

SNOSAW4D-SEPTEMBER 2007-REVISED MARCH 2013

# LMP2234 Quad Micropower, 1.6V, Precision, Operational Amplifier with CMOS Input

Check for Samples: LMP2234

# **FEATURES**

- (For V<sub>S</sub> = 5V, Typical Unless Otherwise Noted)
- Supply Current at 1.8V 31 µA
- Operating Voltage Range 1.6V to 5.5V •
- Low TCV<sub>OS</sub> ±0.75 µV/°C (max)
- $V_{OS} \pm 150 \mu V (max)$
- Input Bias Current ±20 fA
- PSRR 120 dB
- CMRR 97 dB
- Open Loop Gain 120 dB
- Gain Bandwidth Product 130 kHz
- Slew Rate 58 V/ms
- Input Voltage Noise, f = 1 kHz 60 nV/ $\sqrt{Hz}$
- Temperature Range –40°C to 125°C

## APPLICATIONS

- **Precision Instrumentation Amplifiers**
- **Battery Powered Medical Instrumentation**
- **High Impedance Sensors**
- Strain Gauge Bridge Amplifier
- **Thermocouple Amplifiers**

# DESCRIPTION

The LMP2234 is a quad micropower precision amplifier designed for battery powered applications. The 1.6 to 5.5V operating supply voltage range and quiescent power consumption of only 50 µW extend the battery life in portable systems. The LMP2234 is part of the LMP<sup>™</sup> precision amplifier family. The high impedance CMOS input makes it ideal for instrumentation and other sensor interface applications.

The LMP2234 has a maximum offset voltage of 150  $\mu$ V and 0.3  $\mu$ V/°C offset drift along with low bias current of only ±20 fA. These precise specifications make the LMP2234 a great choice for maintaining system accuracy and long term stability.

The LMP2234 has a rail-to-rail output that swings 15 mV from the supply voltage, which increases system dynamic range. The common mode input voltage range extends 200 mV below the negative supply, thus the LMP2234 is ideal for ground sensing in single supply applications.

The LMP2234 is offered in 14-Pin SOIC and TSSOP packages.

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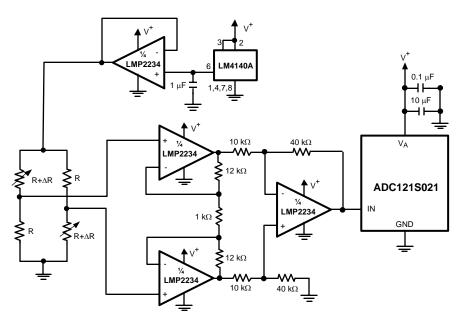
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TEXAS INSTRUMENTS

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#### TYPICAL APPLICATION



#### Figure 1. Strain Gauge Bridge Amplifier

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### Absolute Maximum Ratings <sup>(1)(2)</sup>

ESD Tolerance <sup>(3)</sup>	Human Body Model	2000V
	Machine Model	100V
Differential Input Voltage		±300 mV
Supply Voltage ( $V_S = V^+ - V^-$ )	6V	
Voltage on Input/Output Pins	V <sup>+</sup> + 0.3V, V <sup>-</sup> - 0.3V	
Storage Temperature Range		-65°C to 150°C
Junction Temperature <sup>(4)</sup>		150°C
Mounting Temperature Infrared or Convection (20 sec.)		+235°C
Wave Soldering Lead Temperature (10 s	ec.)	+260°C

(1) Absolute Maximum Ratings indicate limits beyond which damage may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and test conditions, see the Electrical Characteristics.

(2) If Military/Aerospace specified devices are required, please contact the TI Sales Office/ Distributors for availability and specifications.
 (3) Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of

JEDEC)Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

(4) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/|\theta_{JA}|$ . All numbers apply for packages soldered directly onto a PC Board.

SNOSAW4D-SEPTEMBER 2007-REVISED MARCH 2013

### Operating Ratings <sup>(1)</sup>

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Operating Temperature Range <sup>(2)</sup>	perating Temperature Range <sup>(2)</sup>				
Supply Voltage ( $V_S = V^+ - V^-$ )	1.6V to 5.5V				
Package Thermal Resistance ( $\theta_{JA}$ ) <sup>(2)</sup>	14-Pin SOIC	101.5 °C/W			
	14-Pin TSSOP	121 °C/W			

(1) Absolute Maximum Ratings indicate limits beyond which damage may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and test conditions, see the Electrical Characteristics.

(2) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

## 5V DC Electrical Characteristics<sup>(1)</sup>

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 5V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ , and  $R_L > 1 \text{ M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (2)	Тур (3)	Max (2)	Units
V <sub>OS</sub>	Input Offset Voltage			±10	±150 <b>±230</b>	μV
TCV <sub>OS</sub>	Input Offset Voltage Drift	LMP2234A		±0.3	±0.75	μV/°C
		LMP2234B		±0.3	±2.5	
I <sub>BIAS</sub>	Input Bias Current			±0.02	±1 <b>±50</b>	pА
I <sub>OS</sub>	Input Offset Current			±5		fA
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 4V$	81 <b>80</b>	97		dB
PSRR	Power Supply Rejection Ratio	$1.6V \le V^+ \le 5.5V$ $V_{CM} = 0V$	83 <b>82</b>	120		dB
CMVR	Common Mode Voltage Range	CMRR ≥ 80 dB CMRR ≥ 79 dB	-0.2 - <b>0.2</b>		4.2 <b>4.2</b>	V
A <sub>VOL</sub>	Large Signal Voltage Gain	$V_{O} = 0.3V$ to 4.7V R <sub>L</sub> = 10 kΩ to V <sup>+</sup> /2	110 <b>108</b>	120		dB
Vo	Output Swing High	$ \begin{array}{l} R_{L} = 10 \ k\Omega \ to \ V^{+\!/\!2} \\ V_{IN}(diff) = 100 \ mV \end{array} $		17	50 <b>50</b>	mV from either
	Output Swing Low	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ V <sub>IN</sub> (diff) = -100 mV		17	50 <b>50</b>	rail
lo	Output Current	Sourcing, $V_0$ to $V^-$ $V_{IN}(diff) = 100 \text{ mV}$	27 <b>19</b>	30		mA
		Sinking, $V_O$ to $V^+$ $V_{IN}(diff) = -100 \text{ mV}$	17 <b>12</b>	22		
I <sub>S</sub>	Supply Current			36	48 <b>50</b>	μΑ

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No ensured specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ . Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

(2) All limits are specified by testing, statistical analysis or design.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

(4) The short circuit test is a momentary open loop test.



