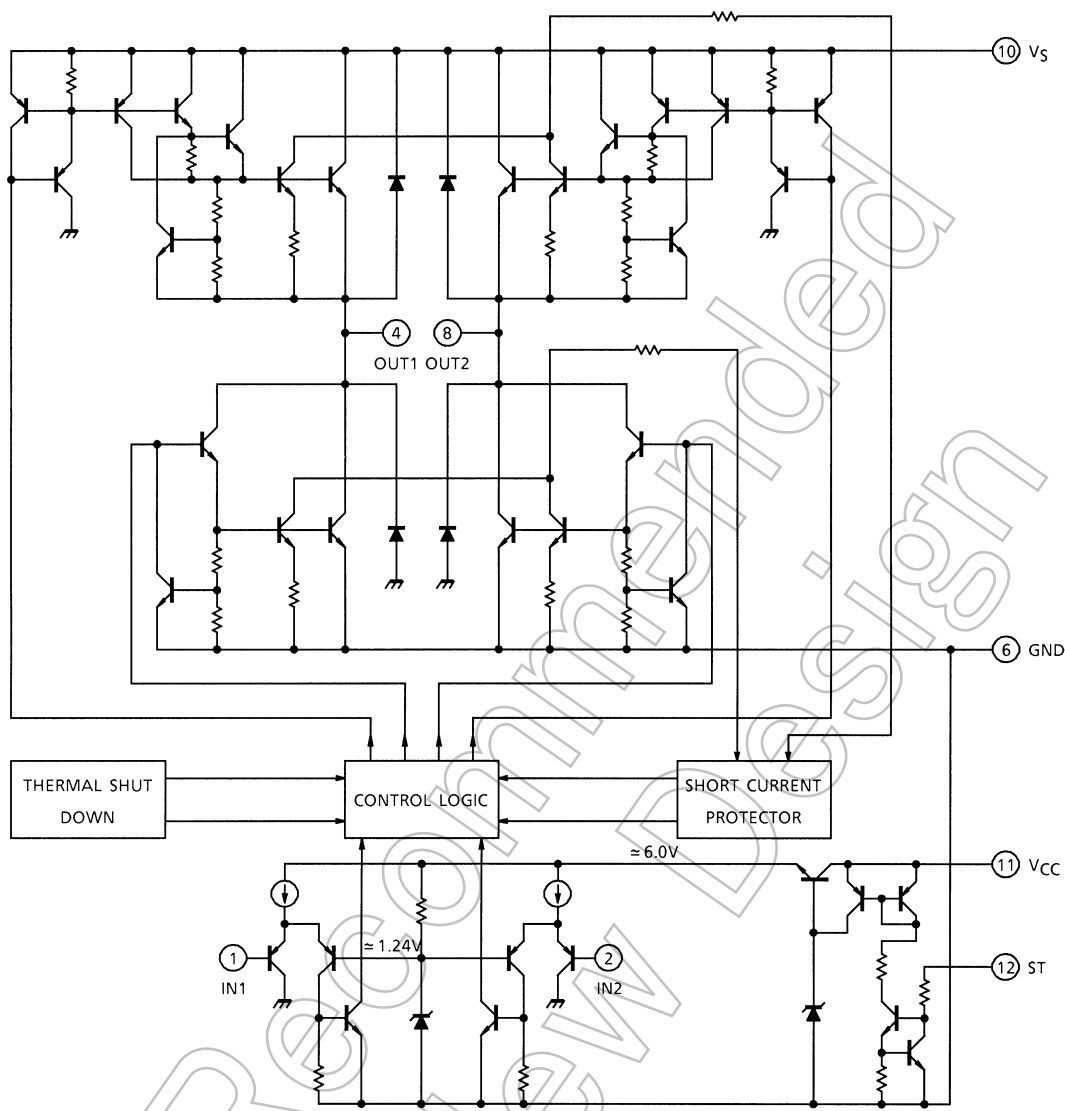
Figure 1 Basic operation

- **Explanation of the operation**

The output current is detected by monitoring the V_{BE} of each output transistor. A detector element is connected to each output transistor and to a short-circuit prevention circuit. If a current higher than the ISD detection current flows through one of the four output transistors, the short-circuit prevention circuit starts operating. This circuit incorporates a timer. If the over-current mode lasts for 20 μs (typically), the output is switched to the high-impedance state. It returns to the ON mode in 80 μs (typically). If the IC is still in the over current mode, the switching mode stated above is repeated until the IC is released from the over-current mode.