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## 5V AC Electrical Characteristics<sup>(1)</sup>

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 5V$ ,  $V^- = 0V$ ,  $V_{CM} = V_0 = V^+/2$ , and  $R_L > 1 \text{ M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions $C_L = 20 \text{ pF}, R_L = 10 \text{ k}\Omega$		Min (2)	Typ	Max (2)	Units
GBWP	Gain Bandwidth Product				130		kHz
SR	Slew Rate	A <sub>V</sub> = +1	Falling Edge	33 <b>32</b>	58		) //ma.a
			Rising Edge	33 <b>32</b>	48		V/ms
θ <sub>m</sub>	Phase Margin	C <sub>L</sub> = 20 pF, F	$R_{L} = 10 \text{ k}\Omega$		68		deg
G <sub>m</sub>	Gain Margin	C <sub>L</sub> = 20 pF, F	R <sub>L</sub> = 10 kΩ		27		dB
e <sub>n</sub>	Input-Referred Voltage Noise Density	f = 1 kHz			60		nV/√Hz
	Input-Referred Voltage Noise	0.1 Hz to 10	Hz		2.3		μV <sub>PP</sub>
i <sub>n</sub>	Input-Referred Current Noise Density	f = 1 kHz	f = 1 kHz		10		fA/√Hz
THD+N	Total Harmonic Distortion + Noise	f = 100 Hz, R	<sub>L</sub> = 10 kΩ		0.002		%

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No ensured specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ . Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

(2) All limits are specified by testing, statistical analysis or design.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

# 3.3V DC Electrical Characteristics<sup>(1)</sup>

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 3.3V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ , and  $R_L > 1 \text{ M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (2)	Тур (3)	Max (2)	Units
V <sub>OS</sub>	Input Offset Voltage			±10	±160 <b>±250</b>	μV
TCV <sub>OS</sub>	Input Offset Voltage Drift	LMP2234A		±0.3	±0.75	µV/°C
		LMP2234B		±0.3	±2.5	
I <sub>BIAS</sub>	Input Bias Current			±0.02	±1 <b>±50</b>	рА
I <sub>OS</sub>	Input Offset Current			±5		fA
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 2.3V$	79 <b>77</b>	92		dB
PSRR	Power Supply Rejection Ratio	$1.6V \le V^+ \le 5.5V$ $V_{CM} = 0V$	83 <b>82</b>	120		dB
CMVR	Common Mode Voltage Range	CMRR ≥ 78 dB CMRR ≥ 77 dB	-0.2 - <b>0.2</b>		2.5 <b>2.5</b>	V
A <sub>VOL</sub>	Large Signal Voltage Gain	$V_O = 0.3V$ to $3V$ $R_L = 10 k\Omega$ to $V^+/2$	108 <b>107</b>	120		dB
Vo	Output Swing High	$\begin{array}{l} R_{L} = 10 \ k\Omega \ to \ V^{+\!\!/2} \\ V_{IN}(diff) = 100 \ mV \end{array}$		14	50 <b>50</b>	mV from either
	Output Swing Low	$R_L = 10 k\Omega \text{ to V}^+/2$ $V_{IN}(diff) = -100 mV$		14	50 <b>50</b>	rail

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No ensured specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ . Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

(2) All limits are specified by testing, statistical analysis or design.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.



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## 3.3V DC Electrical Characteristics<sup>(1)</sup> (continued)

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 3.3V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ , and  $R_L > 1 \text{ M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (2)	Тур (3)	Max (2)	Units
I <sub>O</sub> Output Current	Output Current	Sourcing, $V_O$ to $V^-$ $V_{IN}$ (diff) = 100 mV	11 <b>8</b>	14		mA
		Sinking, $V_O$ to $V^+$ $V_{IN}$ (diff) = -100 mV	8 5	11		
I <sub>S</sub>	Supply Current			34	44 <b>46</b>	μA

(4) The short circuit test is a momentary open loop test.

### 3.3V AC Electrical Characteristics<sup>(1)</sup>

Unless otherwise is specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 3.3V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ , and  $R_L > 1 \text{ M}\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions		Min (2)	Тур (3)	Max (2)	Units
GBWP	Gain Bandwidth Product	$C_{L} = 20 \text{ pF}, R_{L} = 10 \text{ k}\Omega$			128		kHz
SR	Slew Rate	$A_V = +1, C_L = 20 \text{ pF}$	Falling Edge		58		V/ms
		$R_L = 10 \ k\Omega$	Rising Edge		48		v/ms
θ <sub>m</sub>	Phase Margin	C <sub>L</sub> = 20 pF, R <sub>L</sub> = 10 l	xΩ		66		deg
G <sub>m</sub>	Gain Margin	C <sub>L</sub> = 20 pF, R <sub>L</sub> = 10 l	xΩ		26		dB
e <sub>n</sub>	Input-Referred Voltage Noise Density	f = 1 kHz			60		nV/√Hz
	Input-Referred Voltage Noise	0.1 Hz to 10 Hz			2.4		μV <sub>PP</sub>
i <sub>n</sub>	Input-Referred Current Noise Density	f = 1 kHz			10		fA/√Hz
THD+N	Total Harmonic Distortion + Noise	f = 100 Hz, R <sub>L</sub> = 10 k	Ω		0.003		%

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No ensured specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ . Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

(2) All limits are specified by testing, statistical analysis or design.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

# 2.5V DC Electrical Characteristics<sup>(1)</sup>

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 2.5V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ , and  $R_L > 1M\Omega$ . Boldface limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (2)	Тур (3)	Max (2)	Units
V <sub>OS</sub>	Input Offset Voltage			±10	±190 <b>±275</b>	μV
TCV <sub>OS</sub>	Input Offset Voltage Drift	LMP2234A		±0.3	±0.75	
		LMP2234B		±0.3	±2.5	μV/°C
I <sub>BIAS</sub>	Input Bias Current			±0.02	±1.0 <b>±50</b>	pА
I <sub>OS</sub>	Input Offset Current			±5		fA

<sup>(1)</sup> Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No ensured specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ . Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

(2) All limits are specified by testing, statistical analysis or design.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.



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# 2.5V DC Electrical Characteristics<sup>(1)</sup> (continued)

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 2.5V$ ,  $V^- = 0V$ ,  $V_{CM} = V_0 = V^+/2$ , and  $R_L > 1M\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (2)	Тур (3)	Max (2)	Units
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 1.5V$	77 <b>76</b>	91		dB
PSRR	Power Supply Rejection Ratio	$1.6V \le V^+ \le 5.5V$ $V_{CM} = 0V$	83 <b>82</b>	120		dB
CMVR	Common Mode Voltage Range	CMRR ≥ 77 dB CMRR ≥ 76 dB	-0.2 - <b>0.2</b>		1.7 <b>1.7</b>	V
A <sub>VOL</sub>	Large Signal Voltage Gain	$V_{O} = 0.3V$ to 2.2V R <sub>L</sub> = 10 k $\Omega$ to V <sup>+</sup> /2	104 <b>104</b>	120		dB
Vo	Output Swing High	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ $V_{IN}(diff) = 100 \text{ mV}$		12	50 <b>50</b>	mV
	Output Swing Low	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ $V_{IN}(diff) = -100 \text{ mV}$		13	50 <b>50</b>	from either rail
lo	Output Current	Sourcing, $V_O$ to $V^-$ $V_{IN}$ (diff) = 100 mV	5 <b>4</b>	8		— mA
		Sinking, $V_0$ to V <sup>+</sup> $V_{IN}$ (diff) = -100 mV	3.5 <b>2.5</b>	7		
I <sub>S</sub>	Supply Current			32	44 <b>46</b>	μA

(4) The short circuit test is a momentary open loop test.

## 2.5V AC Electrical Characteristics<sup>(1)</sup>

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 2.5V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ , and  $R_L > 1M\Omega$ . Boldface limits apply at the temperature extremes.

Symbol	Parameter	Conditions $C_{L} = 20 \text{ pF},  \text{R}_{L} = 10  \text{k} \Omega$		Min (2)	Тур (3)	Max (2)	Units
GBWP	Gain Bandwidth Product				128		kHz
SR	Slew Rate	$A_V = +1, C_L = 20 \text{ pF}$	Falling Edge		58		N//
		$R_L = 10 \ k\Omega$	Rising Edge		48		V/ms
θ <sub>m</sub>	Phase Margin	$C_{L} = 20 \text{ pF}, R_{L} = 10 \text{ km}$	Ω		64		deg
G <sub>m</sub>	Gain Margin	$C_L = 20 \text{ pF}, R_L = 10 \text{ km}$	Ω		26		dB
en	Input-Referred Voltage Noise Density	f = 1 kHz			60		nV/√Hz
	Input-Referred Voltage Noise	Voltage Noise 0.1 Hz to 10 Hz			2.5		μV <sub>PP</sub>
i <sub>n</sub>	Input-Referred Current Noise Density	f = 1 kHz			10		fA/√Hz
THD+N	Total Harmonic Distortion + Noise	f = 100 Hz, R <sub>L</sub> = 10 kg	2		0.005		%

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No ensured specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ . Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

(2) All limits are specified by testing, statistical analysis or design.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.



### **1.8V DC Electrical Characteristics** <sup>(1)</sup>

Unless otherwise specified, all limits are ensured for  $T_A = 25^{\circ}$ C, V<sup>+</sup> = 1.8V, V<sup>-</sup> = 0V, V<sub>CM</sub> = V<sub>O</sub> = V<sup>+</sup>/2, and R<sub>L</sub> > 1 MΩ. Boldface limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (2)	Тур (3)	Max (2)	Units
V <sub>OS</sub>	Input Offset Voltage			±10	±230 ± <b>325</b>	μV
TCV <sub>OS</sub>	Input Offset Voltage Drift	LMP2234A		±0.3	±0.75	µV/°C
		LMP2234B		±0.3	±2.5	
I <sub>BIAS</sub>	Input Bias Current			±0.02	±1.0 <b>±50</b>	pА
I <sub>OS</sub>	Input Offset Current			±5		fA
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 0.8V$	76 <b>75</b>	92		dB
PSRR	Power Supply Rejection Ratio	$1.6V \le V^+ \le 5.5V$ $V_{CM} = 0V$	83 <b>82</b>	120		dB
CMVR	Common Mode Voltage Range	CMRR ≥ 76 dB CMRR ≥ 75 dB	-0.2 <b>0</b>		1.0 <b>1.0</b>	V
A <sub>VOL</sub>	Large Signal Voltage Gain	$V_{O} = 0.3V$ to 1.5V R <sub>L</sub> = 10 k $\Omega$ to V <sup>+</sup> /2	103 <b>103</b>	120		dB
Vo	Output Swing High	$\begin{array}{l} R_{L} = 10 \ k\Omega \ to \ V^{+\!/\!2} \\ V_{IN}(diff) = 100 \ mV \end{array}$		12	50 <b>50</b>	mV from either
	Output Swing Low	$R_L = 10 \text{ k}\Omega \text{ to V}^+/2$ V <sub>IN</sub> (diff) = -100 mV		13	50 <b>50</b>	rail
l <sub>O</sub>	Output Current <sup>(4)</sup>	Sourcing, $V_0$ to $V^-$ $V_{IN}(diff) = 100 \text{ mV}$	2.5 <b>2</b>	5		mA
		Sinking, $V_O$ to $V^+$ $V_{IN}(diff) = -100 \text{ mV}$	2 <b>1.5</b>	5		
I <sub>S</sub>	Supply Current			31	42 <b>44</b>	μA

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T<sub>J</sub> = T<sub>A</sub>. No ensured specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where T<sub>J</sub> > T<sub>A</sub>. Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

All limits are specified by testing, statistical analysis or design. (2)

Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary (3) over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped (4) The short circuit test is a momentary open loop test.