This circuit cannot limit all types of over current. If the outputs are short-circuited to each other or to a ground, the IC may break down before the protection circuit starts operating. Therefore use a resistor or fuse in the supply voltage (V_S) line.

Internal Circuit



Function

Input			Output		Mode
IN1	IN2	ST	OUT1	OUT2	Motor
H	H	H	L	L	Short brake
L	H	H	L	H	CCW (CW)
H	L	H	H	L	CW (CCW)
L	L	H	OFF (high impedance)		Stop
H/L	H/L	L	OFF (high impedance)		Stand-by

Absolute Maximum Ratings (T_a = 25°C)

Characteristics		Symbol	Rating	Unit
Supply voltage		V _{CC} , V _S	30	V
Input voltage		V _{IN}	-0.3 to V _{CC}	V
Output current	AVE.	I _O (AVE.)	3.0	A
	PEAK	I _O (PEAK)	4.5 (Note 1)	
Power dissipation		P _D	2.25 (Note 2)	W
			21.6 (Note 3)	
Operating temperature		T _{opr}	-30 to 85	°C
Storage temperature		T _{stg}	-55 to 150	°C

Note 1: t = 100 ms

Note 2: No heat sink

Note 3: T_C = 85°C

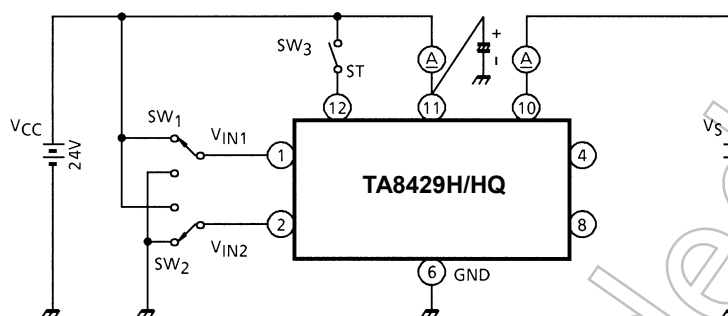
Electrical Characteristics (V_{CC} = 24 V, V_S = 24 V, T_a = 25°C)

Characteristics	Symbol	Test circuit	Test Condition	Min	Typ.	Max	Unit
Quiescent current (I) (V _{CC} Line)	I _{CC1}	1	Stop mode	—	6	12	mA
	I _{CC2}		Forward/reverse mode	—	20	40	
	I _{CC3}		Brake mode	—	20	40	
Quiescent current (II) (V _S Line)	I _{S1}	1	Stop mode	—	3	8	mA
	I _{S2}		Forward/reverse mode	—	16	40	
	I _{S3}		Brake mode	—	3	8	
Input voltage	V _{INL}	2	—	—	—	0.8	V
	V _{INH}		—	2.0	—	—	
Input current	I _{INL}	2	V _{IN} = GND	—	—	12	μA
	I _{INH}		V _{IN} = V _{CC}	—	—	10	
Output saturation voltage (Note)	V _{sat1}	3	I _O = 1.5 A	—	2.1	2.8	V
	V _{sat2}		I _O = 3.0 A	—	3.3	4.1	
Output leakage current	I _{LU}	4	V _L = 25 V	—	—	50	μA
	I _{LL}		V _L = 25 V	—	—	50	
Diode forward voltage	V _{FU}	5	I _F = 3.0 A	—	5.0	—	V
	V _{FL}		I _F = 3.0 A	—	1.5	—	
Thermal shutdown circuit operating temperature	T _{SD}	—	—	—	150	—	°C
Stand-by current	I _{ST}	1	—	—	—	100	μA
Propagation delay time	t _{pLH}	2	—	—	1	—	μs
	t _{pHL}	2	—	—	1	—	