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### **1.8V AC Electrical Characteristics** <sup>(1)</sup>

Unless otherwise is specified, all limits are ensured for  $T_A = 25^{\circ}C$ ,  $V^+ = 1.8V$ ,  $V^- = 0V$ ,  $V_{CM} = V_O = V^+/2$ , and  $R_L > 1 M\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions		Min (2)	Тур (3)	Max (2)	Units
GBWP	Gain Bandwidth Product	$C_L$ = 20 pF, $R_L$ = 10 k $\Omega$			127		kHz
SR	Slew Rate	$A_V = +1, C_L = 20 \text{ pF}$	Falling Edge		58		
		$R_L = 10 \text{ k}\Omega$	Rising Edge		48		V/ms
θ <sub>m</sub>	Phase Margin	$C_{L} = 20 \text{ pF}, R_{L} = 10 \text{ k}\Omega$			70		deg
G <sub>m</sub>	Gain Margin	$C_L = 20 \text{ pF}, R_L = 10$	kΩ		25		dB
e <sub>n</sub>	Input-Referred Voltage Noise Density	f = 1 kHz			60		nV/√Hz
	Input-Referred Voltage Noise	0.1 Hz to 10 Hz			2.4		μV <sub>PP</sub>
i <sub>n</sub>	Input-Referred Current Noise Density	f = 1 kHz			10		fA/√Hz
THD+N	Total Harmonic Distortion + Noise	f = 100 Hz, R <sub>L</sub> = 10 k	Ω		0.005		%

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . No ensured specification of parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ . Absolute Maximum Ratings indicate junction temperature limits beyond which the device may be permanently degraded, either mechanically or electrically.

(2) All limits are specified by testing, statistical analysis or design.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

**Connection Diagram** 

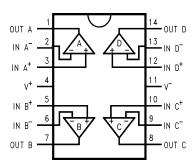


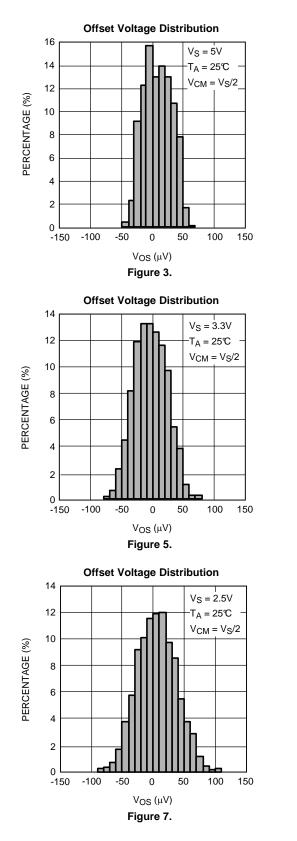
Figure 2. 14-Pin TSSOP/SOIC

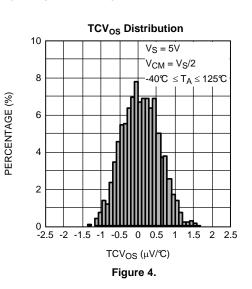






Unless otherwise Specified:  $T_A = 25^{\circ}C$ ,  $V_S = 5V$ ,  $V_{CM} = V_S/2$ , where  $V_S = V^+ - V^-$ 





TCV<sub>OS</sub> Distribution

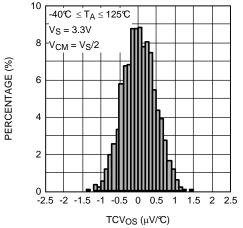
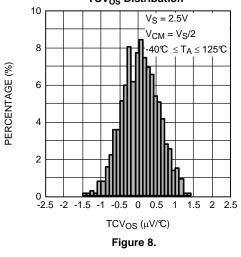


Figure 6.

TCV<sub>OS</sub> Distribution



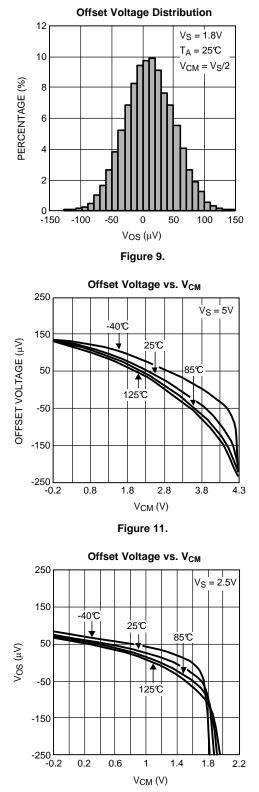
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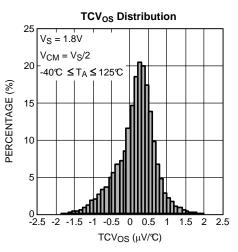
**Texas** 

# Typical Performance Characteristics (continued)

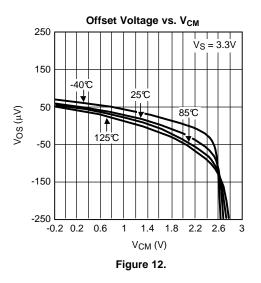
Unless otherwise Specified:  $T_A = 25^{\circ}C$ ,  $V_S = 5V$ ,  $V_{CM} = V_S/2$ , where  $V_S = V^+ - V^-$ 

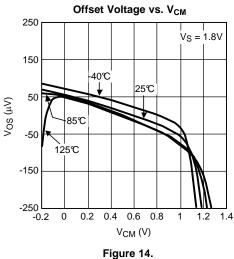






#### Figure 10.



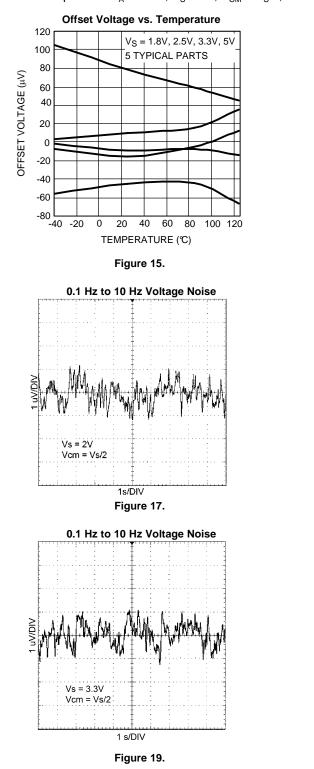


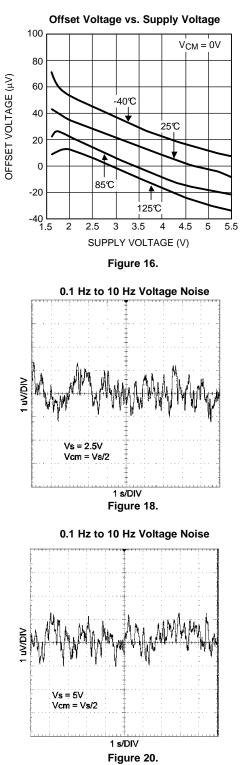


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## **Typical Performance Characteristics (continued)**

Unless otherwise Specified:  $T_A = 25^{\circ}C$ ,  $V_S = 5V$ ,  $V_{CM} = V_S/2$ , where  $V_S = V^+ - V^-$ 





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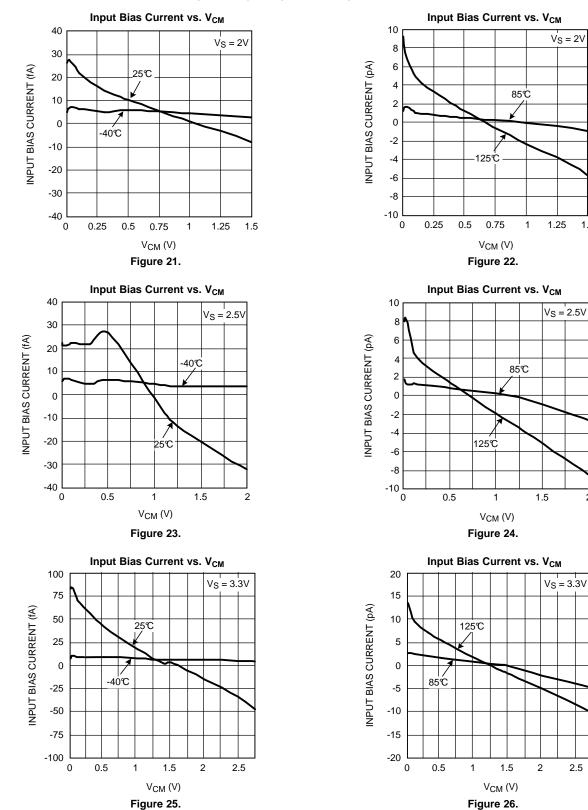
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# **Typical Performance Characteristics (continued)**

Unless otherwise Specified:  $T_A = 25^{\circ}C$ ,  $V_S = 5V$ ,  $V_{CM} = V_S/2$ , where  $V_S = V^+ - V^-$ 

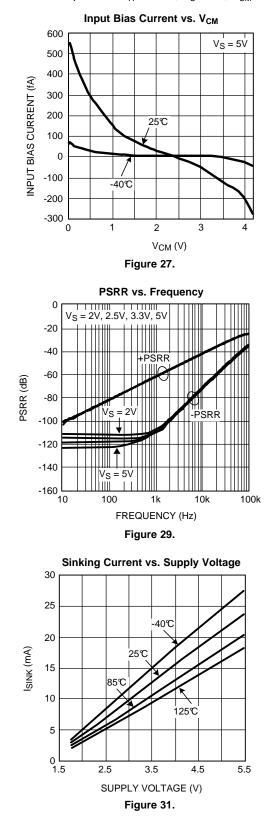


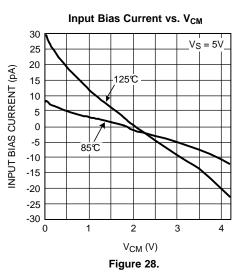


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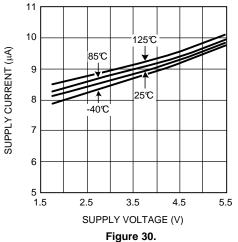
# **Typical Performance Characteristics (continued)**

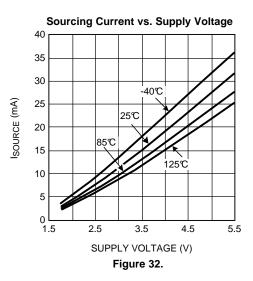
Unless otherwise Specified:  $T_A$  = 25°C,  $V_S$  = 5V,  $V_{CM}$  =  $V_S/2,$  where  $V_S$  =  $V^+$  -  $V^-$ 





Supply Current vs. Supply Voltage (per channel)





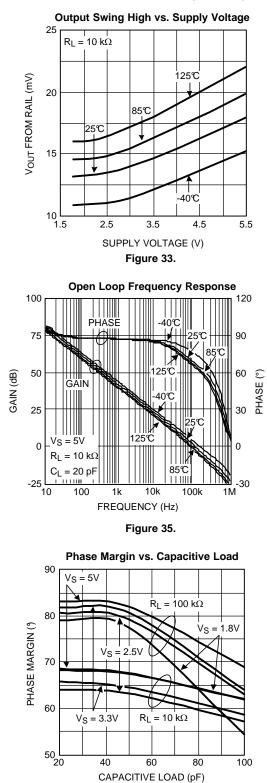
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**ISTRUMENTS** 

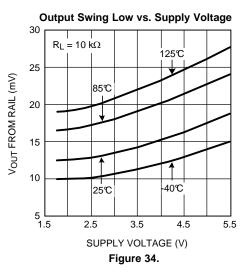
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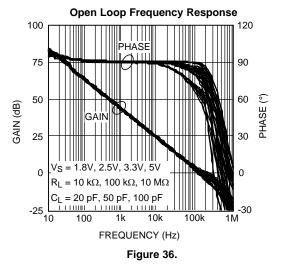
# **Typical Performance Characteristics (continued)**

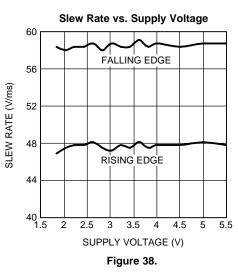
Unless otherwise Specified:  $T_A = 25^{\circ}C$ ,  $V_S = 5V$ ,  $V_{CM} = V_S/2$ , where  $V_S = V^+ - V^-$ 









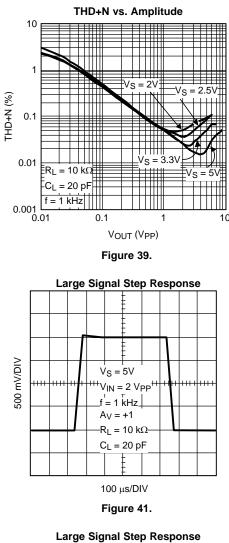


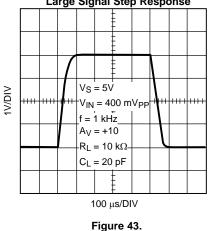


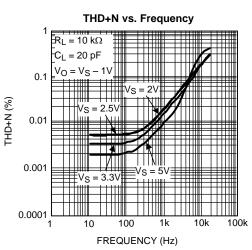
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# **Typical Performance Characteristics (continued)**

Unless otherwise Specified:  $T_{A}$  = 25°C,  $V_{S}$  = 5V,  $V_{CM}$  =  $V_{S}/2,$  where  $V_{S}$  =  $V^{+}$  -  $V^{-}$ 

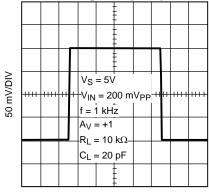






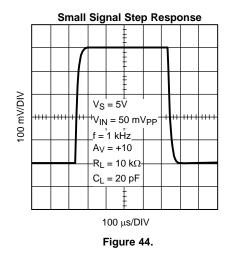
#### Figure 40.