Note: Upper and lower side total

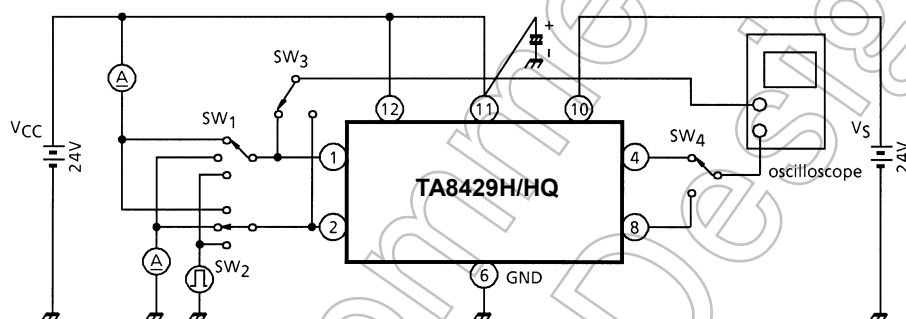
Test Circuit 1

I_{S1} , I_{S2} , I_{S3} , I_{CC1} , I_{CC2} , I_{CC3} , I_{ST}



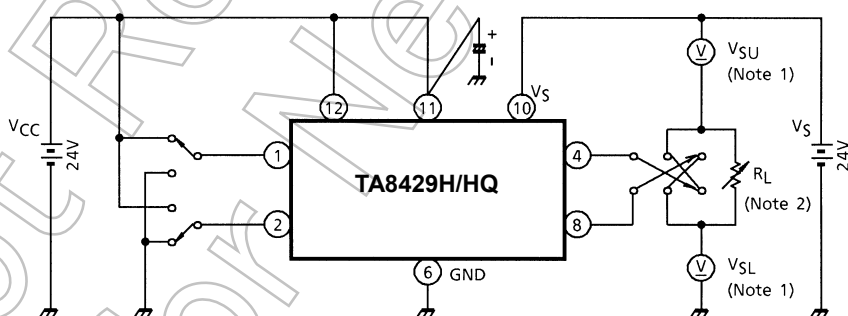
Test Circuit 2

V_{INH} , V_{INL} , I_{INH} , I_{INL} , t_{PHL} , t_{PLH}



Test Circuit 3

V_{sat}

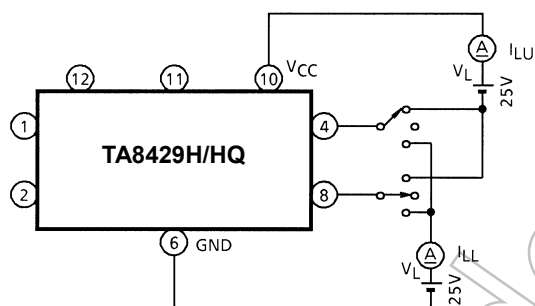