#### 100 μs/DIV

#### Figure 42.



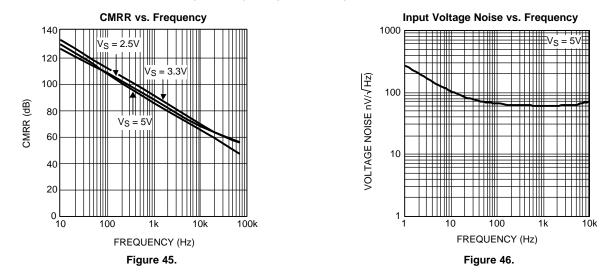
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EXAS

# Typical Performance Characteristics (continued)

Unless otherwise Specified:  $T_{A}$  = 25°C,  $V_{S}$  = 5V,  $V_{CM}$  =  $V_{S}/2,$  where  $V_{S}$  =  $V^{\ast}$  -  $V^{-}$ 





### **APPLICATION INFORMATION**

#### LMP2234

The LMP2234 is a quad CMOS precision amplifier that offers low offset voltage, low offset voltage drift, and high gain while consuming less than 10 µA of supply current per channel.

The LMP2234 is a micropower op amp, consuming only 36  $\mu$ A of current. Micropower op amps extend the run time of battery powered systems and reduce energy consumption in energy limited systems. The ensured supply voltage range of 1.8V to 5.5V along with the ultra-low supply current extend the battery run time in two ways. The extended power supply voltage range of 1.8V to 5.5V enables the op amp to function when the battery voltage has depleted from its nominal value down to 1.8V. In addition, the lower power consumption increases the life of the battery.

The LMP2234 has input referred offset voltage of only ±150  $\mu$ V maximum at room temperature. This offset is ensured to be less than ±230  $\mu$ V over temperature. This minimal offset voltage along with very low TCV<sub>OS</sub> of only 0.3  $\mu$ V/°C typical allows more accurate signal detection and amplification in precision applications.

The low input bias current of only  $\pm 20$  fA gives the LMP2234 superiority for use in high impedance sensor applications. Bias current of an amplifier flows through source resistance of the sensor and the voltage resulting from this current flow appears as a noise voltage on the input of the amplifier. The low input bias current enables the LMP2234 to interface with high impedance sensors while generating negligible voltage noise. Thus the LMP2234 provides better signal fidelity and a higher signal-to-noise ratio when interfacing with high impedance sensors.

Texas Instruments is heavily committed to precision amplifiers and the market segments they serve. Technical support and extensive characterization data is available for sensitive applications or applications with a constrained error budget.

The operating voltage range of 1.8V to 5.5V over the extensive temperature range of -40°C to 125°C makes the LMP2234 an excellent choice for low voltage precision applications with extensive temperature requirements.

The LMP2234 is offered in the 14-pin TSSOP and 14-pin SOIC package. These small packages are ideal solutions for area constrained PC boards and portable electronics.

### TOTAL NOISE CONTRIBUTION

The LMP2234 has very low input bias current, very low input current noise, and low input voltage noise for micropower amplifiers. As a result, this amplifier makes a great choice for circuits with high impedance sensor applications.

shows the typical input noise of the LMP2234 as a function of source resistance at f = 1 kHz where:

- e<sub>n</sub> denotes the input referred voltage noise
- e<sub>i</sub> is the voltage drop across source resistance due to input referred current noise or e<sub>i</sub> = R<sub>S\*</sub> i<sub>n</sub>
- e<sub>t</sub> shows the thermal noise of the source resistance
- e<sub>ni</sub> shows the total noise on the input.

Where:

$$e_{ni} = \sqrt{e_n^2 + e_i^2 + e_t^2}$$

(1)

The input current noise of the LMP2234 is so low that it will not become the dominant factor in the total noise unless source resistance exceeds 300 M $\Omega$ , which is an unrealistically high value. As is evident in Figure 47, at lower R<sub>S</sub> values, total noise is dominated by the amplifier's input voltage noise. Once R<sub>S</sub> is larger than 100 k $\Omega$ , then the dominant noise factor becomes the thermal noise of R<sub>S</sub>. As mentioned before, the current noise will not be the dominant noise factor for any practical application.



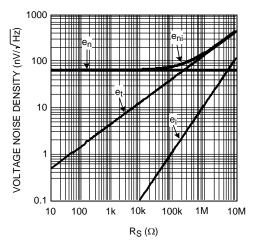


Figure 47. Total Input Noise

## **VOLTAGE NOISE REDUCTION**

The LMP2234 has an input voltage noise of  $60 \text{ nV}/\sqrt{\text{Hz}}$ . While this value is very low for micropower amplifiers, this input voltage noise can be further reduced by placing multiple amplifiers in parallel as shown in Figure 48. The total voltage noise on the output of this circuit is divided by the square root of the number of amplifiers used in this parallel combination. This is because each individual amplifier acts as an independent noise source, and the average noise of independent sources is the quadrature sum of the independent sources divided by the number of sources. For N identical amplifiers, this means:

REDUCED INPUT VOLTAGE NOISE = 
$$\frac{1}{N} \sqrt{e_{n1}^2 + e_{n2}^2 + \dots + e_{nN}^2}$$
  
=  $\frac{1}{N} \sqrt{Ne_n^2} = \frac{\sqrt{N}}{N} e_n$   
=  $\frac{1}{\sqrt{N}} e_n$  (2)

Figure 48 shows a schematic of this input voltage noise reduction circuit using the LMP2234. Typical resistor values are:  $R_G = 10\Omega$ ,  $R_F = 1 k\Omega$ , and  $R_O = 1 k\Omega$ .

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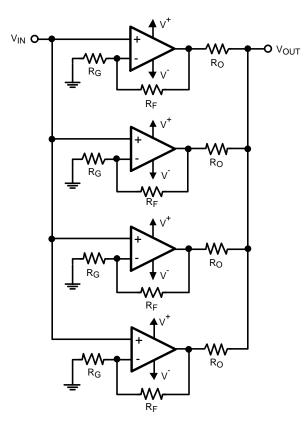
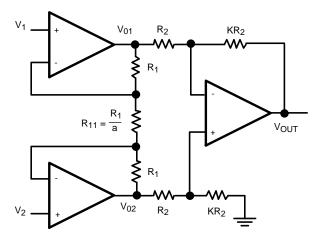


Figure 48. Noise Reduction Circuit

### PRECISION INSTRUMENTATION AMPLIFIER

Measurement of very small signals with an amplifier requires close attention to the input impedance of the amplifier, the gain of the signal on the inputs, and the gain on each input of the amplifier. This is because the difference of the input signal on the two inputs is of interest and the common signal is considered noise. A classic circuit implementation that is used is an instrumentation amplifier. Instrumentation amplifiers have a finite, accurate, and stable gain. They also have extremely high input impedances and very low output impedances. Finally they have an extremely high CMRR so that the amplifier can only respond to the differential signal. A typical instrumentation amplifier is shown in Figure 49.





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(4)

There are two stages in this amplifier. The last stage, the output stage, is a differential amplifier. In an ideal case the two amplifiers of the first stage, the input stage, would be configured as buffers to isolate the inputs. However they cannot be connected as followers because of mismatch in amplifiers. That is why there is a balancing resistor between the two. The product of the two stages of gain will give the gain of the instrumentation amplifier. Ideally, the CMRR should be infinite. However the output stage has a small non-zero common mode gain which results from resistor mismatch.

In the input stage of the circuit, current is the same across all resistors. This is due to the high input impedance and low input bias current of the LMP2234.

$$GIVEN: I_{R_1} = I_{R_{11}}$$
 (3)

By Ohm's Law:

 $V_{O1} - V_{O2} = (2R_1 + R_{11}) I_{R_{11}}$ 

= (2a + 1) R<sub>11</sub> • I<sub>R11</sub>

However:

$$V_{R_{11}} = V_1 - V_2$$
 (5)

So we have:

$$V_{01} - V_{02} = (2a+1)(V_1 - V_2)$$
(6)

Now looking at the output of the instrumentation amplifier:

$V_{O} = \frac{KR_{2}}{R_{2}} (V_{O2} - V_{O1})$	
= -K (V <sub>O1</sub> - V <sub>O2</sub> )	(7)

Substituting from Equation 6:

$$V_{O} = -K (2a + 1) (V_{1} - V_{2})$$
(8)

This shows the gain of the instrumentation amplifier to be:

	-	•	
-K(2a+1)		(9)	

Typical values for this circuit can be obtained by setting: a = 12 and K = 4. This results in an overall gain of -100.

### SINGLE SUPPLY STRAIN GAUGE BRIDGE AMPLIFIER

Strain gauges are popular electrical elements used to measure force or pressure. Strain gauges are subjected to an unknown force which is measured as the deflection on a previously calibrated scale. Pressure is often measured using the same technique; however this pressure needs to be converted into force using an appropriate transducer. Strain gauges are often resistors which are sensitive to pressure or to flexing. Sense resistor values range from tens of ohms to several hundred kilo-ohms. The resistance change which is a result of applied force across the strain gauge might be 1% of its total value. An accurate and reliable system is needed to measure this small resistance change. Bridge configurations offer a reliable method for this measurement.

Bridge sensors are formed of four resistors, connected as a quadrilateral. A voltage source or a current source is used across one of the diagonals to excite the bridge while a voltage detector across the other diagonal measures the output voltage.

Bridges are mainly used as null circuits or to measure differential voltages. Bridges will have no output voltage if the ratios of two adjacent resistor values are equal. This fact is used in null circuit measurements. These are particularly used in feedback systems which involve electrochemical elements or human interfaces. Null systems force an active resistor, such as a strain gauge, to balance the bridge by influencing the measured parameter.



Often in sensor applications at lease one of the resistors is a variable resistor, or a sensor. The deviation of this active element from its initial value is measured as an indication of change in the measured quantity. A change in output voltage represents the sensor value change. Since the sensor value change is often very small, the resulting output voltage is very small in magnitude as well. This requires an extensive and very precise amplification circuitry so that signal fidelity does not change after amplification.

Sensitivity of a bridge is the ratio of its maximum expected output change to the excitation voltage change.

Figure 50(a) shows a typical bridge sensor and Figure 50(b) shows the bridge with four sensors. R in Figure 50(b) is the nominal value of the sense resistor and the deviations from R are proportional to the quantity being measured.

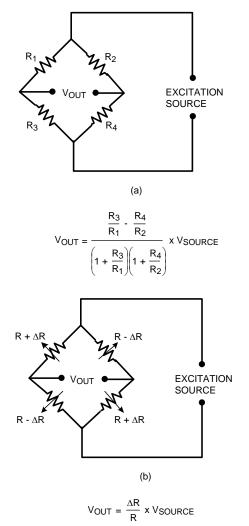


Figure 50. Bridge Sensor

Instrumentation amplifiers are great for interfacing with bridge sensors. Bridge sensors often sense a very small differential signal in the presence of a larger common mode voltage. Instrumentation amplifiers reject this common mode signal.

Figure 51 shows a strain gauge bridge amplifier. In this application one of the LMP2234 amplifiers is used to buffer the LM4140A's precision output voltage. The LM4140A is a precision voltage reference. The other three amplifiers in the LMP2234 are used to form an instrumentation amplifier. This instrumentation amplifier uses the LMP2234's high CMRR and low  $V_{OS}$  and TCV<sub>OS</sub> to accurately amplify the small differential signal generated by the output of the bridge sensor. This amplified signal is then fed into the ADC121S021 which is a 12-bit analog to digital converter. This circuit works on a single supply voltage of 5V.