Note 1: $V_{sat} = V_{SU} + V_{SL}$

Note 2: Calibrate I_O to 1.5/3.0 A by R_L

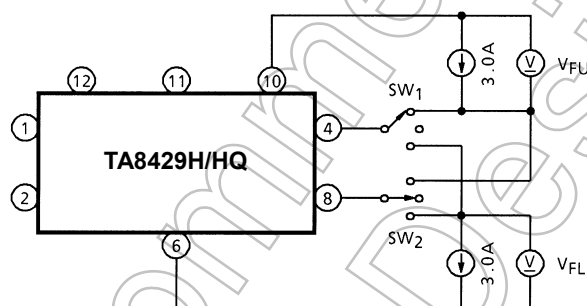
Test Circuit 4

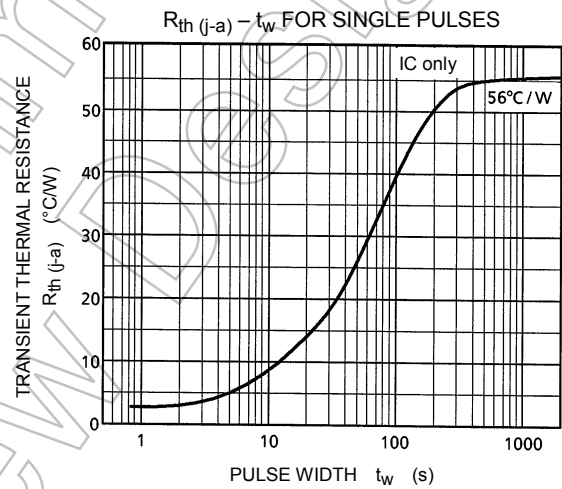
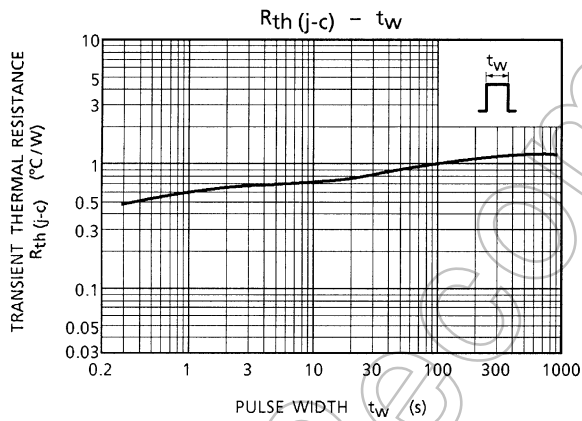
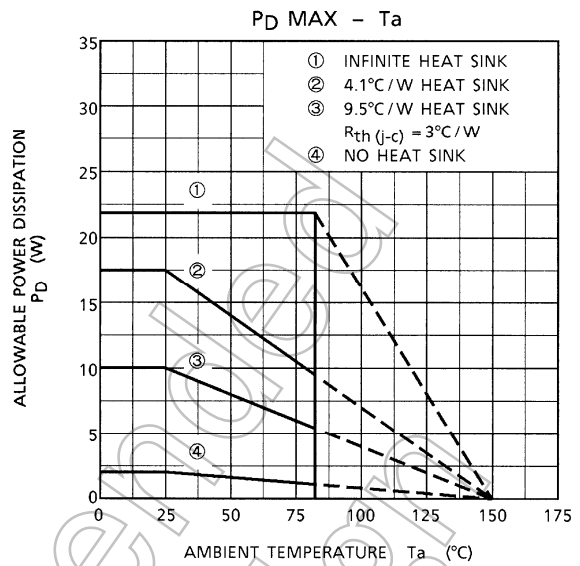
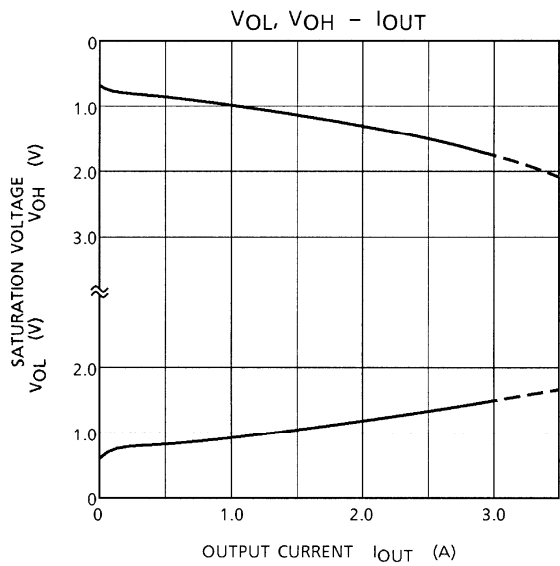
I_{LU} , I_{LL}