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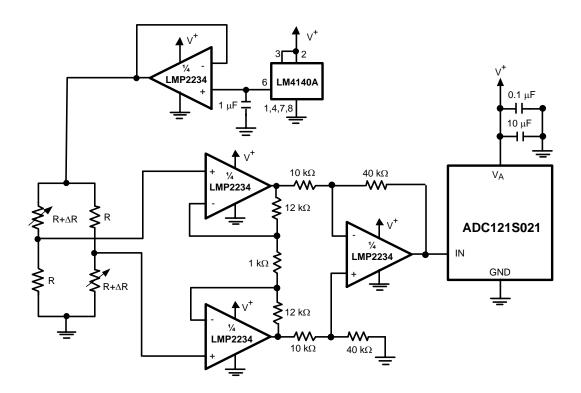


Figure 51. Strain Gauge Bridge Amplifier

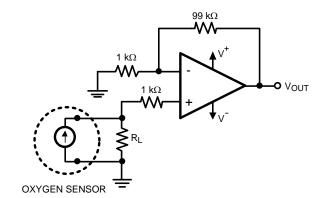
## PORTABLE GAS DETECTION SENSOR

Gas sensors are used in many different industrial and medical applications. They generate a current which is proportional to the percentage of a particular gas sensed in an air sample. This current goes through a load resistor and the resulting voltage drop is measured. Depending on the sensed gas and sensitivity of the sensor, the output current can be in the order of tens of microamperes to a few milliamperes. Gas sensor datasheets often specify a recommended load resistor value or they suggest a range of load resistors to choose from.

Oxygen sensors are used when air quality or oxygen delivered to a patient needs to be monitored. Fresh air contains 20.9% oxygen. Air samples containing less than 18% oxygen are considered dangerous. Oxygen sensors are also used in industrial applications where the environment must lack oxygen. An example is when food is vacuum packed. There are two main categories of oxygen sensors, those which sense oxygen when it is abundantly present (i.e. in air or near an oxygen tank) and those which detect very small traces of oxygen in ppm.

Figure 52 shows a typical circuit used to amplify the output signal of an oxygen detector. The LMP2234 makes an excellent choice for this application as it draws only 36  $\mu$ A of current and operates on supply voltages down to 1.8V. This application detects oxygen in air. The oxygen sensor outputs a known current through the load resistor. This value changes with the amount of oxygen present in the air sample. Oxygen sensors usually recommend a particular load resistor value or specify a range of acceptable values for the load resistor. Oxygen sensors typically have a life of one to two years. The use of the micropower LMP2234 means minimal power usage by the op amp and it enhances the battery life. Depending on other components present in the circuit design, the battery could last for the entire life of the oxygen sensor. The precision specifications of the LMP2234, such as its very low offset voltage, low TCV<sub>OS</sub>, low input bias current, low CMRR, and low PSRR are other factors which make the LMP2234 a great choice for this application.







# **REVISION HISTORY**

Cł	nanges from Revision C (March 2013) to Revision D	Page
•	Changed layout of National Data Sheet to TI format	22



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23-Aug-2017

# PACKAGING INFORMATION

Orderable Device	Status	Package Type	•	Pins	•	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
LMP2234AMA/NOPB	ACTIVE	SOIC	D	14	55	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP2234 AMA	Samples
LMP2234AMAE/NOPB	ACTIVE	SOIC	D	14	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP2234 AMA	Samples
LMP2234AMAX/NOPB	ACTIVE	SOIC	D	14	2500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP2234 AMA	Samples
LMP2234AMT/NOPB	ACTIVE	TSSOP	PW	14	94	Pb-Free (RoHS)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP223 4AMT	Samples
LMP2234AMTE/NOPB	ACTIVE	TSSOP	PW	14	250	Pb-Free (RoHS)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP223 4AMT	Samples
LMP2234BMA/NOPB	ACTIVE	SOIC	D	14	55	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP2234 BMA	Samples
LMP2234BMAE/NOPB	ACTIVE	SOIC	D	14	250	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP2234 BMA	Samples
LMP2234BMAX/NOPB	ACTIVE	SOIC	D	14	2500	Green (RoHS & no Sb/Br)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP2234 BMA	Samples
LMP2234BMT/NOPB	ACTIVE	TSSOP	PW	14	94	Pb-Free (RoHS)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP223 4BMT	Samples
LMP2234BMTE/NOPB	ACTIVE	TSSOP	PW	14	250	Pb-Free (RoHS)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP223 4BMT	Samples
LMP2234BMTX/NOPB	ACTIVE	TSSOP	PW	14	2500	Pb-Free (RoHS)	CU SN	Level-1-260C-UNLIM	-40 to 125	LMP223 4BMT	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> **RoHS**: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <= 1000ppm threshold. Antimony trioxide based flame retardants must also meet the <= 1000ppm threshold requirement.



23-Aug-2017

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# PACKAGE MATERIALS INFORMATION

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### TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal												
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMP2234AMAE/NOPB	SOIC	D	14	250	178.0	16.4	6.5	9.35	2.3	8.0	16.0	Q1
LMP2234AMAX/NOPB	SOIC	D	14	2500	330.0	16.4	6.5	9.35	2.3	8.0	16.0	Q1
LMP2234AMTE/NOPB	TSSOP	PW	14	250	178.0	12.4	6.95	5.6	1.6	8.0	12.0	Q1
LMP2234BMAE/NOPB	SOIC	D	14	250	178.0	16.4	6.5	9.35	2.3	8.0	16.0	Q1
LMP2234BMAX/NOPB	SOIC	D	14	2500	330.0	16.4	6.5	9.35	2.3	8.0	16.0	Q1
LMP2234BMTE/NOPB	TSSOP	PW	14	250	178.0	12.4	6.95	5.6	1.6	8.0	12.0	Q1
LMP2234BMTX/NOPB	TSSOP	PW	14	2500	330.0	12.4	6.95	5.6	1.6	8.0	12.0	Q1

TEXAS INSTRUMENTS

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# PACKAGE MATERIALS INFORMATION

24-Aug-2017



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMP2234AMAE/NOPB	SOIC	D	14	250	210.0	185.0	35.0
LMP2234AMAX/NOPB	SOIC	D	14	2500	367.0	367.0	35.0
LMP2234AMTE/NOPB	TSSOP	PW	14	250	210.0	185.0	35.0
LMP2234BMAE/NOPB	SOIC	D	14	250	210.0	185.0	35.0
LMP2234BMAX/NOPB	SOIC	D	14	2500	367.0	367.0	35.0
LMP2234BMTE/NOPB	TSSOP	PW	14	250	210.0	185.0	35.0
LMP2234BMTX/NOPB	TSSOP	PW	14	2500	367.0	367.0	35.0

D (R-PDSO-G14)

PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AB.





NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
   E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



PW (R-PDSO-G14)

PLASTIC SMALL OUTLINE



A. An integration of the information o

Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.

Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.

E. Falls within JEDEC MO-153





NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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