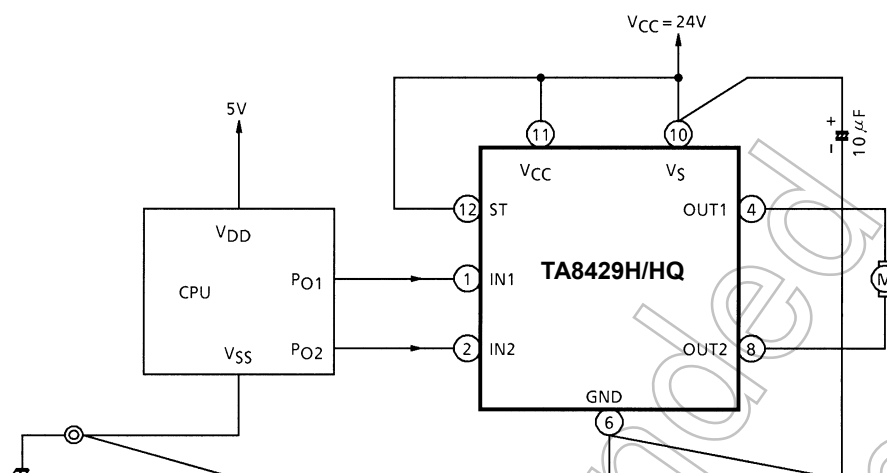
Test Circuit 5

V_{FU} , V_{FL}

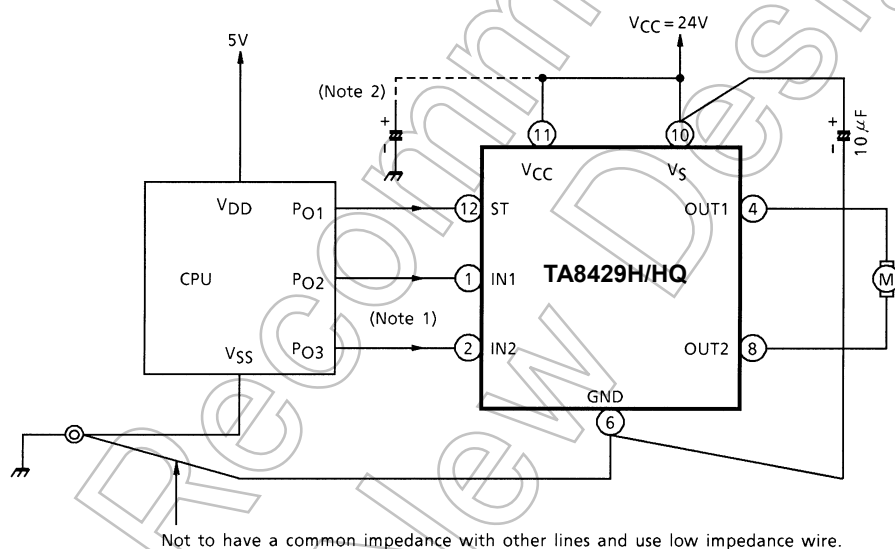




Application Circuit 1



Application Circuit 2 (Separated standby function)

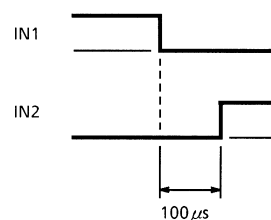


Note 1: Insert OFF-TIME (100 μ s or more) when the input signal is switched (between forward and reverse rotation and between forward/reverse rotation and brake).

Note 2: Connect if required.

Note 3: When turning on the power (V_{CC}/V_S), keep both IN1 and IN2 on a low level. Do not switch the inputs (IN1/IN2) before the V_{CC}/V_S reaches its rated value (as shown in Application Circuit Example 1). If the ST pin is connected to a CPU (Application Circuit Example 2), turn on the power while ST, IN1, and IN2 are kept on a low level. After this, switch the ST/IN1/IN2.

Note 4: Utmost care is necessary in the design of the output, V_{CC} , and GND lines since the IC may be destroyed by short-circuiting between outputs, air contamination faults, or faults due to improper grounding, or by short-circuiting between contiguous pins.



HZIP12-P-1.78B

Technical drawing of a 12-pin connector. The drawing includes three views: a top view, a side view, and a front view. Dimensions are provided in millimeters (mm).

Top View Dimensions:

- Overall width: 15.72 ± 0.2
- Pin pitch: 1.778
- Pin diameter: $\phi 3.6 \pm 0.2$
- Pin length: 1.42 TYP
- Pin spacing from edge: 1.1 ± 0.1
- Pin length: 0.55 ± 0.1
- Pin diameter: $\phi 0.25 \text{ (M)}$

Side View Dimensions:

- Overall height: 14.8 ± 0.3
- Pin length: 11.31 ± 0.3
- Pin length: 6.5 ± 0.3
- Pin length: 1.45 ± 0.2

Front View Dimensions:

- Overall width: 22.9 MAX
- Overall width: 22.4 ± 0.2
- Pin length: 2.075 TYP
- Pin length: $0.4^{+0.1}_{-0.05}$
- Pin length: 2.0

Weight: 4.04 g (typ.)

Notes on Contents**1. Block Diagrams**

Some of the functional blocks, circuits, or constants in the block diagram may be omitted or simplified for explanatory purposes.

2. Equivalent Circuits

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

3. Timing Charts

Timing charts may be simplified for explanatory purposes.

4. Application Circuits

The application circuits shown in this document are provided for reference purposes only. Thorough evaluation is required, especially at the mass production design stage.

Toshiba does not grant any license to any industrial property rights by providing these examples of application circuits.

5. Test Circuits

Components in the test circuits are used only to obtain and confirm the device characteristics. These components and circuits are not guaranteed to prevent malfunction or failure from occurring in the application equipment.

IC Usage Considerations**Notes on handling of ICs**

- [1] The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these ratings.
Exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.
- [2] Use an appropriate power supply fuse to ensure that a large current does not continuously flow in case of over current and/or IC failure. The IC will fully break down when used under conditions that exceed its absolute maximum ratings, when the wiring is routed improperly or when an abnormal pulse noise occurs from the wiring or load, causing a large current to continuously flow and the breakdown can lead smoke or ignition. To minimize the effects of the flow of a large current in case of breakdown, appropriate settings, such as fuse capacity, fusing time and insertion circuit location, are required.
- [3] If your design includes an inductive load such as a motor coil, incorporate a protection circuit into the design to prevent device malfunction or breakdown caused by the current resulting from the inrush current at power ON or the negative current resulting from the back electromotive force at power OFF. IC breakdown may cause injury, smoke or ignition.
Use a stable power supply with ICs with built-in protection functions. If the power supply is unstable, the protection function may not operate, causing IC breakdown. IC breakdown may cause injury, smoke or ignition.
- [4] Do not insert devices in the wrong orientation or incorrectly.
Make sure that the positive and negative terminals of power supplies are connected properly.
Otherwise, the current or power consumption may exceed the absolute maximum rating, and exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.
In addition, do not use any device that is applied the current with inserting in the wrong orientation or incorrectly even just one time.

Points to remember on handling of ICs**(1) Over current Protection Circuit**

Over current protection circuits (referred to as current limiter circuits) do not necessarily protect ICs under all circumstances. If the Over current protection circuits operate against the over current, clear the over current status immediately.

Depending on the method of use and usage conditions, such as exceeding absolute maximum ratings can cause the over current protection circuit to not operate properly or IC breakdown before operation. In addition, depending on the method of use and usage conditions, if over current continues to flow for a long time after operation, the IC may generate heat resulting in breakdown.

(2) Thermal Shutdown Circuit

Thermal shutdown circuits do not necessarily protect ICs under all circumstances. If the thermal shutdown circuits operate against the over temperature, clear the heat generation status immediately.

Depending on the method of use and usage conditions, such as exceeding absolute maximum ratings can cause the thermal shutdown circuit to not operate properly or IC breakdown before operation.

(3) Heat Radiation Design

In using an IC with large current flow such as power amp, regulator or driver, please design the device so that heat is appropriately radiated, not to exceed the specified junction temperature (T_J) at any time and condition. These ICs generate heat even during normal use. An inadequate IC heat radiation design can lead to decrease in IC life, deterioration of IC characteristics or IC breakdown. In addition, please design the device taking into consideration the effect of IC heat radiation with peripheral components.

(4) Back-EMF

When a motor rotates in the reverse direction, stops or slows down abruptly, a current flow back to the motor's power supply due to the effect of back-EMF. If the current sink capability of the power supply is small, the device's motor power supply and output pins might be exposed to conditions beyond maximum ratings. To avoid this problem, take the effect of back-EMF into consideration in system design.

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